

Lecture XXXIII: §4.5 (cont) Eigenvectors & eigenspaces

Recall: Given λ eigenvalue of an $n \times n$ matrix A , we have:

$$E_\lambda = \text{NullSpace}(A - \lambda I_n) = \left\{ \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} : A \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \lambda \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \right\}$$

is a subspace of \mathbb{R}^n and $E_\lambda \neq \{0\}$ whenever λ is an eigenvalue (by definition!)

Define: algebraic multiplicity of λ = order of λ as a root of $P_A(t)$

• geometric multiplicity of λ = $\dim(E_\lambda) \geq 1$.

We are interested in the case where $\text{alg mult}(\lambda) = \text{geom mult}(\lambda)$ for all eigenvalues. In that case, we'll be able to diagonalize A .

We first discuss the bad cases, called defective.

§1 Defective matrices:

Def: Fix an $n \times n$ matrix A . If A has an eigenvalue λ where $\text{alg mult}(\lambda) > \text{geom mult}(\lambda)$, we call A a defective matrix.

• Last time: out of the 3 examples, first 2 were defective.

• Now examples:

Example: $A = \begin{bmatrix} -3 & 1 & 1 & 1 \\ -16 & 4 & 4 & 4 \\ -7 & 2 & 3 & 1 \\ -11 & 1 & 3 & 5 \end{bmatrix}$

Find the eigenvalues of A & determine the algebraic and geometric multiplicities of each of them.

Compute the characteristic polynomial by row/column operations

$$P_A = \det(A - tI_4) = \det \begin{bmatrix} -3-t & 1 & 1 & 1 \\ -16 & 4-t & 4 & 4 \\ -7 & 2 & 3-t & 1 \\ -11 & 1 & 3 & 5-t \end{bmatrix} \xrightarrow{\substack{\text{col}_2 \rightarrow \text{col}_2 - \text{col}_4 \\ \text{col}_3 \rightarrow \text{col}_3 - \text{col}_4}} \det \begin{bmatrix} -3-t & 0 & 0 & 1 \\ -16 & -t & 0 & 4 \\ -7 & 1 & 2-t & 1 \\ -11 & t-4 & -2+t & 5-t \end{bmatrix}$$

$$\xrightarrow{\substack{\text{col}_3 \text{ has a factor } (t-2) \\ \text{col}_2 \rightarrow \text{col}_2 - \text{col}_3 \\ \text{col}_4 \rightarrow \text{col}_4 - \text{col}_3}} = -(t-2) \det \begin{bmatrix} -3-t & 0 & 0 & 1 \\ -16 & -t & 0 & 4 \\ -7 & 1 & 1 & 1 \\ -11 & t-4 & -1 & 5-t \end{bmatrix} \xrightarrow{\substack{\text{col}_2 \rightarrow \text{col}_2 - \text{col}_3 \\ \text{col}_4 \rightarrow \text{col}_4 - \text{col}_3}} = -(t-2) \det \begin{bmatrix} -3-t & 0 & 0 & 1 \\ -16 & -t & 0 & 4 \\ -7 & 0 & 1 & 0 \\ -11 & t-3 & -1 & 6-t \end{bmatrix}$$

$$\xrightarrow{\substack{\text{col}_1 \rightarrow \text{col}_1 + 7\text{col}_3 \\ \text{row}_1 \leftrightarrow \text{row}_3}} = -(t-2) \det \begin{bmatrix} -3-t & 0 & 0 & 1 \\ -16 & -t & 0 & 4 \\ 0 & 0 & 1 & 0 \\ -18 & t-3 & -1 & 6-t \end{bmatrix} = + (t-2) \det \begin{bmatrix} 0 & 0 & 1 & 0 \\ -16 & -t & 0 & 4 \\ -3-t & 0 & 0 & 1 \\ -18 & t-3 & -1 & 6-t \end{bmatrix}$$

→ real or complex root of $P_A(t)$

-(2-t)

$$= (t-2) \det \begin{bmatrix} -16 & -t & 4 \\ -3-t & 0 & 1 \\ -18 & t-3 & 6-t \end{bmatrix} = (t-2) \det \begin{bmatrix} -16 & -t & 4 \\ -3-t & 0 & 1 \\ -18 & t-3 & 6-t \end{bmatrix}$$

$$= (t-2) (-16(-t-3)) - (-t)((-3-t)(6-t) + 18) + 4(-(t+3)(t-3))$$

$$= (t-2) (16t - 48 + t(-18 + 3t - 6t + t^2 + 18) - 4(t^2 - 9))$$

$$= (t-2) (16t - 48 - 3t^2 + t^3 - 4t^2 + 36) = (t-2) (t^3 - 7t^2 + 16t - 12)$$

Note: $t^3 - 7t^2 + 16t - 12$ has roots 3 & 2 (with mult=2 because its derivative also has 2 as a root)

