

## Lecture IV (1/20/16) : § 12.4 : Cross product

§ 1. Definition: Let  $\vec{u} = \langle a_1, b_1, c_1 \rangle$ ,  $\vec{v} = \langle a_2, b_2, c_2 \rangle$  be two vectors in  $\mathbb{R}^3$ .

$$\vec{u} \times \vec{v} := \langle b_1 c_2 - b_2 c_1, a_2 c_1 - a_1 c_2, a_1 b_2 - a_2 b_1 \rangle$$

is called the cross product of  $\vec{u}$  and  $\vec{v}$ . It's a vector in  $\mathbb{R}^3$ .

Tip: How to remember the definition?  $\rightarrow$  Use determinants!

Recall: determinant of a  $2 \times 2$ -matrix

$$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$$

• determinant of a  $3 \times 3$ -matrix:

$$\rightarrow \begin{vmatrix} x & y & z \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} = x \begin{vmatrix} b_1 & c_1 \\ b_2 & c_2 \end{vmatrix} - y \begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix} + z \begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}$$

With these definitions in mind:

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \end{vmatrix} \stackrel{\text{st.}}{=} \hat{i} \begin{vmatrix} b_1 & c_1 \\ b_2 & c_2 \end{vmatrix} - \hat{j} \begin{vmatrix} a_1 & c_1 \\ a_2 & c_2 \end{vmatrix} + \hat{k} \begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}$$

Example:  $\vec{u} = \langle 1, 2, 3 \rangle$ ,  $\vec{v} = \langle 2, -1, 2 \rangle$

$$\vec{u} \times \vec{v} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2 & 3 \\ 2 & -1 & 2 \end{vmatrix} = \hat{i} (2 \cdot 2 - (-1) \cdot 3) - \hat{j} (1 \cdot 2 - 2 \cdot 3) + \hat{k} (1 \cdot (-1) - 2 \cdot 2) \\ = \hat{i} \cdot 7 - \hat{j} (-4) + \hat{k} (-5) = \langle 7, 4, -5 \rangle.$$

Properties:  $\vec{u}, \vec{v}, \vec{w}$  vectors in  $\mathbb{R}^3$ ,  $a, b$  scalars

$$(i) \quad \vec{u} \times \vec{v} = -\vec{v} \times \vec{u} \quad (\text{Anticommutative})$$

$$(ii) \quad (a\vec{u}) \times (b\vec{v}) = ab(\vec{u} \times \vec{v}) \quad (\text{Associative}) \quad (\text{so } \vec{0} \times \vec{v} = \vec{0} \text{ for all } \vec{v})$$

$$(iii) \quad \vec{u} \times (\vec{v} + \vec{w}) = (\vec{u} \times \vec{v}) + \vec{u} \times \vec{w} \quad (\text{Distributive})$$

$$(iv) \quad [\text{Follows from (iii) \& (i)}] \quad (\vec{u} + \vec{v}) \times \vec{w} = \vec{u} \times \vec{w} + \vec{v} \times \vec{w}$$

$$\text{Pf(i)} \quad \left| \begin{matrix} a_1 & b_1 \\ a_2 & b_2 \end{matrix} \right| = - \left| \begin{matrix} a_2 & b_2 \\ a_1 & b_1 \end{matrix} \right| .$$

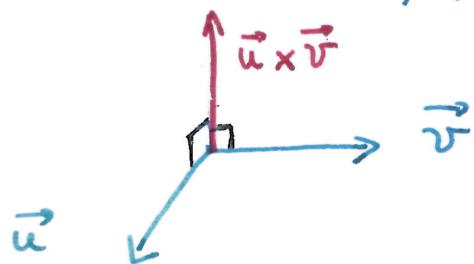
Why? Key Proposition: The vector  $\vec{u} \times \vec{v}$  is perpendicular to both  $\vec{u}$  and  $\vec{v}$ . [2]

Proof We need to verify that  $\vec{u} \cdot (\vec{u} \times \vec{v}) = 0$  (similar for  $\vec{v}$ )

$$\begin{aligned} & \equiv \langle a_1, b_1, c_1 \rangle \cdot \langle b_1 c_2 - b_2 c_1, a_2 c_1 - a_1 c_2, a_1 b_2 - a_2 b_1 \rangle \\ & = a_1(b_1 c_2 - b_2 c_1) + b_1(a_2 c_1 - a_1 c_2) + c_1(a_1 b_2 - a_2 b_1) \\ & = a_1 b_1 c_2 - a_1 b_2 c_1 + a_2 b_1 c_1 - a_1 b_1 c_2 + a_1 b_2 c_1 - a_2 b_1 c_1 \\ & = 0 \end{aligned}$$

