

New topological (computable) invariants for real-valued maps and multivalued maps; application to dynamics

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1 Background

- Maps, TC1-forms, critical values and critical points
- Configurations
- Dynamics

2 The invariants and the results

3 The description of the invariants δ and γ

MAPS, MULTIVALUED MAPS, TC1-forms

- **(tame) map** $f : M \rightarrow \mathbb{R}$
 - (i). M ANR-space, f continuous,
 - (ii). $(f^{-1}(t))$ ANR
- **(tame) multivalued map.** $\{U_i, f_i : U_i \rightarrow \mathbb{R}\}$ or 1-Cech cocycle on M .
 - (i) U_i open sets and $\bigcup U_i = M$,
 - (ii) $f_i - f_j|_{U_i \cap U_j}$ constant
- **equivalent multivalued maps** $\{U_i, f_i\} \sim \{V_j, g_j\}$ iff $\{U_i, V_j, f_i, g_j\}$ is a multivalued map
- A **(tame) TC 1-form** ω is an equivalency class of (tame) multivalued maps
- $(\mathcal{Z}_t^1(M))$ $\mathcal{Z}^1(M)$ the set of all (tame)TC1-forms is a \mathbb{R} -vector space equipped with the uniform convergence topology.

what a TC1-form ω does ?

- ω defines $\xi = \xi_\omega \in H^1(M; \mathbb{R})$, equivalently the homomorphism $\underline{\omega} : H_1(M; \mathbb{Z}) \rightarrow \mathbb{R}$,
- when M is compact $\underline{\omega}$ gives:
 - 1 the group $\Gamma \subset \mathbb{R}$, $\Gamma = \text{img}(\underline{\omega}) \subset \mathbb{R}$, $\Gamma \simeq \mathbb{Z}^n$
 - 2 the Γ -principal covering $\pi : \tilde{M} \rightarrow M$,
- ω provides the real-valued Γ -equivariant maps $f : \tilde{M} \rightarrow \mathbb{R}$ with $\pi^*(\omega) = df$ called lifts of ω unique up to additive constant .

Critical values and critical points

For a tame map $f : M \rightarrow \mathbb{R}$

- $t_0 \in \mathbb{R}$ is a *critical value* iff the topology of $f^{-1}(t)$ changes for in t the neighborhood of t_0 .
- $x \in M$ is a *critical point* if $f(x)$ is a critical value for the restriction of f to any neighborhood U of x .
- *Critical points* make sense for a TC1-form ω

CONFIGURATIONS

For Y topological space

- $Conf(Y) := \{\delta : Y \rightarrow \mathbb{Z}_{\geq 0} \mid \#(\text{supp } \delta) < \infty\}$

$$\delta = \left\{ \begin{array}{l} y_1, y_2, \dots, y_k \\ n_1, n_2, \dots, n_k \end{array} \right\}$$

- $Conf_n(Y) := \{\delta \in Conf(Y) \mid \sum_{y \in M} \delta(y) = n\}$

- $Conf_n(Y) = Y^n / \Sigma_n$

- $Conf(Y) = \bigsqcup_n Conf_n(Y)$

A closed subset $K \subset Y$ induces a topology on $Conf(Y \setminus K)$ the *bottleneck topology*. When $K = \emptyset$ this topology on $Conf(Y)$ is referred to as the *collision topology*

Bottleneck topology

A fundamental neighborhood of $\delta \in \text{Conf}(Y \setminus K)$,

$\text{Conf}_k(Y) \ni \delta = \left\{ \begin{matrix} y_1, y_2, \dots, y_k \\ n_1, n_2, \dots, n_k \end{matrix} \right\}$ is indexed by a collection of disjoint open subsets $\{U_1, \dots, U_k, V\}$ with $U_i \ni y_i$ and $V \supset K$

$$\mathcal{U}(\delta; U_1, \dots, U_k, V) := \left\{ \delta' \in \text{Conf}(Y \setminus K) \mid \begin{array}{l} \text{supp} \delta' \subset \bigcup U_i \cup V \\ \sum_{x \in U_i} \delta'(x) = \delta(y_i) = n_i \end{array} \right.$$

DYNAMICS

Flows on M , M compact ANR= one parameter group of homeomorphisms

$$\mu : \mathbb{R} \times M \rightarrow M, \mu(t, \mu(s, x)) = \mu(t + s, x) \text{ and } \mu(0, x) = x.$$

