

Lecture XXXII: §15.5 Divergence & curl

GOAL for the remaining of the course: lift two forms of Green's Theorem from \mathbb{R}^2 to \mathbb{R}^3 .

Recall: R conn, simply connected region in \mathbb{R}^2 bounded by a piecewise smooth, simple, closed curve C oriented counter-clockwise.
 $\vec{F} = \langle h, g \rangle$ v. field on \mathbb{R}^2 ; h, g with cont. 1st partials



① Green's Theorem in circulation form:

$$\text{Circ}(F) = \oint_C F \cdot T \, ds = \iint_R \underbrace{\left(\frac{\partial g}{\partial x} - \frac{\partial h}{\partial y} \right)}_{=\text{curl}(F)} \, dA \quad T = \text{unit tangent}$$

② Green's Theorem in flux form:

$$\text{Flux}(F) = \oint_C F \cdot \vec{n} \, ds = \iint_R \underbrace{\left(\frac{\partial g}{\partial y} + \frac{\partial h}{\partial x} \right)}_{=\text{divergence}(F)} \, dA$$



How we lift these results:

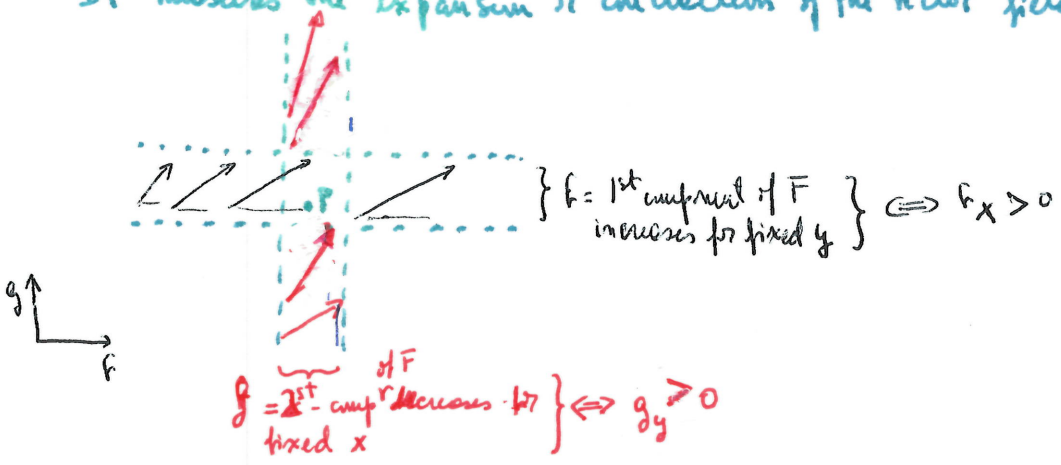
- ① replace line integrals by surface integrals
- ② extend curl & divergence operators to vector fields in \mathbb{R}^3 . ← TODAY'S TOPIC

§1: The Divergence:

Definition: The divergence of $\vec{F} = \langle h, g, k \rangle$ v. field in \mathbb{R}^3 is $\text{div}(F) = \frac{\partial h}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial k}{\partial z}$

It measures the expansion or contraction of the vector field at each point.

[\mathbb{R} -scalar function]



so $\text{div} = h_x + g_y > 0$ at P , indicating outward expansion.
 The converse also holds.

We use the following notation $\nabla = \text{del operator} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle$

So $\nabla \cdot \vec{F} = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \cdot \langle h, g, k \rangle = \frac{\partial h}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial k}{\partial z} = \text{div}(F)$. ↳ we evaluate it on functions.

Example: ① $F = \langle x, y, z \rangle \Rightarrow \text{div}(F) = \nabla \cdot \vec{F} = 1 + 1 + 1 = 3$

② $F = \frac{r}{|r|} = \frac{\langle x, y, z \rangle}{\sqrt{x^2 + y^2 + z^2}}$ radial v. field defined in $\mathbb{R}^3 - \{(0,0,0)\}$



$\frac{\partial f}{\partial x} = \frac{1}{\sqrt{x^2 + y^2 + z^2}} - x(x^2 + y^2 + z^2)^{-3/2} \cdot 2x = \frac{(x^2 + y^2 + z^2) - x^2}{(x^2 + y^2 + z^2)^{3/2}} = \frac{|r|^2 - x^2}{|r|^3}$

By symmetry $\frac{\partial g}{\partial y} = \frac{|r|^2 - y^2}{|r|^3}$ & $\frac{\partial h}{\partial z} = \frac{|r|^2 - z^2}{|r|^3}$

So $\text{div}(F) = \frac{3|r|^2 - |r|^2}{|r|^3} = \frac{2}{|r|} > 0$ so F is expanding outwards.