Fn  $\vec{v} \cdot (\vec{u} \times \vec{v}) = \overset{(1)}{\vec{v}} \cdot (-(\vec{v} \times \vec{u})) = -(\vec{v} \cdot (\vec{v} \times \vec{u})) = -0 = 0$  ✓

→ Direction of  $\vec{u} \times \vec{v}$  is given by the right-hand rule  
(unless  $\vec{u} \times \vec{v} = \vec{0}$ , then it has no direction)



Theorem [Geometric definition] Assume  $\vec{u}, \vec{v}$  are non-zero vectors in  $\mathbb{R}^3$  and let  $\theta$  be the angle between  $\vec{u}$  and  $\vec{v}$ . Then  $(0 \leq \theta \leq \pi)$

$$|\vec{u} \times \vec{v}| = |\vec{u}| |\vec{v}| \sin \theta$$

Proof Write  $\vec{u} = \langle a_1, b_1, c_1 \rangle$ ,  $\vec{v} = \langle a_2, b_2, c_2 \rangle$

Verify that  $|\vec{u} \times \vec{v}|^2 + (\vec{u} \cdot \vec{v})^2 = |\vec{u}|^2 |\vec{v}|^2$  (exercise)

Then, since  $\vec{u} \cdot \vec{v} = |\vec{u}| |\vec{v}| \cos \theta$  (Lecture III), we get

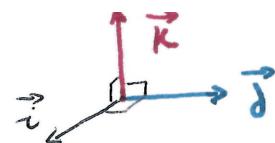
$$|\vec{u} \times \vec{v}|^2 = |\vec{u}|^2 |\vec{v}|^2 (1 - \cos^2 \theta) = |\vec{u}|^2 |\vec{v}|^2 \sin^2 \theta$$

$$\Rightarrow |\vec{u} \times \vec{v}| = |\vec{u}| |\vec{v}| |\sin \theta| = |\vec{u}| |\vec{v}| \sin \theta$$

$[0 \leq \theta \leq \pi]$  ■

Conclusion: (1) We know the magnitude and the direction of  $\vec{u} \times \vec{v}$ .  
(2)  $\vec{u}$  and  $\vec{v}$  are parallel ( $\theta=0$  or  $180^\circ$ ) if and only if  $\vec{u} \times \vec{v} = \vec{0}$ .

## § 2. Consequences :



- Proposition 1: (1)  $\vec{i} \times \vec{j} = \vec{k}$ , (2)  $\vec{j} \times \vec{k} = \vec{i}$ , (3)  $\vec{k} \times \vec{i} = \vec{j}$   
 (4)  $\vec{i} \times \vec{i} = \vec{j} \times \vec{j} = \vec{k} \times \vec{k} = \vec{0}$

Proof (1)-(3) All magnitudes are 1 & use right-hand rule.

(4)  $\vec{i}$  is parallel to  $\vec{i}$ , so  $|\vec{i} \times \vec{i}| = 0$ , hence  $\vec{i} \times \vec{i} = \vec{0}$  ■

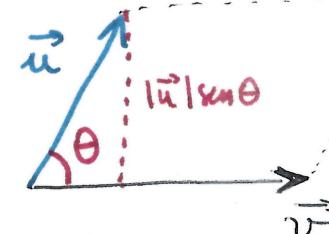
Note:  $\vec{u} \times (\vec{v} \times \vec{w}) \neq (\vec{u} \times \vec{v}) \times \vec{w}$  in general

Example:  $\vec{i} \times (\vec{i} \times \vec{j}) = \vec{i} \times \vec{k} = -(\vec{k} \times \vec{i}) = -\vec{j}$ .

But  $(\vec{i} \times \vec{i}) \times \vec{j} = \vec{0} \times \vec{j} = \vec{0}$ .

## Proposition 2: The Area of the parallelogram

determined by  $\vec{u}$  and  $\vec{v}$  equals  
the magnitude of  $\vec{u} \times \vec{v}$



Proof Area = height · base =  $|\vec{u}| \sin \theta |\vec{v}| = |\vec{u} \times \vec{v}|$ . ■

