

Lecture 31: Rational normal forms, Jordan canonical forms

Last 2 lectures: Saw classification theorems for f.g torsion modules over PIDs

Fix: $M \neq (0)$ a f.g torsion module over a PID R

Classification Theorem 1: $M = \bigoplus_{p_i \text{ prime}} M_{p_i^{n_i}}$ for suitable $n_i \in \mathbb{Z}_{>0}$ with $M_{p_i^{n_i}} \neq \{0\}$.
(n_i minimal)

Furthermore: $M_{p_i^{n_i}} \cong \frac{R}{(p_i^{v_1})} \oplus \dots \oplus \frac{R}{(p_i^{v_s})}$

with $n_i = v_1 + v_2 + \dots + v_s$ & the sequence (v_i) is uniquely determined by M & p_i .

Classification Thm v2: $M \cong \frac{R}{(f_1)} \oplus \dots \oplus \frac{R}{(f_r)}$ where $f_i \neq 0, f_i \in R^x \forall i$.
& $f_1 | f_2 | \dots | f_r$. Furthermore, the sequence of ideals $(f_1), \dots, (f_r)$ is unique.

TODAY'S GOAL: Focus on the case of $\mathbb{K}[x]$ -modules, where \mathbb{K} is a field of characteristic 0 (in char p , perfect fields will be needed (see Math 6112))

Main results: Rational normal form decomposition for $\text{Mat}_{n \times n}(\mathbb{K})$
Jordan canonical form for $\text{Mat}_{n \times n}(\overline{\mathbb{K}})$ e.g. $\overline{\mathbb{K}} = \mathbb{C}$.

$K[x]$ -modules

Q: What is a $K[x]$ -module?

A: a K -vector space V

• multiplication by x defines a map $x \cdot : V \longrightarrow V$
 $m \longmapsto x \cdot m$

• $x \cdot$ is K -linear since $K[x]$ is commutative.

$$x \cdot (a \cdot m) = (x \cdot a) m = (a \cdot x) m = a \cdot (x \cdot m)$$

\downarrow Assoc. \downarrow $K[x]$ comm \downarrow Assoc.

Include: $K[x]$ -module \iff a K -vector space V + $\varphi \in \text{End}_K(V)$.

From now on, we assume V has $\dim_K V = n < \infty$.

So $\varphi \iff A \in \text{Mat}_{n \times n}(K)$ (matrix of the linear transf w.r.t a fixed basis)

Def $A, C \in \text{Mat}_{n \times n}(K)$: $A \sim C \iff \exists G \in \text{GL}_n(K)$ st $A = G^{-1} C G$

The minimal polynomial of A

\rightsquigarrow Define a map $\Psi: K[x] \longrightarrow K[A] \subset \text{End}_K(V)$
 $P(x) \longmapsto P(A)$

• What is $P(A)$? If $v \in V$, then:

$$P = \sum_{i=0}^N a_i x^i \rightsquigarrow P(A)(v) = \sum_{i=0}^N a_i (A^i)(v).$$

$\underbrace{A \circ \dots \circ A}_{i \text{ times}}$

• Ψ is a ring homomorphism, + K -linear

• $\text{Im } \Psi =$ subring of $\text{End}_K(V)$ generated by A & K .

• $\text{Ker } \Psi = ?$ Ideal of $K[x] = \text{PID}$ so $\text{Ker } \Psi = (f)$

Lemma: $\text{Ker } \Psi \neq (0)$ (\rightsquigarrow $f_A =$ monic gen of $\text{Ker } \Psi =$ *minimal polynomial*)

PF: $\text{Im } \Psi = K[A] \subseteq \text{End}_K(V) \simeq \text{Mat}_{n \times n}(K) \Rightarrow \dim_K K[A] < \infty$

• Ψ K -linear & $\dim_K K[x]$ infinite $\Rightarrow \text{Ker } \Psi \neq (0)$

□

Cyclic case

Def V is cyclic (as $K[x]$ -mod) if $\exists v \in V$ st $\{v, Av, A^2v, \dots\}$ spans V .