So $P_A(t) = (t-2)^3 (t-3)$

• $E_3: A - 3I_4 = \begin{bmatrix} -6 & 1 & 1 & 1 \\ -16 & 1 & 4 & 4 \\ -7 & 2 & 0 & 1 \\ -11 & 1 & 3 & 2 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - R_1} \begin{bmatrix} -6 & 1 & 1 & 1 \\ -16 & 1 & 4 & 4 \\ -1 & 1 & -1 & 0 \\ -11 & 1 & 3 & 2 \end{bmatrix} \xrightarrow{R_1 \leftrightarrow R_3} \begin{bmatrix} -1 & 1 & -1 & 0 \\ -16 & 1 & 4 & 4 \\ -6 & 1 & 1 & 1 \\ -11 & 1 & 3 & 2 \end{bmatrix}$

$\xrightarrow{R_2 \rightarrow R_2 - 16R_1, R_3 \rightarrow R_3 - 6R_1, R_4 \rightarrow R_4 - 11R_1} \begin{bmatrix} -1 & 1 & -1 & 0 \\ 0 & -15 & 20 & 4 \\ 0 & -5 & 7 & 1 \\ 0 & -10 & 14 & 2 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - 3R_3, R_4 \rightarrow R_4 - 2R_2} \begin{bmatrix} -1 & 1 & -1 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & -5 & 7 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_3} \begin{bmatrix} -1 & 1 & -1 & 0 \\ 0 & -5 & 7 & 1 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

So $\begin{cases} -x_1 + x_2 - x_3 = 0 \\ -5x_2 + 7x_3 + x_4 = 0 \\ -x_3 + x_4 = 0 \end{cases} \implies \begin{cases} x_1 = x_2 - x_3 \\ 5x_2 = 8x_4 \implies x_2 = \frac{8}{5}x_4 \\ x_3 = x_4 \end{cases} \implies x_1 = x_2 - x_3 = \frac{8}{5}x_4 - x_4 = \frac{3}{5}x_4$

So $\underline{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} \frac{3}{5}x_4 \\ \frac{8}{5}x_4 \\ x_4 \\ x_4 \end{bmatrix} = \frac{x_4}{5} \begin{bmatrix} 3 \\ 8 \\ 5 \\ 5 \end{bmatrix}$ for any x_4 , so $E_3 = \text{Span} \left(\begin{bmatrix} 3 \\ 8 \\ 5 \\ 5 \end{bmatrix} \right)$

• $E_2: A - 2I_4 = \begin{bmatrix} -5 & 1 & 1 & 1 \\ -16 & 2 & 4 & 4 \\ -7 & 2 & 1 & 1 \\ -11 & 1 & 3 & 3 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2 - 3R_1} \begin{bmatrix} -5 & 1 & 1 & 1 \\ -1 & -1 & 1 & 1 \\ -7 & 2 & 1 & 1 \\ -11 & 1 & 3 & 3 \end{bmatrix} \xrightarrow{R_2 \leftrightarrow R_1} \begin{bmatrix} -1 & -1 & 1 & 1 \\ -5 & 1 & 1 & 1 \\ -7 & 2 & 1 & 1 \\ -11 & 1 & 3 & 3 \end{bmatrix}$

$\xrightarrow{R_2 \rightarrow R_2 - 5R_1, R_3 \rightarrow R_3 - 7R_1, R_4 \rightarrow R_4 - 11R_1} \begin{bmatrix} -1 & -1 & 1 & 1 \\ 0 & 6 & -4 & -4 \\ 0 & 9 & -6 & -6 \\ 0 & 12 & -8 & -8 \end{bmatrix} \xrightarrow{R_3 \rightarrow R_3 - \frac{3}{2}R_2, R_4 \rightarrow R_4 - 2R_2} \begin{bmatrix} -1 & -1 & 1 & 1 \\ 0 & 6 & -4 & -4 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \xrightarrow{R_2 \rightarrow R_2/2} \begin{bmatrix} -1 & -1 & 1 & 1 \\ 0 & 3 & -2 & -2 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$

