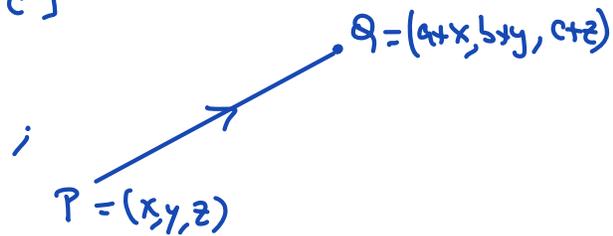
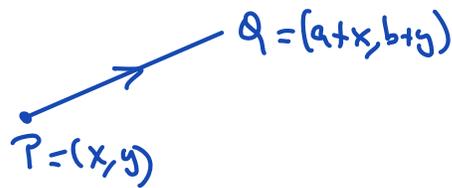


# Lecture XI: § 2.3 The dot product

Recall Last time we discussed vectors in 2 & 3 dimensions geometrically

Algebraically:  $\vec{v} = \begin{bmatrix} a \\ b \end{bmatrix} \in \mathbb{R}^2$ ;  $\vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \in \mathbb{R}^3$

Geometrically

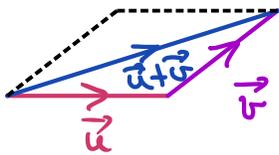


Magnitude of  $v = \|\vec{v}\| = \text{distance}(P, Q)$

$$\vec{v} = \begin{bmatrix} a \\ b \end{bmatrix} \rightsquigarrow \|\vec{v}\| = \sqrt{a^2 + b^2} \quad \text{in } \mathbb{R}^2$$

$$\vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \rightsquigarrow \|\vec{v}\| = \sqrt{a^2 + b^2 + c^2} \quad \text{in } \mathbb{R}^3$$

Geometric interpretation of addition & scalar multiplication.



Triangle/Parallelogram Law

$$\|a\vec{v}\| = |a| \|\vec{v}\| \quad \text{for } a \in \mathbb{R}$$

$$\text{Direction of } a\vec{v} = \begin{cases} \text{same as } \vec{v} & \text{if } a > 0 \\ \text{opposite to } \vec{v} & \text{if } a < 0 \\ \text{no direction} & \text{if } a = 0 \\ & (0 \cdot \vec{v} = \vec{0}) \end{cases}$$

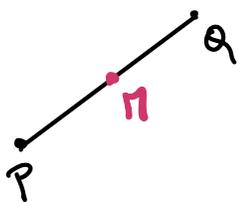
• Basic unit vectors

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad \text{in } \mathbb{R}^2$$

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \text{in } \mathbb{R}^3$$

• Given  $\vec{v} \neq \vec{0}$ , there is a unique unit vector in the direction of  $\vec{v}$ , namely  $\frac{\vec{v}}{\|\vec{v}\|}$

Q Midpoint between 2 points  $P$  &  $Q$  in  $\mathbb{R}^3$ ?



$$P = (p_1, p_2, p_3)$$

$$Q = (q_1, q_2, q_3)$$

$$M = (m_1, m_2, m_3)$$

$M$  has 2 properties

•  $M$  is in the segment joining  $P$  &  $Q$

$$\cdot \|\vec{PM}\| = \|\vec{MQ}\| = \frac{1}{2} \|\vec{PQ}\|$$

$$\vec{PM} = a \vec{PQ} \quad \rightarrow \text{since } a > 0 \quad \& \quad \|\vec{PM}\| = \|a \vec{PQ}\| = |a| \|\vec{PQ}\|$$

(same direction as  $\vec{PQ}$ )

$$\text{hence } a = \frac{1}{2} \quad = a \|\vec{PQ}\| = \frac{1}{2} \|\vec{PQ}\|$$

$$\rightarrow (m_1, m_2, m_3) = (p_1, p_2, p_3) + \frac{1}{2}(q_1 - p_1, q_2 - p_2, q_3 - p_3) = \left(\frac{p_1 + q_1}{2}, \frac{p_2 + q_2}{2}, \frac{p_3 + q_3}{2}\right)$$

### §1. Dot Product:

Recall Given  $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{bmatrix}$ ,  $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}$  in  $\mathbb{R}^m$ , we define the

dot product  $\vec{u} \cdot \vec{v} = \vec{u}^T \vec{v} = u_1 v_1 + u_2 v_2 + \dots + u_m v_m$  (a number!)

