

Lecture XXXII: § 4.1-4.2 Eigenvalues & Eigenvectors  
 § 4.4 The Characteristic Polynomial

§ 1. The Eigenvalue Problem (EV): ("eigen" = "self" in German)

Fix a vector space  $V$  (eg  $V=\mathbb{R}^n$ ) & a linear transformation  $T: V \rightarrow V$ .

Definition: A non-zero vector  $\vec{v}$  in  $V$  is called an eigenvector of  $T$  if  $T(\vec{v}) = \lambda \vec{v}$  for some scalar  $\lambda$  (called the eigenvalue of  $\vec{v}$ )

Ex:  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  with  $T(\vec{x}) = A \vec{x}$  for some  $n \times n$  matrix  $A$   
 $A = [T(\vec{e}_1) \cdots T(\vec{e}_n)]$

EV Problem Find  $\vec{v} \neq \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$  &  $\lambda$  with  $A \vec{v} = \lambda \vec{v}$ .

Equivalent formulation:  $A \vec{v} - \lambda \vec{v} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$

$$(A - \lambda I_n) \vec{v} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \quad \& \quad v \neq \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

EV Problem 2: Find  $\lambda$  number with  $\mathcal{N}(A - \lambda I_n) \neq \left\{ \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \right\}$

Name:  $E_\lambda := \mathcal{N}(A - \lambda I_n) = \text{eigenspace for } \lambda$  ( <sup>$n \times n$</sup>  space of all eigenvectors with eigenvalue  $\lambda$ )

• Experimentally, find  $\lambda$  where  $A - \lambda I_n$  is singular (non-invertible)

Advantage: We can use determinants! [ $\det(C) = 0$  means  $C$  is singular]

Definition: The characteristic polynomial of  $A$  is

$$P_A(t) = \det(A - t I_n) = \det \begin{bmatrix} a_{11}-t & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22}-t & \cdots & \vdots \\ \vdots & & \ddots & \\ a_{n1} & \cdots & \cdots & a_{nn}-t \end{bmatrix} \quad [\text{degree } n \text{ polynomial in } t]$$

Observations (1)  $P_A(t)$  is a degree  $n$  polynomial in  $t$  with leading term  $(-1)^n$

(2) Eigenvalues = roots of  $P_A$   $\rightsquigarrow$  at most  $n$  of them (counted with multiplicity)

$$\underline{\text{Ex:}} \quad A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad \rightsquigarrow P_A(t) = \begin{bmatrix} 1-t & -2 \\ 3 & 4-t \end{bmatrix} = (1-t)(4-t) - 6 = t^2 - 5t + 6 = (t-2)(t-3)$$

### Exercises:

①  $A = \begin{bmatrix} z & 0 \\ 0 & 1 \end{bmatrix}$  Eigenvalues?

$$A \cdot \begin{bmatrix} 1 \\ 0 \end{bmatrix} = z \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \& \quad A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$z \& 1$  are eigenvalues

$$P_A(t) = \det \left( \begin{bmatrix} z-t & 0 \\ 0 & 1-t \end{bmatrix} \right) = (z-t)(1-t) = (-1)^2 t^2 - 3t + z$$

$\hookrightarrow$  upper  $\Delta$

roots:  $z \& 1$   $\rightsquigarrow$  (only eigenvalues)

$$E_1 = \mathcal{W}(A - 1I_2) = \mathcal{W}\left(\begin{bmatrix} z & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = \mathcal{W}\left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}\right) = \text{Sp}\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right)$$

$$E_2 = \mathcal{W}(A - zI_2) = \mathcal{W}\left(\begin{bmatrix} z & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} z & 0 \\ 0 & 2 \end{bmatrix}\right) = \mathcal{W}\left(\begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}\right) = \text{Sp}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right)$$

②  $A = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}$  Eigenvalues = 1 (?)  $\chi_A(t) = \det \left( \begin{bmatrix} 1-t & 1 \\ 0 & 1-t \end{bmatrix} \right)$

