

Lecture VI: §1.5 (cont.) Matrix multiplication, §1.6 Algebraic properties

Recall (Last time). defined addition, scalar multiplication on matrices (operate entry by entry)

- defined dot product on vectors in  $\mathbb{R}^n = (\underline{n} \times 1)$  matrices
- used this to write the general solution to a system of equations.

TODAY: Last operation (multiplication) & algebraic properties of  $\begin{pmatrix} m \times n \\ \text{all} \end{pmatrix}$  the operations on matrices

§1. Matrix multiplication of a matrix  $A$  and a vector  $x$

• Only defined if  $A$  has size  $m \times n$  &  $x$  is in  $\mathbb{R}^n$

• If so,  $Ax$  is a vector in  $\mathbb{R}^m$  and

$$(Ax)_{i1} = a_{i1}x_1 + a_{i2}x_2 + \dots + a_{in}x_n = \sum_{j=1}^n a_{ij}x_j \quad \text{for } 1 \leq i \leq m$$

$Ax = x_1(\text{col}_1 A) + x_2(\text{col}_2 A) + \dots + x_n(\text{col}_n A)$

Why? Using this operation, we can write a system with augmented matrix  $[A|b]$  as  $Ax = b$  for  $A$  an  $m \times n$  matrix,  $b$  in  $\mathbb{R}^m$ ,  $x$  in  $\mathbb{R}^n$

Example 1:  $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -1 \end{bmatrix}$ ,  $y = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \implies Ay = \begin{bmatrix} 1 \cdot 1 + 2 \cdot (-1) + 3 \cdot 0 \\ 0 \cdot 1 + 1 \cdot (-1) + (-1) \cdot 0 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$

In particular  $\begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$  is a solution of the system  $\begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$ .

Example 2:  $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -1 \end{bmatrix}$ ,  $y = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \in \mathbb{R}^2 \implies Ay$  not defined!

Example 3: Solve  $a \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} + b \begin{bmatrix} 4 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} -1/3 \\ -2/3 \\ -1 \end{bmatrix}$  for  $a, b$  in  $\mathbb{R}$ .

By definition (LHS) =  $\begin{bmatrix} 1 & 4 \\ 2 & 0 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$  so we have a system  $\left[ \begin{array}{cc|c} 1 & 4 & -1/3 \\ 2 & 0 & -2/3 \\ 2 & -1 & -1 \end{array} \right]$

Use Gauss-Jordan elimination:

$$\left[ \begin{array}{cc|c} 1 & 4 & -1/3 \\ 2 & 0 & -2/3 \\ 2 & -1 & -1 \end{array} \right] \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 2R_1}} \left[ \begin{array}{cc|c} 1 & 4 & -1/3 \\ 0 & -8 & -8/3 \\ 0 & -9 & -5/3 \end{array} \right] \xrightarrow{\substack{R_2 \rightarrow R_2 / -8 \\ R_3 \rightarrow R_3 / -3}} \left[ \begin{array}{cc|c} 1 & 4 & -1/3 \\ 0 & 1 & 1/3 \\ 0 & 1 & 1/3 \end{array} \right] \xrightarrow{\substack{R_3 \rightarrow R_3 - R_2 \\ R_1 \rightarrow R_1 - 4R_2}} \left[ \begin{array}{cc|c} 1 & 0 & -1/3 \\ 0 & 1 & 1/3 \\ 0 & 0 & 0 \end{array} \right]$$

so  $a = -1/3$   
 $b = 1/3$ .

§2. Matrix multiplication of 2 matrices:

• Only defined for  $A$  of size  $m \times n$  &  $B$  of size  $n \times s$ .  $A = (a_{ij}), B = (b_{kj})$

• In so,  $AB$  is an  $(m \times s)$  matrix and  $\underbrace{j^{\text{th}} \text{ column of } AB}_{\text{vector in } \mathbb{R}^m} = A \underbrace{(j^{\text{th}} \text{ column of } B)}_{\text{vector in } \mathbb{R}^n}$

More precisely:

$$(AB)_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj} = \sum_{k=1}^n a_{ik}b_{kj} \quad \text{for } 1 \leq i \leq m, 1 \leq j \leq s.$$

