

Lecture XXX : 39.1-4.2 The Eigenvalue Problem for (ex2) matrices

§ 1 The eigenvalue problem: (German: eigen = "self")

(EV) $\left\{ \begin{array}{l} \text{Fix an } n \times n \text{ matrix } A. \text{ Find all scalars } \lambda \text{ in } \mathbb{R} \text{ such that} \\ A\underline{x} = \lambda \underline{x} \\ \text{has a nonzero solution } \underline{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}. \end{array} \right.$

Definition: Scalars satisfying (EV) are called eigenvalues of A.
 The solutions \underline{x} to $A\underline{x} = \lambda \underline{x}$ are called eigenvectors of the eigenvalue λ .

Why is (x) relevant? Use eigenvalues to:

- (1) solve differential equations,
- (2) analyze population growth,
- (3) calculate powers of matrices,
- (4) diagonalize linear transformations $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$.
- (5) simplify and draw quadratic forms: $Ax^2 + By^2 + Cxy + Dx + Ey + F = 0$
 A, B, C, D, E, F fixed real numbers.

Diagonalizing $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$:

Fix those vectors v in \mathbb{R}^n , where $T(v) = \lambda v$ for some λ .

Eg. $\lambda = 0$, then these vectors form the NullSpace of T

If we can find a basis $B = \{v_1, \dots, v_n\}$ of \mathbb{R}^n where $T(v_i) = \lambda_i v_i$ for each i :
 then $[T]_{BB} = \begin{bmatrix} \lambda_1 & & & \\ & \lambda_2 & & \\ & & \ddots & \\ 0 & & & \lambda_n \end{bmatrix}$ so it's a diagonal matrix (simplest kind of transformations!)

Since $v_i \neq 0$, & $T(v_i) = \lambda_i v_i$, then λ_i is an eigenvalue for T .

So to "diagonalize T " we need to find the eigenvalues.

Remark: $A\underline{x} = \lambda \underline{x}$ always has $\underline{x} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$ as a solution, so to find eigenvalues we need to search for $\underline{x} \neq \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$ solving (EV)

§2.5 Strategy to solve the (EV) problem for λ : A is a fixed $n \times n$ matrix.

Notice: $A\mathbf{x} = \lambda\mathbf{x}$ has a nontrivial solution \mathbf{x} is equivalent to
 $A\mathbf{x} - \lambda\mathbf{x} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$.

But $A\mathbf{x} - \lambda\mathbf{x} = A\mathbf{x} - \lambda I_n \mathbf{x} = (A - \lambda I_n)\mathbf{x}$
matrix ↓ scalar

so (EV) is equivalent to $(A - \lambda I_n)\mathbf{x} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$ has a nontrivial solution \mathbf{x}

This is the SAME as says $(A - \lambda I_n)$ is a singular $n \times n$ matrix.

STRATEGY:

(1) Find all λ 's where $A - \lambda I_n$ is singular (at most n of them)

[How? $\det(A - \lambda I_n) = 0$]

(2) Given all the finitely many λ 's from (1), find all \mathbf{x} solving

$(A - \lambda I_n)\mathbf{x} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$ by Gauss-Jordan elimination!

\Rightarrow NullSpace $(A - \lambda I_n) = \{\mathbf{x} : (A - \lambda I_n)\mathbf{x} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}\} = E_\lambda$
 is the Eigenspace of the eigenvalue λ .

§3. The EV Problem for 2×2 matrices:

Write $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$: Then:

$$A - \lambda I_2 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} a-\lambda & b \\ c & d-\lambda \end{bmatrix}$$

$\cdot A - \lambda I_2$ is singular if and only if $\det(A - \lambda I_2) = 0$

\cdot We write the determinant explicitly:

$$\begin{aligned} \det \begin{pmatrix} a-\lambda & b \\ c & d-\lambda \end{pmatrix} &= (a-\underline{\lambda})(d-\underline{\lambda}) - bc = ad - a\underline{\lambda} - \underline{\lambda}d + \underline{\lambda}^2 - bc \\ &= \underline{\lambda}^2 + (-a-d)\underline{\lambda} + \underbrace{ad-bc}_{=0} = 0 \end{aligned}$$