Example  $\vec{u} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$   $\vec{v} = \begin{bmatrix} 0 \\ 3 \\ 5 \end{bmatrix}$ ,  $\vec{u} \cdot \vec{v} = 1 \cdot 0 + (-1) \cdot 3 + 1 \cdot 5 = -3 + 5 = 2$

By construction, dot products inherit several properties from matrix addition, scalar multiplication & product. More precisely:

Algebraic properties: Fix  $\vec{u}, \vec{v}, \vec{w}$  vectors in  $\mathbb{R}^n$ ,  $a = \text{scalar}$

- ①  $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$  (not true for general matrices!)
- ② [Distributive]  $(\vec{u} + \vec{v}) \cdot \vec{w} = \vec{u} \cdot \vec{w} + \vec{v} \cdot \vec{w} = \vec{w} \cdot (\vec{u} + \vec{v})$
- ③ [Associative]  $(a\vec{u}) \cdot \vec{v} = a(\vec{u} \cdot \vec{v}) = \vec{u} \cdot (a\vec{v})$
- ④  $\vec{u} \cdot \vec{u} = \|\vec{u}\|^2$

Application:  $\|\vec{u} + \vec{v}\|^2 = ?$  in terms of  $\vec{u}$  &  $\vec{v}$

$$\|\vec{u} + \vec{v}\|^2 = (\vec{u} + \vec{v}) \cdot (\vec{u} + \vec{v}) = \vec{u} \cdot \vec{u} + \vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{u} + \vec{v} \cdot \vec{v}$$

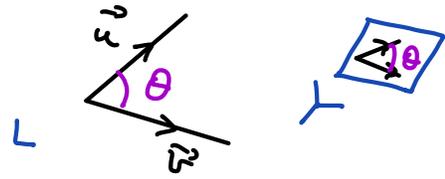
$$\stackrel{\text{Distrib } \textcircled{2}}{=} \|\vec{u}\|^2 + 2\vec{u} \cdot \vec{v} + \|\vec{v}\|^2$$

④

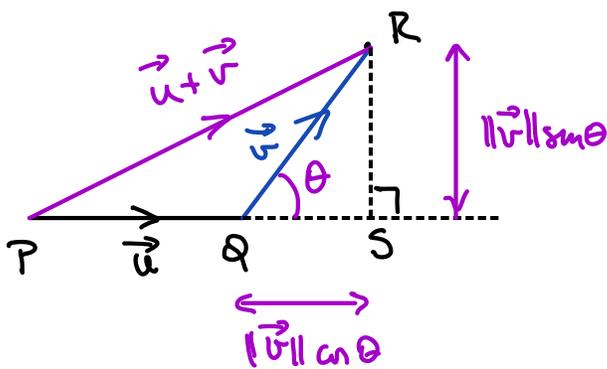
Q: Can we compute  $\vec{u} \cdot \vec{v}$  in  $\mathbb{R}^2$  &  $\mathbb{R}^3$  using Geometry? A: YES

• Geometric formula for  $\vec{u} \cdot \vec{v}$ : If  $\theta = \text{angle between } \vec{u} \text{ \& } \vec{v}$  ( $0 \leq \theta \leq \pi$ )

then  $\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$



Why? We compute  $\|\vec{u} + \vec{v}\|^2$  geometrically and compare it with the formula written in the application above.



$$\begin{aligned} \|\vec{u} + \vec{v}\|^2 &= \|\vec{PR}\|^2 \\ &= \|\vec{PQ}\|^2 + \|\vec{QR}\|^2 \\ &= (\|\vec{u}\| + \|\vec{v}\| \cos \theta)^2 + (\|\vec{v}\| \sin \theta)^2 \\ &= \|\vec{u}\|^2 + \|\vec{v}\|^2 (\underbrace{\cos^2 \theta + \sin^2 \theta}_{=1}) \\ &\quad + 2\|\vec{u}\| \|\vec{v}\| \cos \theta \end{aligned}$$