So to compute  $(i,j)$ -entry of  $AB = (\text{row}_i(A) \cdot \text{col}_j(B))$

$$i \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \boxed{a_{i1}} & \dots & \boxed{a_{in}} \\ \vdots & & \vdots \\ a_{m1} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} b_{11} & \dots & \boxed{b_{1j}} & \dots & b_{1n} \\ b_{21} & & \boxed{b_{2j}} & & b_{2n} \\ \vdots & & \vdots & & \vdots \\ b_{m1} & & \boxed{b_{mj}} & & b_{mn} \end{bmatrix} = \begin{bmatrix} c_{11} & \dots & c_{1j} & \dots & c_{1n} \\ \vdots & & \boxed{c_{ij}} & & \vdots \\ \vdots & & \vdots & & \vdots \\ c_{m1} & \dots & c_{mj} & \dots & c_{mn} \end{bmatrix}$$

Example 4  $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & -1 \end{bmatrix}_{2 \times 3}$   $B = \begin{bmatrix} 1 & 0 & 1 & 0 \\ -1 & 4 & 1 & 0 \\ 0 & 5 & 1 & 0 \end{bmatrix}_{3 \times 4}$

$\Rightarrow AB = \begin{bmatrix} -1 & 2 \cdot 4 + 3 \cdot 5 & 1 + 2 + 3 & 2 \cdot 0 \\ -1 & 1 \cdot 4 + (-1) \cdot 5 & 1 - 1 & 1 \cdot 0 \end{bmatrix}_{2 \times 4}$

$\xrightarrow{\text{ex 1}} = \begin{bmatrix} -1 & 23 & 6 & 2 \\ -1 & -1 & 0 & 1 \end{bmatrix}$

$BA$  not defined (cols  $B \neq$  rows  $A$ )

Example 5: Solve  $\begin{cases} x_1 = 3y_1 - y_2 + y_3 \\ x_2 = -3y_1 + 5y_2 \end{cases}$  &  $\begin{cases} y_1 = -4z_1 + z_3 \\ y_2 = z_2 - z_3 \\ y_3 = 0 \end{cases}$ , i.e. write  $x$  in terms of  $z$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 & -1 & 1 \\ -3 & 5 & 0 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} \quad \& \quad \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} -4 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix}$$

So  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 3 & -1 & 1 \\ -3 & 5 & 0 \end{bmatrix} \begin{bmatrix} -4 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} = \begin{bmatrix} 3(-4) + 0 & -1 & 3 + 1 \\ (-3)(-4) + 0 & 5 & -3 - 5 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix}$

$$= \begin{bmatrix} -12 & -1 & 4 \\ 12 & 5 & -8 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix}$$

Conclusion:  $\begin{cases} x_1 = -12z_1 - z_2 + 4z_3 \\ x_2 = 12z_1 + 5z_2 - 8z_3 \end{cases}$

Example: Given  $A = \begin{bmatrix} -1 & 2 & -3 \\ 1 & 0 & 4 \\ 5 & 1 & 2 \end{bmatrix}$ , solve  $Ax = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$  &  $Ay = \begin{bmatrix} 0 \\ 1 \\ 4 \end{bmatrix}$

Solution:  $A \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$   $\Rightarrow$  Use Gauss-Jordan on  $\left[ \begin{array}{ccc|c} -1 & 2 & -3 & 1 \\ 1 & 0 & 4 & 2 \\ 5 & 1 & 2 & 3 \end{array} \right]$

$$\xrightarrow{\begin{matrix} R_1 \rightarrow R_1 + R_2 \\ R_3 \rightarrow R_3 - 5R_2 \end{matrix}} \left[ \begin{array}{ccc|c} 0 & 2 & -35 & 3 \\ 1 & 0 & 4 & 2 \\ 0 & 1 & -18 & -7 \end{array} \right] \xrightarrow{\begin{matrix} R_1 \leftrightarrow R_2 \\ R_3 \leftrightarrow R_2 \end{matrix}} \left[ \begin{array}{ccc|c} 1 & 0 & 4 & 2 \\ 0 & 1 & -18 & -7 \\ 0 & 2 & -35 & 3 \end{array} \right] \xrightarrow{R_3 \rightarrow R_3 - 2R_2} \left[ \begin{array}{ccc|c} 1 & 0 & 4 & 2 \\ 0 & 1 & -18 & -7 \\ 0 & 0 & 1 & 17 \end{array} \right]$$

$$\xrightarrow{\begin{matrix} R_2 \rightarrow R_2 + 18R_3 \\ R_1 \rightarrow R_1 - 4R_3 \end{matrix}} \left[ \begin{array}{ccc|c} 1 & 0 & 0 & -66 \\ 0 & 1 & 0 & 299 \\ 0 & 0 & 1 & 17 \end{array} \right] \quad \text{so } x = \begin{bmatrix} -66 \\ 299 \\ 17 \end{bmatrix} \quad \& \quad y = \begin{bmatrix} -11 \\ 53 \\ 3 \end{bmatrix}$$

