

Lecture 37: §9.7 Similarities & Diagonalization

Recall: An $n \times n$ real matrix A is diagonalizable over \mathbb{C} if $A \sim D$

where $D = \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix}$ is a diagonal matrix in $\text{Mat}_{n \times n}(\mathbb{C})$

So $D = S^{-1} A S$ \Leftrightarrow $S \in \text{Mat}_{n \times n}(\mathbb{C})$ nonsingular ($\det S \neq 0$)

• $\exists d_1, \dots, d_n \in \mathbb{C}$ are the eigenvalues of A (with possible repetitions)

• If $S = [\vec{v}_1, \dots, \vec{v}_n]$ then $A \vec{v}_1 = d_1 \vec{v}_1$ & $\exists \vec{v}_1, \dots, \vec{v}_n$ is a basis for \mathbb{C}^n
 $A \vec{v}_2 = d_2 \vec{v}_2$ (basis of eigenvectors!)
 $A \vec{v}_n = d_n \vec{v}_n$

• S invertible so $S^{-1} = \frac{\text{Cof}(S)^T}{\det(S)}$, also $(S | I_n) \xrightarrow{\text{row-operations}} (I_n | S^{-1})$

Conclusion: A is diagonalizable over \mathbb{C} means \mathbb{C}^n has a basis of eigenvectors

Example: $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ $P_A(\lambda) = \det \begin{pmatrix} -\lambda & 1 \\ -1 & -\lambda \end{pmatrix} = \lambda^2 + 1 = (\lambda - i)(\lambda + i) \Rightarrow \lambda = \pm i$ eigenvalues

$E_i(A) = \mathcal{N}(A - iI) = \mathcal{N} \begin{pmatrix} -i & 1 \\ -1 & i \end{pmatrix} = \mathcal{N} \begin{pmatrix} 1 & i \\ 0 & 0 \end{pmatrix} = \text{Sp} \left(\begin{bmatrix} i \\ 1 \end{bmatrix} \right)$ $\begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}$

$\Rightarrow E_{-i}(A) = \overline{E_i(A)} = \text{Sp} \left(\begin{bmatrix} +i \\ 1 \end{bmatrix} \right)$ so $D = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$ $S = \begin{bmatrix} -i & +i \\ 1 & 1 \end{bmatrix} \Rightarrow S^{-1} = \frac{1}{-2i} \begin{bmatrix} 1 & -i \\ -1 & -i \end{bmatrix}$

Real Symmetric Matrices

Diagonalizable over \mathbb{R} !

Theorem: Fix A $n \times n$ real symmetric matrix. Then:

- ① A has only real eigenvalues $\lambda_1, \dots, \lambda_n$ (possibly repeated!) L35
- ② \mathbb{R}^n has an orthonormal basis B of eigenvectors for A that is, $B = \{ \vec{v}_1, \dots, \vec{v}_n \}$ with v_i in $E_{\lambda_i}(A)$. and $v_i \cdot v_j = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$
- ③ $\begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix} = Q^T A Q$ with $Q = [\vec{v}_1 \dots \vec{v}_n]$
($Q^{-1} = Q^T$ because B is orthonormal!)

Example: $A = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = A^T$ $P_A(\lambda) = \det \begin{pmatrix} 1-\lambda & -1 \\ -1 & 1-\lambda \end{pmatrix} = (1-\lambda)^2 - 1 = \lambda(\lambda-2)$

$$E_0 = \mathcal{N}(A) = \mathcal{N} \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix} = \text{Sp} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right) = \text{Sp} \left(\begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right) \rightarrow \text{norm} = 1$$

$$E_2 = \mathcal{N}(A - 2I_2) = \mathcal{N} \begin{pmatrix} -1 & -1 \\ -1 & -1 \end{pmatrix} = \mathcal{N} \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} = \text{Sp} \left(\begin{bmatrix} 1 \\ -1 \end{bmatrix} \right) = \text{Sp} \left(\begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix} \right)$$

Check: $\begin{bmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{bmatrix} \cdot \begin{bmatrix} \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \end{bmatrix} = 0$ Take $Q = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{bmatrix}$ $C = \begin{bmatrix} 0 & 0 \\ 0 & 2 \end{bmatrix}$.

Why diagonalize?

A: We can perform power operations very fast!

