

Part III Model Theory, Lecture 6, 23 Oct

② (cf Ex 5.13) $T = Th(\mathbb{R}, +, \cdot, 0, 1)$. $\varphi(x)$ is $\exists y(x = y^2)$. Note φ defines $\mathbb{R}^{\geq 0}$.

Suppose $\psi(x)$ is g.f. So $\psi(x)$ is a Boolean combination of polynomial equations.

So ψ defines a finite or cofinite subset of \mathbb{R} . T does not have QE.

Later: $Th(\mathbb{R}, +, \cdot, <, 0, 1)$ does have QE. Note $x < y$ iff $\exists z (z \neq 0 \wedge y - x = z^2)$.

So $(\mathbb{R}, +, \cdot, 0, 1)$ and $(\mathbb{R}, +, \cdot, <, 0, 1)$ have the same definable sets.

Lemma 6.1 Suppose T is an L -theory st for any g.f. formula $\varphi(x_1, \dots, x_n, y)$ there is a g.f. $\psi(x_1, \dots, x_n)$ st $T \models \forall \bar{x} (\exists y \varphi(\bar{x}, y) \leftrightarrow \psi(\bar{x}))$. Then T has QE.

Proof: Induction on formulas. (Exercise).

Theorem 6.2 Let T be an L -theory. TFAE.

i) T has QE.

ii) Suppose $M, N \models T$ and $A \subseteq M, A \subseteq N$. ^{are arbitrary} Then for any g.f. formula $\varphi(\bar{x}, y)$ and any tuple \bar{a} from A , if $M \models \exists y \varphi(\bar{a}, y)$ then $N \models \exists y \varphi(\bar{a}, y)$.

iii) For any L -structure A , $T \cup D(A)$ is a complete L_A -theory.

Proof (i) \Rightarrow (iii). Assume T has QE. Let A be an L -structure and suppose

$M, N \models T \cup D(A)$. WTS $M \equiv_{L_A} N$. Let σ be an L_A -sentence st $M \models \sigma$.

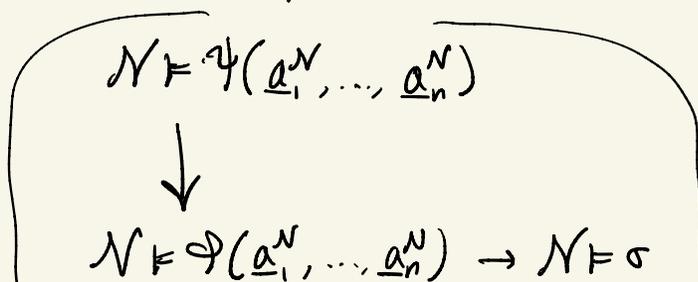
WTS $N \models \sigma$. Write σ as $\varphi(a_1, \dots, a_n)$ for some L -formula $\varphi(x_1, \dots, x_n)$

and $a_1, \dots, a_n \in A$. By QE, there is g.f. $\psi(x_1, \dots, x_n)$ st $T \models \forall \bar{x} (\varphi(\bar{x}) \leftrightarrow \psi(\bar{x}))$.

Since $M \models T$ and $M \models \varphi(\bar{a})$, we have $M \models \psi(\bar{a})$. Since $M \models D(A)$,

we have $\psi(a_1, \dots, a_n) \in D(A)$. So $N \models \psi(a_1, \dots, a_n)$. Since $N \models T$,

$N \models \varphi(a_1, \dots, a_n)$, i.e. $N \models \sigma$.



(iii) \Rightarrow (ii). Let $M, N, A, \phi(\bar{x}, y)$, and \bar{a} be as (ii).

Since $A \in M$ and $A \in N$, we have $M, N \models T \cup D(A)$ by Cor 2.4.

By (iii), $M \equiv_{\mathcal{L}_A} N$. So $M \models \underbrace{\exists y \phi(\bar{a}, y)}_{\mathcal{L}_A\text{-sentence}} \Rightarrow N \models \exists y \phi(\bar{a}, y)$.

