

Jan 8

Chapter 1 of book

- Solving simultaneous systems of linear equations
- meaning of linear
- Matrices;
- Gaussian elimination & row echelon form
- Matrix Multiplication

Chapter 2:

- Vectors in $\mathbb{R}^2$ & $\mathbb{R}^3$
- Dot product

Chapter 3

- The vector space $\mathbb{R}^n$, subspaces
 - Span of set of vectors
 - linear independence, basis dimension
 - Linear transformations = Matrix Multiplication
-

Vectors in plane or space

Algebraic vector in plane
= ordered pair of real
numbers $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$

in space = ordered triple

Addition: $v + w$

Scalar Multiplication: $c \in \mathbb{R}$

$c \in \mathbb{R}$

length:

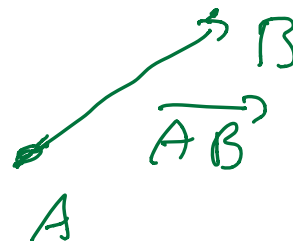
Geometric vectors:

difference between 2 pts

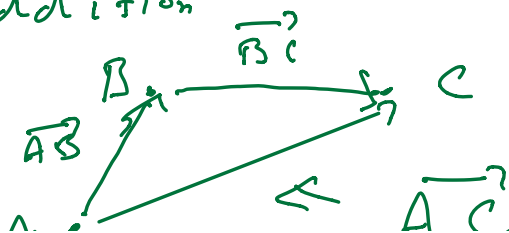
$$A = (a_1, a_2)$$

$$B = (b_1, b_2)$$

$$\overrightarrow{AB} = \begin{bmatrix} b_1 - a_1 \\ b_2 - a_2 \end{bmatrix}$$



Geometric Interpretation of
Addition

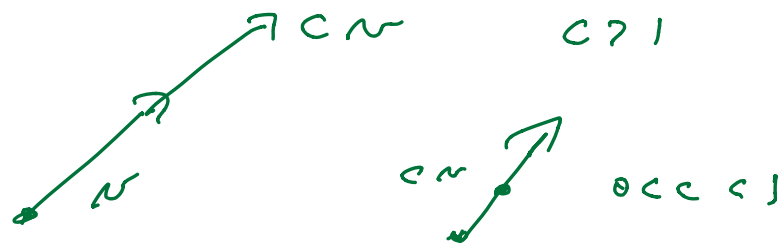


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Scalar Mult



Basic Properties of Addition
+ Scalar mult.

- $(u + v) + w = u + (v + w)$
- $u + v = v + u$
- $\exists$ a vector $\vec{0}$ ($= \begin{bmatrix} 0 \\ 0 \end{bmatrix}$)
s.t. $v + \vec{0} = \vec{0} + v$
- For any v , $\exists$ vector $-v$
s.t. $v + (-v) = \vec{0}$

Scalar Mult. $r, s \in \mathbb{R}$

- $r(su) = (rs)'u$
 - $r(u+v) = ru + rv$
-

Jan 10

Vectors in $\mathbb{R}^2$ & $\mathbb{R}^3$

- linear combination
(2 vectors in $\mathbb{R}^3$)
- Standard basis for $\mathbb{R}^2, \mathbb{R}^3$

- Other basis for $\mathbb{R}^2$

say $\begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

Write $\begin{bmatrix} 5 \\ 8 \end{bmatrix}$ as linear combination of these 2 vectors

i.e. solve linear system.

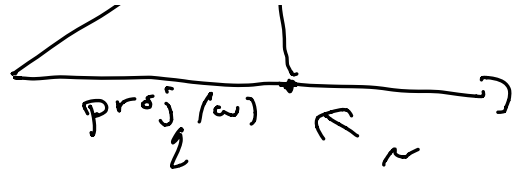
- linear independence

- Dot Product. $\vec{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$

$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ $\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2$

- $\text{proj}_{\vec{q}}(\vec{w}) = \vec{r}$





$$\begin{aligned}\text{proj}_z(w) &= \frac{w \cdot z}{\|z\|^2} z \\ &= \frac{(\cos \theta) \|w\| \|z\|}{\|z\|} \frac{z}{\|z\|}\end{aligned}$$

$$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos \theta$$



• What does $\vec{u} \cdot \vec{v} = 0$ mean?

Def

A linear combination of a set of vectors say in $\mathbb{R}^3$, $\{\vec{v}_1, \dots, \vec{v}_n\}$ is combination

$$c_1 \vec{v}_1 + \dots + c_n \vec{v}_n$$

where $c_i \in \mathbb{R}$

Set of all linear combination $\{ r \vec{v}_1 + s \vec{v}_2 \}$ is a plane passing through, called Span of $\{ \vec{v}_1, \vec{v}_2 \}$

Def $\{ v_1, \dots, v_k \}$ is basis for $\mathbb{R}^n$ mean

- $\text{Span} \{ v_1, \dots, v_k \} = \mathbb{R}^n$
 - $\{ v_1, \dots, v_k \}$ is lin independent
-

Ex In $\mathbb{R}^2$
 $\{\vec{v}, \vec{w}\}$ is basis

means

- Any $\vec{u}$ is a linear combination.
- $r\vec{v} + p\vec{w} = \vec{0}$
has only trivial solut
 $r=0, p=0$

Jan 12

Assignment 2 (due Jan 24)