Proposition: ① If $D = S^{-1}AS$ (AND), then $A^k = S D^k S^{-1}$ for all $k=1,2,\dots$
 ② If $D = \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix}$, then $D^k = \begin{pmatrix} d_1^k & & 0 \\ & \ddots & \\ 0 & & d_n^k \end{pmatrix}$ for all $k=1,2,\dots$

If D is invertible, the same formulas work for $k=-1, -2, \dots$

Why? ① $D = S^{-1}AS \implies SDS^{-1} = A$

$$\left. \begin{aligned} \bullet A^2 &= A \cdot A = SDS^{-1} \underbrace{SDS^{-1}}_{=I_n} = SD^2S \\ \bullet A^3 &= A \cdot A^2 = SDS^{-1} \underbrace{SD^2S}_{=I_n} = SD^3S, \text{ etc.} \end{aligned} \right\} \begin{array}{l} \text{In general} \\ A^k = SD^k S^{-1} \end{array}$$

$$\textcircled{2} \quad D^2 = \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix} \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix} = \begin{pmatrix} d_1^2 & & 0 \\ & \ddots & \\ 0 & & d_n^2 \end{pmatrix}$$

$$D^3 = D D^2 = \begin{pmatrix} d_1 & & 0 \\ & \ddots & \\ 0 & & d_n \end{pmatrix} \begin{pmatrix} d_1^2 & & 0 \\ & \ddots & \\ 0 & & d_n^2 \end{pmatrix} = \begin{pmatrix} d_1^3 & & 0 \\ & \ddots & \\ 0 & & d_n^3 \end{pmatrix} \text{ etc.}$$

• If D is invertible, all $d_i \neq 0$ so $D^{-1} = \begin{pmatrix} d_1^{-1} & & 0 \\ & \ddots & \\ 0 & & d_n^{-1} \end{pmatrix}$ is also diagonal.
 & $A^{-1} = (SDS^{-1})^{-1} = (S^{-1})^{-1} D^{-1} S^{-1} = S D^{-1} S^{-1}$ Same ideas work for $A^{-1} \sim D^{-1}$

Example (last time) $A = \begin{bmatrix} 5 & -6 \\ 3 & -4 \end{bmatrix}$ $P_A(\lambda) = (\lambda-2)(\lambda+1)$ $E_{-1} = \text{Sp} \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \right)$
 $E_2 = \text{Sp} \left(\begin{bmatrix} 2 \\ 1 \end{bmatrix} \right)$

$$D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}, \quad S = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix}, \quad S^{-1} = \frac{1}{1-2} \begin{bmatrix} 1 & -2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$$

$$D = S^{-1}AS, \quad \text{so} \quad A = SDS^{-1}$$

\swarrow basis for E_{-1} \searrow basis for E_2

① Compute A^{-1} : $A^{-1} = (SDS^{-1})^{-1} = S D^{-1} S^{-1} = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 1/2 \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$
 $= \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & -2 \\ 1/2 & -1/2 \end{bmatrix} = \begin{bmatrix} 1+1 & -2-1 \\ 1+1/2 & -2-1/2 \end{bmatrix} = \begin{bmatrix} 2 & -3 \\ 3/2 & -5/2 \end{bmatrix}$

Check $\begin{bmatrix} 5 & -6 \\ 3 & -4 \end{bmatrix} \begin{bmatrix} 2 & -3 \\ 3/2 & -5/2 \end{bmatrix} = \begin{bmatrix} 10-9 & -15+15 \\ 6-6 & -9+10 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \checkmark$

② Compute A^{10} : $A^{10} = S D^{10} S^{-1} = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 2^{10} \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$
 $= \begin{bmatrix} 1 & 2^{11} \\ 1 & 2^{10} \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} -1+2^{11} & 2-2^{11} \\ -1+2^{10} & 2-2^{10} \end{bmatrix} = \begin{bmatrix} 2047 & -2046 \\ 1023 & -1022 \end{bmatrix}$

③ Compute $(A^{-1})^{10}$: $A^{-10} = S (D^{-1})^{10} S^{-1} = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1/2^{10} \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix}$
 $= \begin{bmatrix} 1 & 1/2^9 \\ 1 & 1/2^{10} \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} \frac{-2^9+1}{2^9} & \frac{2^{10}-1}{2^9} \\ \frac{-2^{10}+1}{2^{10}} & \frac{2^{11}-1}{2^{10}} \end{bmatrix} = \begin{bmatrix} \frac{-511}{512} & \frac{1023}{512} \\ \frac{-1023}{1024} & \frac{2047}{1024} \end{bmatrix}$

Diagonalization over \mathbb{R} vs over \mathbb{C}

Fix A an $n \times n$ matrix with entries in \mathbb{R} .