### §3 Identity matrix:

Def For any  $n$  in  $\mathbb{N}$ , the identity matrix of size  $n \times n$  has 1's in the diagonal & 0's elsewhere:  $I_n = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & & \\ \vdots & & \ddots & \\ 0 & & & 1 \end{bmatrix}$   $\rightarrow$  diagonal. Eg  $I_2 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ ,  $I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ , etc

### §4 Algebraic properties of matrix operations

Theorem 1:  $A, B, C$  ( $m \times n$ ) matrices. Then:

- (1)  $A + B = B + A$  [Commutative]
- (2)  $(A + B) + C = A + (B + C)$  [Associative]
- (3) There exists a zero matrix  $O$  of size  $m \times n$  with  $A + O = O + A = A$  for any  $A$ .  
 $[O_{ij} = 0 \text{ for all } 1 \leq i \leq m, 1 \leq j \leq n]$
- (4) [Inverses] given  $A$ , there is an ( $m \times n$ ) matrix  $P$  with  $A + P = P + A = O$   
 $[P_{ij} = -(A_{ij}) \text{ for all } 1 \leq i \leq m, 1 \leq j \leq n]$

Justification: Addition is done on each entry separately & addition in  $\mathbb{R}$  satisfies (1) - (4).

Theorem 2:  $A$  of size  $m \times n$ ,  $B$  of size  $n \times s$ ,  $C$  of size  $s \times q$

- (1)  $(AB)C = A(BC)$  [Associative]
- (2)  $\alpha, \beta$  scalars in  $\mathbb{R}$   $\alpha(\beta A) = (\alpha\beta)A$ .
- (3)  $\alpha(AB) = (\alpha A)B = A(\alpha B)$ .
- (4)  $I_n$  = identity matrix of size  $n \times n$   
 $I_m$  = identity matrix of size  $m \times m$   
 Then:  $A = I_m A = A I_n$

Proof: Use the definitions! In all 3 cases all matrices have the same size, so the identities will follow if we show all entries agree.

$$(1) (AB)_{ij} = \sum_{k=1}^n A_{ik} B_{kj} \Rightarrow ((AB)C)_{il} = \sum_{j=1}^s (AB)_{ij} C_{jl} = \sum_{j=1}^s \sum_{k=1}^n A_{ik} B_{kj} C_{jl} = \sum_{k=1}^n \sum_{j=1}^s A_{ik} B_{kj} C_{jl} = \sum_{k=1}^n A_{ik} (\sum_{j=1}^s B_{kj} C_{jl}) = A_{ik} (BC)_{kl} = (A(BC))_{il}$$

↑ exchange sums

$$(2) (\alpha(\beta A))_{ij} = \alpha(\beta A)_{ij} = \alpha\beta A_{ij} = (\alpha\beta A)_{ij} \quad \square$$

$$(3) (\alpha(AB))_{ij} = \alpha(AB)_{ij} = \alpha \sum_{k=1}^n A_{ik} B_{kj} = \sum_{k=1}^n A_{ik} \alpha B_{kj} = (A(\alpha B))_{ij}$$

Theorem 3: Relate + & multiplication

- (1)  $A, B$  of size  $m \times n$ ,  $C$  of size  $(n \times p)$ , then  $(A+B)C = AC + BC$
- (2)  $A$  of size  $m \times n$ ,  $B, C$  of size  $(n \times p)$ , then  $A(B+C) = AB + AC$
- (3)  $\alpha, \beta$  scalars,  $A$  of size  $m \times n$ , then  $(\alpha+\beta)A = \alpha A + \beta A$
- (4)  $\alpha$  scalar,  $A, B$  of size  $m \times n$ , then  $\alpha(A+B) = \alpha A + \alpha B$ .

