

Lecture 27: §5.9 Matrix representations for linear transformations

Recall A linear transf $T: \mathbb{R}^n \longrightarrow \mathbb{R}^m$ is always given by a matrix A $m \times n$

$$A = [T(\vec{e}_1), \dots, T(\vec{e}_n)]$$

Ex: $T: \mathbb{R}^2 \longrightarrow \mathbb{R}^3$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \longmapsto \begin{bmatrix} x_1 - x_2 \\ 2x_1 + 4x_2 \\ x_2 \end{bmatrix}$$

TODAY'S GOAL: Find a similar way to interpret $T: V \longrightarrow W$ linear transf

Summary: • If $\dim V = n$ $B_V = \{\vec{v}_1, \dots, \vec{v}_n\}$ basis for V

• If $\dim W = m$ $B_W = \{\vec{w}_1, \dots, \vec{w}_m\}$ basis for W

Then $\vec{v} \in V \xrightarrow{T} W \xrightarrow{\text{isom}} \mathbb{R}^m$

$\vec{v} \mapsto [\vec{v}]_{B_V}$ $\mathbb{R}^n$ $\xrightarrow[\text{matrix } A]{\sim} \mathbb{R}^m$ $\xrightarrow{\text{isom}} W \xrightarrow{\text{isom}} \mathbb{R}^m$

$\vec{w} = \beta_1 \vec{w}_1 + \dots + \beta_m \vec{w}_m$

$\uparrow$ $[\beta_1, \dots, \beta_m]$

$$A = [[T(\vec{v}_1)]_{B_W} \dots [T(\vec{v}_n)]_{B_W}]$$

$$\implies [T(\vec{v})]_{B_W} = A [\vec{v}]_{B_V} \quad m \times n$$

NOTE: $A = \text{matrix of } T \text{ relative to the bases } B_V \text{ \& } B_W$.

Three Fundamental Facts

$T: V \rightarrow W$ linear

FACT ① T is completely determined by its values on a basis for W .

FACT ② If $\dim W = n$ & $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ is a basis for W , then

$T: W \rightarrow \mathbb{R}^n$ is linear and invertible with $T^{-1}: \mathbb{R}^n \rightarrow W$

$$\vec{v} \mapsto [\vec{v}]_B$$

$$\begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} \mapsto \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n$$

Write $T = T_B$ to emphasize the crucial role of the basis B .

Upshot: By choosing a basis B for W we can always think of W as $\mathbb{R}^n$.

Conclusion 1: If we choose coordinates for W & W by picking a basis for each space, then T can be thought of as $\tilde{T}: \mathbb{R}^n \rightarrow \mathbb{R}^m$ linear

FACT ③ Composition of linear maps is linear

$$V \xrightarrow{F} W \xrightarrow{G} U$$

$G \circ F(\vec{v}) = G(F(\vec{v}))$

①

$$T: \mathcal{P}_3 \longrightarrow \mathcal{P}_2$$

$$p(x) \longmapsto p'(x)$$

Examples

$$T(a+bx+cx^2+dx^3) = b+2cx+3dx^2$$

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ T_B^{-1} \uparrow & \boxed{\frac{2}{1}} & \downarrow T_B \\ \mathbb{R}^n & & \mathbb{R}^m \end{array}$$

② $T: \text{Mat}_{2 \times 3} \longrightarrow \mathbb{R}^3$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} = A \longmapsto \begin{bmatrix} 2a_{11} - 4a_{22} \\ a_{13} + a_{21} \\ a_{12} - a_{23} \end{bmatrix}$$

$$T: \text{Mat}_{2 \times 3} \longrightarrow \mathbb{R}^3$$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} = A \longmapsto \begin{bmatrix} 2a_{11} - 4a_{22} \\ a_{13} + a_{21} \\ a_{12} - a_{23} \end{bmatrix}$$

$$B_{\text{Mat}_{2 \times 3}} = \{E_{11}, E_{12}, E_{13}, E_{21}, E_{22}, E_{23}\}$$

