

Lecture 1: Course outline & Introduction to groups

§1 Overview:

① Group Theory

(5 weeks)

- Basic definitions (gp, subgroups, normal subgps, homomorphisms)
- Isomorphism Thms
- Presentations by gens Δ relations
- Group Actions + Counting Lemmas
- p-groups & Sylow Thms
- Simple groups (Example: A_n for $n \geq 5$)
- Classification of finitely generated abelian gps
- Direct / Semidirect Products
- Automorphisms of cyclic gps
- Solvable & Nilpotent groups
- Composition series & Jordan-Hölder

NICE EXAMPLES

- S_n perm on $[n] = \{1, \dots, n\}$
- D_n (symm of n-gon)
- $GL_n(K)$ (K field)
- $\text{Aut}(X)$ X graph
- $\text{Pic}(\text{graph}), \text{Jac}(\text{curve})$
- Coxeter gps (Weyl gps)
- Fundamental gps $\pi_1(X)$
- Cohomology groups
- Group of isometries of a metric space (X, d)
- Valued gp (DVR) (& many more ...)

② Ring Theory

(6 weeks)

- Basic definitions (rings, subrings, left/right ideals, homs...)
- Isomorphism Thms
- Modules over rings (\oplus , Π , homs)
- Prime / Maximal ideals
- Prime avoidance, Chinese Remainder Thm.
- Rings & modules of fractions, **Localization**
(essential for Alg. Geometry!)
- Nil- & Jacobson Radicals
- Artinian & **Noetherian rings**
(f.g. structures)

Hilbert Basis Thm.

Primary Decomposition
(topological & alg. structure
of solutions to polynomial syst)

- PID & Modules over PID
 \rightsquigarrow Classification Thm
 (Application: finite ab grps)
- Number Theory connections
 - UFD \rightsquigarrow Gauss' Lemma & Eisenstein criterion
 - Euclidean / Dedekind domains
 - $\mathbb{Z}[\sqrt{-D}]$ (quadratic integers)
- Invariant Theory:
 - Symmetric polynomials
 - discriminants (A-disc)
- Extras:
 - Valuation rings (DVRs)
 \rightsquigarrow non-Archimedean geometry
 - Gröbner basis.
(Computational Alg Geom)

③ Linear & Multilinear Algebra (3 weeks)

- Vector spaces over K
 - basis, \oplus , $\text{Hom}_K(V, W)$, duals, \otimes_{IK}
 - $V^* \otimes W \cong \text{Hom}_K(V, W)$ (Hom-tensor adjointness)
- $B(\cdot, \cdot) : V_1 \times V_2 \rightarrow K$ bilinear forms
- $B : V_1 \times \dots \times V_n \rightarrow K$ multilinear forms
- \implies Universal properties defining $V, \otimes_{IK} \dots \otimes_{IK} V_n$
- Non-degenerate bilinear forms $B : V \times V \rightarrow K$
 - \implies $\Omega_B \in V \otimes V^*$ canonical tensor (indep. of basis!)
- Matrix repr-n of symm. non-deg bilinear forms.
 - Over \mathbb{R} : can diagonalize this matrix \implies (rank, signature)
 - \implies positive def / semidef matrices. [Sylvester's Thm]
- Tensor Algebra: $T(V) = \bigoplus_{n=0}^{\infty} T^n(V)$ [$T^n(V) = \underbrace{V \otimes \dots \otimes V}_{n \text{ times}}$]
- \implies $\text{Sym}^n(V)$ & $\Lambda^n(V)$ \implies Decomposition Thm
 - (symmetric) (exterior)
 - Properties, interplay with \oplus & $*$

- Determinants & minors via skew-symmetric forms

Cayley-Hamilton Thm

- \implies Nakayama's Lemma
 - $(A, m) \subset M$ & $mM = M \implies M = 0$
f.g.
- Symplectic & orthogonal gps of matrices
- Decomposition Thm for matrices
 - polar
 - Jordan
 - Gaussian

§1 Basics on groups & some examples:

Definition: A group G is a set together with:

(1) a function $G \times G \longrightarrow G$ (group operation or multiplication)
 $(a, b) \longmapsto a * b$
↖ just notation

(2) an element $e \in G$, called unit / identity / neutral element

satisfying the following 3 properties:

(i) Associativity: $(a * b) * c = a * (b * c)$ for all $a, b, c \in G$.

(ii) e Neutral: $e * a = a * e = a \quad \forall a \in G$.