So $\begin{cases} -x_1 - x_2 + x_3 + x_4 = 0 \\ 3x_2 - 2x_3 - 2x_4 = 0 \end{cases} \implies \begin{cases} x_1 = -x_2 + x_3 + x_4 = \frac{1}{3}x_3 + \frac{1}{3}x_4 \\ x_2 = \frac{2}{3}x_3 + \frac{2}{3}x_4 \end{cases}$

$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} \frac{1}{3}x_3 + \frac{1}{3}x_4 \\ \frac{2}{3}x_3 + \frac{2}{3}x_4 \\ x_3 \\ x_4 \end{bmatrix} = \frac{x_3}{3} \begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix} + \frac{x_4}{3} \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix}$ for any x_3, x_4 : So $E_2 = \text{Span} \left(\begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix} \right)$

Conclusion: $\lambda = 2$ eigenvalue with alg mult = 3 & geom mult = 2
 $\lambda = 3$ eigenvalue with alg mult = 1 & geom mult = 1

So A is defective (because of $\lambda = 2$)

Prop: For any eigenvalue λ of an $n \times n$ matrix A , we have
 alg mult (λ) \geq geom. mult (λ) ≥ 1 .

So if alg mult (λ) = 1, we have alg mult (λ) = geom mult (λ) = 1.

Theorem: Given a matrix A of size $n \times n$ and a list of distinct eigenvalues $\lambda_1, \dots, \lambda_k$, each with a nonzero eigenvector $v_j, j=1, \dots, k$ [$A \cdot v_j = \lambda_j v_j$]
 Then $S = \{v_1, \dots, v_k\}$ is a linearly independent set in \mathbb{R}^n .

Proof: If $k=1$, the result is true because a nonzero vector is always l.i.

• Assume $k > 1$ but the set S is linearly dependent. Then, we can find some $m = 2, \dots, k$ where:

- $S_1 = \{v_1, \dots, v_{m-1}\}$ is l.i.
- $S_2 = \{v_1, \dots, v_{m-1}, v_m\}$ is l.d.

Write a non-trivial linear combination showing that S_2 is l.d.:

(*) $c_1 v_1 + c_2 v_2 + \dots + c_{m-1} v_{m-1} + c_m v_m = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$

but not all c_1, \dots, c_m are 0. Since the 1st $m-1$ vectors are l.i, we know $c_m \neq 0$.

Multiply (*) by A :

$$A(c_1 v_1 + \dots + c_m v_m) = A \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$c_1 \underbrace{A v_1}_{\lambda_1 v_1} + \dots + c_m \underbrace{A v_m}_{\lambda_m v_m} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$c_1 \lambda_1 v_1 + \dots + c_{m-1} \lambda_{m-1} v_{m-1} + c_m \lambda_m v_m = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix} \quad (**)$$

Performing (**) - λ_m (*) gives:

$$c_1 \underbrace{(\lambda_1 - \lambda_m)}_{\neq 0} v_1 + \dots + c_{m-1} \underbrace{(\lambda_{m-1} - \lambda_m)}_{\neq 0} v_{m-1} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

Since S_1 is l.i we get

$$\begin{array}{lcl}
 c_1(\lambda_1 - \lambda_m) = 0 & \xrightarrow{\lambda_1 \neq \lambda_m} & c_1 = 0 \\
 c_2(\lambda_2 - \lambda_m) = 0 & \xrightarrow{\lambda_2 \neq \lambda_m} & c_2 = 0 \\
 \vdots & & \vdots \\
 c_{m-1}(\lambda_{m-1} - \lambda_m) = 0 & \xrightarrow{\lambda_{m-1} \neq \lambda_m} & c_{m-1} = 0
 \end{array}$$

Then, we go back to (*) & get $\underline{0} + c_m v_m = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$ & $v_m \neq \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$,
 so $c_m = 0$, contradicting our original statement.
 We conclude the set S is l.i. \square

Back to the example: $S = \left\{ \begin{bmatrix} 3 \\ 8 \\ 5 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix} \right\}$ is l.i by the Thm (and we can check it in the example!)

Also $S = \left\{ \begin{bmatrix} 3 \\ 8 \\ 5 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \\ 3 \end{bmatrix} \right\}$ is l.i by the Theorem (we can also check it!).

Corollary: If A of size $n \times n$ has n distinct eigenvalues, then A has a basis of eigenvectors (one per eigenvalue).