

§1. Consistent vs Inconsistent:

Last time: Test for consistent vs inconsistent systems via $B' = [A' | b'] \in \mathbb{R}^{m \times (n+1)}$

(Consistent = B' has no $[0 \dots 0 | 1]$ row.) $\text{Rank}(B') = \# \text{ non-zero rows}$

Theorem: In the consistent case: number of free parameters = $n - \text{rank}(B')$
 $(\text{rank}(B') \leq \min\{m, n+1\})$
 $\text{rank}(B') \leq \min\{m, n+1\}$ for consistent syst.

In particular: unique solution if and only if (1) consistent

Consequence: A linear system has one, infinitely many or no solutions
(2) $\text{rank}(B') = n$
consistent inconsistent

Special case: If $m < n$ (more unknowns than equations), we have either no solution or infinitely many.

Why? $\text{rank}(B') \leq \min\{m, n\} = m < n$ for consistent systems, so $0 < n - \text{rank}(B')$ free parameters.

Examples:

① $B = \left[\begin{array}{ccc|c} 1 & 3/2 & -2 & 3/2 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - 3/2 R_2 + 2 R_3} \left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{array} \right] = B' \text{ REF}$ inconsistent!

$\text{rank}(B') = 3$
 $n = 3$ } no free variables! Unique solution = $\begin{cases} x_1 = 0 \\ x_2 = 1 \\ x_3 = 0 \end{cases} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

② $B = \left[\begin{array}{ccc|c} 1 & 3/2 & -2 & 3/2 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] \xrightarrow{R_1 \rightarrow R_1 - 3/2 R_2} \left[\begin{array}{ccc|c} 1 & 0 & -7/2 & 3/2 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right] = B'$ consistent!

$\text{rank}(B') = 2$
 $n = 3$ } 1 free parameter = x_3
 $x_1, x_2 = \text{dependent vars}$
 $\begin{cases} x_1 = \frac{5}{2} + \frac{7}{2} x_3 \\ x_2 = -x_3 \\ x_3 \text{ ANY} \end{cases}$ infinitely many solns!

Soln $(x_1, x_2, x_3) = (\frac{5}{2}, 0, 0) + x_3 (\frac{7}{2}, -1, 1) = \begin{bmatrix} 5/2 \\ 0 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 7/2 \\ -1 \\ 1 \end{bmatrix}$

Parametric form of a line in \mathbb{R}^3

§2. Homogeneous vs Inhomogeneous systems

Def: A system with augmented matrix $B = [A|b]$ is homogeneous if all constant terms (b_i 's) are zero. We say it is inhomogeneous, otherwise.

Why? • Gauss Jordan elimination processes homogeneous systems, hence also inhomogeneous.
• Homogeneous systems are ALWAYS CONSISTENT: $x_1 = \dots = x_n = 0$ is always a soln. (trivial or zero solution)

$$\begin{cases} a_{11}x_1 + \dots + a_{1n}x_n = 0 \\ \vdots \\ a_{m1}x_1 + \dots + a_{mn}x_n = 0 \end{cases} \implies \text{we evaluate at } x_1 = x_2 = \dots = x_n = 0 \implies \text{get } \begin{cases} 0 = 0 \\ \vdots \\ 0 = 0 \end{cases} \implies \text{''}$$

Thm: A homogeneous $m \times n$ system has infinitely many solutions if $m < n$.

Δ It will have them if $n > \text{rank}(B')$, but this can happen if $m \geq n$.