Trajectory through $x \in M$: the set $\tau \subset M$ of the form

$$\tau = \mu(\mathbb{R} \times x)$$

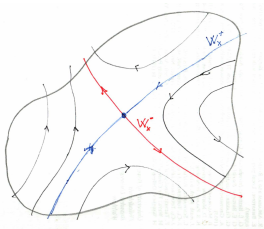
EXAMPLE: A smooth vector field X , on a smooth closed manifold M generates a smooth flow, a one parameter group of diffeomorphisms $\mu^X : \mathbb{R} \times M \rightarrow M$.

ELEMENTS OF DYNAMICS

- 1 **Rest points** $\mathcal{R}(X) := \{x \in M \mid X(x) = 0\}$,
- 2 **Instantons** $\mathcal{I}(x, y) =$ isolated trajectories, from x to y ,
 $x, y \in \mathcal{R}(X)$,
- 3 **Closed trajectories** (isolated).

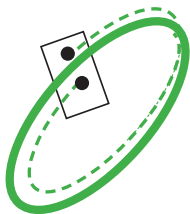
Rest - points For $x \in \mathcal{R}(X)$

- W_x^- unstable set, $i(x) := \dim W_x^-$ **Morse index** of x
- W_x^+ stable set

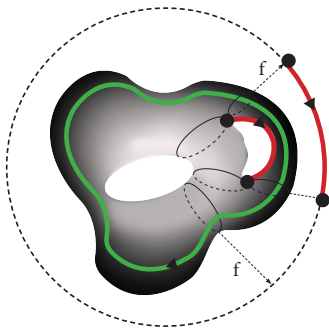


Closed trajectories

A closed trajectory τ has a Poincaré return map, (conjugacy class of) linear isomorphism $T_\tau; V_\tau \rightarrow V_\tau$. The closed trajectory τ is *isolated* iff T_τ has no eigenvalue = 1.



an example



Morse-Smale vector fields satisfy:

- 1 All rest points are hyperbolic, (i.e. W_x^\mp are smooth sub manifolds diffeomorphic to $\mathbb{R}^{i(x)}, \mathbb{R}^{n-i(x)}$).
- 2 For any two rest points x, y , W_x^- and W_y^+ are transversal.
- 3 Any closed trajectory is isolated.

The set of Morse-Smale vector fields is generic (in C^1 – topology).

As a consequence:

- The set $\mathcal{R}(X)$ is finite,
- $\mathcal{I}(x, y) \neq \emptyset$ then $i(x) - i(y) = 1$ and each homotopy class of paths from x to y , $x, y \in \mathcal{R}(X)$, contains a finite number of elements in $\mathcal{I}(x, y)$,
- If an orientation on each W_x^- is given then each $\tau \in \mathcal{I}(x, y)$ has a sign, $\epsilon(\tau) = \pm 1$.
- Each homotopy class of closed curves contains a finite number (possibly zero) of closed trajectories.

LYAPUNOV FUNCTION / Lyapunov TC1-FORM

Definition

- 1 A tame map $f : M \rightarrow \mathbb{R}$ is Lyapunov for X iff it is strictly decreasing on nonconstant trajectories (for f smooth iff $df(X)(x) < 0$ iff $x \in M \setminus \mathcal{R}(X)$).
- 2 A TC1-form $\omega \in \mathcal{Z}^1(M)$ is Lyapunov for X if for one (and then for any) representative U_j, f_j of ω the maps f_j are strictly decreasing on each non constant trajectory (for ω smooth iff $\omega(X)(x) < 0$ iff $x \in M \setminus \mathcal{R}(X)$)

The new invariants

For a compact ANR M , a field κ , an integer $r \geq 0$, based on homology with coefficients in κ , one produces:

- for a tame map $f : M \rightarrow \mathbb{R}$ the configurations

$$\delta_r^f \in \mathbf{Conf}(\mathbb{C}) \quad , \quad \gamma_r^f \in \mathbf{Conf}(\mathbb{C} \setminus \Delta)$$

$\Delta = \{z \in \mathbb{C} \mid z = i\bar{z}\}$, the first diagonal in \mathbb{C} ,