Q: What if we chose a different basis for $\mathbb{R}^3$?

$$B'_{\mathbb{R}^3} = \left\{ \overset{\vec{w}_1}{\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}}, \overset{\vec{w}_2}{\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}, \overset{\vec{w}_3}{\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}} \right\}$$

$$\text{New } A = \begin{bmatrix} 2 & 0 & -1 & -1 & -4 & 0 \\ 0 & -1 & 1 & 1 & 0 & 1 \\ 0 & 1 & 0 & 0 & 0 & -1 \end{bmatrix}$$

$$\tilde{T} = T_{B_{\text{Mat}_{2 \times 3}}}^{B'_{\mathbb{R}^3}} : \mathbb{R}^6 \xrightarrow{(T_{B_{\text{Mat}}})^{-1}} \text{Mat}_{2 \times 3} \xrightarrow{T} \mathbb{R}^3 \xrightarrow{T_{B'_{\mathbb{R}^3}}} \mathbb{R}^3$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} \longmapsto \begin{bmatrix} x_1 & x_2 & x_3 \\ x_4 & x_5 & x_6 \end{bmatrix} \longrightarrow \begin{bmatrix} 2x_1 - 4x_5 \\ x_3 + x_4 \\ x_2 - x_6 \end{bmatrix} \longrightarrow \left[\begin{bmatrix} 2x_1 - 4x_5 \\ x_3 + x_4 \\ x_2 - x_6 \end{bmatrix} \right]_{B'_{\mathbb{R}^3}}$$

$$T\left(\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ 0 \\ 0 \end{bmatrix} =$$

$$T\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} =$$

$$T\left(\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}\right) = T\left(\begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} =$$

$$T\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}\right) = \begin{bmatrix} -4 \\ 0 \\ 0 \end{bmatrix} =$$

$$T\left(\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}\right) = \begin{bmatrix} 0 \\ 0 \\ -1 \end{bmatrix} =$$

Matrix Representation

Representation Theorem: Fix $T: V \longrightarrow W$ linear transf with $\dim V = n$ & $\dim W = m$. Pick $B_V = \{\vec{v}_1, \dots, \vec{v}_n\}$ basis for V
 $B_W = \{\vec{w}_1, \dots, \vec{w}_m\}$ basis for W .

Then, T, B_V & B_W gives rise to a linear transformation

$$T_{B_V B_W}: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

defined by
$$T_{B_V B_W} \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = T_{B_W} \circ T \circ T_{B_V}^{-1} \begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = [T(a_1 \vec{v}_1 + \dots + a_n \vec{v}_n)]_{B_W}$$

Furthermore, the associated $m \times n$ matrix is obtained as follows:

$$[T]_{B_V B_W} = \begin{bmatrix} [T(\vec{v}_1)]_{B_W} & \dots & [T(\vec{v}_n)]_{B_W} \end{bmatrix}$$

Consequence: $T(\vec{v}) = \beta_1 \vec{w}_1 + \dots + \beta_m \vec{w}_m$ where $\begin{bmatrix} \beta_1 \\ \vdots \\ \beta_m \end{bmatrix}_{m \times 1} = [T]_{B_V B_W} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}_{n \times 1}$
 $\vec{v} = \alpha_1 \vec{v}_1 + \dots + \alpha_n \vec{v}_n$

