Bordifications of hyperplane arrangements and their curve complexes

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Abstract

The complement of an arrangement of hyperplanes in \( \mathbb{C}^n \) has a natural bordification to a manifold with corners formed by removing (or “blowing up”) tubular neighborhoods of the hyperplanes and certain of their intersections. When the arrangement is the complexification of a real simplicial arrangement, the bordification closely resembles Harvey’s bordification of moduli space. We prove that the faces of the universal cover of the bordification are parameterized by the simplices of a simplicial complex \( C \), the vertices of which are the irreducible “parabolic subgroups” of the fundamental group of the arrangement complement. So, the complex \( C \) plays a similar role for an arrangement complement as the curve complex does for moduli space. Also, in analogy with curve complexes and with spherical buildings, we prove that \( C \) has the homotopy type of a wedge of spheres. Our results apply in particular to spherical Artin groups, where the associated arrangement is a reflection arrangement of a finite Coxeter group.

Introduction

Background. A “compactification” of a possibly noncompact manifold \( X^\circ \) is a compact manifold with boundary \( X \) so that \( X^\circ \) is identified with the interior of \( X \). For example, \( X^\circ \) could be a finite volume hyperbolic manifold and \( X \) the manifold with boundary obtained by adding a flat manifold as a boundary component for each cusp. Let \( Y^\circ \) denote the universal cover of \( X^\circ \) and \( Y \) the universal cover of \( X \), then \( Y \) is called a “bordification” of \( Y^\circ \). Put \( G = \pi_1(X^\circ) = \pi_1(X) \). There are some classical examples of locally symmetric manifolds and various moduli spaces each of which can be compactified to manifold with corners (in fact, the compactification has the extra property of being a “manifold with faces” as in Subsection 1.2). Here are two basic examples.

(I) (The Borel–Serre compactification of an arithmetic manifold). Suppose \( G = \text{GL}(n, \mathbb{Z}) \), \( Y^\circ = O(n) \backslash \text{GL}(n, \mathbb{R}) \) and \( X^\circ = Y^\circ / G \). (For \( X \) to be a manifold rather than an orbifold, we actually should replace \( G \) by a torsion-free subgroup of finite index.) Siegel [52] described a \( G \)-equivariant bordification of \( Y^\circ \) to a manifold with faces \( Y \). This was then generalized to other arithmetic groups in the foundational paper of Borel–Serre [5].

(II) (The Harvey compactification of moduli space). Suppose that \( S_{g,n} \) is a surface, possibly with boundary, of genus \( g \) and with \( n \) punctures, \( G = \text{Mod}(g,n) \) the corresponding mapping class group, \( Y^\circ \) the corresponding Teichmüller space and \( X^\circ = Y^\circ / G \) the corresponding moduli space. In [34] Harvey defined a \( G \)-equivariant bordification \( Y \) of \( Y^\circ \).
In both cases, $Y$ is a manifold with faces. Let $C$ be the nerve of the covering of $\partial Y$ by the codimension-one boundary faces of $Y$: the $(k-1)$-simplices of $C$ correspond to the boundary faces of codimension $k$ in $Y$.

In both cases, $C$ admits an alternative group theoretic description. In case (I) $C$ can be identified with the Tits building $B$ for $GL(n, \mathbb{Q})$ (see [5, Theorem 8.4.1]), where $B$ can be defined from the poset of parabolic subgroups of $G$. In case (II), $C$ is isomorphic to the curve complex $C(S_{g,n})$ for the surface $S_{g,n}$ [34], where $C(S_{g,n})$ can be described in terms of subgroups of $G$: each vertex of $C$ corresponds to an infinite cyclic subgroup of $G$ generated by a Dehn twist along a simple close curve of $S_{g,n}$. A $(k-1)$-simplex in $C$ corresponds to a family of $k$ commuting Dehn twists $\mathbb{Z}$-subgroups.

In both cases (I) and (II), the simplicial complex $C$ has the homotopy type of a wedge of spheres [34, 53]. Moreover, $Y$ as well as each of its boundary faces is contractible.

**Algebraic and topological versions of curve complexes.** Let $A$ be a finite arrangement of linear hyperplanes in $\mathbb{C}^n$ and let $\mathcal{M}(A)$ denote the complement of the union of these hyperplanes. We assume for simplicity that $A$ is irreducible, that is, $A$ is not the direct sum of two arrangements. Let $X^\circ$ be the intersection of $\mathcal{M}(A)$ with the unit sphere of $\mathbb{C}^n$. So, $\mathcal{M}(A)$ is homeomorphic to $X^\circ \times [0, \infty)$. Our goal in this paper is to develop a picture for $X^\circ$ and $G = \pi_1(X^\circ)$ similar to the compactifications of Borel–Serre and Harvey. We are particularly interested in the case where $G$ is a pure Artin group of spherical type and $A$ is the associated arrangement of reflection hyperplanes. A standard way to attach a boundary to $X^\circ$ is to remove from $\mathbb{C}^n$ an algebraic regular neighborhood of the union of hyperplanes in $A$ as in Durfee [28] (since the union of hyperplanes is an algebraic subset of $\mathbb{C}^n$). This gives a well-defined manifold with boundary $(X, \partial X)$. However, we want to give $X$ the structure of a smooth manifold with corners. The manifold with corners structure is not canonical, as discussed below it depends on a choice of a certain subset of the intersection poset of the arrangement, this subset is called a “building set” in [25]. The manifold with corners structure on $X$ induces further structure on $\partial X$, namely, a decomposition of $\partial X$ into boundary pieces (the codimension-one faces of $X$) corresponding to the elements of the chosen building set.