- for a tame TC1-form $\omega \in \mathcal{Z}_t^1(M)$ the configurations

$$\delta_r^\omega \in \mathbf{Conf}(\mathbb{R}) \quad , \quad \gamma_r^\omega \in \mathbf{Conf}(\mathbb{R} \setminus 0)$$

- $\mathbf{Conf}(C) \ni \delta = \left\{ \begin{array}{l} z_1, z_2, \dots, z_k \\ n_1, n_2, \dots, n_k \end{array} \right\} \Leftrightarrow P^\delta(z) = \prod (z - z_i)^{n_i}$

Topological results

Let $f : M \rightarrow \mathbb{R}$ be a tame map, M a compact ANR. Then

1. $\sum_{z \in \mathbb{C}} \delta_r^f(z) = \text{deg} P_r^f(z) = \dim H_r(M; \kappa)$,
2. $\dim H_r(f^{-1}([a, b]))$ can be expressed in terms of $\delta_r^f(z)$, and $\gamma_r^f(z)$ (homology calculations),
3. If M is a closed κ -orientable n -manifold then

$$\delta_r^f(z) = \delta_{n-r}^f(i\bar{z}) \quad \text{and} \quad \gamma_r^f(z) = \gamma_{n-1-r}^f(i\bar{z})$$

(Poincaré duality).

Dynamical results

1. If f is a Morse function on a closed smooth manifold, $Cr_r(f)$ denotes the set of critical points of index r and $C^+ = \{z = (a + ib) \mid a < b\}$ then

$$\#Cr_r(f) = \sum_{z \in \mathbb{C}} \delta_r^f(z) + \sum_{z \in C^+} \gamma_r^f(z) + \sum_{z \in C^+} \gamma_{r-1}^f(z).$$

2. If X is a vector field with f Lyapunov function and \mathcal{I}_r denotes the set of instantons between rest points of index r and $r - 1$ then

$$\sum_{z \in C^+} \gamma_r^f(z) \neq 0 \text{ implies } \#\mathcal{I}_r \neq \emptyset.$$

Robustness results

Let M be a compact ANR, $C(M)$ denote real-valued continuous functions and $C_t(M) \subset C(M)$ tame functions equipped with the uniform convergence topology. Let $\beta_r := \dim H_r(M; \kappa)$.

1. The assignment $C_t(M) \ni f \rightsquigarrow \delta_r^f \in \mathit{Conf}_{\beta_r(M)}(\mathbb{C})$ extends to a continuous map on $C(M)$ (Burghelea-Haller).
2. The assignment $C_t(M) \ni f \rightsquigarrow \gamma_r^f \in \mathit{Conf}(\mathbb{C} \setminus \Delta)$ is continuous (Edelsbruner-Harer).

A more precise statements involving metrics on both spaces permit to calculate the configurations with arbitrary accuracy. Note that the computer accepts only rational numbers.

Topological results

1. Let $\omega \in \mathcal{Z}_t^1(M)$, M a compact ANR and $NH_r(M; \xi_\omega)$ be the Novikov homology associated with the pair $(M, \xi_\omega \in H^1(M, R))$.
Then

$$\sum_{t \in \mathbb{R}} \delta_r^\omega(t) = \dim NH_r(M; \xi_\omega).$$

2. If M is a closed κ -orientable n -manifold then

$$\delta_r^\omega(t) = \delta_{n-r}^\omega(-t) \quad \text{and} \quad \gamma_r^\omega(t) = \gamma_{n-1-r}^\omega(-t).$$

Dynamical results

Let $\omega \in \mathcal{Z}^1(M)$ be a TC1-form Lyapunov for a Morse-Smale vector field X on a closed smooth manifold M with $Cr_r(\omega)$ the set of critical points of index r , and \mathcal{I}_r the set of instantons between rest points of index r and $r - 1$. Then

- 1 $\#Cr_r(\omega) = \sum_{t \in \mathbb{R}} \delta_r^\omega(t) + \sum_{t \in \mathbb{R}_{>0}} \gamma_r^\omega(t) + \sum_{t \in \mathbb{R}_{>0}} \gamma_{r-1}^\omega(t)$,
- 2 $\sum_{t \in \mathbb{R}_{>0}} \gamma_r^\omega(t) \neq 0$ implies $\#\mathcal{I}_r \neq \emptyset$,
- 3 $\sum_{t \in \mathbb{R}} \delta_r^\omega(t) \neq \dim H_r(M; \kappa)$ implies that the set of closed trajectories is not empty.

