

Lecture XVI: § 3.4 (cont.) Bases for Subspaces, § 3.5 Dimension

Recall: Given a nonzero subspace W of \mathbb{R}^n a set $B = \{v_1, \dots, v_d\}$ is a basis for W if (i) B spans W (every v in W is a linear combination of v_1, \dots, v_d).
 (ii) B is l.i.

Then: Every v in W has a unique representation in terms of B , that is (basis)

$$v = \alpha_1 v_1 + \dots + \alpha_d v_d$$

& $(\alpha_1, \dots, \alpha_d)$ are unique, we call them the coordinates of v with respect to the basis B .

Eg: For \mathbb{R}^n ; $\{e_1, \dots, e_n\}$ is the (canonical) basis for \mathbb{R}^n &

$$\begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 e_1 + \dots + x_n e_n$$

so the usual words are the words w.r.t. the canonical basis.

§: How to find a basis from a spanning set $\{w_1, \dots, w_r\}$?

METHOD 1: Write $W = \mathcal{R}(A)$ for $A = [w_1 \dots w_r]$ of size $n \times r$.
 ↪ range

Step 1: Find dependence relations among the r -vectors & remove one per dependence relation.

For this $A \sim B$ with B in red. echelon form.
 ↪ row equiv

Step 2: Basis = $\{w_i\}$'s indexed by DEPENDENT variables in $\mathcal{N}(A)$.

Example 1: $W = \text{Sp} \left(\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \\ 5 \end{bmatrix}, \begin{bmatrix} 3 \\ 5 \\ 6 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ -4 \end{bmatrix} \right)$ Dependencies = solns to $Ax=0$

$$A = \begin{bmatrix} 1 & 2 & 3 & -1 \\ 2 & 3 & 5 & -1 \\ 1 & 5 & 6 & -4 \end{bmatrix} \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 + R_1}} \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & -1 & -1 & 1 \\ 0 & 3 & 3 & -3 \end{bmatrix} \xrightarrow{\substack{R_1 \rightarrow -R_1 \\ R_3 \rightarrow R_3 - 3R_2}} \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\xrightarrow{R_1 \rightarrow R_1 - 2R_2} \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix} = B$$

↑ ↑
dependent

Solns to $Ax=0$ are soln to $Bx=0$

$$\begin{cases} x_1 + x_3 + x_4 = 0 & x_1 = -x_3 - x_4 \\ x_2 + x_3 - x_4 = 0 & x_2 = -x_3 + x_4 \end{cases}$$

so general soln $\underline{x} = x_3 \begin{bmatrix} -1 \\ -1 \\ 1 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$ for any x_3, x_4 .

This means: $-v_1 - v_2 + v_3 = 0$ & $-v_1 + v_2 + v_4 = 0$ are the dependency relations

So we get $w_3 = v_1 + v_2$ $\implies W = \text{Sp}(v_1, v_2)$ & $\{v_1, v_2\}$ is l.i. (here no reln!)
 $v_4 = v_1 - v_2$
Note: x_1, x_2 were the dependent variables! Basis = $\{v_1, v_2\}$.

METHOD 2: Write $W = \text{RowSp}(A)$ for $A = \begin{bmatrix} w_1^T \\ \vdots \\ w_r^T \end{bmatrix}$ of size $n \times r$.

Step 1 Find $A \sim B$ in (R)E.F. (row equiv)

Step 2 Basis of $A = \{\text{nonzero rows of } B\}$.

Notes: The set just has no relation to $\{w, \dots, w_r\}$.

- This works since $\text{RowSp}(A) = \text{RowSp}(B)$ (Then from Lecture XIV)

Example (revisited): W as in Example 1

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 5 \\ 3 & 5 & 6 \\ -1 & -1 & -4 \end{bmatrix} \xrightarrow{\substack{R_2 \rightarrow R_2 - 2R_1 \\ R_3 \rightarrow R_3 - 3R_1 \\ R_4 \rightarrow R_4 + R_1}} \begin{bmatrix} 1 & 2 & 1 \\ 0 & -1 & 3 \\ 0 & -1 & 3 \\ 0 & 1 & -3 \end{bmatrix} \xrightarrow{\substack{R_3 \rightarrow R_3 - R_2 \\ R_4 \rightarrow R_4 + R_2 \\ R_2 \rightarrow -R_2}} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \left. \begin{array}{l} \text{nonzero rows} \\ \text{Basis} = \left\{ \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ -3 \end{bmatrix} \right\} \end{array} \right\}$$

Can take B to be in REF $B \sim \begin{bmatrix} 1 & 0 & 7 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ Basis = $\left\{ \begin{bmatrix} 1 \\ 0 \\ 7 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -3 \end{bmatrix} \right\}$

52. Dimension:

In the examples above, we see that the bases constructed here the same size!

