

§1 Matrices & linear systems

Recall: An $m \times n$ system of linear equations is a set of m linear equations in n unknowns. We write:

$$(*) \begin{cases} a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1 & (\text{Eqn 1}) \\ a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2 & (\text{Eqn 2}) \\ \vdots \\ a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m & (\text{Eqn } m) \end{cases}$$

where,

- a_{11}, \dots, a_{mn} are coefficients ($m \cdot n$ many $\leadsto (a_{ij})_{\substack{1 \leq i \leq m \\ 1 \leq j \leq n}}$) $i = \text{eqn number}$
 $j = \text{unknown index}$
- m constant terms b_1, \dots, b_m ($\text{in } \mathbb{Q}, \mathbb{R}, \mathbb{C}, \dots$) $\leadsto (b_i)_{1 \leq i \leq m}$
- n unknowns x_1, \dots, x_n

Collect the coefficients & constant terms into matrices. This gives a convenient framework to represent & solve linear systems

Def: An $m \times n$ matrix A is a rectangular array of numbers with m rows & n columns. Write them as:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} = (a_{ij})_{ij}$$

\swarrow row # \searrow column #

Example: $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 0 \end{bmatrix}$ 2×3 matrix - $A = \begin{bmatrix} 1 & 0 \\ 6 & 1 \end{bmatrix}$ 2×2 matrix

. If $n = m$ we say A is a square matrix.

§2 Representing linear systems via matrices: - equations \leadsto rows
- unknowns \leadsto columns
& constant terms

Def: The coefficient matrix for the system (*) is the $m \times n$ matrix $A = (a_{ij})$
 . The augmented matrix --- $m \times (n+1)$ --- B ,

where $B = [A | \underline{b}] = \begin{bmatrix} a_{11} & \dots & a_{1n} & b_1 \\ a_{21} & \dots & a_{2n} & b_2 \\ \vdots & & \vdots & \vdots \\ a_{m1} & \dots & a_{mn} & b_m \end{bmatrix}$ where $\underline{b} = \begin{bmatrix} b_1 \\ \vdots \\ b_m \end{bmatrix}$

(col 1) for x_1 (col n) for x_n (col n+1) for b_i 's

← row 1
← row 2
← row m

Example:
$$\begin{cases} x_1 + 3x_2 - 2x_3 = 4 \\ 4x_1 - 5x_3 = 0 \\ -2x_1 + 6x_2 = 24 \end{cases}$$

Align \implies

$$\begin{cases} \underline{1}x_1 + \underline{3}x_2 + \underline{(-2)}x_3 = \underline{4} \\ \underline{4}x_1 + \underline{0}x_2 + \underline{(-5)}x_3 = \underline{0} \\ \underline{(-2)}x_1 + \underline{6}x_2 + \underline{0}x_3 = \underline{24} \end{cases}$$

"missing terms" = "coeffs equal 0"

$\implies B = \left[\begin{array}{ccc|c} 1 & 3 & -2 & 4 \\ 4 & 0 & -5 & 0 \\ -2 & 6 & 0 & 24 \end{array} \right]$

Last time = manipulated (combined multiplication by scalars with adding/subtracting 2 equations) to solve systems. in the system

Upside = can use certain operations allowed to go from one system to a simpler one without changing the solution set. Have Parallel operations on the assoc. augmented matrix side.

§ 2. Elementary operations

2 steps to solve a system: (1) Reduce to a simpler one equivalent (eliminating variables)
(2) Describe the solutions from the simpler one

Def: 2 systems in n unknowns are equivalent if they have the same solution set

Examples: (1) $\begin{cases} x + y = 5 \\ 2x + 2y = 10 \end{cases}$ & $\begin{cases} x + y = 5 \end{cases}$ are equivalent

(2) $\begin{cases} 2x + 4y = 18 \\ 4x - 4y = 0 \end{cases}$ (last time) & $\begin{cases} x = 3 \\ y = 3 \end{cases}$ are equivalent.

(3) $\begin{cases} x + y = 0 \\ x + y = 4 \end{cases}$ & $\{0 = 1\}$ are equivalent (they both have no solutions).