So  $\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2\|\vec{u}\| \|\vec{v}\| \cos \theta$

But  $\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2 \cdot \vec{u} \cdot \vec{v}$

Conclude:  $\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$

Examples (1) Pick  $\vec{u}, \vec{v}$  of length 3 & 6 respectively with angle  $\theta = 60^\circ$  between them. Find  $\vec{u} \cdot \vec{v}$ .

Soln  $\vec{u} \cdot \vec{v} = \|\vec{u}\| \cdot \|\vec{v}\| \cos 60^\circ = 3 \cdot 6 \cdot \frac{1}{2} = \boxed{9}$

(2) Find the angle between  $\vec{u} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$  &  $\vec{v} = \begin{bmatrix} -1 \\ 1 \\ 5 \end{bmatrix}$

Soln:  $\|\vec{u}\| = \sqrt{2^2 + 1^2} = \sqrt{5}$

$\|\vec{v}\| = \sqrt{1^2 + 1^2 + 5^2} = \sqrt{27}$

$\Rightarrow \cos \theta = \frac{-1}{\sqrt{5} \sqrt{27}} = \frac{-1}{3\sqrt{15}} \Rightarrow \theta \approx 95^\circ$

$\vec{u} \cdot \vec{v} = 2 \cdot (-1) + 1 \cdot 1 + 0 \cdot 5 = -1$

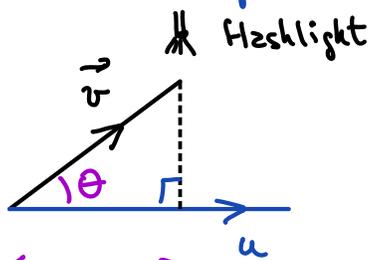
## §2. Orthogonal vectors & projection:

Definition: Two vectors  $\vec{u}$  &  $\vec{v}$  are orthogonal (or perpendicular) if

$$\vec{u} \cdot \vec{v} = 0 \quad (\theta \text{ between them is } 90^\circ \text{ since } \cos \theta = 0)$$

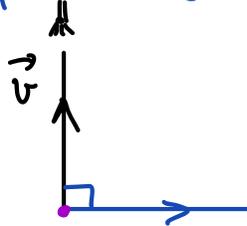
We denote this by  $\vec{u} \perp \vec{v}$ .

- In Physical problems, we sometimes have to compute the "component of  $\vec{v}$  along  $\vec{u}$ " or the "projection of  $\vec{v}$  onto  $\vec{u}$ ". This construction will be later use to build orthogonal bases for  $\mathbb{R}^n$  (Gramm-Schmidt Algorithm)



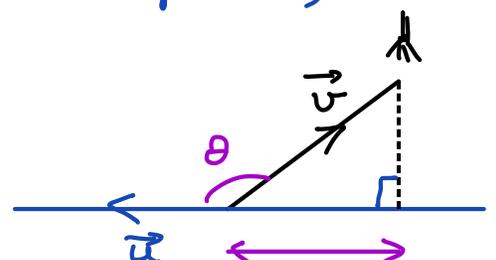
$$\text{comp}_{\vec{u}} \vec{v} = \|\vec{v}\| \cos \theta > 0$$

$0^\circ \leq \theta < 90^\circ$



$$\text{comp}_{\vec{u}} \vec{v} = 0$$

$\theta = 90^\circ$



$$-\text{comp}_{\vec{u}} \vec{v} > 0$$

$90^\circ < \theta \leq 180^\circ$

• Component of  $\vec{v}$  along  $\vec{u}$  =  $\text{comp}_{\vec{u}} \vec{v} = \|\vec{v}\| \cos \theta$

$$= \|\vec{v}\| \left( \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \right)$$

Conclude:

$$\text{comp}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|}$$

(signed length)