Robustness results

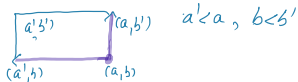
For M a compact ANR let $\mathcal{Z}(M)$ denote the set of TC1-forms, $\mathcal{Z}_t(M) \subset \mathcal{Z}(M)$ tame TC1-forms equipped with the uniform convergence topology.

1. The assignment $\mathcal{Z}_t(M) \ni f \rightsquigarrow \delta_r^\omega \in \text{Conf}_{\eta^N}(\mathbb{R})$ with $\beta_r^N = \dim NH_r(M; \omega)$ extends to a continuous map defined on $\mathcal{Z}(M)$.
2. The assignment $\mathcal{Z}_t(M) \ni f \rightsquigarrow \delta_r^\omega \in \text{Conf}_{\beta_r^N}(\mathbb{R} \setminus 0)$ is continuous.

A more precise statements involving metrics insures the possibility to calculate these configurations with arbitrary accuracy. Note that the computer accept only rational numbers.

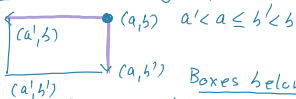
Measure theoretic approach The map δ_r^f

Boxes $B = (a', a] \times (b, b']$

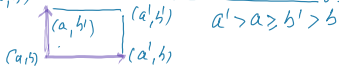


(a, b) the first vertex
 (a', b') the last vertex

Boxes above diagonal $B = (a', a] \times (b', b]$



Boxes below diagonal $B = (a', a] \times (b, b')$



- For a tame map $f : M \rightarrow \mathbb{R}$ denote

$$\mathbb{I}_a^f(r) := \text{img}(H_r(f^{-1}((-\infty, a]) \rightarrow H_r(M)),$$

$$\mathbb{I}_f^a(r) := \text{img}(H_r(f^{-1}([a, \infty)) \rightarrow H_r(M)).$$

and for $(a, b) \in \mathbb{R}^2$

$$F_r^f(a, b) := \mathbb{I}_a^f(r) \cap \mathbb{I}_f^b(r)$$

For $a' \leq a, b' \geq b$ one has $F_r(a', b') \subseteq F_r(a, b)$.

- Consider sets = **boxes**

$B = (a', a] \times [b, b'] \subset \mathbb{R}^2$, $a' < a$, $b' > b$ and define

$$F_r(B) := F_r(a, b) / F_r(a', b) + F_r(a, b')$$

$$\begin{array}{ccc} \mathbb{F}_r(a', b') & \longrightarrow & \mathbb{F}_r(a, b') \\ \downarrow & & \downarrow \subseteq \\ \mathbb{F}_r(a', b) & \xrightarrow{\subseteq} & \mathbb{F}_r(a, b) \end{array}$$

An inclusion $B' \subseteq B$ of boxes with the same first vertex induces the surjective linear map $\pi_{B'}^B : F_r(B) \rightarrow F_r(B')$ and an inclusion of boxes with the same last vertex induces the injective linear map $\iota_{B'}^B : F_r(B') \rightarrow F_r(B)$.

- Denote $B(a, b; \epsilon) := (a - \epsilon, a] \times [b, b + \epsilon)$, $\epsilon > 0$. For $\epsilon' > \epsilon''$ the linear map $F_r^f(B(a, b; \epsilon')) \rightarrow F_r^f(B(a, b; \epsilon''))$ is surjective. Define

$$\hat{\delta}_r^f(a, b) := \lim_{\epsilon \rightarrow 0} F_r^f(B(a, b; \epsilon)), \quad \delta_r^f(a, b) = \dim \hat{\delta}_r^f(a, b).$$

Since f is tame $\delta_r^f(a, b) \neq 0 \Rightarrow a, b \in CR(f)$.