Theorem: ① A is diagonalizable over \mathbb{R} if, and only if, all eigenvalues of A are real & \mathbb{R}^n has a basis of eigenvectors for A .

• If $\{\lambda_1, \dots, \lambda_r\}$ are the eigenvalues, then each $E_{\lambda_i}(A)$ is a subspace of \mathbb{R}^n . We have a basis of eigenvectors if, and only if,

$$\dim_{\mathbb{R}} E_{\lambda_1}(A) + \dots + \dim_{\mathbb{R}} E_{\lambda_r}(A) = n$$

Equivalently: $\dim_{\mathbb{R}} E_{\lambda_i}(A) = \text{mult}(\lambda_i, P_A)$ for all $i=1, \dots, r$ (A non-defective)

② A is diagonalizable over \mathbb{C} if, and only if, \mathbb{C}^n has a basis of eigenvectors for A . This happens if and only if

$$\dim_{\mathbb{C}} E_{\lambda}(A) = \text{mult}(\lambda, P_A) \text{ for each eigenvalue } \lambda.$$

Fr ②: View $E_{\lambda}(A)$ as a subspace of \mathbb{C}^n even if λ is real
[If λ is real, we can pick a basis for $E_{\lambda}(A)$ using vectors in \mathbb{R}^n .

• Diagonalization of A over $\mathbb{C} \xrightarrow{\textcircled{1}}$ basis for \mathbb{C}^n with eigenvectors

Why? $\textcircled{1} A = S \Delta S^{-1}$ $\xrightarrow{\textcircled{2}}$ Eigenvalues of A are diagonal entries of Δ
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Write $S = [\vec{v}_1, \dots, \vec{v}_n]$. Then: $S^{-1} v_i = S^{-1} \text{col}_i(S) = \text{col}_i(S^{-1}S) = \text{col}_i(I_n) = e_i$

$$\text{So } A \vec{v}_i = S \Delta S^{-1} \vec{v}_i = S \Delta e_i = S(d_i e_i) = d_i S e_i = d_i \vec{v}_i$$

So \vec{v}_i is an eigenvector for A

S is nonsingular means the columns are li, so $\{\vec{v}_1, \dots, \vec{v}_n\}$

is a basis for \mathbb{C}^n (li + size = $\dim \mathbb{C}^n$)

$\textcircled{2}$ Pick $B = \{\vec{v}_1, \dots, \vec{v}_n\}$ basis for \mathbb{C}^n using eigenvectors

Then $S = [\vec{v}_1, \dots, \vec{v}_n]$ is nonsingular. Pick $i = 1, \dots, n$: $[A v_i = \lambda_i v_i]$

$$\text{col}_i(S^{-1} A S) = S^{-1} A \text{col}_i(S) = S^{-1} A \vec{v}_i = S^{-1} \lambda_i \vec{v}_i = \lambda_i S^{-1} \text{col}_i(S) = \lambda_i e_i$$

So $S^{-1} A S = \begin{pmatrix} \lambda_1 & & 0 \\ & \lambda_2 & \\ 0 & & \lambda_n \end{pmatrix}$ is diagonal! Conclude: A is diagonalizable

• From \mathbb{C} to \mathbb{R} : eigenvalues λ_i in \mathbb{R} & E_{λ_i} : computations can be done in \mathbb{R}^n .

Diagonalizable = non-defective

A in $\text{Mat}_{n \times n}(\mathbb{R})$

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Proposition: Pick $\lambda_1, \dots, \lambda_p$ distinct eigenvalues for A & $S = \{\vec{v}_1, \dots, \vec{v}_p\}$ with $\vec{v}_i \neq \vec{0}$ & $A\vec{v}_i = \lambda_i \vec{v}_i$. Then S is li

Consequence: If $\{\lambda_1, \dots, \lambda_r\}$ are all the eigenvalues of A (in \mathbb{C}) & $\dim_{\mathbb{C}} E_{\lambda_i}(A) = \text{mult}(\lambda_i, P_A)$ for $i=1, \dots, r$, then \mathbb{C}^n has a basis of eigenvectors.
 \leq (always)

Why? If $m_i = \dim_{\mathbb{C}} E_{\lambda_i}(A)$ then $m_1 + m_2 + \dots + m_r = \deg(P_A) = n$.
 \leq (always!)

