

## Lecture 21: SS.1-S.2 (Abstract) Vector Spaces

Motivation: So far, we have constructed  $\mathbb{R}^n$  & subspaces  $V$  of  $\mathbb{R}^n$

$$\textcircled{1} \quad V = \mathbb{R}^n$$

$$\textcircled{2} \quad V = \{\vec{0}\}$$

$$\textcircled{3} \quad V = \text{Sp}(\vec{v}_1, \dots, \vec{v}_r)$$

$$\textcircled{4} \quad V = \text{Row Space } (\underline{A}) = \text{Sp}(\underbrace{\text{Row}_1 A, \text{Row}_2 A, \dots, \text{Row}_m A}_{m \times n})$$

$$\textcircled{5} \quad V = R(A) = \underset{m \times n}{\text{Sp}}(\text{Col}_1 A, \dots, \text{Col}_n A) \text{ in } \mathbb{R}^m$$

Range / Col Space of  $A$

$$= R(T) \text{ where } T: \mathbb{R}^n \rightarrow \mathbb{R}^m \quad T(\vec{v}) = \vec{Av}$$

$$\textcircled{6} \quad V = N(A) = \left\{ \underset{m \times n}{\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}} : A \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \vec{0} \text{ in } \mathbb{R}^m \right\} = N(T)$$

Nullspace of  $A$

Common feature: (1)  $\vec{0}$  in  $V$

(2) We have addition + of vectors & if  $\vec{u}$  &  $\vec{v}$  are in  $V$ ,  
so is  $\vec{u} + \vec{v}$

(3) We can scalar multiply any  $\vec{u}$  in  $V$  & remain in  $V$

(4) + & scalar mult interact nicely (we have nice  
algebraic properties, inherited from  $\mathbb{R}^n$ )

These properties appear in many other contexts in Mathematics.

Example ①: A set of solutions to a homogeneous differential equation.

(\*)  $y''(x) - y(x) = 0$  has 2 types of solutions

Solution 1:  $y_1(x) = e^x$

Solution 2  $y_2(x) = -e^{-x}$

⇒ Any linear combination of these 2 solns is also a solution!

$$y(x) = ae^x + b(-e^{-x}) \quad \text{with } a, b \text{ in } \mathbb{R}$$

$$y'(x) = ae^x + b(-1)(-1)e^{-x} = ae^x + be^{-x}$$

$$y''(x) = ae^x - b e^{-x} = y(x) \quad \checkmark$$

⇒ Solutions 1 & 2 are "linearly independent"

$$0 = ae^x + b(-e^{-x}) \quad \text{for all } x \text{ in } \mathbb{R}$$

Evaluate at special  $x$ 's to confirm  $a=b=0$

• At  $x=0$ :  $0 = a - b \Rightarrow a = b$

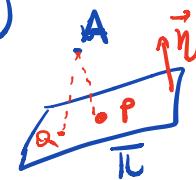
• At  $x=1$   $0 = a \cdot e - b \cdot e^{-1} = ae - \frac{b}{e} = \frac{ae^2 - b}{e} = \frac{a e^2 - 1}{e}$  so  $a=0$

• We can show solutions to (\*) =  $\{y(x) : y'' + y = 0\} = \text{Span}(e^x, -e^{-x})$ .

Example ②: Fix  $A$  in  $\mathbb{R}^3$  and a plane  $\Pi$  through  $(0,0,0)$

Q: What is the closest point  $P$  to  $A$  in the plane?

A: Need to minimize the distance  $d(A, P) = \|\vec{AP}\|$   $P$  in  $\Pi$   
 $= \sqrt{\vec{AP} \cdot \vec{AP}}$



Geometry says  $\vec{AP} \perp$  plane, so it must be proportional to the normal  $\vec{n}$ .