In concrete terms, we want to accomplish the following.

(a) Define a natural bordification of $X^\circ$ to a manifold with corners $X$, the universal cover of which is denoted by $Y(A)$.

(b) Define an analog of curve complex $C_{\text{top}}$ ($= C_{\text{top}}(A)$) as the nerve of the covering of $\partial Y$ by its boundary pieces.

(c) Define another analog of curve complex $C_{\text{alg}}$ ($= C_{\text{alg}}(A)$) from an algebraic viewpoint by looking at commutation of certain $\mathbb{Z}$-subgroups of $G$.

(d) Prove that $C_{\text{top}}$ and $C_{\text{alg}}$ are isomorphic.

(e) Prove that $C_{\text{alg}}$ is homotopy equivalent to a wedge of spheres.

The simplicial complex $C_{\text{alg}}$ captures the intersection pattern of certain collection of abelian subgroups in $G$. In the study of symmetric spaces, mapping class groups and right-angled Artin groups, the analogous simplicial complex has been fundamental to understanding the asymptotic geometry of $G$.

Point (d) is the link between the topology of $Y(A)$ and the simplicial complex $C_{\text{alg}}$. We do not know the extent to which points (c), (d), and (e) hold for general hyperplane arrangements; however, they all hold for the complexifications of real simplicial arrangements as studied by Deligne [26] and this covers the case where $G$ is a pure Artin group of spherical type. Most of this paper is devoted to proving (d) for such arrangements. In the remainder of the introduction we elaborate points (a)–(e).

Let $V = \mathbb{C}^n$. Suppose that $\mathcal{Q}(A)$ denotes the set of subspaces of $V$ that occur as intersections of hyperplanes in $A$. The set $\mathcal{Q}(A)$, partially ordered by inclusion, is the intersection poset
of \( \mathcal{A} \). The idea for constructing the bordification of \( \mathcal{M}(\mathcal{A}) \) as in (a) is to remove tubular neighborhoods of a collection of subspaces \( \mathcal{S} \subseteq \mathcal{Q}(\mathcal{A}) \). (Each hyperplane of \( \mathcal{A} \) is required to belong to \( \mathcal{S} \).) Actually, rather than removing tubular neighborhoods, it is better to attach boundary pieces to \( \mathcal{M}(\mathcal{A}) \) where the boundary piece corresponding to a subspace \( E \in \mathcal{S} \) is the normal sphere bundle of \( E \) restricted to arrangement complement \( \mathcal{M}(\mathcal{A}^E) \), where \( \mathcal{A}^E \) means the restriction of \( \mathcal{A} \) to \( E \). In order for this process to yield a bordification of \( \mathcal{M}(\mathcal{A}) \) which is independent of various choices, it is necessary for \( \mathcal{S} \) to be a “building set” in the sense of De Concini–Procesi [25]. The details of this construction are carried out by Gaiffi in [32].

A subspace \( E \) is irreducible if the normal arrangement \( \mathcal{A}_{V/E} \) to \( E \) is irreducible, that is, if the induced arrangement on \( V/E \) does not decompose as a nontrivial direct sum. The bordification of \( \mathcal{M}(\mathcal{A}) \) with \( \mathcal{S} \) being the set of irreducible subspaces induces a compactification \( X \) of \( X^e \). Motivated by the examples of locally symmetric spaces and moduli spaces, define a simplicial complex \( C_{\text{top}}(\mathcal{A}) \) to be the nerve of the covering of \( \partial Y \) by the codimension-one faces of the universal cover \( Y \) of \( X \). We call this the topological curve complex of \( \mathcal{A} \).

There is also an algebraic version of the curve complex that can be defined in terms of commuting families of \( \mathbb{Z} \)-subgroups of \( G = \pi_1(\mathcal{M}(\mathcal{A})) \). Given a subspace \( E \in \mathcal{Q}(\mathcal{A}) \) with normal arrangement \( \mathcal{A}_{V/E} \) the image of \( \pi_1(\mathcal{M}(\mathcal{A}_{V/E})) \) in \( G \) is a parabolic subgroup of \( G \) of type \( E \) (cf. Definition 1.11 in Section 1); the parabolic subgroup is irreducible if \( \mathcal{A}_{V/E} \) is irreducible. Each irreducible parabolic subgroup has a well-defined central \( \mathbb{Z} \)-subgroup corresponding to the Hopf fiber coming from the action of \( \mathbb{C}^\ast \) on \( \mathcal{M}(\mathcal{A}) \). Such a \( \mathbb{Z} \)-subgroup is analogous to the subgroup of \( \text{Mod}(g,n) \) generated by a Dehn twist. Take these central \( \mathbb{Z} \)-subgroups of irreducible parabolic subgroups to be the vertices of simplicial complex; two vertices are connected by an edge if and only if the corresponding \( \mathbb{Z} \)-subgroups commute; the algebraic curve complex \( C_{\text{alg}}(\mathcal{A}) \) is the associated flag complex. In other words, \( C_{\text{alg}}(\mathcal{A}) \) is the flag complex associated to the “commutation graph” of these central \( \mathbb{Z} \)-subgroups. (see [39] for the analogous notion for right-angled Artin groups).