(ii) \Rightarrow (i). Assume (ii). WTS QE. By Lemma 6.1, it suffices to fix q.f. $\phi(\bar{x}, y)$ and find q.f. $\psi(\bar{x})$ st $T \models \forall \bar{x} (\exists y \phi(\bar{x}, y) \leftrightarrow \psi(\bar{x}))$.

Let $\mathcal{L}^* = \mathcal{L} \cup \{c_1, \dots, c_n\}$ where c_i is a new constant symbol.

Let $\Gamma = \{ \psi(\bar{c}) : \psi(\bar{x}) \text{ is a q.f. } \mathcal{L}\text{-formula} + T \models \forall \bar{x} (\exists y \phi(\bar{x}, y) \rightarrow \psi(\bar{x})) \}$.

Claim: $T \cup \Gamma \models \exists y \phi(\bar{c}, y)$.

First, assume the claim holds. By compactness, \exists q.f. $\psi_1(\bar{x}), \dots, \psi_m(\bar{x})$ st $T \cup \{ \psi_1(\bar{c}), \dots, \psi_m(\bar{c}) \} \models \exists y \phi(\bar{c}, y)$ and $T \models \forall \bar{x} (\exists y \phi(\bar{x}, y) \rightarrow \bigwedge_{i=1}^m \psi_i(\bar{x}))$. since each $\psi_i(\bar{c})$ is in Γ !

Let $\psi(\bar{x})$ be $\bigwedge_{i=1}^m \psi_i(\bar{x})$. Then $T \models (\psi(\bar{c}) \rightarrow \exists y \phi(\bar{c}, y))$.

So $T \models \forall \bar{x} (\psi(\bar{x}) \rightarrow \exists y \phi(\bar{x}, y))$ (exercise, "generalization")

So $T \models \forall \bar{x} (\psi(\bar{x}) \leftrightarrow \exists y \phi(\bar{x}, y))$.

Proof of Claim Suppose not. There is $N \models T \cup \Gamma \cup \{ \neg \exists y \phi(\bar{c}, y) \}$.

Let $a_i = c_i^N$ and let $A \in N$ be the substructure generated by a_1, \dots, a_n .

Then $N \models T$, $A \in N$, and $N \models \neg \exists y \phi(\bar{a}, y)$.

By ES1 #7, any $b \in A$ is of the form $t^N(\bar{a})$ for some \mathcal{L} -term t .

So we can view $D(A)$ as a \mathcal{L}^* -theory by replacing \bar{b} with $t(c_1, \dots, c_n)$.

Let $\Sigma \models T \cup D(A) \cup \{ \exists y \phi(\bar{c}, y) \}$. If we build $M \models \Sigma$ then

$M \models T$, $A \in M$ and $M \models \exists y \phi(\bar{a}, y)$, contradicting (ii).

So it suffices to show Σ has a model. Suppose not. By compactness,

Here are m f. $\psi_1(\bar{x}), \dots, \psi_m(\bar{x})$ st $\psi_1(\bar{c}), \dots, \psi_m(\bar{c}) \in D(A)$ and

$\mathcal{T} \cup \left\{ \bigwedge_{i=1}^m \psi_i(\bar{c}) \right\} \cup \left\{ \exists y \phi(\bar{c}, y) \right\}$ is unsatisfiable. Let $\psi(\bar{x})$ be $\neg \bigwedge_{i=1}^m \psi_i(\bar{x})$.

Then $\mathcal{T} \models (\exists y \phi(\bar{c}, y) \rightarrow \psi(\bar{c}))$. So $\mathcal{T} \models \forall \bar{x} (\exists y \phi(\bar{x}, y) \rightarrow \psi(\bar{x}))$.

So $\psi(\bar{c}) \in \mathcal{T}$. So $\mathcal{N} \models \psi(\bar{c})$. Since $\mathcal{N} \models \mathcal{D}(A)$, we have

$\mathcal{N} \models \neg \psi(\bar{c})$. Contradiction. □