We have other situations where we want to minimize distances:

- Fix the space  $V$  of all continuous functions over  $[0,1]$

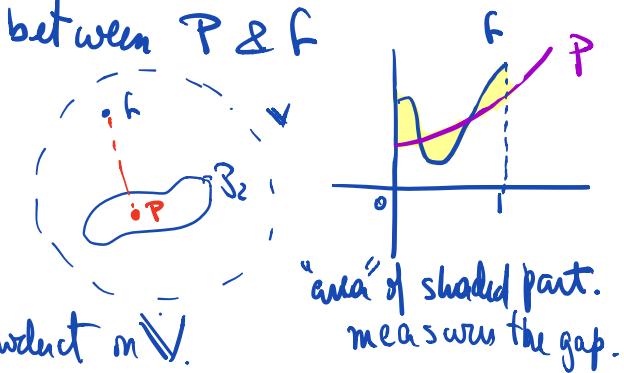
We want to approximate a given  $f: [0,1] \rightarrow \mathbb{R}$  by a polynomial

$P(x)$  of degree  $\leq 2$ , minimizing the "gap" between  $P$  &  $f$

$$P_2 = \{a + bx + cx^2 : a, b, c \in \mathbb{R}\}$$

$$\text{Error} = \|f - P\| = \int_{(x)}^{(x)} (f - P)^2 dx$$

$$\langle g, h \rangle = \int g(x) h(x) dx \quad \text{is an inner product in } V.$$



## Vector Spaces

Q: What defines an abstract vector space?

A. We need a set  $\mathbb{V}$ . We call each element of  $\mathbb{V}$  a vector  $\vec{v}$

- We need to have two operations on  $\mathbb{V}$ :

① Addition :  $+ : \mathbb{V} \times \mathbb{V} \longrightarrow \mathbb{V}$  (add two vectors to get a new vector)  
 $(\vec{u}, \vec{v}) \longmapsto \vec{u} + \vec{v}$

② Scalar Multiplication :  $\cdot : \mathbb{R} \times \mathbb{V} \longrightarrow \mathbb{V}$   $\alpha \vec{v}$  is a new vector  
 $(\alpha, \vec{v}) \longmapsto \alpha \vec{v}$   
 scalar      vector

- We need  $+ \& \cdot$  to have nice properties

Examples:

- ①  $\mathbb{R}^n$  & subspaces  $\mathbb{V}$  of  $\mathbb{R}^n$  (usual  $+ \& \cdot$ )
- ②  $\text{Mat}_{n \times m}(\mathbb{R}) = n \times m$  matrices with real entries (  )
- ③ Polynomials with real coefficients eg  $\mathbb{P}_2 = \{ax^2 + bx + c : a, b, c\}$

## Defining properties for vector spaces

Def A set  $\mathbb{V}$  with addition + & scalar mult. is a vector space if it satisfies

① Closure Properties: (C1)  $\vec{x}, \vec{y} \in \mathbb{V}$ , then  $\vec{x} + \vec{y} \in \mathbb{V}$

(C2)  $\vec{x} \in \mathbb{V}$ , then  $\alpha \vec{x} \in \mathbb{V}$

② Addition Properties: (A1)  $\vec{x} + \vec{y} = \vec{y} + \vec{x}$  (Commutative)

(A2)  $\vec{x} + (\vec{y} + \vec{z}) = (\vec{x} + \vec{y}) + \vec{z}$  (Associative)

(Neutral element)  $\leftarrow$  (A3)  $\vec{0}$  in  $\mathbb{V}$  satisfies  $\vec{x} + \vec{0} = \vec{0} + \vec{x} = \vec{x}$  for all  $\vec{x}$ .

(Additive Inverses)  $\leftarrow$  (A4) given  $\vec{x}$  in  $\mathbb{V}$  we can find " $-\vec{x}$ " in  $\mathbb{V}$   
with  $\vec{x} + (-\vec{x}) = \vec{0}$  (here " $-x$ " =  $(-1)\vec{x}$ )

③ Scalar Mult. Properties: (M1)  $\alpha(\beta \vec{x}) = (\alpha\beta) \vec{x}$  (Associative)

(M2)  $\alpha(\vec{x} + \vec{y}) = \alpha \vec{x} + \alpha \vec{y}$  (Distributive 1)

(M3)  $(\alpha + \beta) \vec{x} = \alpha \vec{x} + \beta \vec{x}$  ( — 2)