• Projection of  $\vec{v}$  onto  $\vec{u}$  = (component of  $\vec{v}$  along  $\vec{u}$ ) · (unit vector along  $\vec{u}$ )

$$= \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|} \cdot \frac{\vec{u}}{\|\vec{u}\|}$$

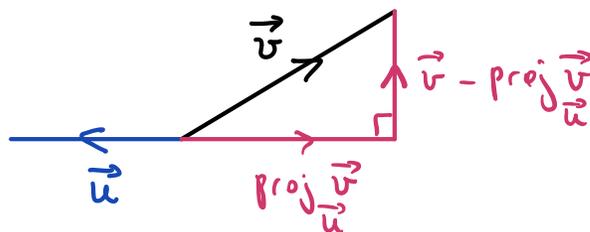
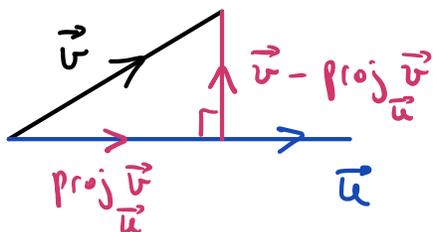
Conclude:

$$\text{proj}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \vec{u}$$

Q: Why is this important? A We can decompose  $\vec{v}$  as a sum  $\vec{w} + \vec{s}$

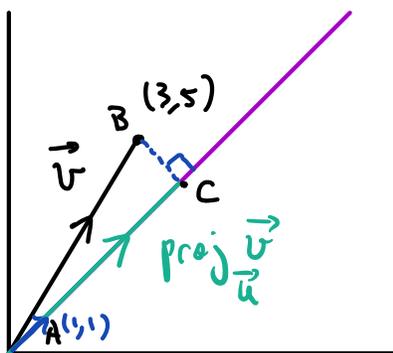
$$\vec{v} = \vec{w} + \vec{s} \quad \text{where } \vec{w} \parallel \vec{u} \text{ \& } \vec{s} \perp \vec{u}$$

$$\vec{v} = \text{proj}_{\vec{u}} \vec{v} + (\vec{v} - \text{proj}_{\vec{u}} \vec{v}) \quad \left( \text{these is the only option for } \vec{w} \text{ \& } \vec{s} \right)$$



Example 1: Fix  $\vec{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$  \&  $\vec{v} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$  Compute the projection of  $\vec{v}$  onto  $\vec{u}$

$$\text{proj}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{1 \cdot 3 + 1 \cdot 5}{1^2 + 1^2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{8}{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$



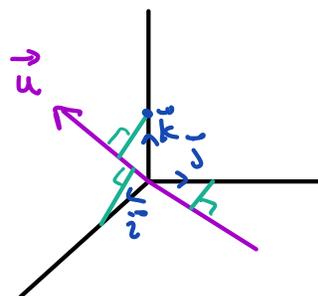
Example 2: Compute the projection of  $\vec{e}_1, \vec{e}_2$  \&  $\vec{e}_3$  along  $\vec{u} = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$

$$\vec{u} \cdot \vec{u} = \left\| \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} \right\|^2 = 1^2 + (-1)^2 + 2^2 = 6, \quad \vec{u} \cdot \vec{e}_1 = 1, \quad \vec{u} \cdot \vec{e}_2 = -1, \quad \vec{u} \cdot \vec{e}_3 = 2$$

$$\text{proj}_{\vec{u}} \vec{e}_1 = \frac{\vec{u} \cdot \vec{e}_1}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{1}{6} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1/6 \\ -1/6 \\ 1/3 \end{bmatrix}$$

$$\text{proj}_{\vec{u}} \vec{e}_2 = \frac{\vec{u} \cdot \vec{e}_2}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{-1}{6} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} -1/6 \\ 1/6 \\ -1/3 \end{bmatrix}$$

$$\text{proj}_{\vec{u}} \vec{e}_3 = \frac{\vec{u} \cdot \vec{e}_3}{\vec{u} \cdot \vec{u}} \vec{u} = \frac{2}{6} \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix} = \begin{bmatrix} 1/3 \\ -1/3 \\ 2/3 \end{bmatrix}$$



