

Lecture II: §1.1 (cont.) Matrices & §1.2 Echelon form

§1 Matrices:

Recall: $m \times n$ system of linear equations $\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = b_1 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n = b_m \end{cases}$ (*)
 (x_j) unknowns, (a_{ij}) coefficients, (b_i) constant terms

Why? Matrices give a convenient framework to represent & solve linear systems.

Def: An $m \times n$ matrix A is a rectangular array of numbers with m rows & n columns. Write them as:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} = (a_{ij})$$

row # \swarrow
column # \searrow

Eg: $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}$ (2×3 matrix) ; $A = \begin{bmatrix} 1 & 0 \\ 6 & 1 \end{bmatrix}$ (2×2 matrix) $\begin{matrix} m=2 \\ n=2 \end{matrix}$
 "square matrix" $m=n$

§2 Matrix Representation of a Linear System:

equations \rightsquigarrow rows
 unknowns \rightsquigarrow columns
 & constant terms

Def: The coefficient matrix for the system (*) is the $m \times n$ matrix $A = (a_{ij})$

• The augmented matrix is the $m \times (n+1)$ — B , where

$$B = \left[\begin{array}{ccc|c} a_{11} & \dots & a_{1n} & b_1 \\ \vdots & & \vdots & \vdots \\ a_{m1} & \dots & a_{mn} & b_m \end{array} \right] = [A | \underline{b}] \text{ for short}$$

\uparrow col 1 \dots \uparrow col n \uparrow col $n+1$

where $\underline{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$

Example: $\begin{cases} x_1 + 3x_2 - 2x_3 = 4 \\ 4x_1 - 5x_3 = 0 \\ -2x_1 + 6x_2 = 24 \end{cases}$

\rightsquigarrow Align $\begin{cases} \underline{1} x_1 + \underline{3} x_2 + \underline{(-2)} x_3 = 4 \\ \underline{4} x_1 + \underline{0} x_2 + \underline{-5} x_3 = 0 \\ \underline{(-2)} x_1 + \underline{6} x_2 + \underline{0} x_3 = 24 \end{cases}$
 (empty boxes get value = 0)

$\rightsquigarrow B = \begin{bmatrix} 1 & 3 & -2 & 4 \\ 4 & 0 & -5 & 0 \\ -2 & 6 & 0 & 24 \end{bmatrix}$

§ 3 Elementary operations:

- 2 Steps to solve a system: (1) Reduce the system (i.e. eliminate variables)
 (2) Describe the solution set.

→ Want to perform operations on the system to simplify it but keeping the same solution set

Def: 2 systems in n unknowns are equivalent if they have the same solution set.

Theorem 1: The following elementary operations give equivalent systems:

- (1) interchange 2 equations (E_i & E_j , write $E_i \leftrightarrow E_j$)
- (2) multiply an equation by a nonzero number & replace it
 ($E_i, k \neq 0$, write $E_i \rightarrow kE_i$) ("reverse" it $kE_i \rightarrow \frac{1}{k}E_i$)
- (3) replace an equation by adding to it a constant multiple of a different equation
 ($E_i \rightarrow E_i + kE_j$ for $i \neq j, k$ any number)
("reverse" it $(E_i + kE_j)$)

Example:

$$\begin{cases} x_1 + x_2 = 4 \\ -x_1 + 3x_2 = 9 \end{cases} \xrightarrow{E_1 \rightarrow E_1 + E_2} \begin{cases} 4x_2 = 13 \\ -x_1 + 3x_2 = 9 \end{cases} \xrightarrow{E_1 \rightarrow \frac{1}{4}E_1} \begin{cases} x_2 = \frac{13}{4} \\ -x_1 + 3x_2 = 9 \end{cases}$$

$$\xrightarrow{E_2 \rightarrow E_2 - 3E_1} \begin{cases} x_2 = \frac{13}{4} \\ -x_1 = 9 - 3 \cdot \frac{13}{4} = -\frac{3}{4} \end{cases} \xrightarrow{E_2 \rightarrow (-1)E_2} \begin{cases} x_2 = \frac{13}{4} \\ x_1 = \frac{3}{4} \end{cases} \xrightarrow{E_1 \leftrightarrow E_2} \begin{cases} x_1 = \frac{3}{4} \\ x_2 = \frac{13}{4} \end{cases}$$

$E_2 = (E_1 + kE_j) + (-k)E_j$

By Thm 1, the original system has a unique sol = $(\frac{3}{4}, \frac{13}{4})$ EASY TO SOLVE!
(only 1 solution)

§ 4: On the matrix side = Row operations

Def: There are 3 elementary row operations:

- (1) interchange 2 rows ($R_i \leftrightarrow R_j$)
- (2) replace a row by a non-zero scalar multiple of it ($R_i \rightarrow kR_i$)
 for $k \neq 0$
- (3) replace a row by adding to it a constant multiple of a different row
 ($R_i \rightarrow R_i + kR_j$)
 for $i \neq j$

Def: Two matrices are row equivalent if we can obtain one from the other by a sequence of elementary row operations.