Theorem: Divergence of Radial v. fields

If $\vec{F} = \frac{r}{|r|^p} = \frac{\langle x, y, z \rangle}{(x^2 + y^2 + z^2)^{p/2}}$, then $\text{div}(F) = \frac{3-p}{|r|^p}$

Pr/. If $p=0$ $\vec{F} = \langle x, y, z \rangle$ $\text{div} = 3 = \frac{3-0}{|r|^0}$ ✓

We differentiate $\frac{\partial f}{\partial x} = \frac{\partial}{\partial x} \left(\frac{x}{(x^2 + y^2 + z^2)^{p/2}} \right) = \frac{|r|^p - x |r|^{p-2} \cdot 2x}{|r|^{2p}}$

$\Rightarrow \frac{\partial h}{\partial x} = \frac{|r|^{p-2} (|r|^2 - px^2)}{|r|^{2p}} = \frac{|r|^2 - px^2}{|r|^{p+2}}$

By symmetry: $\frac{\partial g}{\partial y} = \frac{|r|^2 - py^2}{|r|^p}$, $\frac{\partial h}{\partial z} = \frac{|r|^2 - pz^2}{|r|^p}$.

So $\text{div}(F) = \frac{3|r|^2 - p|r|^2}{|r|^{p+2}} = \frac{3-p}{|r|^p}$

Note: In particular $\text{div}(F) = 0 \iff p=3$.

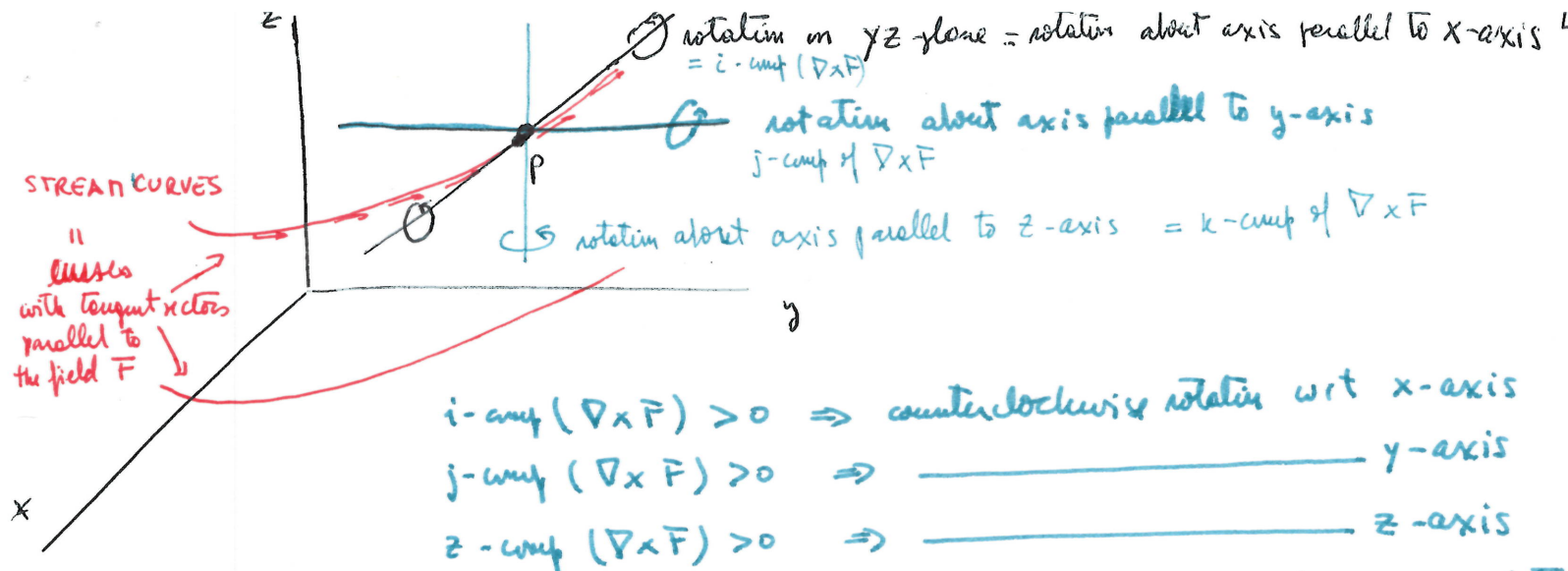
§ 2 Curl:

To generalize the curl = $g_x - f_y$ from \mathbb{R}^2 to \mathbb{R}^3 , we use $\nabla \times F$.