(M4)  $1 \vec{x} = \vec{x}$  for all  $\vec{x}$

(M4) follows from (C2)

Example 1:  $\text{Mat}_{m \times n}(\mathbb{R})$

- $\dagger A, B$  of size  $m \times n \Rightarrow A+B$  of size  $m \times n \quad (A+B)_{ij} = A_{ij} + B_{ij}$   
(+ entry-by-entry)
- $\dagger A$  of size  $m \times n$ ,  $\alpha$  scalar  $\Rightarrow \alpha A$  of size  $m \times n$  &  $(\alpha A)_{ij} = \alpha A_{ij}$   
(• entry-by-entry)

$$\mathbb{0} = \begin{bmatrix} 0 & \cdots & 0 \\ \vdots & & \vdots \\ 0 & \cdots & 0 \end{bmatrix} \text{ zero matrix}, \quad (-A) = (-1) \cdot A.$$

In terms of operations, we can think of  $\text{Mat}_{m \times n}(\mathbb{R})$  as  $\mathbb{R}^{m \cdot n}$   
 (write all entries as 1 long column (write col 1, then col 2, ...))

Since  $\mathbb{R}^{m \cdot n}$  is a vector space, so is  $\text{Mat}_{m \times n}(\mathbb{R})$ . [the operations are done entry-by-entry so how we "arrange" the entries is irrelevant]

Nm-example  $\mathbb{V} = \{A \text{ } 2 \times 2 \text{ & singular}\}$  (C1) fails

Why?  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \text{ & } \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$  in  $\mathbb{V}$  but  $\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$  is not in  $\mathbb{V}$ .

## Example 2: Polynomials

Set  $\mathbb{P}_n = \{ \text{polynomials of degree at most } n \} \ni q_0 + q_1 x + \dots + q_n x^{n-1} : q_0, q_1, \dots, q_n \text{ in } \mathbb{R} \}$

$\doteq$  Coefficient-by-coefficient

$$P(x) = q_0 + q_1 x + \dots + q_n x^n$$

$$+ Q(x) = b_0 + b_1 x + \dots + b_n x^n$$


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$$P+Q(x) = (q_0+b_0) + (q_1+b_1)x + \dots + (q_n+b_n)x^n$$

$\doteq$  Coefficient-by-coefficient  $\alpha P(x) = (\alpha q_0) + (\alpha q_1) x + \dots + (\alpha q_n) x^n$

$\bullet \quad \emptyset = 0 + 0 \cdot x + \dots + 0 \cdot x^{n-1} = \text{zero polynomial}$

$\bullet$  We identify P in  $\mathbb{P}_n$  with its list of coefficients  $\begin{bmatrix} q_0 \\ \vdots \\ q_n \end{bmatrix}$  in  $\mathbb{R}^{n+1}$

So  $\mathbb{P}_n$  behaves like  $\mathbb{R}^{n+1}$  for all practical purposes, so the 10 properties are satisfied!

Ex  $\mathbb{P}_2 = \{ q_0 + q_1 x + q_2 x^2 \} = \text{Sp}(1, x, x^2)$ .

Nm-example  $\nabla = \{ P \in \mathbb{P}_2 \text{ with } P(0) = 1 \}$  ( $\text{so } P = 1 + q_1 x + q_2 x^2$ )

(A3) fails  $\emptyset$  is NOT in  $\nabla$ .

Example  $\mathbb{W} = \mathbb{R}^2$  with usual scalar mult, but funky +:

$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} u_1 + v_1 - 1 \\ u_2 + v_2 - 1 \end{bmatrix}$$

• (1) & (2) 2 closure properties hold. (We get vectors in  $\mathbb{R}^2$ )

