

## Lecture 36 : §4.7 Similarities & Diagonalization

Last time Defined  $\mathbb{C}$ -vector spaces & focused on 5 examples

$$\textcircled{1} \quad \mathbb{C}^n = \left\{ \vec{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \mid v_1, \dots, v_n \in \mathbb{C} \right\}$$

+ & scalar multiplication (by  $\mathbb{C}$ ) : entry-by-entry

$$\textcircled{2} \quad \text{Span}_{\mathbb{C}}(\vec{v}_1, \dots, \vec{v}_p) = \text{all } \mathbb{C}\text{-linear comb. of } \vec{v}_1, \dots, \vec{v}_p$$

$$= \{ \alpha_1 \vec{v}_1 + \dots + \alpha_p \vec{v}_p \mid \alpha_1, \dots, \alpha_p \in \mathbb{C} \}$$

$$\textcircled{3} \quad \text{Mat}_{m \times n}(\mathbb{C}) = \{ A = (a_{ij}) \text{ of size } m \times n : a_{ij} \in \mathbb{C} \}$$

+ & scalar multiplication (by  $\mathbb{C}$ ) : entry-by-entry

$$\textcircled{4} \quad W(A) = \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \in \mathbb{C}^n \mid A \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \right\} \rightsquigarrow A \sim A' \text{ REF}$$

Compute  $A'$  via Gauss-Jordan using  $\mathbb{C}$  in elementary row operations

$$\textcircled{5} \quad P_n(\mathbb{C}) = \{ a_0 + a_1 x + \dots + a_n x^n \mid a_0, \dots, a_n \in \mathbb{C} \}$$

+ & scalar mult : coeff-by-coeff

## Similarities

Definition Fix  $A, C$  in  $\text{Mat}_{n \times n}(\mathbb{C})$ . We say  $A$  is similar to  $C$  (and write  $A \sim C$ ) if we can find  $S$  non-singular in  $\text{Mat}_{n \times n}(\mathbb{C})$  ( $\det(S) \neq 0$  in  $\mathbb{C}$ ) with  $C = S^{-1} \cdot A \cdot S$ .

Motivation:  $A$  &  $C$  will represent the same  $\mathbb{C}$ -linear transformation

$T: \mathbb{C}^n \rightarrow \mathbb{C}^n$  with respect to different bases :  $B_A$  &  $B_C$ .

Then  $S$  will be the matrix according the change of basis from  $B_C$  to  $B_A$

Typical situation :  $T(\vec{v}) = A\vec{v}$  so  $[T]_{EE} = A$   $E = \{\vec{e}_1, \dots, \vec{e}_n\}$

If  $B_C = \{\vec{v}_1, \dots, \vec{v}_n\}$ , then  $C = S^{-1} \cdot A \cdot S$  with  $S = [\vec{v}_1 \ \dots \ \vec{v}_n]$

Q: Why do we care about similar matrices?

Proposition 1: Similar matrices have the same characteristic polynomials  
(so same eigenvalues with the same algebraic multiplicity!)

 If  $P_A(\lambda) = P_C(\lambda)$ , this does NOT mean  $A \sim C$ .

Q: How are  $E_\lambda(C)$  &  $E_\lambda(A)$  related when  $A \sim C$ ?

Proposition 2: If  $C = S^{-1}AS$  &  $\vec{v} \neq \vec{0}$  is in  $E_\lambda(C)$ , then  $\vec{w} = S\vec{v}$  is in  $E_\lambda(A)$ . Moreover,  $\dim E_\lambda(C) = \dim E_\lambda(A)$  &

$$B = \{\vec{v}_1, \dots, \vec{v}_p\}$$

basis for  $E_\lambda(C)$

$$\tilde{B} = \{S\vec{v}_1, \dots, S\vec{v}_p\}$$

basis for  $E_\lambda(A)$ .

Example  $A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ ,  $C = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

## Diagonalization

Def: We say an  $n \times n$  real matrix  $A$  is diagonalizable over  $\mathbb{Q}$  if it is similar to a diagonal matrix  $D = \begin{pmatrix} d_1 & & \\ & \ddots & \\ & & d_n \end{pmatrix}$  in  $\text{Mat}_{n \times n}(\mathbb{Q})$

So  $D = S^{-1}AS$  for  $S \in \text{Mat}_{n \times n}(\mathbb{Q})$  nonsingular ( $\det S \neq 0$ )

Example ①  $A = \begin{bmatrix} 5 & -6 \\ 3 & -4 \end{bmatrix}$

Example ②:  $A = \begin{bmatrix} 5 & -6 & 0 \\ 3 & -4 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

## Real Symmetric Matrices

Diagonalizable over  $\mathbb{R}$ !

Theorem: Fix  $A$   $n \times n$  real symmetric matrix. Then :

①  $A$  has only real eigenvalues  $\lambda_1, \dots, \lambda_n$

②  $\mathbb{R}^n$  has an orthonormal basis  $B$  of eigenvectors for  $A$

that is,  $B \{ \vec{v}_1, \dots, \vec{v}_n \}$  with  $v_i$  in  $E_{\lambda_i}(A)$ . and  $v_i \cdot v_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$

③  $\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} = Q^T A Q \quad \text{with } Q = [\vec{v}_1 \dots \vec{v}_n]$