\cdot How do we solve $\lambda^2 + p\lambda + q = 0$? Use quadratic formula $\lambda = \frac{-p \pm \sqrt{p^2 - 4q}}{2}$

Example 1 : $A = \begin{bmatrix} 5 & -1 \\ 8 & -1 \end{bmatrix}$ Find the eigenvalues of A & the corresponding eigenspaces.

$$\det(A - \lambda I_2) = \lambda^2 + (-5+1)\lambda + (-5+8) = \lambda^2 - 4\lambda + 3 = 0$$

$$\text{Sols: } \lambda = \frac{4 \pm \sqrt{16-4 \cdot 3}}{2} = \frac{4 \pm \sqrt{4}}{2} = \frac{4 \pm 2}{2} = 2 \pm 1 \quad \begin{matrix} \nearrow 3 \\ \searrow 1 \end{matrix}$$

Or Directly = factor the polynomial $\lambda^2 - 4\lambda + 3 = (\lambda-3)(\lambda-1)$.

Eigenspaces? For each λ : $E_\lambda = \{ \mathbf{x} : (A - \lambda I_2) \mathbf{x} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \}$.

$$E_3 : (A - 3I_2) \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$A - 3I_2 = \begin{bmatrix} 5-3 & -1 \\ 8 & -1-3 \end{bmatrix} \quad \text{Use GJ to find the solutions!}$$

$$\begin{bmatrix} 2 & -1 \\ 8 & -4 \end{bmatrix} \xrightarrow[R_2 \rightarrow R_2 + R_1]{R_2} \begin{bmatrix} 2 & -1 \\ 0 & 0 \end{bmatrix} \quad \begin{matrix} 2x_1 - x_2 = 0 \\ 2x_1 = x_2 \end{matrix} \quad \text{sols} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\Rightarrow E_3 = \text{Span} \left(\begin{bmatrix} 1 \\ 2 \end{bmatrix} \right) \quad \text{check } A \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5 & -1 \\ 8 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} 5-2 \\ 8-2 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$E_1 : (A - I_2) = \begin{bmatrix} 5-1 & -1 \\ 8 & -1-1 \end{bmatrix} = \begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix} \quad \text{Solve } \begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & -1 \\ 8 & -2 \end{bmatrix} \xrightarrow[R_2 \rightarrow R_2 - 2R_1]{R_2} \begin{bmatrix} 4 & -1 \\ 0 & 0 \end{bmatrix} \quad \begin{matrix} 4x_1 - x_2 = 0 \\ 4x_1 = x_2 \end{matrix} \quad \text{sols} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = x_1 \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

$$\Rightarrow E_1 = \text{Span} \left(\begin{bmatrix} 1 \\ 4 \end{bmatrix} \right)$$

→ Basis for \mathbb{R}^2 of eigenvectors = $\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 1 \\ 4 \end{bmatrix} \}$

Example 2 : $A = \begin{bmatrix} 3 & 0 \\ 0 & -1 \end{bmatrix}$ Find the eigenvalues & eigenspaces.

$$\det(A - \lambda I_2) = \begin{bmatrix} 3-\lambda & 0 \\ 0 & -1-\lambda \end{bmatrix} = (3-\lambda)(-1-\lambda) = (\lambda-3)(\lambda+1) = 0$$

$$\text{Sols: } \lambda = 3, \lambda = -1.$$

$$E_3 : A - 3I_2 = \begin{bmatrix} 0 & 0 \\ 0 & -4 \end{bmatrix} \Rightarrow \text{sols: } \begin{matrix} x_1 \text{ any} \\ x_2 = 0 \end{matrix} \quad E_3 = \text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$$

$$E_{-1} : A - (-I_2) = \begin{bmatrix} 3+1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow \text{sols: } \begin{matrix} x_1 = 0 \\ x_2 \text{ any} \end{matrix} \quad E_{-1} = \text{Span} \left\{ \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

$$\text{Check: } A \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix} = 3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} \quad \& \quad A \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ -1 \end{bmatrix} = - \begin{bmatrix} 0 \\ 1 \end{bmatrix}.$$