

Lecture 39: Bilinear forms II (Symmetric forms)

Last time: $\text{Bil}_{\mathbb{K}}(V_1, V_2, \mathbb{K}) = \text{Hom}_{\mathbb{K}}(V_1 \otimes V_2, \mathbb{K}) = (V_1 \otimes V_2)^*$

• $f \in \text{Bil}_{\mathbb{K}}(V_1, V_2, \mathbb{K})$ non-deg \Leftrightarrow induces linear injections

$$\begin{array}{ccc} V_1 & \xrightarrow{\varphi_1} & V_2^* \\ v & \longmapsto & f(v, -) \end{array} \quad \begin{array}{ccc} V_2 & \xrightarrow{\varphi_2} & V_1^* \\ v & \longmapsto & f(-, v) \end{array}$$

Prop: V_1, V_2 finite dimensional, f non-deg $\Rightarrow \dim V_1 = \dim V_2$

A: If $V_1 \cong \mathbb{K}^n \cong V_2$ write $B_1 = \{\vec{v}_1, \dots, \vec{v}_n\}$ basis for V_1
 $B_2 = \{\vec{w}_1, \dots, \vec{w}_n\}$ $\xrightarrow{\quad\quad\quad}$ V_2

$f \in \text{Bil}_{\mathbb{K}}(V_1, V_2, \mathbb{K}) \Leftrightarrow Q \in \text{Mat}_{n \times n}(\mathbb{K})$

$$f(v, w) = [v]_{B_1}^T Q [w]_{B_2} \iff Q_{ij} = f(v_i, w_j)$$

Note: $[\varphi_1]_{B_2, B_1^*} = Q^T$ $[\varphi_2]_{B_1, B_2^*} = Q$

Proposition: f is non-deg $\Leftrightarrow Q$ is invertible

Symmetric - Skew-symmetric & alternating forms

Def. We say f in $\text{Bil}(V, V, \mathbb{K})$ is

① symmetric if $f(v, w) = f(w, v) \quad \forall v, w \in V$

② skew-symmetric if $f(v, w) = -f(w, v) \quad \forall v, w \in V$

③ alternating if $f(v, v) = 0 \quad \forall v \in V$.

} same unless
char $\mathbb{K} = 2$

Ex ① Dot product on $V = \mathbb{R}^n$ is symmetric.

In general: $f(x, y) = x^T Q y$ with $Q = Q^T$ gives a symmetric bilinear form on \mathbb{K}^n

Ex ② $V = \mathbb{K}$ & $f(x, y) = xy$ is symmetric not alternating bilinear form. Skew symmetric when char $\mathbb{K} = 2$

Ex ③ $f((x, y), (x', y')) = xy' - x'y = \det \begin{pmatrix} x & x' \\ y & y' \end{pmatrix}$ is skew-symmetric & alternating bilinear form on \mathbb{R}^2

Ex ④ Pick $u \in \mathbb{R}^3$, $f_u(v, w) = u \cdot (v \times w)$ is alternating, skew-sym. form on \mathbb{R}^3 .

Ex ⑤ $\dim V = n < \infty$ & $W = \text{End}_{\mathbb{K}}(V) = \text{Mat}_{n \times n}(\mathbb{K})$

$f \in \text{Bil}(W, W, \mathbb{K})$ via $f(A, A') = \text{Tr}(AA')$ Trace form
symmetric by construction.

Ex ⑥ $V = C[0, 1] = \{f: [0, 1] \rightarrow \mathbb{R} \text{ cont.}\}$ inf-dim'd \mathbb{R} -v.s.

• $F: V \times V \rightarrow \mathbb{R}$ via $F(g, h) = \int_0^1 g(x)h(x) dx$

F is a symmetric bilinear form.

• Pick $k: [0, 1]^2 \rightarrow \mathbb{R}$ continuous:

$F_k: V \times V \rightarrow \mathbb{R}$ via $F_k(g, h) = \iint_{[0, 1]^2} g(x)h(y)k(x, y) dx dy$

• F_k bilinear but not symmetric. (unless k is).