Def The dimension of a subspace W of \mathbb{R}^n is the number of vectors in a basis B of W .

Obs: If $W = \{0\}$, then W has no basis because $\{0\}$ is l.d. so the dim = 0

Note: $\dim \mathbb{R}^n = n$ for any $n \geq 1$ ($\{e_1, \dots, e_n\}$ is a basis)

Q: Why do all basis of W have the same number of vectors?

Theorem 1: Let W be a nonzero subspace of \mathbb{R}^n & $S = \{w_1, \dots, w_p\}$ a spanning set for W . Then, any set with $p+1$ or more elements in W is linearly dependent.

Pf/ Pick v_1, \dots, v_m in W with $m \geq p+1$ & write each one as a lin comb of S .

$$\begin{cases} v_1 = a_{11}w_1 + \dots + a_{p1}w_p \\ \vdots \\ v_m = a_{1m}w_1 + \dots + a_{pm}w_p \end{cases}$$

Want to find a nontrivial solution to $\alpha_1 v_1 + \dots + \alpha_m v_m = 0$.

Rephrase it in terms of (a_{ij}) & $\{w_1, \dots, w_p\}$:

$$\text{Since } \underbrace{\begin{bmatrix} v_1 & \dots & v_m \end{bmatrix}}_{\text{size } n \times m} = \underbrace{\begin{bmatrix} w_1 & \dots & w_p \end{bmatrix}}_{\text{size } n \times p} \underbrace{\begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & & \vdots \\ a_{p1} & \dots & a_{pm} \end{bmatrix}}_{\text{size } p \times m}$$

$$\text{Then } \vec{0} \stackrel{?}{=} \begin{bmatrix} v_1 & \dots & v_m \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix} = \begin{bmatrix} w_1 & \dots & w_p \end{bmatrix} \underbrace{\begin{bmatrix} a_{11} & \dots & a_{1m} \\ \vdots & & \vdots \\ a_{p1} & \dots & a_{pm} \end{bmatrix}}_A \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix}$$

The columns of A are $m > p$ vectors in \mathbb{R}^p so they are l.d. In particular A is singular & we can find $\begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix}$ nonzero with $A \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix} = \vec{0}$ in \mathbb{R}^p .
 then this $\begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_m \end{bmatrix}$ gives a nontrivial relation among v_1, \dots, v_m so these vectors are l.d. \square . Lecture VII (Thm 1)

Corollary: If \mathbb{W} has a basis B with p elements, any basis of \mathbb{W} must have p elements.
 Pf/ If we pick another basis B' since it's l.i it has $\leq p$ elements. If it had less, then B would be l.d. (it has more elements than B'). But this can't happen if B is a basis. So B' has also p elements. \square .

Lecture VII (Thm 1): A set of $m > p$ vectors in \mathbb{R}^p is l.d.

Similar situation happens for a general subspace of $\dim = p$.

Thm 2: Given a nonzero subspace \mathbb{W} of \mathbb{R}^n of $\dim \mathbb{W} = p$, we have:

- (1) A set of $p+1$ or more vectors in \mathbb{W} is linearly dependent
- (2) Any set of $p-1$ or fewer vectors in \mathbb{W} can't span \mathbb{W} .
- (3) Any set of p linearly independent vectors in \mathbb{W} is a basis for \mathbb{W}
- (4) Any set of p vectors in \mathbb{W} that spans \mathbb{W} is a basis for \mathbb{W} .

Application: See next page

Pf/ (1) Follows from Thm 1.

(2) If a set like this spanned, then a basis with $p > \text{size}(S)$ elements would be l.d (by Thm 1) This can't happen!

(3) If it were not a spanning set, we could add a vector v to it and remain l.i, so we would have a set contradicting (1).

(4) If it weren't l.i, we could remove one or more vectors and still span \mathbb{W} . Therefore $\dim \mathbb{W} < p$, contradicting our original assumption.

§ 3. The Rank of a matrix:

A matrix of size $m \times n$ \rightsquigarrow $\text{Null}(A)$ subspace of \mathbb{R}^n $\dim = \text{nullity of } A$
 \rightsquigarrow $\text{R}(A)$ subspace of \mathbb{R}^m $\dim = \text{rank}(A)$
 \hookrightarrow range

Q: How to compute nullity and rank?

For Nullity: Find $A \sim B$ R.E.F. then nullity = # independent variables

Example 1 (revisited) $A = \begin{bmatrix} 1 & 2 & 3 & -1 \\ 2 & 3 & 5 & -1 \\ 1 & 5 & 6 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ 2 indep. variables
 nullity = 2.

For Range: Find $A^T \sim B$ REF then rank = # nonzero rows of A.

Example 1 (revisited) $A^T = \begin{bmatrix} 1 & 2 & 1 \\ 2 & 3 & 5 \\ 3 & 5 & 6 \\ -1 & -1 & -4 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 7 \\ 0 & 1 & -3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ rank = 2.