Proposition Assume $V \neq 0$ is cyclic. Then:

- (1) $\deg(q_A)$ is minimal $d > 0$ st $\{v, Av, \dots, A^d v\}$ is l.d., i.e.:
 - $\{v, Av, \dots, A^{d-1}v\}$ is l.i. $\&$ • $\{v, Av, \dots, A^d v\}$ is l.d.
- (2) Furthermore, in this situation $\{v, Av, \dots, A^{d-1}v\}$ is a basis for V .

Prf/ Since V is f. dim'd we have $\{v, Av, \dots, A^d v\}$ l.d. for some d

(2) Pick d minimal $A^d v \in \text{Span}(\underbrace{\{v, Av, \dots, A^{d-1}v\}}_{\text{l.i.}})$ & by induction on n $k \geq 0$ $A^{d+k} v \in \text{Span}(\{v, Av, \dots, A^{d-1}v\}) \Rightarrow V \subseteq \text{Sp}\{v, Av, \dots, A^{d-1}v\}$

\Rightarrow Basis claim follows

(1) Write a nontrivial l.d. relation:

$$a_0 v + a_1 Av + a_2 A^2 v + \dots + a_{d-1} A^{d-1} v + a_d A^d v = 0$$

Since $a_d \neq 0$, we can assume $a_d = 1$. Call: $h = \sum_{i=0}^{d-1} a_i x^i$

Claim: $h = \varphi_A$

BF/ (1) $h \in \text{Ker } \Psi$ ($h(A)v = 0, h(A)(Av) = Ah(A)v = 0,$
 $\dots, h(A)(A^l v) = A^l h(A)v = 0.$ $\Rightarrow h(A)|_V = 0$)
 $\Rightarrow h = \varphi_A g$ for $g \in K[x]$

$A \& h(A)$ commute
 \downarrow
 $A^l \& h(A)$ commute
 \downarrow
 $\exists v \{l \geq 0\}$ spans V

(2) If $\deg \varphi_A < \deg h = d \Rightarrow$ We would have a dependency relation
for $\{v, Av, A^2v, \dots, A^{d-1}v\}$ Contr!

Conclude: $\deg \varphi_A = \deg h$, $\varphi_A | h$ & both are monic $\Rightarrow \varphi_A = h$. □

Corollary 1: If V is cyclic and $\varphi_A = x^d + a_{d-1}x^{d-1} + \dots + a_1x + a_0$,
then in the basis $B = \{v, Av, \dots, A^{d-1}v\}$ we have:

$$[A]_{BB} = \begin{bmatrix} 0 & & & -a_0 \\ 1 & & & -a_1 \\ & \ddots & & \vdots \\ & & 1 & -a_{d-1} \end{bmatrix} = C_{\varphi_A} = \underline{\text{Companion matrix}} \text{ for the polynomial } \varphi_A$$

(Characteristic poly = φ_A)

Corollary 2: If V is cyclic, then: $V \cong \frac{K[x]}{f_A(x)}$ (as K -r.s.)

(Why? $K[x] \xrightarrow{\varphi} V$ is surj & $\ker \varphi = (f_A(x))$)
 $f(x) \mapsto f(v)$

Moreover $f_A(x)$ is independent of the choice of generator v for V
= an invariant of V .

(Reason: -Problem 6
HW10 $\frac{K[x]}{(f)} \cong \frac{K[x]}{(g)} \iff \deg f = \deg g$ (same dim!))

Q: What happens in the non-cyclic case?

Obs: $\dim_K V < \infty$, then V is a Torsion module over $K[x]$.

Why? $f_A(A) = 0 \in \text{End}_K(V)$, meaning $f_A(A)(v) = 0 \forall v \in V$
 $\implies \text{Ann}(V) \supseteq (f_A(x)) \neq (0)$.

A: Classification Theorems for f.g Torsion modules / $K[x]$.

Rational normal forms

Theorem 1: V \mathbb{K} -vector space & $A \in \text{End}_{\mathbb{K}}(V)$ $A \neq 0$. Then,

V admits a direct sum decomposition:

$$V = V_1 \oplus \dots \oplus V_r$$

where each V_i is a cyclic $\mathbb{K}[x]$ -module with invariants $f_i \neq 0$,

satisfying $f_1 \mid f_2 \mid \dots \mid f_r$

Furthermore, the sequence (f_1, \dots, f_r) is uniquely determined

by V & A & $f_r = f_A$.