So 1 is the only eigenvalue (double root)  $= (1-t)^2$

$$E_1 = \mathcal{W}\left(\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = \mathcal{W}\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right) = \text{Sp}\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) \quad \dim E_1 = 1$$

③  $A = \begin{bmatrix} 5 & -1 \\ 8 & -1 \end{bmatrix}$  Eigenvalues?

$$P_A(t) = \det \left( \begin{bmatrix} 5-t & -1 \\ 8 & -1-t \end{bmatrix} \right) = (5-t)(-1-t) + 8 = t^2 - 4t + 3$$

Roots? Use quadratic formula!  $t^2 + bt + c = 0 \Rightarrow t = \frac{-b \pm \sqrt{b^2 - 4c}}{2}$

$t^2 - 4t + 3 = 0$  has roots  $\frac{-(-4) \pm \sqrt{(-4)^2 - 4 \cdot 3}}{2} = \frac{4 \pm \sqrt{16}}{2} = \frac{4 \pm 2}{2} \begin{cases} 3 \\ 1 \end{cases}$

$\Rightarrow$  2 eigenvalues: 1 & 3 (simple roots)

$$E_1 = \mathcal{W}\left(\begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix}\right) = \text{Sp}\left(\begin{bmatrix} 1 \\ 4 \end{bmatrix}\right) \quad \begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - 2R_1} \begin{bmatrix} 4 & -1 \\ 0 & 0 \end{bmatrix} \quad x_2 = 4x_1$$

$$E_3 = \mathcal{W}\left(\begin{bmatrix} 2 & -1 \\ 8 & -4 \end{bmatrix}\right) = \text{Sp}\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) \quad \begin{bmatrix} 2 & -1 \\ 8 & -4 \end{bmatrix} \xrightarrow{\quad} \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix} \quad x_2 = 2x_1$$

$$\dim E_1 = \dim E_3 = 1$$

Obs:  $B = \left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \end{bmatrix} \right\}$  is a basis for  $\mathbb{R}^2$  & in this basis

$T: \mathbb{R}^2 \xrightarrow{\quad} \mathbb{R}^2$  has matrix  $[T]_{BB} = \begin{bmatrix} 3 & 0 \\ 0 & 1 \end{bmatrix}$  (diagonal)

$\vec{x} \longmapsto A\vec{x}$

$(T(\vec{v}_1) = 3\vec{v}_1 \quad \& \quad T(\vec{v}_2) = \vec{v}_2)$

④ Eigenvalues can be complex numbers (§4.6)

$$\bullet A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \quad \chi_A(t) = \det \begin{pmatrix} -t & 1 \\ -1 & -t \end{pmatrix} = t^2 + 1 \quad \text{has no real roots}$$

$$\text{Over the complex numbers } t = \pm \sqrt{-1} = i$$

$$\bullet A = \begin{bmatrix} z-1 & \\ 1 & z \end{bmatrix} \quad P_A(t) = \det \begin{bmatrix} z-t & -1 \\ 1 & z-t \end{bmatrix} = (z-t)^2 + 1 = t^2 - 4t + 5$$

$$\Rightarrow t^2 - 4t + 5 = 0 \quad \text{has solutions } t = \frac{4 \pm \sqrt{4^2 - 20}}{2} = \frac{4 \pm \sqrt{-4}}{2} = \frac{4 \pm 2i}{2} = 2 \pm i$$

## § 2 Why solve the EV problem?

① Diagonalize linear transformations  $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$  [§4.7]

[Find a basis  $B = \{\vec{v}_1, \dots, \vec{v}_n\}$  of eigenvectors, so  
 $\downarrow$   $\downarrow$  (allowing repetitions)]

$$[T]_{BB} = \begin{bmatrix} \lambda_1 & & 0 \\ 0 & \ddots & \vdots \\ & & \lambda_n \end{bmatrix} \quad \text{diagonal matrix representing } T.$$