Proposition

- *If f is proper or if f is a lift of a TC1-form on a compact ANR then $\delta_r^f(a, b)$ is finite .*
- *If M is compact then the map δ_r^f is a configuration and the assignment $B \rightsquigarrow \dim F_r(B)$ defines a \mathbb{Z} -valued measure on the sigma-algebra generated by boxes, whose density is δ_r^f .*

Measure theoretic approach; the map γ_r^f

- For $a < b$ define

$$T_r^f(a, b) := \ker(H_r(f^{-1}((-\infty, a])) \rightarrow H_r(f^{-1}((-\infty, b])))$$

$a' \leq a, b' \leq b, a' < a, a < b$ induce

$$\iota_{a', b'}^{a, b} : T_r(a', b') \rightarrow T_r(a, b);$$

when $a' = a$ this linear map is injective.

- For $a > b$ define

$$T_r^f(a, b) := \ker(H_r(f^{-1}([a, \infty))) \rightarrow H_r(f^{-1}([b, \infty))).$$

$a' \geq a, b' \geq b, a' > b', a > b$ induce

$$\iota_{a', b'}^{a, b} : T_r(a', b') \rightarrow T_r(a, b);$$

when $a' = a$ this linear map is injective.

- For sets = **boxes above diagonal**, $B = (a' a] \times (b', b]$ i.e. $a' < a \leq b' < b$ with (a, b) the first vertex and (a', b') the last vertex define

$$T_r^f(B) = T_r^f(a, b) \setminus T_r^f(a', b) + T_r^f(a, b').$$

- For set = **boxes below diagonal**, $B = [a, a'') \times [b, b'')$, i.e. $b < b'' \leq a < a''$ with (a, b) the first vertex and (a'', b'') the last vertex define

$$T_r^f(B) = T_r^f(a, b) \setminus T_r^f(a'', b) + T_r^f(a, b'').$$

- For $a < b$, $\epsilon < (b - a)$ let $B(a, b; \epsilon) = (a - \epsilon, a] \times (b - \epsilon, b]$,
For $a > b$ $\epsilon < (a - b)$ let $B(a, b; \epsilon) = [a, a + \epsilon) \times [b, b + \epsilon)$,
 $\epsilon' > \epsilon'' \Rightarrow T_r^f(B(a, b; \epsilon')) \geq T_r^f(B(a, b; \epsilon''))$.
- Define

$$\hat{\gamma}_r^f(a, b) := \lim_{\epsilon \rightarrow 0} T_r^f(B(a, b; \epsilon)) \quad \gamma_r^f(a, b) := \dim \hat{\gamma}_r^f(a, b)$$

Since f is tame $\gamma_r^f(a, b) \neq 0 \Rightarrow a, b \in CR(f)$.

Proposition

- If f is proper or if f is a lift of a TC1-form then $\gamma_r^f(a, b)$ is finite .
- If M is compact then the map γ_r^f is a configuration and the assignment $B \rightsquigarrow \dim T_r(B)$ defines a \mathbb{Z} -valued measure on the sigma-algebra generated by boxes above diagonal and below diagonal whose density is γ_r^f .

Proposition






If $f : \tilde{M} \rightarrow \mathbb{R}$ is the lift of a tame TC1-form then $S^\delta := \text{supp} \delta_r^f : \mathbb{R}^2 \rightarrow \mathbb{Z}_{\geq 0}$ and $S^\gamma := \text{supp} \gamma_r^f : \mathbb{R}^2 \rightarrow \mathbb{Z}_{\geq 0}$ satisfy the following:

- 1 $S^\delta \subset CR(f) \times CR(f)$ $S^\gamma \subset CR(f) \times CR(f) \setminus \Delta$
- 2 S^{\dots} is Γ -invariant, i.e. if $(a, b) \in S^{\dots}$ then $(a + g, b + g) \in S^{\dots}$ for any $g \in \Gamma$
- 3 S^δ resp S^γ is located on a finite collection of lines $y = x + a_i^\delta, i = 1, 2, \dots, N_r^\delta$ resp. $y = x + a_i^\gamma, i = 1, 2, \dots, N_r^\gamma$ of finite multiplicities. $n_1^\delta, n_2^\delta, \dots, n_{N_r^\delta}^\delta$ resp $n_1^\gamma, n_2^\gamma, \dots, n_{N_r^\gamma}^\gamma$

Then define

$$\delta_r^\omega(t) := \sum_{t=a_i^\delta} n_i^\delta$$

$$\gamma_r^\omega(t) := \sum_{t=a_i^\gamma} n_i^\gamma$$

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