In the special case when \( G \) is a pure spherical Artin group, \( C_{\text{alg}} \) coincides with the “complex of irreducible parabolic subgroups” defined by Cumplido, Gebhardt, González-Meneses, and Wiest in [13].

One advantage of defining \( C_{\text{alg}} \) in the more general setting of hyperplane complements is that the stabilizer of a simplex of \( C_{\text{alg}} \) is again the fundamental group of \( \mathcal{M}(\mathcal{A}') \) where \( \mathcal{A}' \) is an arrangement with fewer hyperplanes. When \( \mathcal{A} \) is the complexification of a real simplicial arrangement, the same is true for \( \mathcal{A}' \). This gives a convenient inductive method of studying \( G \). On the other hand, if one restricts to the class of pure spherical Artin groups, then it is not clear that stabilizer of a simplex of \( C_{\text{alg}} \) is commensurable to another pure spherical Artin group, since the restriction of a Coxeter arrangement might not be a Coxeter arrangement.

Both \( C_{\text{top}} \) and \( C_{\text{alg}} \) admit simplicial \( G \)-actions; in both cases the quotient complex can be characterized in terms of irreducible subspaces of \( \mathcal{A} \) (cf. Definition 1.4). In this generality it seems possible, albeit unlikely, that the topological and algebraic versions of curve complex are always equal. However, we can verify this whenever \( \mathcal{A} \) is the complexification of a central real simplicial arrangement. In this case we also deduce that \( C_{\text{alg}} \) is homotopy equivalent to a wedge of spheres.

Statements of the results.

**Main Theorem** (Theorem 5.12 in the sequel). Suppose that \( \mathcal{A} \) is the complexification in \( \mathbb{C}^n \) of real simplicial arrangement and that \( \mathcal{A} \) has \( l \) irreducible factors, \( \mathcal{A} \cong \mathcal{A}_1 \oplus \cdots \oplus \mathcal{A}_l \). Let \( X \) be the \((2n-l)\)-dimensional manifold with corners discussed above and let \( Y \) be its universal cover. The following statements are true.

(i) The algebraic and topological versions of the curve complex \( C_{\text{alg}} \) and \( C_{\text{top}} \) are identical (and we denote this simplicial complex by \( C \)).
Let $A_W$ be the spherical Artin group associated to a finite Coxeter group $W$ and let $S$ be the standard generating set of $A_W$. A parabolic subgroup of $A_W$ is any conjugate of a subgroup generated by a subset of $S$. The pure Artin group $PA_W$ is the kernel of $A_W \to W$. Associated to the Coxeter group $W$ there is a reflection arrangement $A_W$ of hyperplanes in $\mathbb{C}^n$ so that $\pi_1(M(A_W)) = PA_W$. The bordification of $M(A)$ is homotopy equivalent to the compact manifold with corners $X = X(A_W)$ described as above. Let $Y$ be the universal cover of $X$. The group $W$ acts freely on $X$ and the fundamental group of $X/W$ is $A_W$. So $A_W$ acts on $Y$ by an action that permutes the boundary faces. The arrangement $A_W$ is known to be simplicial; so, the Main Theorem can be applied. Hence, $A_W \rtimes C_{\text{top}}(A_W) = C_{\text{alg}}(A_W)$.

In [13] a similar simplicial complex $C(A_W)$ is defined for the full Artin group $A_W$ rather than just for the pure Artin group $PA_W$. As before, $C(A_W)$ is defined using centers of irreducible parabolic subgroups of $A_W$. Since irreducible parabolic subgroups of $A_W$ correspond to parabolic subgroups arising from irreducible subspaces in $Q(A_W)$, there is an $A_W$-equivariant isomorphism from between $C_{\text{alg}}(A_W)$ and $C(A_W)$. So, we have the following corollary of the Main Theorem.

**Corollary.** Suppose that the spherical Artin group $A_W$ has $l$ irreducible factors. Then the complex $C(A_W)$ of [13] is homotopy equivalent to a wedge of $(n - l - 1)$-spheres.

This paper differs from [13] in that the curve complex is not only defined algebraically as the complex of irreducible parabolics, but it also has a topological interpretation as the nerve of the cover of the boundary of its bordification. This provides the extra information in the above corollary.