Example 1: Find the area of the parallelogram formed by  $\langle 1, 0, 1 \rangle$  and  $\langle 2, 1, -2 \rangle$

$$\text{Sln: Area} = |\langle 1, 0, 1 \rangle \times \langle 2, 1, -2 \rangle|$$

$$\langle 1, 0, 1 \rangle \times \langle 2, 1, -2 \rangle = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 1 \\ 2 & 1 & -2 \end{vmatrix} = -\vec{i} - (-4)\vec{j} + \vec{k}$$

$$\Rightarrow \text{Area} = \sqrt{(-1)^2 + (-4)^2 + (1)^2} = \sqrt{18}.$$

Example 2: Find a vector perpendicular to the plane containing  
 $P = (0, 1, 0)$ ,  $Q = (1, 1, 0)$ ,  $R = (1, 1, 1)$

$$\text{Sln } \overrightarrow{PQ} = \langle 1, 0, 0 \rangle$$

$$\overrightarrow{PR} = \langle 1, 0, 1 \rangle$$

$$\overrightarrow{PQ} \times \overrightarrow{PR} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 0 \\ 1 & 0 & 1 \end{vmatrix} = 0\vec{i} - \vec{j}(1-0) + \vec{k} \cdot 0 = -\vec{j} = \langle 0, -1, 0 \rangle$$



### §3. Applications:

(4)

I. Volume of a parallelopipede formed by  $\vec{u}$ ,  $\vec{v}$  and  $\vec{w}$  is given by

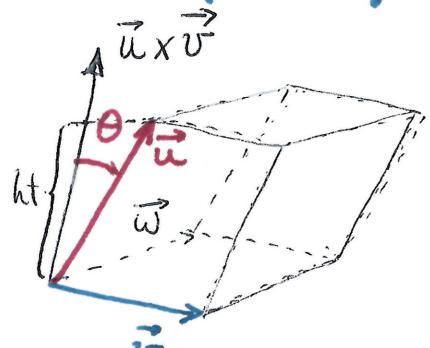
$$|\vec{u} \cdot (\vec{v} \times \vec{w})| \quad (\text{absolute value})$$

Why? Area of the base =  $|\vec{v} \times \vec{w}|$

$$\text{Height} = |\vec{u}| |\cos \theta|$$

where  $\theta = \text{angle between } \vec{u} \text{ and } \vec{v} \times \vec{w}$

$$\Rightarrow \text{Volume} = |\vec{u}| |\vec{v} \times \vec{w}| |\cos \theta| = |\vec{u} \cdot (\vec{v} \times \vec{w})|$$



Example: Determine whether the following 4 points lie on a plane (that is, they are coplanar) or not:

$$P = (1, 3, 2), \quad Q = (3, -1, 6), \quad R = (5, 2, 0), \quad S = (3, 6, 4)$$

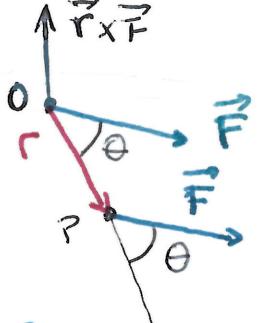
Soln:  $\vec{PQ} = \langle 2, -4, 4 \rangle, \quad \vec{PR} = \langle 4, -1, -2 \rangle, \quad \vec{PS} = \langle 2, 3, -6 \rangle$

The 4 points are coplanar if and only if the parallelopipede formed by  $\vec{PQ}, \vec{PR}$  and  $\vec{PS}$  has volume 0.

$$\text{Vol} = |\vec{PQ} \cdot (\vec{PR} \times \vec{PS})| = |\langle 2, -4, 4 \rangle \cdot \begin{vmatrix} i & j & k \\ 4 & -1 & -2 \\ 2 & 3 & -6 \end{vmatrix}| = |\langle 2, -4, 4 \rangle \cdot \langle 12, 20, 14 \rangle| = 24 - 80 + 56 = 0$$



II TORQUE: Apply a force  $\vec{F}$  to a wrench  $\vec{r} = \vec{OP}$  at the point P and see the twist effect about the point O.



$$\text{Twist effect} = \vec{r} \times \vec{F}$$

$$\cdot \text{magnitude} = |\vec{r}| |\vec{F}| \sin \theta$$

• direction = right-hand rule.

So maximum torque if  $\theta = 90^\circ$  & minimum torque:  $\theta = 0^\circ$  or  $\theta = 180^\circ$

Example:  $\vec{r} = \vec{OP} = i - j + 2k$ . A force  $\vec{F} = \langle 10, 10, 0 \rangle$  is applied at P

Find the torque about O that is produced.

$$\text{Soln: } \vec{G} = \vec{r} \times \vec{F} = \begin{vmatrix} i & j & k \\ 1 & -1 & 2 \\ 10 & 10 & 0 \end{vmatrix} = -20i - (1-20)j + (10+10)k = \langle -20, 20, 20 \rangle$$

$$\Rightarrow \text{Torque} = |\vec{r} \times \vec{F}| = 20\sqrt{3}$$