2.4: 2, 4, 10, 22

3.1: 8, 15, 16, 19

3.2: 1, 2, 3, 4, 10, 27, 28

3.7: 4, 7

1.1: 2, 5, 6, 8

Dot product of 2 vectors
in $\mathbb{R}^n$, say $n=2$ or 3

$$\vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} \quad \vec{w} = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix}$$

$$\vec{v} \cdot \vec{w} = v_1 w_1 + v_2 w_2 + v_3 w_3$$

Basic Properties: $\vec{v} \cdot \vec{w}$ is
symmetric, bilinear form:

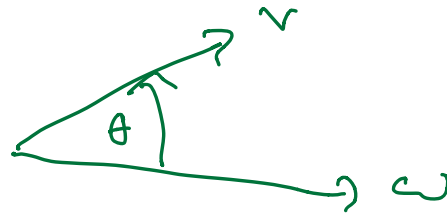
- $u \cdot (v+w) = u \cdot v + u \cdot w$
 $(v+w) \cdot u = v \cdot u + w \cdot u$
- $c \in \mathbb{R} \quad u \cdot (cv) = c(u \cdot v)$
 $(cu) \cdot v = c(u \cdot v)$
- $u \cdot v = v \cdot u$ (symmetric)

$$\text{Also, } \vec{v} \cdot \vec{v} = v_1^2 + v_2^2 + v_3^2 \geq 0$$

$$= |\vec{v}|^2 \quad (= \|\vec{v}\|^2)$$

Key Formula: $\vec{v} \cdot \vec{w} = |\vec{v}| |\vec{w}| \cos \theta$

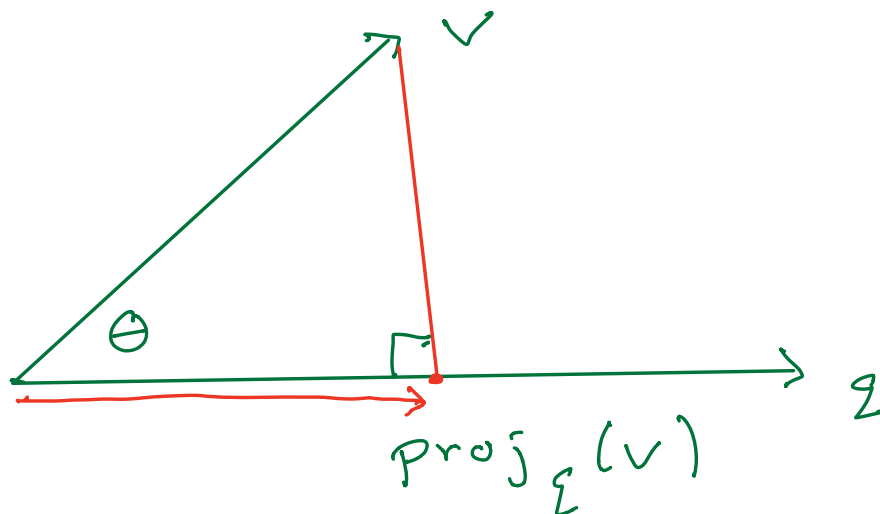
Def'n $\vec{v}, \vec{w}$ are orthogonal
if $\vec{v} \cdot \vec{w} = 0$



Orthogonal projection

v and z are vectors

Define $\text{proj}_z(v)$ the
orthogonal projection of v
in direction z



$$X = \text{proj}_{\vec{q}} (\vec{v})$$

$$|X| = |\vec{v}| |\cos \theta|$$

X should be parallel to $\vec{q}$

$$\begin{aligned} X &= \frac{(\vec{q} \cdot \vec{v})}{(\vec{q} \cdot \vec{q})} \vec{q} \\ &= \frac{|\vec{q}| |\vec{v}| \cos \theta}{|\vec{q}|^2} \vec{q} \end{aligned}$$

Ex $\vec{q} = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$ $\vec{v} = \begin{bmatrix} 2 \\ 1 \\ -3 \end{bmatrix}$

$$\begin{aligned} \text{Then } X &= \text{proj}_{\vec{q}} (\vec{v}) = \frac{\vec{v} \cdot \vec{q}}{\vec{q} \cdot \vec{q}} \vec{q} \\ &= \begin{pmatrix} -4 \\ -1 \\ 5 \end{pmatrix} \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} -4/5 \\ 0 \\ -8/5 \end{bmatrix} \end{aligned}$$

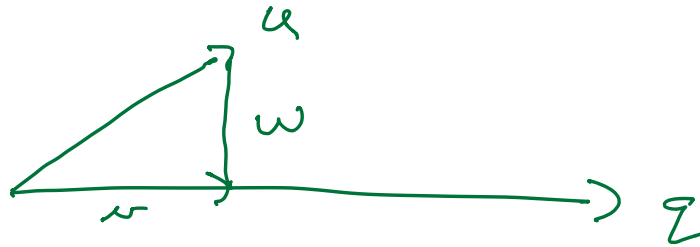
Problem : Given vector u

write it as sum of 2

vectors $u = v + w$ where

$$v \cdot w = 0$$

Ans



$$v = \text{proj}_L(u)$$

$$w = u - v$$

Check $v \cdot w = 0$

$$v \cdot (u - v) = v \cdot u - v \cdot v \stackrel{?}{=} 0$$