

## A NOTE ON STABILITY IN A MODEL

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This note contains a combinatorial result about bipartite graphs (Proposition 2), which is motivated by certain definitions in model theory. Given an  $\mathcal{L}$ -structure  $M$ , an  $\mathcal{L}$ -formula  $\varphi(x, y)$  is called **stable in  $M$**  if there do not exist sequences  $(a_i)_{i \in I}$  in  $M^x$  and  $(b_i)_{i \in I}$  in  $M^y$ , indexed by an infinite linear order  $I$ , such that  $M \models \varphi(a_i, b_j)$  if and only if  $i \leq j$ . Note that it suffices to assume  $I$  is either  $\omega$  or  $\omega^*$  (where the latter denotes the reverse order on  $\omega$ ). This variation of the order property seems to have first appeared in an early paper of Pillay [4], and was later popularized by a paper of Ben Yaacov [1] on the connection between stability and work of Grothendieck [2] in functional analysis.

Following the definition of stable in a model, it is natural to ask for an analogous definition of NIP in a model. In this case, one does not want to look for the independence property to be fully realized by sequences in  $M$ , since this would require  $M$  to have size at least continuum. Thus, in [3], Khanaki and Pillay say that  $\varphi(x, y)$  is **NIP in  $M$**  if there does not exist an infinite set  $A \subseteq M^x$  such that the set system  $\{\varphi(x, b) : b \in M^y\}$  shatters all finite subsets of  $A$ . Equivalently,  $\varphi(x, y)$  is NIP in  $M$  if and only if there do not exist sequences  $(a_i)_{i \in \omega}$  in  $M^x$  and  $(b_X)_{X \subseteq \omega}$  in  $N^y$ , where  $N \succeq M$ , such that  $N \models \varphi(a_i, b_X)$  if and only if  $i \in X$  (see [3, Remark 1.2] for further discussion).

Now, since the definition of NIP in a model is not directly analogous to the definition of stable in a model, it becomes necessary to prove that if  $\varphi(x, y)$  is stable in  $M$  then it is also NIP in  $M$ . This can be done by showing that stability in a model has a formulation analogous to NIP in model. Specifically, the following is [3, Lemma 2.6].

**Fact 1.** *A formula  $\phi(x, y)$  is stable in  $M$  if and only if there is no infinite linear order  $I$ , and sequences  $(a_i)_{i \in I}$  in  $M^x$  and  $(b_i)_{i \in I}$  in  $N^y$ , with  $N \succeq M$ , such that  $N \models \phi(a_i, b_j)$  if and only if  $i \leq j$ .*

In [3], this is obtained as a quick corollary of Pillay's account in [5] of the Grothendieck approach to stability and, in particular, definability of types. Given this short but rather high-powered proof, Pillay asked for a direct combinatorial proof, which we will present here. Since this is a combinatorial argument, we will phrase our result (Proposition 2) in terms of bipartite graphs, and align things with an equivalent formulation of the righthand side of Fact 1 involving only the initial model  $M$ . For aesthetic reasons, Proposition 2 will also correspond to switching the positions of  $M$  and  $N$  in Fact 1. But this does not matter since  $\varphi(x, y)$  is stable in  $M$  if and only if  $\varphi^*(y, x)$  is stable in  $M$ , where  $\varphi^*(y, x)$  is identical to  $\varphi(x, y)$  but with the roles of  $x$  and  $y$  switched.

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A relation  $R \subseteq U \times V$  is **stable** if there is no infinite linear order  $I$ , and sequences  $(a_i)_{i \in I}$  from  $U$  and  $(b_i)_{i \in I}$  from  $V$ , such that  $R(a_i, b_j)$  holds if and only if  $i \leq j$ . (So  $\varphi(x, y)$  is stable in  $M$  if and only if  $\varphi$  is stable as a relation on  $M^x \times M^y$ .)