$B_1 = \{\vec{v}_1^{(1)}, \dots, \vec{v}_{m_1}^{(1)}\}$ basis for E_{λ_1}
 \vdots
 $B_r = \{\vec{v}_1^{(r)}, \dots, \vec{v}_{m_r}^{(r)}\}$ ————— E_{λ_r}] Claim $B_1 \cup \dots \cup B_r$ is a basis for \mathbb{C}^n

Show B is li: (*) $\vec{0} = \underbrace{\alpha_{11}\vec{v}_1^{(1)} + \dots + \alpha_{1m_1}\vec{v}_{m_1}^{(1)}}_{=\vec{v}_1 \text{ in } E_{\lambda_1}} + \dots + \underbrace{\alpha_{r1}\vec{v}_1^{(r)} + \dots + \alpha_{rm_r}\vec{v}_{m_r}^{(r)}}_{=\vec{v}_r \text{ in } E_{\lambda_r}}$

• If $\vec{v}_i = \vec{0}$ then $\alpha_{i1} = \dots = \alpha_{im_i} = 0$ (B_i is li)

• After removing the \vec{v}_i 's that are $\vec{0}$ from (*), the remaining ones will be li (their sum is $\vec{0}$!) This contradicts the Proposition, so all $\vec{v}_i \neq \vec{0}$

Example: $A = \begin{bmatrix} 25 & -8 & 30 \\ 24 & -7 & 30 \\ -12 & 4 & -14 \end{bmatrix} \rightsquigarrow P_A(\lambda) = -\lambda^3 + 4\lambda^2 - 5\lambda + 2$
 $= -(\lambda-1)^2(\lambda-2)$

Eigenvalues: $\lambda = 1$ with mult 2 & $\lambda = 2$ with mult 1

We compute E_1 & E_2 to decide if A is diagonalizable or not! (E_1 is key!)

$E_1 = \mathcal{N}(A - I_3) = \mathcal{N} \begin{pmatrix} 24 & -8 & 30 \\ 24 & -8 & 30 \\ -12 & 4 & -14 \end{pmatrix} = \mathcal{N} \begin{pmatrix} 24 & -8 & 30 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} = \mathcal{N} \begin{pmatrix} 1 & -\frac{1}{3} & \frac{5}{4} \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$

x_1 dep, x_2 & x_3 indep

$x_1 = \frac{1}{3}x_2 - \frac{5}{4}x_3$

$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \frac{1}{3}x_2 - \frac{5}{4}x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} \frac{1}{3} \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -\frac{5}{4} \\ 0 \\ 1 \end{bmatrix}$

REF

$E_1 = \text{Sp} \left(\begin{bmatrix} \frac{1}{3} \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{5}{4} \\ 0 \\ 1 \end{bmatrix} \right) = \text{Sp} \left(\begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 4 \\ 0 \end{bmatrix} \right)$

$\dim E_1(A) = 2$

$E_2 = \mathcal{N}(A - 2I_3) = \mathcal{N} \begin{pmatrix} 23 & -8 & 30 \\ 24 & -9 & 30 \\ -12 & 4 & -16 \end{pmatrix} = \mathcal{N} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} = \mathcal{N} \begin{pmatrix} 1 & 0 & 2 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{pmatrix} = \text{Sp} \left(\begin{bmatrix} -2 \\ -2 \\ 1 \end{bmatrix} \right)$

$\dim E_1 = 2 = \text{mult}(1, P_A)$ & $\dim E_2 = 1 = \text{mult}(2, P_A)$ so A is diagonalizable

$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$

$S = \begin{bmatrix} 1 & -5 & -2 \\ 3 & 4 & -2 \\ 0 & 0 & 1 \end{bmatrix}$

$S^{-1} = \begin{bmatrix} 4/19 & 5/19 & 18/19 \\ -3/19 & 1/19 & -4/19 \\ 0 & 0 & 1 \end{bmatrix}$

$\left(S = \begin{bmatrix} -5 & 1 & -2 \\ 4 & 3 & -2 \\ 0 & 0 & 1 \end{bmatrix} \right)$

$D = S^{-1}AS$

(diagonalizable over \mathbb{R})

would also work!