Thm 3 The rank of $A = \text{rank of } A^T$. So the range and row space of A have the same dimension.

In particular, $\left. \begin{array}{l} \text{rank } A = \# \text{ dependent variables} \\ \text{nullity } A = \# \text{ independent } \text{---} \end{array} \right\} n = \# \text{ cols } A = \text{rank}(A) + \text{null}(A)$

Example above: $4 = 2 + 2$.

Thm 4: A system $A\underline{x} = \underline{b}$ is consistent if and only if $\text{rank}(A) = \text{rank}(A|b)$

Proof: The system is consistent if and only if \underline{b} in $\text{Sp}(\text{col}_1 A, \dots, \text{col}_n A) = \text{R}(A)$
 so $\text{Sp}(\text{col}_1 A, \dots, \text{col}_n A, \underline{b}) = \text{R}(A)$ & both have the same dimension.
 $\dim = \text{rank}([A|b])$ $\dim = \text{rank}(A)$.

Thm 5: A matrix A of size $n \times n$ is nonsingular if and only if $\text{rank}(A) = n$.

Proof: A is nonsingular if and only if n cols of A are l.i., if and only if $\dim \text{R}(A) = n$, that is $\text{rank}(A) = n$.

(*) Q: Example above: Which pairs of $\{v_1, \dots, v_4\}$ are bases for \mathbb{W} ?

Enough to check which pairs are l.i. $\underline{A} = \{v_1, v_2\}, \{v_1, v_3\}, \{v_1, v_4\}, \{v_2, v_3\}, \{v_2, v_4\}, \{v_3, v_4\}$ (Why? Use Thm 2 (3)).

Proof of Thm 3: Write $A = \begin{bmatrix} a_1 \\ \vdots \\ a_m \end{bmatrix}$ $a_i = [a_{i1}, \dots, a_{in}]$

① Show $\text{rank}(A) \leq \text{rank}(A^T)$:

Write $k = \text{rank}(A^T)$ so $W = \text{Sp}(a_1, \dots, a_m)$ has $\dim W = k$, W is a subspace of \mathbb{R}^n . By Thm 2 (2): $m \geq k$. Fix a basis $B = \{w_1, \dots, w_k\}$ of W . Write each a_i as a linear combination of B :

$$a_1^T = \begin{bmatrix} a_{11} \\ a_{12} \\ \vdots \\ a_{1n} \end{bmatrix} = \alpha_{11} \begin{bmatrix} w_{11} \\ w_{12} \\ \vdots \\ w_{1n} \end{bmatrix} + \dots + \alpha_{1k} \begin{bmatrix} w_{k1} \\ w_{k2} \\ \vdots \\ w_{kn} \end{bmatrix}$$

$$\vdots$$

$$a_m^T = \begin{bmatrix} a_{m1} \\ a_{m2} \\ \vdots \\ a_{mn} \end{bmatrix} = \alpha_{m1} \begin{bmatrix} w_{11} \\ w_{12} \\ \vdots \\ w_{1n} \end{bmatrix} + \dots + \alpha_{mk} \begin{bmatrix} w_{k1} \\ \vdots \\ w_{kn} \end{bmatrix}$$

Take the j^{th} component of each equation:

$$\begin{cases} a_{1j} = \alpha_{11} w_{1j} + \dots + \alpha_{1k} w_{kj} \\ \vdots \\ a_{mj} = \alpha_{m1} w_{1j} + \dots + \alpha_{mk} w_{kj} \end{cases}$$

$$\text{so } \begin{bmatrix} a_{1j} \\ \vdots \\ a_{mj} \end{bmatrix} = \text{col}_j A = w_{1j} \begin{bmatrix} \alpha_{11} \\ \vdots \\ \alpha_{m1} \end{bmatrix} + \dots + w_{kj} \begin{bmatrix} \alpha_{1k} \\ \vdots \\ \alpha_{mk} \end{bmatrix} \quad \text{for each } j$$

$$\text{so } R(A) \text{ is a subset of } \text{Sp} \left(\begin{bmatrix} \alpha_{11} \\ \vdots \\ \alpha_{m1} \end{bmatrix}, \dots, \begin{bmatrix} \alpha_{1k} \\ \vdots \\ \alpha_{mk} \end{bmatrix} \right) = W$$

$$\text{So } \text{rank}(A) = \dim R(A) \leq \dim W \leq k := \text{rank}(A^T)$$

② Use $(A^T)^T = A$ to conclude $\text{rank}(A^T) \leq \text{rank}((A^T)^T) = \text{rank}(A)$

We get $\text{rank } A \leq \text{rank } A^T \leq \text{rank } A$ so $\text{rank } A = \text{rank } A^T$ as we wanted to show.
 by ① applied to A^T .