**Remarks on the braid arrangement $A_{n-1}$.** Let $M_{0,n+1}$ be the moduli space of complex structures on $S_{0,n+1}$, the $(n + 1)$-punctured 2-sphere. Let $A_{n-1}$ be the arrangement of type $A_{n-1}$ in $\mathbb{C}^{n-1}$ (this is the braid arrangement for the braid group on $n$ strands). The following statements are true.

- Start with the Harvey compactification $X'$ of $M_{0,n+1}$ and take its universal cover $Y'$. Then the nerve of the covering of $\partial Y'$ by its codimension-one faces is isomorphic to the curve complex of $S_{0,n+1}$, see [34].
- Let $X$ be the bordification of $M(A_{n-1})$ discussed above (see Definition 1.15 for more details). The natural action of $C^* = \mathbb{C} - \{0\}$ on $M(A_{n-1})$ extends to $C^* \rtimes X$. Then $X'$ and $X/C^*$ are diffeomorphic as smooth manifolds with corners, see [38] and also [31, Section 4].
- The algebraic curve complex for the arrangement $M(A_{n-1})$ is canonically isomorphic to the curve complex of $S_{0,n+1}$.

So, Harvey’s result can be reinterpreted as saying that the topological curve complex for $A_{n-1}$ as defined above is isomorphic to its algebraic curve complex.
**Discussion of the proof.** We begin with the isomorphism between $C_{\text{alg}}$ and $C_{\text{top}}$. The starting point (step 0) is to reduce this isomorphism problem to a collection of purely group theoretic properties of $G = \pi_1(X)$.

Start with an arbitrary central arrangement $A$ of hyperplanes in $V = \mathbb{C}^n$ and let $G = \pi_1(M(A))$. Given an irreducible subspace $E$, let $A^E$ and $A_{V/E}$ denote, respectively, the restriction of the arrangement to $E$ and its normal arrangement. There are natural homomorphisms $f_1 : \pi_1(M(A^E)) \to G$, $f_2 : \pi_1(M(A_{V/E})) \to G$ and $f_3 : \pi_1(M(A^E \times A_{V/E})) \to G$ where $f_3 = f_1 \times f_2$. Here $f_1$ induced by pushing off $M(A^E)$ from $E$ into $V$ so that it sits inside $M(A)$, and $f_2$ is obtained by considering arrangement in a normal disk at a point in $E$. The image of $f_2$ is an irreducible parabolic subgroup and the central $\mathbb{Z}$-subgroup of $\text{Im} f_2$ corresponds to the Hopf fiber in $M(A_{V/E})$. In Section 1.4 we define the following four properties.

(a) Property A asserts $f_1$ is injective. (Since there is a retraction $M(A) \to M(A_{V/E})$, $f_2$ is always injective.)

(b) Property B concerns intersections of images of the homomorphisms $f_3$ arising for different irreducible subspaces.

(c) Property C states that $\text{Im} f_3$ is the normalizer of the central $\mathbb{Z}$-subgroup in $\text{Im} f_2$.

(d) Property D characterizes when two central $\mathbb{Z}$-subgroups commute.

In Proposition 1.27 we show that when these properties hold, there is a canonical isomorphism between $C_{\text{alg}}$ and $C_{\text{top}}$. This works for any central arrangement $A$.

The proof of the Main Theorem uses several facts special to real simplicial arrangements. First, since the arrangements $A^E$ and $A_{V/E}$ also are complexifications of real simplicial arrangements, it follows from Deligne [26] that each of the arrangement complements $M(A)$, $M(A^E)$, and $M(A_{V/E})$ is aspherical. Second, Salvetti [49] defined a finite CW complex that is homotopy equivalent to $M(A)$ (this only requires that $A$ is real). Finally, in his proof of asphericity in [26], Deligne used ideas of Garside concerning the word problem in the associated “Deligne groupoid.”

The first step of the proof of the theorem is to reduce Properties A–D to properties concerning subcomplexes of Salvetti complexes and their Deligne groupoids. (For this step to work we need $A$ to be a real arrangement; however, it need not to be simplicial.) It is obvious that $\text{Im} f_2$ can be represented as the fundamental group of a subcomplex of the Salvetti complex; however, this is less clear for $\text{Im} f_1$. We find a certain subset of the Salvetti complex whose fundamental group corresponds to $\text{Im} f_1$ (this subset is very close to being a subcomplex). This reduces the verification Properties A–D to computations in the one skeleton of the Salvetti complex, which is the underlying graph for the Deligne groupoid.

The second step of the proof is to prove versions of Properties A–D for the Deligne groupoid. (For this step to work we need $A$ to be a simplicial arrangement so that Garside theory is available.) A simple reduction shows that we only need to prove Properties A, C, and D. For spherical Artin groups, Properties C and D were proved previously in [13, 46]. Our proof of Properties C and D is along the same line as in [13, 46]; however, our treatment is more geometric and works for any simplicial arrangement. We also prove Property A for simplicial arrangements.

We speculate that these properties hold outside the realm of simplicial arrangements. For example, there are partial results on Properties A and C for supersolvable arrangements [48].