Def Write $F = \langle f, g, h \rangle$. The curl of F is defined by the formula

$\nabla \times F = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix} = i \left(\frac{\partial h}{\partial y} - \frac{\partial g}{\partial z} \right) - j \left(\frac{\partial h}{\partial x} - \frac{\partial f}{\partial z} \right) + k \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right)$

Recall: Curl in $\mathbb{R}^2 = g_x - f_y$ we view it as $k \left(\frac{\partial g}{\partial x} - \frac{\partial f}{\partial y} \right)$ where $F = \langle f, g, 0 \rangle$
 k -comp of curl gives the rotation of F in the xy -plane at a point. $\text{curl} > 0 = \text{COUNTERCLOCKWISE rotation in } \mathbb{R}^2$
 Thus: i - & j -comp. of curl give the rotation of F in the yz - & xz -planes respectively.



i -comp $(\nabla \times \vec{F}) > 0 \Rightarrow$ counterclockwise rotation wrt x -axis
 j -comp $(\nabla \times \vec{F}) > 0 \Rightarrow$ _____ y -axis
 z -comp $(\nabla \times \vec{F}) > 0 \Rightarrow$ _____ z -axis

Def If $\nabla \times \vec{F} = \vec{0}$, we say the vector field is irrotational (in \mathbb{R}^2 the circulation was $= 0$).

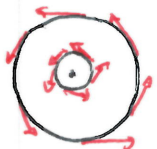
§ 3. Curl of a General Rotation Vector Field:

Special vector fields $= \vec{F} = \vec{a} \times \vec{r}$ where $\vec{a} = \langle a_1, a_2, a_3 \rangle$ is a constant vector $\vec{a} \neq \vec{0}$ & $\vec{r} = \langle x, y, z \rangle$ in coordinates:

$$\vec{F} = \vec{a} \times \vec{r} = \begin{vmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ x & y & z \end{vmatrix} = \langle a_2 z - a_3 y, a_3 x - a_1 z, a_1 y - a_2 x \rangle$$

It's called a general rotational field in \mathbb{R}^3 .

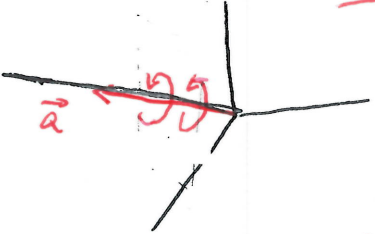
Eg. $a_1 = a_2 = 0, a_3 = 1$, we get $\vec{F} = \langle -y, x, 0 \rangle = \langle -y, x \rangle$ usual rotational v. field in \mathbb{R}^2



axis of rotation = z -axis.
counterclockwise rotation if looking from the positive z -axis.

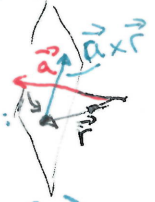
In general: \vec{F} is a rotational field with axis of rotation in the direction of \vec{a} .

Properties:
 ① $\nabla \cdot \vec{F} = \frac{\partial}{\partial x}(a_2 z - a_3 y) + 0 + 0 = 0$. So $\text{div}(\vec{F}) = 0$



② $\vec{F} = \vec{a} \times \vec{r}$ circles the vector \vec{a} in the counterclockwise direction looking along \vec{a} from head to tail.

Why? \vec{F} lies in orthogonal plane to \vec{a} . & use right-hand rule:



③ $\nabla \times \vec{F} = i(\underline{a_2} + a_1) - j(-a_2 - a_2) + k(a_3 - (-a_3)) = \langle 2a_1, 2a_2, 2a_3 \rangle = 2\vec{a}$

$$\begin{cases} b = a_2 z - a_3 y \\ g = a_3 x - a_1 z \\ h = a_1 y - a_2 x \end{cases}$$

& use definition of $\nabla \times \vec{F}$.