Proof: Use the definitions! The matrices on each side of  $=$  has the same size, so we need to compare the entries of each side to show the desired equalities.

$$(1) ((A+B)C)_{ij} = \sum_{k=1}^n (A+B)_{ik} C_{kj} = \sum_{k=1}^n (A_{ik} + B_{ik}) C_{kj} = \sum_{k=1}^n A_{ik} C_{kj} + \sum_{k=1}^n B_{ik} C_{kj} \\ = \sum_{k=1}^n A_{ik} C_{kj} + \sum_{k=1}^n B_{ik} C_{kj} = (AC)_{ij} + (BC)_{ij} = (AC + BC)_{ij} \quad \square$$

↑  
word sum

$$(2) (A(B+C))_{ij} = \sum_{k=1}^n A_{ik} (B+C)_{kj} = \sum_{k=1}^n A_{ik} (B_{kj} + C_{kj}) = \sum_{k=1}^n A_{ik} B_{kj} + \sum_{k=1}^n A_{ik} C_{kj} \\ = \sum_{k=1}^n A_{ik} B_{kj} + \sum_{k=1}^n A_{ik} C_{kj} = (AB)_{ij} + (AC)_{ij} = (AB + AC)_{ij} \quad \square$$

↑  
word sum

$$(3) ((\alpha + \beta)A)_{ij} = (\alpha + \beta) A_{ij} = \alpha A_{ij} + \beta A_{ij} = (\alpha A)_{ij} + (\beta A)_{ij} = (\alpha A + \beta A)_{ij} \quad \square$$

$$(4) (\alpha(A+B))_{ij} = \alpha(A+B)_{ij} = \alpha(A_{ij} + B_{ij}) = \alpha A_{ij} + \alpha B_{ij} = (\alpha A)_{ij} + (\alpha B)_{ij} \\ = (\alpha A + \alpha B)_{ij} \quad \square$$

### §5 The transpose of a matrix:

Idea: interchange rows & columns of A

Def: Given A of size  $m \times n$ , the transpose of A is a matrix  $A^T$  of size  $n \times m$

with  $(A^T)_{ij} = A_{ji}$  for  $\begin{matrix} 1 \leq i \leq n \\ 1 \leq j \leq m \end{matrix}$

Example:  $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \implies A^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$

Def: A is symmetric if  $A^T = A$  (in particular  $m = n$ , A is a square matrix)

Theorem 4: A, B of size  $m \times n$ , C of size  $n \times p$ :

$$(1) (A+B)^T = A^T + B^T$$

$$(2) (AC)^T = C^T A^T$$

$$(3) (A^T)^T = A$$

Proof: As usual both matrices in each identity have the same size, so need to compare the entries on each side:

$$(1) ((A+B)^T)_{ij} = (A+B)_{ji} = A_{ji} + B_{ji} = (A^T)_{ij} + (B^T)_{ij} = (A^T + B^T)_{ij}$$

$$(2) (AC)^T_{ij} = (AC)_{ji} = \sum_{k=1}^n A_{jk} C_{ki} = \sum_{k=1}^n (A^T)_{kj} (C^T)_{ik} = \sum_{k=1}^n (C^T)_{ik} (A^T)_{kj} \\ = (C^T A^T)_{ij} \quad \square$$

$$(3) (A^T)^T_{ij} = (A^T)_{ji} = A_{ij} \quad \square$$

Property: If A has size  $n \times n$ , then  $AA^T$  is a symmetric matrix of size  $n \times n$

PF/  $AA^T$  exists and has size  $n \times n$ .  $(AA^T)^T \stackrel{(2)}{=} (A^T)^T A^T \stackrel{(3)}{=} AA^T \quad \square$

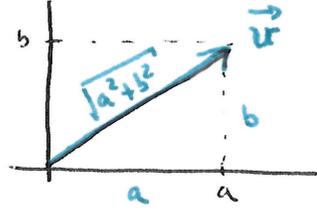
# §6 Scalar products and Vector Norms

Recall:  $u, v$  in  $\mathbb{R}^n$   $u \cdot v = u_1 v_1 + \dots + u_n v_n = \sum u_i v_i$

Better way  $u = \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix}, v = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}$   $\implies u \cdot v = \underbrace{u^T}_{1 \times n} \underbrace{v}_{n \times 1}$  is a  $1 \times 1$  matrix so a number in  $\mathbb{R}$

From Calculus III: Norm of a vector ( $v$ ) =  $\|v\| = \sqrt{v \cdot v} = \sqrt{v^T v}$

In  $\mathbb{R}^2$ :



$$\vec{v} \cdot \vec{v} = (a, b) \cdot (a, b) = a^2 + b^2$$

Def:  $\|v\| = \sqrt{v_1^2 + \dots + v_n^2} = \sqrt{v^T v}$  is the Euclidean length or Euclidean norm in  $\mathbb{R}^n$