To prove part (iii) of the Main Theorem we need to show that $C_{\text{top}}$ (or $C_{\text{alg}}$) is a wedge of spheres. For a general $A$ it follows from previous work on the cohomology of $M(A)$ in [20, 54] that $C_{\text{top}}$ has the same homology as a wedge of spheres. So, in order to show that $C_{\text{alg}}$ is homotopy equivalent to a wedge of spheres, it suffices to show that $C_{\text{alg}}$ (or $C_{\text{top}}$) is simply connected whenever its dimension is $> 1$. That $C_{\text{top}}$ is simply connected is a consequence
of standard result on arrangement complements, see Remark 1.28 below. We also give an independent elementary proof that $C_{\text{alg}}$ is simply connected in Subsection 4.2.

Structure of the paper. In Section 1 we discuss hyperplane arrangements and their compactifications, and we explain Properties A–D. Section 2 gives background on zonotopes, Salvetti complexes, and Deligne groupoids. Section 3 concerns Garside-theoretic computations in Deligne groupoids, and completes the argument in the second step of the proof of the Main Theorem. Section 4 concerns the proof that $C_{\text{alg}}$ is simply connected when its dimension is $> 1$. This is needed in the proof that it is homotopy equivalent to a wedge of spheres. In Section 5 the first step of the proof is finished and the results are tied together.

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1. Bordifications of complements of hyperplane arrangements

1.1. Hyperplane arrangements

A hyperplane arrangement in a complex vector space $V$ is a collection $\mathcal{A}$ of linear hyperplanes in $V$. The set of linear subspaces that can be obtained as intersections of elements of $\mathcal{A}$ is called the intersection poset; it is denoted by $\hat{Q}(\mathcal{A})$ or simply by $\hat{Q}$. The partial order is inclusion. The ambient space $V$ (corresponding to the empty intersection) is the maximum element of $\hat{Q}$. The set of proper subspaces in $\hat{Q}$ is denoted by $Q(\mathcal{A})$. The arrangement $\mathcal{A}$ is essential if the zero subspace $0$ lies in $Q(\mathcal{A})$, that is, if $0$ is the intersection of all hyperplanes in $\mathcal{A}$. If $\mathcal{A}$ is essential, then put $Q_0 := Q - 0$.

The normal arrangement to a subspace $E \in Q(\mathcal{A})$ is the hyperplane arrangement $\mathcal{A}_{V/E}$ in $V/E$ defined by

$$\mathcal{A}_{V/E} := \{ H/E \mid H \in \mathcal{A} \text{ and } E \subseteq H \}. \quad (1.1)$$

There is also an arrangement $\mathcal{A}^E$, called the restriction of $\mathcal{A}$ to $E$, defined by

$$\mathcal{A}^E := \{ H \cap E \mid H \in \mathcal{A} \text{ and } E \nsubseteq H \}. \quad (1.2)$$

If $E' < E$ is another subspace in $Q(\mathcal{A})$, then the image of $\mathcal{A}^{E'}$ in $\mathcal{A}_{E'/E}$ is a subnormal arrangement to $E$, that is, It is the arrangement in $E'/E$ defined by

$$\mathcal{A}_{E'/E} = \{ H/E \mid H \in \mathcal{A}^{E'} \text{ and } E \subseteq H \}. \quad (1.3)$$

The complement in $V$ of the union of hyperplanes in $\mathcal{A}$ is denoted by $\mathcal{M}(\mathcal{A})$. Notice that if $SV$ is the sphere of directions in $V$, then we have a homeomorphism

$$\mathcal{M}(\mathcal{A}) \cong (SV \cap \mathcal{M}(\mathcal{A})) \times (0, \infty). \quad (1.4)$$

Remark 1.1. In later sections we will consider arrangements which are obtained by complexifying an arrangement of real hyperplanes in a real vector space (a “real arrangement”). For example, any finite Coxeter group has a representation as a linear reflection group on $\mathbb{R}^n$. The resulting hyperplane arrangement in $\mathbb{C}^n$ is called a reflection arrangement.

Irreducible subspaces. Suppose that $\mathcal{A}'$ and $\mathcal{A}''$ are arrangements in vector spaces $V'$ and $V''$. Their direct sum $\mathcal{A}' \oplus \mathcal{A}''$ is the arrangement in $V' \oplus V''$ consisting of hyperplanes which are the form of a sum of a hyperplane in one summand with the other summand, that is, $\mathcal{A}' \oplus \mathcal{A}'' := \{ H' \oplus V'', V' \oplus H'' \mid H' \in \mathcal{A}', H'' \in \mathcal{A}'' \}$. An arrangement is irreducible if it cannot be decomposed as a nontrivial direct sum. Any arrangement $\mathcal{A}$ in $V$ can be decomposed into its
irreducible factors $A_1, \ldots, A_k$, where $A_i$ is irreducible in $V_i$. That is to say, $A \cong A_1 \oplus \cdots \oplus A_k$ and $V \cong V_1 \oplus \cdots \oplus V_k$. It follows from (1.4) that

$$\mathcal{M}(A) \cong \left( \prod_{i=1}^{k} SV_i \cap \mathcal{M}(A_i) \right) \times (0, \infty)^k. \quad (1.5)$$