Theorem 1: The following elementary operations give equivalent systems:

(1) interchange 2 equations (E_i & E_j , write $E_i \leftrightarrow E_j$)

(2) multiply an equation by a nonzero number & replace it

(E_i , $\alpha \neq 0$, write $E_i \rightarrow \alpha E_i$)

(3) replace an equation by adding to it a constant multiple of a different equation ($E_i \rightarrow E_i + \lambda E_j$ for $j \neq i$ & any fixed number λ)

Why does this work? (1) is clear

(2) Since $\alpha \neq 0$, we can reverse the operation $E_i \rightarrow \alpha E_i \rightarrow \frac{1}{\alpha}(\alpha E_i) = E_i$

(3) can "reverse" this operation as well:

$$\left\{ \begin{array}{l} E_i \\ \text{rest} \end{array} \right\} \rightarrow \left\{ \begin{array}{l} (E_i + \lambda E_j) \\ \text{rest} \end{array} \right\} = \text{new } E'_i \rightarrow \left\{ \begin{array}{l} (E_i + \lambda E_j) + (-\lambda) E_j \\ \text{rest} \end{array} \right\} = E_i$$

Example:

$$\left\{ \begin{array}{l} X_1 + X_2 = 9 \\ -X_1 + 3X_2 = 9 \end{array} \right. \xrightarrow{E_1 \rightarrow E_1 + E_2} \left\{ \begin{array}{l} 4X_2 = 12 \\ -X_1 + 3X_2 = 9 \end{array} \right. \xrightarrow{E_1 \rightarrow \frac{1}{4}E_1} \left\{ \begin{array}{l} X_2 = 12/4 = 3 \\ -X_1 + 3X_2 = 9 \end{array} \right.$$

$$\xrightarrow{E_2 \rightarrow E_2 - 3E_1} \left\{ \begin{array}{l} X_2 = 3 \\ -X_1 = 9 - 9 = 0 \end{array} \right. \xrightarrow{E_2 \rightarrow -E_2} \boxed{\left\{ \begin{array}{l} X_2 = 3 \\ X_1 = 0 \end{array} \right.}$$

EASY TO SOLVE!
(unique solution)

By Thm 1, we conclude $\left\{ \begin{array}{l} X_1 + X_2 = 3 \\ -X_1 + 3X_2 = 9 \end{array} \right.$ has a unique soln = (0, 3).

§ 4. On the matrix side = Row operations

Def: There are 3 elementary row operations corresponding the elementary operat. on systems:

(1) interchanging two rows ($R_i \leftrightarrow R_j$)

(2) replace a row by a non-zero scalar multiple of it ($R_i \rightarrow \alpha R_i$)
for $\alpha \neq 0$

(3) replace a row by adding to it a constant multiple of a different row.
($R_i \rightarrow R_i + \lambda R_j$ for $i \neq j$)
any λ

Def: Two matrices are row equivalent if we can obtain one from the other by a sequence of elementary row operations.

Example: $\left[\begin{array}{cc|c} 1 & 1 & 3 \\ -1 & 3 & 9 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 0 & 4 & 12 \\ -1 & 3 & 9 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 0 & 1 & 3 \\ -1 & 3 & 9 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 0 & 1 & 3 \\ -1 & 0 & 0 \end{array} \right] \rightarrow \left[\begin{array}{cc|c} 0 & 1 & 3 \\ 1 & 0 & 0 \end{array} \right]$
(above) $\xrightarrow{R_1 \leftrightarrow R_2} \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 3 \end{array} \right]$

reduced echelon form

Obs: If two row equivalent matrices record two linear systems (as their augmented matrices), then these systems are equivalent.

\Rightarrow Algorithm for solving $m \times n$ linear systems:

- ALGORITHM: (1) Write the augmented matrix B of the input system
- (2) do elementary row operations to go from B to a simpler matrix B' (Gauss-Elimination)
- Jordan
- (3) solve the system represented by B'

Ex above:

Step 1: $\begin{cases} x + y = 3 \\ -x + 3y = 9 \end{cases} \rightsquigarrow B = \left[\begin{array}{cc|c} 1 & 1 & 3 \\ -1 & 3 & 9 \end{array} \right]$

Step 2: From B we get $B' = \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 3 \end{array} \right]$

Step 3: We write the system $\begin{cases} x = 0 \\ y = 3 \end{cases}$. It's already solved!

So the original system has a unique solution $(x, y) = (0, 3)$.

What do we mean by a simpler matrix?

- Staircase shape, where each row starts with a 1 and has 0's to the left & below each one of these 1's = Echelon form
- Reduced echelon form = 0's also above the 1's

Examples: $\left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 1 & 3 \end{array} \right]$ RED ECH. , $\left[\begin{array}{cc|c} 1 & 1 & 3 \\ 0 & 1 & 3 \end{array} \right]$ ECH.

$\left[\begin{array}{cc|c} 0 & 1 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 3 \end{array} \right]$ ECH.

$\left[\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{array} \right]$ ECH

$\left[\begin{array}{cc|c} 0 & 0 & 1 \\ 1 & 0 & 2 \\ 0 & 0 & 0 \end{array} \right]$ not ECH

Next time: More on echelon & reduced echelon forms & Gauss-Jordan Elimination