Example: $B = \left[\begin{array}{cccc|c} 1 & 0 & -2 & 0 & 0 \\ 0 & 1 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \end{array} \right] \xrightarrow{R_2 \rightarrow R_2 - R_3} \left[\begin{array}{cccc|c} 1 & 0 & -2 & 0 & 0 \\ 0 & 1 & -1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & -1 & 0 \end{array} \right] = B'$ REF

$$\begin{cases} x_1 = 2x_3 \\ x_2 = x_3 - x_5 \\ x_4 = x_5 \\ x_3, x_5 \text{ ANY} \end{cases}$$

x_1, x_2, x_4 = dependent (rank $B' = 3$)
 x_3, x_5 = indep.
2 free parameters = dimension 2.
Solu = $x_3(2, 1, 1, 0, 0) + x_5(0, -1, 0, 1, 1) = x_3 \begin{bmatrix} 2 \\ 1 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \\ 1 \end{bmatrix}$
(Plane in \mathbb{R}^5 through the origin $= (0, 0, 0, 0, 0)$)

Application: Find conics in \mathbb{R}^2 through a fixed set of points.

Def: A conic in \mathbb{R}^2 is $\boxed{ax^2 + bxy + cy^2 + dx + ey + f = 0}$ (*)

for fixed values of a, b, c, d, e, f , NOT all zero. (dep on 2 eqn in x, y)
(coefficients)

GOAL: Find coefficient values so that $(x_1, y_1), \dots, (x_m, y_m)$ satisfy the equation (*).

• How? Evaluate at each (x_i, y_i) gives 1 linear eqn in (a, b, \dots, f)
• Finding conic = finding a non-trivial solution to this system homog of m equations in the 6 unknowns (a, b, c, d, e, f) .

Note: If $m < 6$ we will always have a non-trivial solution (at most 5 pts)

Example: Pick 5 points $(-1,0), (0,1), (2,2), (2,-1), (0,-3)$ & find the conic through them.

$P_1 = (-1,0) \implies a(-1)^2 + b(-1) \cdot 0 + c \cdot 0^2 + d(-1) + e \cdot 0 + f = 0$
 becomes $a - b - d + f = 0$

The system has augmented matrix

$$B = \begin{array}{cccccc|c} a & b & c & d & e & f & \\ \hline 1 & -1 & 0 & -1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 1 & 0 \\ 4 & 4 & 4 & 2 & 2 & 1 & 0 \\ 4 & -2 & 1 & 2 & -1 & 1 & 0 \\ 0 & 0 & 9 & 0 & -3 & 1 & 0 \\ \hline x^2 & xy & y^2 & x & y & 1 & \end{array} \begin{array}{l} P_1 = (-1,0) \\ P_2 = (0,1) \\ P_3 = (2,2) \\ P_4 = (2,-1) \\ P_5 = (0,-3) \end{array}$$

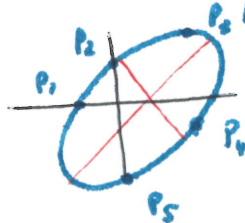
$$\sim B' = \begin{array}{cccccc|c} 1 & 0 & 0 & 0 & 0 & \frac{7}{18} & 0 \\ 0 & 1 & 0 & 0 & 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 1 & 0 & 0 & \frac{1}{3} & 0 \\ 0 & 0 & 0 & 1 & 0 & -\frac{11}{18} & 0 \\ 0 & 0 & 0 & 0 & 1 & \frac{2}{3} & 0 \end{array}$$

Soln: $a = -\frac{7}{18}f$
 $b = \frac{1}{2}f$
 $c = -\frac{1}{3}f$
 $d = \frac{11}{18}f$
 $e = -\frac{2}{3}f$

$= f \begin{bmatrix} -\frac{7}{18} \\ \frac{1}{2} \\ -\frac{1}{3} \\ \frac{11}{18} \\ -\frac{2}{3} \end{bmatrix}$

Eqn: $f \left(-\frac{7}{18}x^2 + \frac{1}{2}xy - \frac{1}{3}y^2 + \frac{11}{18}x - \frac{2}{3}y + 1 \right) = 0$
 for any $f \neq 0$, can take $f=18$, so we get

Conic: $0 = -7x^2 + 9xy - 6y^2 + 11x - 12y + 18$



(rotated ellipse)