A subspace $E \in \mathcal{Q}(A)$ is reducible if its normal arrangement in $V/E$ splits as a nontrivial direct sum. In other words, $E$ is reducible if there are subspaces $E', E''$ in $\mathcal{Q}(A)$ such that $E = E' \cap E''$ and $\mathcal{A}_{V/E} \cong \mathcal{A}_{V/E'} \oplus \mathcal{A}_{V/E''}$. A subspace $E \in \mathcal{Q}(A)$ is irreducible if it is not reducible. For example, any hyperplane $H \in \mathcal{A}$ is an irreducible subspace. Any subspace $E \in \mathcal{Q}$ has a decomposition into irreducibles. This means that there are irreducible subspaces $E_1, \ldots, E_k$ such that

$$E = E_1 \cap \cdots \cap E_k \quad \text{and} \quad \mathcal{A}_{V/E} \cong \bigoplus_{i=1}^{k} \mathcal{A}_{V/E_i}.$$ 

Up to order, the summands are uniquely determined.

**Remark 1.2.** Suppose $A \cong A_1 \oplus \cdots \oplus A_k$ with $V \cong V_1 \oplus \cdots \oplus V_l$ is the decomposition of $A$ into irreducibles. Let $E_i$ be the subspace of the direct sum with $i$-component equal to the zero vector and with $j$-component, $j \neq i$, equal to the subspace $V_j$. Then $E_i$ is irreducible; moreover, it is a minimal irreducible with respect to the partial order on $\mathcal{Q}(A)$.

**Definition of the complex of irreducibles.** We shall define a simplicial complex $\mathcal{I}$ ($= \mathcal{I}(A)$) that encodes the intersection pattern of the irreducible subspaces. Its vertex set $\mathcal{I}^{(0)}$ ($= \mathcal{I}^{(0)}(A)$) is the set of irreducible subspaces $E \in \mathcal{Q}$. So, $\mathcal{I}^{(0)}$ is a subposet of $\mathcal{Q}$. A set of two vertices $\{E, E'\}$ determines a 1-simplex $\alpha$ in $\mathcal{I}$ in exactly two cases: either $E$ and $E'$ are comparable (which means that $E < E'$ or $E' < E$), or the normal arrangement to $E \cap E'$ is reducible. This describes a simplicial graph $\mathcal{I}^1$ that is the 1-skeleton of the complex which we wish to define. The complex of irreducibles $\mathcal{I}$ is the flag complex associated to the graph $\mathcal{I}^1$. One can directly describe the simplices of $\mathcal{I}$ as being the “nested subsets” of $\mathcal{I}^{(0)}$ defined below.

**Definition 1.3** (cf. [25], as well as, [29], [23, p. 1308]). A subset $\alpha$ of $\mathcal{I}^{(0)}$ is nested if for any subset $\{E_i\}$ of $\alpha$ consisting of pairwise incomparable elements, the intersection $F = \bigcap E_i$ is reducible and $\mathcal{A}_{V/F} \cong \bigoplus_{i=1}^{k} \mathcal{A}_{V/E_i}$. A subset $\alpha$ of $\mathcal{I}^{(0)}$ is the vertex set of a simplex in $\mathcal{I}$ if and only if it is nested. (We shall often confuse a simplex with its vertex set.) Call a simplex $\beta \in \mathcal{I}$ purely incomparable if its vertex set consists entirely of incomparable elements.

**Definition 1.4.** If $A$ is irreducible (that is, if $0$ is an irreducible subspace in $\mathcal{Q}$), then let $\mathcal{I}_0(A)$ denote the full subcomplex of $\mathcal{I}(A)$ spanned by $\mathcal{I}^{(0)} - \{0\}$. In general, if $A = A_1 \oplus \cdots \oplus A_l$ is the decomposition of $A$ into irreducible factors, then $\mathcal{I}_0(A)$ is defined to be the join:

$$\mathcal{I}_0(A) = \mathcal{I}_0(A_1) * \cdots * \mathcal{I}_0(A_l).$$

Since $\mathcal{I}(A_i)$ is equal to the cone, $\mathcal{I}_0(A_i) * 0_i$, where $0_i$ denotes the cone point, we see that $\mathcal{I}(A) = \mathcal{I}_0(A) * \Delta^{l-1}$, where $\Delta^{l-1}$ is the $(l-1)$-simplex on $\{0_1, \ldots, 0_l\}$. The reason that we are interested in $\mathcal{I}_0(A)$ is that its simplices index the boundary faces of the compact manifold with corners $X$ (cf. Definition 1.24 below.)