So $\text{curl}(\vec{F})$ has the same direction as the axis of rotation (\vec{a}).
 $|\text{curl}(\vec{F})| = |\nabla \times \vec{F}| = 2|\vec{a}|$

$|\vec{a}|$ is the constant angular speed of rotation = rate at which a particle rotates about the axis of the field

Q: Suppose a paddle wheel is placed in \vec{F} at pt P with the axis of the wheel in the direction of a unit vector \vec{n} . For which \vec{n} 's does the paddle spin fastest?



$$\text{comp}_{\vec{n}} \nabla \times \vec{F} = \frac{(\nabla \times \vec{F}) \cdot \vec{n}}{|\vec{n}|} = |\nabla \times \vec{F}| \cdot |\vec{n}| \cos \theta \quad \text{has to be maximal.}$$

$\Rightarrow \cos \theta = 1$, i.e. $\theta = 0$. Conclusion: Fastest speed when \vec{n} is parallel to $\nabla \times \vec{F}$

If $\theta = \pm \frac{\pi}{2}$, then no rotation at all. (the wheel doesn't spin)

§4 Divergence & curl properties

Recall: $\nabla \cdot (\vec{F} + \vec{G}) = \nabla \cdot \vec{F} + \nabla \cdot \vec{G} \quad \rightsquigarrow \text{div}(\vec{F} + \vec{G}) = \text{div}(\vec{F}) + \text{div}(\vec{G})$

$\text{div} \left\{ \begin{array}{l} \nabla \cdot (c\vec{F}) = c \nabla \cdot \vec{F} \quad \rightsquigarrow \text{div}(c\vec{F}) = c \text{div}(\vec{F}). \end{array} \right.$

$\text{curl} \left\{ \begin{array}{l} \nabla \times (\vec{F} + \vec{G}) = \nabla \times \vec{F} + \nabla \times \vec{G} \quad \rightsquigarrow \text{curl}(\vec{F} + \vec{G}) = \text{curl}(\vec{F}) + \text{curl}(\vec{G}) \\ \nabla \times (c\vec{F}) = c \nabla \times \vec{F} \quad \rightsquigarrow \text{curl}(c\vec{F}) = c \text{curl}(\vec{F}). \end{array} \right.$

Thm 1: Suppose \vec{F} is a conservative v. field in an open region D of \mathbb{R}^3 & whose potential function φ has cont. 2nd order partials in D . Then, $\nabla \times \vec{F} = \nabla \times \nabla \varphi = \vec{0}$ ($\text{curl}(\vec{F}) = \vec{0}$)

PF/ $\nabla \times \nabla \varphi = \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial \varphi}{\partial x} & \frac{\partial \varphi}{\partial y} & \frac{\partial \varphi}{\partial z} \end{vmatrix} = (\underbrace{\varphi_{zy} - \varphi_{yz}}_{=0})i - j(\underbrace{\varphi_{zx} - \varphi_{xz}}_{=0}) + k(\underbrace{\varphi_{yx} - \varphi_{xy}}_0) = \vec{0}$
= 0 mixed partials are cont.

Note: If D is connected & simply connected, the converse is also true (see §15.7 Stokes's Thm)

Thm 2: If $\vec{F} = \langle f, g, h \rangle$ where f, g, h have cont. 2nd partials, then $\nabla \cdot (\nabla \times \vec{F}) = 0$ v. field
 meaning $\text{div}(\text{curl}(\vec{F})) = 0$.

PF/ $\nabla \cdot (\nabla \times \vec{F}) = \frac{\partial}{\partial x}(h_y - g_z) + \frac{\partial}{\partial y}(f_z - h_x) + \frac{\partial}{\partial z}(g_x - f_y) = (h_{yx} - h_{xy}) + (f_{zy} - f_{yz}) + (g_{xz} - g_{zx}) = 0$
 because all mixed partials are cont, so they agree.

Thm 3 (Prod Rule for divergence):

α scalar function in D & $\vec{F}: D \rightarrow \mathbb{R}^3$ differentiable v. field. Then

$\nabla \cdot (\alpha \vec{F}) = \nabla \alpha \cdot \vec{F} + \alpha (\nabla \cdot \vec{F})$ is a scalar function.