(Last example)

② Solving differential equations  $\Rightarrow$  MATH 2415, 2255

(eg:  $T: \mathcal{F} \rightarrow \mathcal{F}$  where  $\mathcal{F}$  = differentiable functions in 1 variable  
 $f \mapsto \frac{df}{dx}$  has eigenvector  $f(x) = e^x$  ( $f' = e^x$ ))

③ Calculating powers of matrices  $A, A^2, A^3, \dots, A^{100}, \dots$

Ex: Fix a graph  $G$ :

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$



$A$  = adjacency matrix  $3 \times 3$

$a_{ij} = \# \text{ edges between } i \text{ & } j$

$$A^2 = \begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \quad (i,j)\text{ entry: paths of length 2 between } i \text{ & } j$$

$\dots A^l = \underbrace{A \cdots A}_{l \text{ terms}}$   $(i,j)$  entry = # of paths of length  $l$  between  $i$  &  $j$

- If  $A$  is diagonal, then  $A^l = \begin{bmatrix} a_{11}^l & & & \\ & a_{22}^l & & \\ & & \ddots & \\ 0 & & & a_{nn}^l \end{bmatrix}$  is easy to do.
- If  $A$  is diagonalizable (meaning  $T(\vec{x}) = A \cdot \vec{x}$  is diagonalizable) we'll see that  $A^l$  is also easy to compute

### § 3. Properties of Eigenvalues:

Properties: Fix an  $n \times n$  matrix  $A$

①  $A$  has at most  $n$  eigenvalues (counted with multiplicity)

Why? eigenvalues = roots of  $P_A(t)$  &  $P_A(t)$  has degree  $n$  in  $t$ .

② If  $\lambda$  is an eigenvalue of  $A$ , then  $\lambda^k$  is an eigenvalue of  $A^k$  ( $\forall k=1, 2, 3, \dots$ )

Why?  $A \vec{v} = \lambda \vec{v}$  implies  $A^2 \vec{v} = A(A \vec{v}) = A \lambda \vec{v} = \lambda A \vec{v} = \lambda \lambda \vec{v} = \lambda^2 \vec{v}$

Similarly  $A^k \vec{v} = A^{k-1}(A \vec{v}) = A^{k-1}(\lambda \vec{v}) = \lambda A^{k-1} \vec{v} = \lambda \lambda^{k-1} \vec{v} = \lambda^k \vec{v}$ .

③ If  $A$  is invertible &  $\lambda$  is an eigenvalue of  $A$ , then  $\lambda \neq 0$  &  $\frac{1}{\lambda}$  is an eigenvalue of  $A^{-1}$ . &  $E_\lambda(A) = E_{\lambda^{-1}}(A^{-1})$

Why? If  $\lambda = 0$  is an eigenvalue then  $A \vec{v} = 0 \vec{v} = \vec{0}$  for some  $\vec{v} \neq \vec{0}$  so  $N(A) \neq \{\vec{0}\}$  meaning  $A$  is singular. This is a contradiction!

Now  $A \vec{v} = \lambda \vec{v}$  for  $\vec{v} \neq \vec{0}$

Multiply by  $A^{-1}$  in the left on both sides:

$$\vec{v} = A^{-1} A \vec{v} = A^{-1} \lambda \vec{v} = \lambda A^{-1} \vec{v}$$

so  $\frac{1}{\lambda} \vec{v} = A^{-1} \vec{v}$  so  $\frac{1}{\lambda}$  is an eigenvalue for  $A^{-1}$ .

This process can be reversed so the eigenvectors are the same!

Thus:  $E_\lambda(A) = E_{\lambda^{-1}}(A^{-1})$ .

④  $A$  &  $A^T$  have the same eigenvectors because  $P_A(t) = P_{A^T}(t)$   
 $(P_A(t) = \det(A - tI_n)) = \det((A - tI_n)^T) = \det(A^T - tI_n) = P_{A^T}(t)$