Examples

$$\textcircled{1} \quad T: \mathcal{P}_3 \longrightarrow \mathcal{P}_2 \\ p_{(x)} \longmapsto p'_{(x)}$$

$$\mathcal{B}_{\mathcal{P}_3} = \{1, x, x^2, x^3\} \\ \mathcal{B}_{\mathcal{P}_2} = \{1, x, x^2\}$$

$$\underline{Q} [T]_{\mathcal{B}_{\mathcal{P}_3} \mathcal{B}_{\mathcal{P}_2}} = ?$$

$$\textcircled{2} \quad T: \mathcal{P}_2 \longrightarrow \mathbb{R}^2$$

$$a+bx+cx^2 \mapsto \begin{bmatrix} c-b \\ 2c+a \end{bmatrix}$$

$$T(1) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$T(x) = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$$

$$T(x^2) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\mathcal{B}_{\mathcal{P}_2} = \{1, x, x^2\}$$

$$\mathcal{B}_{\mathbb{R}^2} = \left\{ \underbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}_{\vec{w}_1}, \underbrace{\begin{bmatrix} -1 \\ 1 \end{bmatrix}}_{\vec{w}_2} \right\}$$

$$\bullet \quad [T(3+4x+5x^2)]_{\mathcal{B}_{\mathbb{R}^2}}$$

$$\text{So } T(3+4x+5x^2) =$$

$$\textcircled{3} \quad T: \text{Mat}_{2 \times 2} \longrightarrow \mathcal{P}_3 \quad T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = (a+d)x^2 + ax + (b-3c)$$

$$\mathcal{B}_{\text{Mat}_{2 \times 2}} = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\} \quad \mathcal{B}_{\mathcal{P}_3} = \{1, x, x^2\}$$

$$T\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right) = x^2 + x \rightsquigarrow [\]_{\mathcal{B}_{\mathcal{P}_3}} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \quad ; \quad T\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right) = -3 \rightsquigarrow [\]_{\mathcal{B}_{\mathcal{P}_3}} = \begin{bmatrix} 0 \\ 0 \\ -3 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\right) = 1 \rightsquigarrow [\]_{\mathcal{B}_{\mathcal{P}_3}} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$T\left(\begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\right) = x^2 \rightsquigarrow [\]_{\mathcal{B}_{\mathcal{P}_3}} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$\rightsquigarrow [T]_{\mathcal{B}_{\text{Mat}_{2 \times 2}} \mathcal{B}_{\mathcal{P}_3}} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & -3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Algebraic Properties

3 operations on $T: V \rightarrow W$.

(I) ADDITION

$$F+G: V \rightarrow W \text{ linear}$$

$$(F+G)(\vec{v}) = F(\vec{v}) + G(\vec{v})$$

$\uparrow$
 $\in W$

(II) SCALAR MULTIPLICATION

$$\alpha T: V \rightarrow W \text{ linear}$$

$$(\alpha T)(\vec{v}) = \alpha \cdot T(\vec{v})$$

$\uparrow$
 $\in W$

(III) COMPOSITION

$$F: V \rightarrow W \text{ linear}$$

$$G: W \rightarrow U \text{ linear}$$

Then $G \circ F: V \rightarrow U$ linear

$$(G \circ F)(\vec{v}) = G(\underbrace{F(\vec{v})}_{\in W})$$

$$[F+G] = [F] + [G]$$

Using bases B_V
 B_W

(same for all 3 matrices)

$$[\alpha T] = \alpha [T]$$

Using bases B_V
 B_W

(same for both matrices)

$$[G \circ F]_{B_U B_V} = [G]_{B_U B_W} [F]_{B_W B_V}$$

$m \times n$ $m \times l$ $l \times n$

$\dim V = n$
 $\dim W = l$
 $\dim U = m$

Any $B_{W \rightarrow U}$.

Application $T: V \rightarrow W$ is invertible if and only if $[T]_{B_W B_V}$ is invertible for any $B_V = \text{basis for } V$ & $B_W = \text{basis for } W$ (so $\dim V = \dim W$)

Example: $F: \text{Mat}_{2 \times 2} \longrightarrow \mathcal{P}_2$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \rightarrow (a+d)x^2 + ax + (b-c)$$

$$G: \mathcal{P}_2 \longrightarrow \mathbb{R}^2$$

$$P_{(x)} \mapsto \begin{bmatrix} P(1) \\ P'(2) \end{bmatrix}$$