Note: If these matrices are the augmented matrices of two $(m \times n)$ lin systems, then the systems would be equivalent because elementary row operations mimic elementary operations on systems.

GOAL Start from an augmented matrix B, do elem. row operations to get rows with more zeros on a row equiv matrix C, then C is simpler.

Algorithm (1) from the linear system write the augmented matrix B
 (2) do elem. row operations to obtain a simpler matrix C
 (3) solve the system that C represent (equivalent to the original one!)

Example:
$$\begin{cases} x_2 + x_3 - x_4 = 3 \\ x_1 + 2x_2 - x_3 + x_4 = 1 \\ -x_1 + x_2 + 7x_3 - x_4 = 0 \end{cases} \implies (1) B = \left[\begin{array}{cccc|c} 0 & 1 & 1 & -1 & 3 \\ 1 & 2 & -1 & 1 & 1 \\ -1 & 1 & 7 & -1 & 0 \end{array} \right]$$

(2) Row Operations on B: goal = have exactly one 1 in a column & all other entries = 0 in that column

$$B \xrightarrow{E_3 \rightarrow E_3 + E_2} \left[\begin{array}{cccc|c} 0 & 1 & 1 & -1 & 3 \\ 1 & 2 & -1 & 1 & 1 \\ 0 & 3 & 6 & 0 & 1 \end{array} \right] \xrightarrow{E_1 \rightarrow E_2} \left[\begin{array}{cccc|c} 1 & 2 & -1 & 1 & 1 \\ 0 & 1 & 1 & -1 & 3 \\ 0 & 3 & 6 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{E_3 \rightarrow E_3 - (3)E_2} \left[\begin{array}{cccc|c} 1 & 2 & -1 & 1 & 1 \\ 0 & 1 & 1 & -1 & 3 \\ 0 & 0 & 3 & 3 & -8 \end{array} \right] \xrightarrow{E_3 \rightarrow \frac{1}{3}E_3} \left[\begin{array}{cccc|c} 1 & 2 & -1 & 1 & 1 \\ 0 & 1 & 1 & -1 & 3 \\ 0 & 0 & 1 & 1 & -8/3 \end{array} \right]$$

ideal column format, move to the right to repair the next one using 2^{nd} & 3^{rd} rows

Use 1's to get zeros above them:

$$\xrightarrow{E_2 \rightarrow E_2 - E_3} \left[\begin{array}{cccc|c} 1 & 2 & -1 & 1 & 1 \\ 0 & 1 & 0 & -2 & 17/3 \\ 0 & 0 & 1 & 1 & -8/3 \end{array} \right] \xrightarrow{E_1 \rightarrow E_1 + E_3} \left[\begin{array}{cccc|c} 1 & 2 & 0 & 2 & -5/3 \\ 0 & 1 & 0 & -2 & 17/3 \\ 0 & 0 & 1 & 1 & -8/3 \end{array} \right]$$

column is fixed

$$\xrightarrow{E_1 \rightarrow E_1 - 2E_2} \left[\begin{array}{cccc|c} 1 & 0 & 0 & 6 & -13 \\ 0 & 1 & 0 & -2 & 17/3 \\ 0 & 0 & 1 & 1 & -8/3 \end{array} \right] = C \implies \begin{cases} x_1 + 6x_4 = -13 \\ x_2 - 2x_4 = 17/3 \\ x_3 + x_4 = -8/3 \end{cases}$$

(Reduced Echelon form)

dependent variables *independent variable*

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\Rightarrow Solutions: $(*) \begin{cases} x_1 = -13 - 6x_4 \\ x_2 = \frac{17}{3} + 2x_4 \\ x_3 = -\frac{8}{3} - x_4 \end{cases}$ (general form)
 \rightarrow ANY choice of x_4

How many solutions? $(x_1, x_2, x_3, x_4) = (-13 - 6x_4, \frac{17}{3} + 2x_4, -\frac{8}{3} - x_4, x_4)$

Check that $(*)$ are solutions of the original system: so infinitely many!

(Eq 1) $3 \stackrel{?}{=} x_2 + x_3 - x_4 = \frac{17}{3} + 2x_4 + (-\frac{8}{3} - x_4) - x_4 = \frac{9}{3} = 3 \checkmark$

(Eq 2) $1 \stackrel{?}{=} x_1 + 2x_2 - x_3 + x_4 = (-13 - 6x_4) + 2(\frac{17}{3} + 2x_4) - (-\frac{8}{3} - x_4) + x_4 = 1 + \underbrace{(-6 + 4 + 1 + 1)}_{=0}x_4 = 1 \checkmark$

Check that (Eq 3) is also satisfied!

Next time: Echelon form, reduced echelon form & Gauss-Jordan elimination algorithm (to put a matrix in echelon form).