Lemma: $f \in \text{Bil}(K^n, K^n, K)$ with associated matrix Q . Then

① f is symmetric if & only if $Q = Q^T$ (symmetric matrix)

② f is skew-symmetric if & only if $Q^T = -Q$ (skew-sym matrix)

③ f is alternating if & only if $Q^T = -Q$ & $Q_{ii} = 0 \forall i$.

Proposition: $\text{Bil}(V, V, K) \underset{\varphi}{\cong} \text{Bil}^{\text{Sym}}(V, V, K) \oplus \text{Bil}^{\text{Skew-Sym}}(V, V, K)$

($\Leftrightarrow \text{char } K \neq 2$)

$$\text{Pf/ } \varphi(f) = f_1 + f_2$$

$$f_1(v, w) = \frac{f(v, w) + f(w, v)}{2}$$

$$f_2(v, w) = \frac{f(v, w) - f(w, v)}{2}$$

□

Alternative: $(V \otimes V)^* \cong V^* \otimes V^* \cong S^2(V^*) \oplus \Lambda^2(V^*)$

Lemma: If $\text{char } K \neq 2$ $\dim V < \infty$, then $f \in \text{Bil}^{\text{Sym}}(V, V, K)$

is completely determined by $f(v, v) \forall v \in V$.

$$\begin{aligned} \text{Pf/ } f(v+w, v+w) &= f(v, v+w) + f(w, v+w) = f(v, v) + f(v, w) + f(w, v) + f(w, w) \\ &= f(v, v) + 2f(v, w) + f(w, w) \end{aligned}$$

$$\text{So } f(v, w) = (f(v+w, v+w) - f(v, v) - f(w, w)) / 2$$

□

Q: How to work with degenerate symm. forms in $\text{Bil}(V, V, K)$?

Same idea works for skew-symmetric forms.

A: Given $f \in \text{Bil}^{\text{sym}}(V, V, K)$, & $v \in V$, set

$$v^\perp = \{w \in V \mid f(v, w) = 0\}$$

$$\text{Rad}(f) = \{v \mid f(v, -) = 0 \in V^*\} \subseteq V \text{ subspace.}$$

If $V' = \frac{V}{\text{Rad}(f)}$ View $V = W \oplus \text{Rad}(f)$ (via a section)
with $W \cong V'$

Claim: $f|_{W \times W}$ is non-deg

PF/ The matrix for f has the form

$$\begin{pmatrix} W & \text{Rad}(f) \\ \hline Q & 0 \\ 0 & 0 \end{pmatrix} \begin{matrix} W \\ \text{Rad}(f) \end{matrix}$$

by symmetry $\rightarrow f(v, -) = 0 \quad \forall v \in \text{Rad}(f)$

If $w \in \ker(\varphi_1: W \rightarrow W^*)$
 $w' \mapsto f(w, w')$

then $f(w, w') = 0 \quad \forall w' \in W$.

But $f(w, v) = 0 \quad \forall v \in \text{Rad}(f)$

} $f(w, v) = 0 \quad \forall v \in V$
so $w \in \text{Rad}(f)$

Conclude $w \in W \cap \text{Rad}(f) = 0$, so $\varphi_1: W \hookrightarrow W^*$.

Since f is symmetric $\varphi_2: W \hookrightarrow W^*$ as well. □

Classification of real symmetric forms

GOAL Classify symmetric non-deg bilinear forms on $V \cong \mathbb{R}^n$ via invariants

STEP 1: Degenerate vs non-degenerate

① 1st invariant = rank of $f = \text{rk}([F]) = \dim V - \dim \text{Rad}(f)$

STEP 2: Classify non-deg symm forms = Sylvester's Thm

Sylvester's Theorem: Fix $f: V \times V \rightarrow \mathbb{R}$ non-deg symmetric bil form

Then \exists basis $B = \{e_1, \dots, e_n\}$ of V s.t. $f(e_i, e_j) = \pm \delta_{ij}$

Moreover, the # of > 0 is independent of the basis.