(iii) Existence of Inverses: for every $a \in G$, there exists $b \in G$
such that $a * b = e = b * a$

Notation = $b = a^{-1}$ if $*$ is "multiplication" \rightsquigarrow *non-abelian notation*
 $b = -a$ if $*$ is "addition" \rightsquigarrow *abelian setting*

Definition $(G, *)$ is abelian or commutative if $a * b = b * a \quad \forall a, b \in G$

EXAMPLES:

① $G = \mathbb{Z} = \{\dots, -1, 0, 1, 2, \dots\}$ (integers)
 $a * b = a + b$ $e = 0$ (abelian!)

Inverse of $a = -a$

② $G = \mathbb{R}_{>0}$ (positive reals)
 $a * b = a \cdot b$ (usual multiplication) , $e = 1$
Inverse of $a = \frac{1}{a}$ (abelian!)

Non-examples:

① $G = \mathbb{R}_{>0}$ but $a * b = a^b (= \exp(b \ln a))$, $e = 1$

Issue: Not associative! (topical addition = \oplus)

② $G = \mathbb{R} \cup \{-\infty\}$ $a * b = \max\{a, b\}$, $e = -\infty$

Issue: No inverses (except when $a = \infty$)

Weaker structures: monoid & semigroups

Def.: A monoid is a set G with $*$: $G \times G \rightarrow G$ & $e \in G$

where the operation $*$ satisfies (i) Associativity

Examples: (ii) Existence of Neutral Element (e)

① All groups are monoids.

② $(\mathbb{R} \cup \{-\infty\}, \oplus)$ is a monoid.

③ $\mathbb{N} = \{0, 1, 2, 3, \dots\}$, $*$ = usual addition $e = 0$.

④ E set $X = 2^E = \{\text{subsets of } E\} = \mathcal{P}(E)$ $A * B = A \cup B$
 $e = \emptyset$.

Def.: A semigroup is a set G with $\alpha: G \times G \rightarrow G$ (law of composition) satisfying Associativity

Example: $\mathbb{Z}_{>0} = \{1, 2, 3, \dots\}$ with $+$ is semigrp, not monoid
 \cdot is monoid.

More examples of groups

③ $G = GL_2(\mathbb{R})$ = real 2×2 matrices with non-zero determinant
 $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$

• gp. operation = matrix multiplication $[(AB)_{ij} = \sum_{k=1}^2 A_{ik} B_{kj}]$

• $e = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ = identity = I_2

$$\Rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

↖ cofactor matrix

Claim: G is non-abelian

Eg: $A = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$, $B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \Rightarrow AB = \begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$ $BA = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$

$\Rightarrow G = GL_N(K)$ for any field K is a non-abelian gp.

NEXT TIME: Symmetric group S_n & Dihedral group D_n

Basic Uniqueness Lemmas

Lemma 1: Neutral elements on groups are unique.

Pf/ Assume e, e' in two neutral elements in a group $(G, *)$:

$$e = e * e' = e'$$

\downarrow \downarrow
 e' neutral e neutral

□

Lemma 2: Inverses on groups are unique

Pf/ Fix $x \in G$ & write y, y' for two inverses of x in G

$$y = y * e = y * (x * y') = (y * x) * y' = e * y' = y'$$

\downarrow \downarrow \downarrow \downarrow
 e neutral y' inverse Assoc y inverse y' inverse

□

Lemma 3: If $x \in G$ and $x * x = x$, then $x = e$

Pf/

$$e = x * x^{-1} = (x * x) * x^{-1} = x * (x * x^{-1}) = x * e = x$$

\downarrow \downarrow \downarrow \downarrow
 x^{-1} inverse hyp. Assoc x^{-1} inverse

□

§ 2. Group homomorphisms: G, G' groups

Def A map $\varphi: G \rightarrow G'$ is a group homomorphism if $\varphi(a *_G b) = \varphi(a) *_G \varphi(b)$ (algebraic structure is preserved!)

Lemma 4: Let $\varphi: G \rightarrow G'$ be gr homomorphism.

Then $\varphi(e) = e$ & $\varphi(x^{-1}) = (\varphi(x))^{-1}$.

PF/ $\varphi(e) = \varphi(e *_G e) = \varphi(e) *_G \varphi(e)$

By Lemma 3 applied to $x = \varphi(e)$, we get $\varphi(e) = e' \in G'$ \square

\triangle This fails for monoids! (Ex: $\varphi(A) = E \neq A \subseteq E$)

\leadsto Def: Homomorphisms of monoids: $\varphi(a *_G b) = \varphi(a) *_G \varphi(b)$ \square $\varphi(e) = e'$