**Remark 1.5.** Feichtner and Müller prove in [29] that $\mathcal{I}(A)$ has a subdivision isomorphic to $|Q(A)|$ (where $|Q(A)|$ denotes the geometric realization of the order complex of $Q(A)$). So, when $A$ is irreducible, $\mathcal{I}_0(A)$ is homeomorphic to $|Q_0(A)|$. A classical result of Folkman [30]
asserts that $|Q_0(A)|$ is a wedge of spheres of dimension $n - 2$, where $n = \dim V$. Hence, when $A$ is irreducible $I_0(A)$ is a wedge of spheres of the same dimension. When $A$ has $l$ irreducible factors, it then follows from Definition 1.4 that $\dim I_0(A) = n - l - 1$ and that $I_0(A)$ is a wedge of $(n - l - 1)$-spheres.

**Definition 1.6.** Using the poset structure of $I^{(0)}$ the vertices of a simplex $\alpha$ of $I$ can be organized into a forest as follows. The minimal elements of $\text{Vert} \alpha$ are said to be at level 0. Suppose, by induction, that the notion of level $\alpha$ is as follows. The minimal elements of $\text{Vert} \alpha$ is homeomorphic to the complement of the affine arrangement $\hat{A}$, factors, it then follows from Definition 1.4 that $\dim I_0(A) = n - l - 1$ and that $I_0(A)$ is a wedge of $(n - l - 1)$-spheres.

**Lemma 1.7.** Suppose that $A$ is an essential, central hyperplane arrangement with irreducible decomposition $A = A_1 \oplus \cdots \oplus A_k$. Put $G = \pi_1(M(A))$ and let $Z(G)$ be its center.

1. The center $Z(G)$ contains a free abelian subgroup of rank $k$.
2. If $M(A)$ is aspherical, then $Z(G) \cong \mathbb{Z}^k$.

**Question 1.8.** Is it always true that $Z(G) \cong \mathbb{Z}^k$?

Sketch of proof of Lemma 1.7. The fundamental group of the complement of any central arrangement has a $Z$ in its center coming from the Hopf fiber. Hence, if $A$ has $k$ irreducible factors, then $Z^k \subset Z(G)$.

Next suppose that $M(A)$ is aspherical and that $A$ is irreducible. Let $\mathbb{P}A$ be the associated projective arrangement and $M(\mathbb{P}A)$ its complement in projective space. Since $M(A) \cong C^* \times M(\mathbb{P}A)$, we see that $M(\mathbb{P}A)$ is also aspherical. Also, if $Z$ is a proper subgroup of $Z(G)$, then the center $C$ of $\pi_1(M(\mathbb{P}A))$ is nontrivial. Since $M(\mathbb{P}A)$ is aspherical, this implies that its Euler characteristic is 0. (If a group of type $F$ has a nontrivial normal abelian subgroup, then its Euler characteristic is 0.) A theorem of Crapo (cf. [11]) asserts that if $A'$ is an arrangement of affine hyperplanes and if the complement $M(A')$ has Euler characteristic 0, then $A'$ decomposes as $A'' \times A_1$, where $A_1$ is a nontrivial central arrangement (cf. [23, Section 5.3]). Since $M(\mathbb{P}A)$ is homeomorphic to the complement of the affine arrangement $A'$ obtained by regarding one of the hyperplanes of $\mathbb{P}A$ as being a hyperplane at $\infty$, Crapo's theorem implies that $A'$ splits off another central arrangement $A_1$. But this contradicts the assumption that $A$ is irreducible. Hence, the Euler characteristic of $M(A')$ must be 0; so, $C$ must be trivial. The case when $A$ is irreducible immediately implies (2) in the general case when $A$ has more than one irreducible factors.

**Definition of parabolic subgroups and the algebraic curve complex.** Let $E \in Q(A)$ be a subspace. Let $D$ be a small disk about $E/E$ in $V/E$. Then $D \cap M(A_{V/E})$ is homeomorphic to $M(A_{V/E})$. Since $D$ can regarded as a normal disk to $E$ at a point in $M(E^4)$, we see that when $D$ is sufficiently small, $D \cap M(A_{V/E})$ is a subset of $M(A)$. Composing the inclusion with the inverse of a homeomorphism $D \cap M(A_{V/E}) \cong M(A_{V/E})$, we get $i : M(A_{V/E}) \rightarrow M(A)$. The set of hyperplanes $A_{V/E}$ can be identified with the set $A_E := \{H \in A \mid E \subseteq H\}$ and $M(A_E)$ is homeomorphic to $E \times M(A_{V/E})$. Since $A_E \subset A$, we have an inclusion $M(A) \hookrightarrow M(A_E)$. The composition of this inclusion with the natural projection $M(A_E) \rightarrow M(A_{V/E})$ gives the retraction $r : M(A) \rightarrow M(A_{V/E})$. The following is clear.

**Lemma 1.9.** The composition $M(A_{V/E}) \xrightarrow{i} M(A) \rightarrow M(A_E) \rightarrow M(A_{V/E})$ is homotopic to the identity map. Thus $i : M(A_{V/E}) \rightarrow M(A)$ is $\pi_1$-injective.
COROLLARY 1.10. If $\mathcal{M}(\mathcal{A})$ is aspherical, then so is $\mathcal{M}(\mathcal{A}_{V/E})$ for any $E \in \mathcal{Q}$.