Def Signature(f) = # 1's (For degenerate forms = (# 1's, # -1's))

② 2nd invariant = signature of f



• Proof involves 2 parts (1) Building basis $B \leftrightarrow$ Gram-Schmidt algorithm

(2) S is indep of $B \Rightarrow$ invariant of f

Part 1: Find $B = \{\varepsilon_1, \dots, \varepsilon_n\}$ basis for \mathbb{R}^n with $f(\varepsilon_i, \varepsilon_j) = \pm \delta_{ij}$

STEP 1 Gram-Schmidt algorithm: INPUT: $\{v_1, \dots, v_n\}$ basis for $V \simeq \mathbb{R}^n$

OUTPUT: $\{w_1, \dots, w_n\}$ basis for $V \simeq \mathbb{R}^n$
with $f(w_i, w_j) = 0$ if $i \neq j$

- $w_1 = v_1 \neq 0$ so $f(w_1, w_1) \neq 0$. 
- Fix $1 \leq k < n$ & assume we've constructed $\{w_1, \dots, w_k\}$ satisfying
 - ① $\text{Sp}(v_1, \dots, v_k) = \text{Sp}(w_1, \dots, w_k) \Rightarrow \{w_1, \dots, w_k\}$ li
 - ② $w_i \neq 0$ & $f(w_i, w_j) = 0 \quad \forall i \neq j, 1 \leq i, j \leq k$ ($\Rightarrow f(w_i, w_i) \neq 0 \forall i$) 

Then $w_{k+1} = v_{k+1} - \sum_{i=1}^k \frac{f(w_i, v_{k+1})}{f(w_i, w_i)} w_i$

So $f(w_j, w_{k+1}) = f(w_j, v_{k+1} - \sum_{i=1}^k \frac{f(w_i, v_{k+1})}{f(w_i, w_i)} w_i)$
 $= f(w_j, v_{k+1}) - \sum_{i=1}^k \frac{f(w_i, v_{k+1})}{f(w_i, w_i)} f(w_j, w_i)$
 $= f(w_j, v_{k+1}) - \frac{f(w_j, v_{k+1})}{f(w_i, w_i)} f(w_i, w_i) = 0$
only $i=j$ survives

By construction: ① $\text{Sp}(v_1, \dots, v_{k+1}) = \text{Sp}(w_1, \dots, w_{k+1})$, so $\{w_1, \dots, w_{k+1}\}$ is li.

② $w_i \neq 0 \quad \forall i$ & $f(w_i, w_j) = 0 \quad \forall i \neq j, 1 \leq i, j \leq k$. \square

We have $\{w_1, \dots, w_n\}$ basis for \mathbb{R}^n with $f(w_i, w_j) = 0 \quad \forall i \neq j$


STEP 2: Set $S = \#\{i : f(w_i, w_i) > 0\}$. Then, reorder $\{w_1, \dots, w_n\}$ so

$$\begin{cases} f(w_i, w_i) > 0 & \text{for } i < S \\ f(w_i, w_i) < 0 & \text{for } i > S \\ (\neq 0 \text{ because } f \text{ is non-deg}) \end{cases} \implies \text{Define } \boxed{\varepsilon_j} = \begin{cases} \frac{w_j}{\sqrt{f(w_j, w_j)}} & \text{for } j < S \\ \frac{w_j}{\sqrt{-f(w_j, w_j)}} & \text{for } j > S \end{cases}$$

Then: $\{\varepsilon_1, \dots, \varepsilon_n\}$ is a basis for \mathbb{R}^n , $f(\varepsilon_i, \varepsilon_j) = 0 \quad \forall i \neq j$ &

$$f(\varepsilon_j, \varepsilon_j) = \begin{cases} 1 & \text{for } j = 1, \dots, S \\ -1 & \text{for } j = S+1, \dots, n \end{cases} \quad \square$$

Part 2: Show S is an invariant of f . (Next time!)

 Step one fails if at any point $f(w_i, w_i) = 0$. Next time we will discuss an alternative proof that works.