BF/ Classification Theorem v2 gives the f_i 's. Uniqueness also follows

To finish: $\text{Ann}(V) = (f_A) \supseteq f_r$ since $f_i \mid f_r \ \forall i$

But $f_r \mid f_A$ since $f_A(x) \cdot V_r = 0$ so $f_r = f_A$ (both minic) \square

Corollary: V admits a basis B with

$$[A]_{BB} = \begin{bmatrix} \boxed{C_{q_1}} & & 0 \\ & \ddots & \\ 0 & & \boxed{C_{q_r}} \end{bmatrix} \quad C_{q_i} = \text{companion matrix for } q_i$$

This is known as the rational normal form for A . ($A \sim \text{RNF}(A)$)

Pr/ Pick v_i generator for $V_i \leadsto B_i = \{v, Av, \dots, A^{d_i-1}v\}$ with $d_i = \deg q_i$.
Then, take $B = B_1 \cup \dots \cup B_r$. □

Q: What about alternative Classification Thm?

We factor $q_A(x) = p_1^{n_1}(x) \cdots p_s^{n_s}(x)$ into distinct monic prime powers
(Everything is monic, so no unit is needed in the factorization)

Theorem 2 $V = V_{p_1^{n_1}} \oplus \cdots \oplus V_{p_r^{n_r}}$ & each $V_{p_i^{n_i}}$ decomposes further as

$$V_{p_i^{n_i}} \cong \bigoplus_{j=1}^{s_i} \frac{\mathbb{K}[x]}{(p_i^{y_j^{(i)}})} \quad n_i = y_1^{(i)} \geq \dots \geq y_{s_i}^{(i)} \quad (\text{sequence } y_j^{(i)} \text{ is unique})$$

Jordan canonical form

Assume $K = \overline{K}$, char 0 (Eg $K = \mathbb{C}$) Then $p_i \in K[x]$ irred & monic $\Rightarrow p_i = (x - \alpha_i)^{m_i}$

Each $\frac{K[x]}{(p_i)^{m_i}}$ piece gives a cyclic submodule $W_{p_i, m_i} \neq \{0\}$ of V of dimension m_i
 " $K[A] \langle w \rangle$

Theorem 3: W_{p_i, m_i} has a basis B over K such that

$$[A|_{W_{p_i, m_i}}]_B = \begin{bmatrix} \alpha_i & & & \\ & \ddots & & \\ & & \ddots & \\ & & & \alpha_i \end{bmatrix} = J(\alpha_i, m_i) \quad (m_i \times m_i \text{ matrix})$$

PF/

• Claim $B = \{ w, (A - \alpha)w, \dots, (A - \alpha)^{m-1}w \}$ is a basis for W_{p_i, m_i}

• LI: $(x - \alpha)^m$ is the minimal polynomial of W_{p_i, m_i} . (*)

(Any dependency will yield a polynomial g with $g(A)|_{W_{p_i, m_i}} = 0$)

• $\dim W_{p_i, m_i} = m = |B|$

• Note: $(A - \alpha)^{k+1}(w) = (A - \alpha)((A - \alpha)^k(w))$ yields $\left. \begin{array}{l} A(A - \alpha)^{k+1}(w) = (A - \alpha)^{k+1}(w) + \alpha(A - \alpha)^k(w) \\ (A - \alpha)^m(w) = 0 \text{ by } (*) \end{array} \right\} \Rightarrow [A|_{W_{p_i, m_i}}]_B = J(\alpha, m) \quad \square$

Corollary: Given V & A with $q_A = p_1^{n_1} \dots p_r^{n_r}$, \exists B basis for V s.t.

$$[A]_B = \begin{bmatrix} \boxed{A_1} & & 0 \\ & \ddots & \\ 0 & & \boxed{A_r} \end{bmatrix} \quad \text{block diagonal decmp.}$$

Furthermore for $p_i = (x - \alpha_i)$, we have.

$$A_i = \begin{bmatrix} \boxed{J(\alpha_i, m_{s_i}^{(i)})} & & 0 \\ & \ddots & \\ 0 & & \boxed{J(\alpha_i, m_{s_i}^{(i)})} \end{bmatrix} \quad \text{with } n_i = m_{s_i}^{(i)} \geq \dots \geq m_{s_i}^{(i)}$$

• This block decomposition is the Jordan canonical form of A