

Lecture 31: Rational normal forms, Jordan canonical forms

Last 2 lectures: Saw Classification theorems for f.g. torsion modules over PIDs

Fix: $M \neq (0)$ f.g. torsion module over a PID R

Classification Theorem 1: $M = \bigoplus_{p_i \text{ prime}} M_{p_i^{n_i}}$ for suitable $n_i \in \mathbb{Z}_{\geq 0}$ with $M_{p_i^{n_i}} \neq \{0\}$.
(n_i minimal)

Furthermore: $M_{p_i^{n_i}} \cong \frac{R}{(p_i^{v_1(i)})} \oplus \dots \oplus \frac{R}{(p_i^{v_{s(i)}(i)})}$

with $n_i = v_1(i) + v_2(i) + \dots + v_{s(i)}(i)$ & the sequence (v_i) is uniquely determined by M & p_i .

Classification Thm v2: $M \cong \frac{R}{(f_1)} \oplus \dots \oplus \frac{R}{(f_r)}$ where $f_i \neq 0, f_i \in R^\times \forall i$.
& $f_1 | f_2 | \dots | f_r$. Furthermore, the sequence of ideals $(f_1), \dots, (f_r)$ is unique.

TODAY'S GOAL: Focus on the case of $K[x]$ -modules, where K is a field of characteristic 0 (in char p , perfect fields will be needed (see Math 6112))

Main results: Rational normal form decomposition for $\text{Mat}_{n \times n}(K)$
Jordan canonical form for $\text{Mat}_{n \times n}(\bar{K})$ e.g. $\bar{K} = \mathbb{C}$.

$K[x]$ -modules

Q: What is a $K[x]$ -module?

Include: $K[x]$ -module $\longleftrightarrow$ a K -vector space V + $\varphi \in \text{End}_K(V)$.

From now on, we assume V has $\dim_K V = n < \infty$.

So $\varphi \longleftrightarrow A \in \text{Mat}_{n \times n}(K)$ (matrix of the linear transf w.r.t a fixed basis)

Def $A, C \in \text{Mat}_{n \times n}(K)$: $A \sim C \iff \exists G \in GL_n(K)$ st $A = G^{-1} C G$

The minimal polynomial of A

$\Rightarrow$ Define a map $\Psi: \mathbb{K}[x] \longrightarrow \mathbb{K}[A] \subset \text{End}_{\mathbb{K}}(V)$
 $p(x) \longmapsto p(A)$

Lemma: $\text{Ker } \Psi \neq (0)$ ($\Rightarrow$ q_A = monic gen of $\text{Ker } \Psi$ = minimal polynomial)

Cyclic case

Def V is cyclic (as $K[x]$ -mod) if $\exists v \in V$ s.t. $\{v, Av, A^2v, \dots\}$ spans V .

Proposition Assume $V \neq 0$ is cyclic. Then:

- (1) $\deg(q_A)$ is minimal $d > 0$ s.t. $\{v, Av, \dots, A^d v\}$ is ld, i.e.:
- $\{v, Av, \dots, A^{d-1}v\}$ is li & • $\{v, Av, \dots, A^d v\}$ is ld.
- (2) Furthermore, in this situation $\{v, Av, \dots, A^{d-1}v\}$ is a basis for V .

Corollary 1: If V is cyclic and $\chi_A = x^d + a_{d-1}x^{d-1} + \dots + a_1x + a_0$,
 then in the basis $B = \{v, Av, \dots, A^{d-1}v\}$ we have

$$[A]_{BB} = \begin{bmatrix} 0 & & & -a_0 \\ 1 & & & -a_1 \\ & \ddots & & \vdots \\ & & 1 & -a_{d-1} \end{bmatrix}$$

Corollary 2: If V is cyclic, then: $V \simeq \frac{K[x]}{f_A(x)}$ (as K -r.s.)

Moreover $f_A(x)$ is independent of the choice of generator v for V

Q: What happens in the non-cyclic case?

Obs: $\dim_K V < \infty$, then V is a Torsion module over $K[x]$.

Rational normal forms

Theorem 1: V K -vector space & $A \in \text{End}_K(V)$ $A \neq 0$. Then,
 V admits a direct sum decomposition:

$$V = V_1 \oplus \dots \oplus V_r$$

where each V_i is a cyclic $K[x]$ -module with invariants $q_i \neq 0$,
satisfying $q_1 \mid q_2 \mid \dots \mid q_r$

Furthermore, the sequence $(q_1, \dots, q_r)$ is uniquely determined
by V & A & $q_r = q_A$.

Corollary: V admits a basis B with

$$[A]_{BB} = \begin{bmatrix} \overline{C_{q_1}} & & 0 \\ & \ddots & \\ 0 & & \overline{C_{q_r}} \end{bmatrix} \quad C_{q_i} = \text{companion matrix for } q_i$$

This is known as the rational normal form for A . ($A \sim \text{RNF}(A)$)

Q: What about alternative Classification Thm?

We factor $q_A(x) = p_1^{n_1}(x) \cdots p_s^{n_s}(x)$ into distinct monic prime powers
(Everything is monic, so no unit is needed in the factorization)

Theorem 2 $V = V_{p_1^{n_1}} \oplus \cdots \oplus V_{p_r^{n_r}}$ & each $V_{p_i^{n_i}}$ decomposes further as

$$V_{p_i^{n_i}} \cong \bigoplus_{j=1}^{s_i} \frac{K[x]}{(p_i^{v_j^{(i)}})} \quad n_i = v_1^{(i)} \geq \cdots \geq v_{s_i}^{(i)} \quad (\text{sequence } v_j^{(i)} \text{ is unique})$$

Jordan canonical form

Assume $K = \overline{K}$, char 0 (Eg $K = \mathbb{C}$) Then $p_i \in K[x]$ irred & monic $\Rightarrow p_i = (x - \alpha_i)$

Each $\frac{K[x]}{(p_i)^m}$ piece gives a cyclic submodule $W_{p_i^m}^{\neq (0)}$ of V of dimension m
 $\uparrow$
 $K[A] \langle w \rangle$

Theorem 3: $W_{f,i,m}$ has a basis B over K such that

$$[A]_{W_{p,m}} = \begin{bmatrix} \alpha_1 & & \\ & \ddots & \\ & & \alpha_m \end{bmatrix} = J(\alpha, m) \quad (m \times m \text{ matrix})$$

Corollary: Given V & A with $q_A = p_1^{n_1} \cdots p_r^{n_r}$, $\exists$ B basis for V s.t.

$$[A]_B = \begin{bmatrix} \boxed{A_1} & & 0 \\ & \ddots & \\ 0 & & \boxed{A_r} \end{bmatrix} \quad \text{block diagonal decomp.}$$

Furthermore for $p_i = (x - \alpha_i)$, we have.

$$A_i = \begin{bmatrix} \boxed{J(\alpha_i, m_1^{(i)})} & & 0 \\ & \ddots & \\ 0 & & \boxed{J(\alpha_i, m_{s_i}^{(i)})} \end{bmatrix} \quad \text{with } n_i = m_1^{(i)} \geq \cdots \geq m_{s_i}^{(i)}$$

• This block decomposition is the Jordan canonical form of A