### § 3. Cross product in $\mathbb{R}^3$ :

Fix  $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \end{bmatrix}$ ,  $\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$  in  $\mathbb{R}^3$

Definition: The cross product  $\vec{u} \times \vec{v}$  is a vector in  $\mathbb{R}^3$  with

coordinates  $\vec{u} \times \vec{v} = \begin{bmatrix} u_2 v_3 - u_3 v_2 \\ -(u_1 v_3 - u_3 v_1) \\ u_1 v_2 - u_2 v_1 \end{bmatrix}$

Note: Each component is a  $2 \times 2$  determinant [  $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$  ]

$$\det \begin{pmatrix} x & y & z \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{pmatrix} = x \begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix} - y \begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix} + z \begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}$$

*remove row 1 col 1*      *remove row 1 col 2*      *remove row 1 col 3*

So  $\vec{u} \times \vec{v} = \det \begin{bmatrix} \vec{i} & \vec{j} & \vec{k} \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{bmatrix} = \underbrace{\begin{vmatrix} u_2 & u_3 \\ v_2 & v_3 \end{vmatrix}}_{\text{scalar}} \vec{i} - \underbrace{\begin{vmatrix} u_1 & u_3 \\ v_1 & v_3 \end{vmatrix}}_{\text{scalar}} \vec{j} + \underbrace{\begin{vmatrix} u_1 & u_2 \\ v_1 & v_2 \end{vmatrix}}_{\text{scalar}} \vec{k}$

Example  $\vec{u} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$   $\vec{v} = \begin{bmatrix} 2 \\ -1 \\ 2 \end{bmatrix}$

$$\begin{aligned} \vec{u} \times \vec{v} &= \det \begin{pmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 2 & 3 \\ 2 & -1 & 2 \end{pmatrix} = \begin{vmatrix} 2 & 3 \\ -1 & 2 \end{vmatrix} \vec{i} - \begin{vmatrix} 1 & 3 \\ 2 & 2 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & 2 \\ 2 & -1 \end{vmatrix} \vec{k} \\ &= (4+3) \vec{i} - (2-6) \vec{j} + (-1-4) \vec{k} = \begin{bmatrix} 7 \\ 4 \\ -5 \end{bmatrix} \end{aligned}$$

Properties  $\vec{u}, \vec{v}, \vec{w}$  in  $\mathbb{R}^3$ ,  $a, b$  scalars

① [Anticommutative]  $\vec{u} \times \vec{v} = -\vec{v} \times \vec{u}$

In particular,  $\vec{u} \times \vec{u} = -\vec{u} \times \vec{u} = \vec{0}$ .

② [Associative]  $(a\vec{u}) \times (b\vec{v}) = (ab) \vec{u} \times \vec{v}$  , so  $\vec{0} \times \vec{u} = \vec{0}$

③ [Distributive]

$$\vec{u} \times (\vec{v} + \vec{w}) = \vec{u} \times \vec{v} + \vec{u} \times \vec{w}$$

$$(\vec{u} + \vec{v}) \times \vec{w} = \vec{u} \times \vec{w} + \vec{v} \times \vec{w}$$

④  $\vec{u} \cdot (\vec{v} \times \vec{w}) = (\vec{u} \times \vec{v}) \cdot \vec{w}$

Why ①?  $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc = -\det \begin{pmatrix} c & d \\ a & b \end{pmatrix}$

Consequence of ④:  $\vec{u} \perp \vec{u} \times \vec{v}$  &  $\vec{v} \perp \vec{u} \times \vec{v}$

Why?  $\vec{u} \cdot (\vec{u} \times \vec{v}) = (\vec{u} \times \vec{u}) \cdot \vec{v} = \vec{0} \cdot \vec{v} = 0$   
&  $\vec{v} \cdot (\vec{u} \times \vec{v}) = \vec{v} \cdot (-\vec{v} \times \vec{u}) = -\vec{v} \cdot (\vec{v} \times \vec{u}) = 0$   
↓  
same idea