• (A1)  $\vec{u} \oplus \vec{v} = \vec{v} \oplus \vec{u}$  holds

$$\begin{aligned} \text{• (A2)} \quad \vec{u} \oplus (\vec{v} \oplus \vec{w}) &= \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \left( \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \oplus \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} \right) = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \begin{bmatrix} v_1 + w_1 - 1 \\ v_2 + w_2 - 1 \end{bmatrix} \\ &\stackrel{\text{same } ||}{=} \begin{bmatrix} u_1 + (v_1 + w_1 - 1) - 1 \\ u_2 + (v_2 + w_2 - 1) - 1 \end{bmatrix} = \begin{bmatrix} u_1 + v_1 + w_1 - 2 \\ u_2 + v_2 + w_2 - 2 \end{bmatrix} \end{aligned}$$

$$(\vec{u} \oplus \vec{v}) \oplus \vec{w} = \begin{bmatrix} u_1 + v_1 - 1 \\ u_2 + v_2 - 1 \end{bmatrix} \oplus \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} (u_1 + v_1 - 1) + w_1 - 1 \\ (u_2 + v_2 - 1) + w_2 - 1 \end{bmatrix} = \begin{bmatrix} u_1 + v_1 + w_1 - 2 \\ u_2 + v_2 + w_2 - 2 \end{bmatrix}$$

$$\begin{aligned} \text{• (A3) Neutral element} \quad \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \begin{bmatrix} a \\ b \end{bmatrix} &= \begin{bmatrix} u_1 + a - 1 \\ u_2 + b - 1 \end{bmatrix} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \Rightarrow a = b = 1 \\ \text{so } \textcircled{1}_{\text{new}} &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \text{• (A4) Additive inverse} \quad \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \begin{bmatrix} a \\ b \end{bmatrix} &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ forces } \begin{cases} u_1 + a - 1 = 1 \\ u_2 + b - 1 = 1 \end{cases} \end{aligned}$$

$$\text{so Inverse of } \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} -u_1 + 2 \\ -u_2 + 2 \end{bmatrix}$$

$\mathbb{W} = \mathbb{R}^2$  with usual scalar mult but  $\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} u_1 + v_1 - 1 \\ u_2 + v_2 - 1 \end{bmatrix}$

(M1) Associative  $\alpha (\beta \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}) = (\alpha \beta) \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$  ✓ inherited from  $\mathbb{R}^2$  (same scalar mult!)

(M4)  $1 \cdot \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$  also inherited from  $\mathbb{R}^2$  ✓

(M2) Distributive 1  $\alpha (\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}) = \alpha \begin{bmatrix} u_1 + v_1 - 1 \\ u_2 + v_2 - 1 \end{bmatrix} = \begin{bmatrix} \alpha u_1 + \alpha v_1 - \alpha \\ \alpha u_2 + \alpha v_2 - \alpha \end{bmatrix}$

$$\alpha \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \oplus \alpha \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \alpha u_1 \\ \alpha u_2 \end{bmatrix} \oplus \begin{bmatrix} \alpha v_1 \\ \alpha v_2 \end{bmatrix} = \begin{bmatrix} \alpha u_1 + \alpha v_1 - 1 \\ \alpha u_2 + \alpha v_2 - 1 \end{bmatrix}$$

so the property fails when  $\alpha \neq 1$ .

(M3) Distributive 2 also fails

$$(\alpha + \beta) \begin{bmatrix} u_1 \\ v_1 \end{bmatrix} = \begin{bmatrix} (\alpha + \beta) u_1 \\ (\alpha + \beta) v_1 \end{bmatrix} = \begin{bmatrix} \alpha u_1 + \beta u_1 \\ \alpha v_1 + \beta v_1 \end{bmatrix}$$

$$\alpha \begin{bmatrix} u_1 \\ v_1 \end{bmatrix} \oplus \beta \begin{bmatrix} u_1 \\ v_1 \end{bmatrix} = \begin{bmatrix} \alpha u_1 \\ \alpha v_1 \end{bmatrix} \oplus \begin{bmatrix} \beta u_1 \\ \beta v_1 \end{bmatrix} = \begin{bmatrix} \alpha u_1 + \beta u_1 - 1 \\ \alpha v_1 + \beta v_1 - 1 \end{bmatrix}$$

Conclusion:  $\mathbb{R}^2$  with  $\oplus$  & usual. is NOT a vector space.