**Proposition 2.** *Given  $R \subseteq U \times V$ , the following are equivalent.*

- (i)  *$R$  is stable.*
- (ii) *There is no infinite linear order  $I$  and sequences  $(a_i^X)_{i \in X \subset_{\text{fin}} I}$  in  $U$  and  $(b_i)_{i \in I}$  in  $V$ , such that given  $i, j \in X \subset_{\text{fin}} I$ ,  $R(a_i^X, b_j)$  holds if and only if  $i \leq j$ .*

*Proof.* (ii)  $\Rightarrow$  (i) is trivial. We prove the contrapositive of (i)  $\Rightarrow$  (ii). Suppose there is some infinite linear order  $I$  as in (ii). We may assume  $I$  is either  $\omega$  or  $\omega^*$ . Suppose first that  $I$  is  $\omega$ . So we have  $(a_i^k)_{i \leq k \in \omega}$  in  $U$  and  $(b_i)_{i \in \omega}$  in  $V$  such that, for all  $i, j \leq k \in \omega$ ,  $R(a_i^k, b_j)$  holds if and only if  $i \leq j$ . Call  $t \in \omega$  *good* if for all  $k \geq t$ , the set  $\{u \in \omega : R(a_t^k, b_u)\}$  is finite.

*Case 1:* There is some good  $t \in \omega$ .

We construct a strictly increasing sequence  $(k_i)_{i \in \omega}$  such that  $k_0 = t$  and, for all  $i < j \in \omega$ ,  $\neg R(a_t^{k_i}, b_{k_j})$ . Let  $k_0 = t$  and suppose we have constructed  $k_0, \dots, k_i$  as above. Since  $t$  is good, the set  $\{u \in \omega : R(a_t^{k_j}, b_u) \text{ for some } j \leq i\}$  is finite. So we may choose some  $k_{i+1} > k_i$  such that  $\neg R(a_t^{k_j}, b_{k_{i+1}})$  holds for all  $j \leq i$ . This finishes the construction.

Now set  $c_i = a_t^{k_i}$  and  $d_i = b_{k_i}$ . If  $i \geq j$  then  $R(c_i, d_j)$  holds since  $k_i \geq k_j \geq t$ . If  $i < j$  then  $\neg R(c_i, d_j)$  holds since  $k_i < k_j$ . Altogether,  $R$  is not stable.

*Case 2:* There is no good  $t \in \omega$ .

We construct  $(k_t)_{t \in \omega}$  in  $\omega$  and  $(I_t)_{t \in \omega}$  in  $\mathcal{P}(\omega)$  such that, for all  $t \in \omega$ ,  $I_t$  is infinite,  $i_t := \min I_t \leq k_t$ , and  $I_{t+1} = \{u \in I_t : u > k_t, R(a_{i_t}^{k_t}, b_u)\}$ . Let  $I_0 = \omega$ . Fix  $t \geq 0$  and suppose we have constructed  $I_s$  for all  $s \leq t$ , and  $k_s$  for all  $s < t$ . We find  $I_{t+1}$  and  $k_t$ . Since  $i_t$  is not good, and  $I_t$  is infinite, there is some  $k_t \geq i_t$  such that the set  $I_{t+1} := \{u \in I_t : u > k_t, R(a_{i_t}^{k_t}, b_u)\}$  is infinite. This finishes the construction.

Now set  $c_t = a_{i_t}^{k_t}$  and  $d_t = b_{i_t}$ . Fix  $s, t < \omega$ . If  $s = t$  then  $R(c_s, d_t)$  holds since  $i_t \leq k_t$ . If  $s > t$  then  $\neg R(c_s, d_t)$  holds since  $i_t < i_s \leq k_s$ . Suppose  $s < t$ . Then  $i_t = \min I_t \subseteq I_{s+1}$ , and so  $i_t \in I_{s+1}$ . So  $R(a_{i_s}^{k_s}, b_{i_t})$  holds, i.e.,  $R(c_s, d_t)$  holds. Altogether,  $R$  is not stable.

Finally, suppose  $I$  is  $\omega^*$ . So we have  $(a_i^k)_{i \leq k \in \omega}$  in  $U$  and  $(b_i)_{i \in \omega}$  in  $V$  such that, for all  $i, j \leq k \in \omega$ ,  $R(a_i^k, b_j)$  holds if and only if  $i \geq j$ . For  $i \in \omega$ , let  $c_i = b_{i+1}$ . Then, for all  $i, j \leq k \in \omega$ , we have  $\neg R(a_i^k, c_j)$  if and only if  $i \leq j$ . So  $\neg R$  is not stable by the above argument, which implies that  $R$  is not stable.  $\square$

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