DEFINITION 1.11. Let $i : \mathcal{M}(\mathcal{A}_{V/E}) \to \mathcal{M}(\mathcal{A})$ be the inclusion map defined above. Take a base point $x \in \mathcal{M}(\mathcal{A})$ and $x' \in \mathcal{M}(\mathcal{A}_{V/E})$. Let $\gamma$ be a path from $x \to i(x')$. A parabolic subgroup of $G = \pi_1(\mathcal{M}(\mathcal{A}), x)$ of type $E$ is a subgroup that is conjugate to $\gamma(i_*(\pi_1(\mathcal{M}(\mathcal{A}_{V/E}), x')))\gamma^{-1}$. The parabolic subgroup is irreducible (respectively, proper) if the subspace $E$ is irreducible (respectively, if $E \neq \{0\}$).

EXAMPLE 1.12. If $\mathcal{A}$ is a finite reflection arrangement, then $G$ is the corresponding pure spherical Artin group. If $E$ is the fixed subspace of a subset of the Artin generators, then, up to conjugation, the parabolic subgroup $P_E$ associated with $E$ coincides the usual notion of a parabolic subgroup of $G$, that is, the intersection with $G$ and the subgroup of the Artin group generated by this subset of the generators (cf. [13]). The parabolic subgroup $P_E$ is irreducible if the normal representation $\mathcal{A}_{V/E}$ is irreducible or equivalently, if the Coxeter group corresponding to $E$ has a connected Coxeter diagram (cf. [19]).

Let $\text{Par}(G)$ denote the set of parabolic subgroups of $G$ and let $\text{IPar}(G)$ be the subset of irreducible parabolics. For any irreducible parabolic subgroup $P$ of type $E$, define its central $\mathbb{Z}$-subgroup to be

$$Z_P := \text{Ker}[\pi_1(\mathcal{M}(\mathcal{A}_{V/E})) \to \pi_1(\mathcal{M}(\mathcal{P}_{A_{V/E}}))].$$

In other words, $Z_P$ is the subgroup of $\pi_1(\mathcal{M}(\mathcal{A}_{V/E}))$ corresponding to the Hopf fiber. By Lemma 1.7, if $\mathcal{M}(\mathcal{A})$ is aspherical, then $Z_P$ is equal to the center of $P$.

Let $H_1 = H_1(\mathcal{M}(\mathcal{A}), \mathbb{Z})$. Then $H_1$ has a basis of form $\{e_H\}_{H \in \mathcal{A}}$ where $e_H$ is the 1-cycle corresponding to a positively oriented loop around a hyperplane $H$. If $Z_P$ is the central $\mathbb{Z}$ subgroup of an irreducible parabolic subgroup $P$ of type $E$, then its image in $H_1$ can be written as an integral combination of basis elements: $\sum n_H e_H$. In fact, $n_H$ is either 1 or 0 depending on whether or not the hyperplane $H$ contains $E$. Putting $\text{supp } Z_P = \{H \in \mathcal{A} \mid n_H \neq 0\}$ we see that $\text{supp } Z_P$ depends only on the conjugacy class of $Z_P$ (or of $P$). Moreover, since $\text{supp } Z_P = \mathcal{A}_E$, the conjugacy class of $Z_P$ determines the subspace $E$. So, we have established the following lemma.

LEMMA 1.13. Suppose that $Z$ and $Z'$ are the central $\mathbb{Z}$ subgroups of irreducible parabolic subgroups $P$ and $P'$. If $Z$ and $Z'$ are conjugate in $G$, then type $P = \text{type } P'$. In particular, each central $\mathbb{Z}$-subgroup has a well-defined type.

DEFINITION 1.14. We define a simplicial complex $\mathcal{C}_{\text{alg}}$, called the algebraic curve complex, as follows. First suppose that the arrangement $\mathcal{A}$ is irreducible. The vertex set of $\mathcal{C}_{\text{alg}}$ is in one-to-one correspondence with central $\mathbb{Z}$-subgroup of irreducible proper parabolic subgroups of $G$. Two vertices $v'$ and $v$ are connected by an edge if the corresponding $\mathbb{Z}$-subgroups generate a subgroup isomorphic to $\mathbb{Z} \oplus \mathbb{Z}$. This defines the algebraic curve graph. The algebraic curve complex will be the completion of this graph to a flag complex. The algebraic curve complex for a reducible arrangement is the join of the algebraic curve complex of its irreducible components.

It follows from Lemma 1.13 that each vertex of $\mathcal{C}_{\text{alg}}$ has a well-defined type, which is an element in $\mathcal{I}^{(0)}$.

Now we describe certain collection of edges in $\mathcal{C}_{\text{alg}}$. Take irreducible subspaces $E$ and $E'$. If $E < E'$, then for appropriate choices of base points and paths connecting them, we can find parabolic subgroups $P$ and $P'$ of type $E$ and $E'$, respectively, such that $P' < P$. This implies that the infinite cyclic subgroups $Z_P$ and $Z_{P'}$ commute (since $Z_P$ commutes with everything in $P$) and that they generate a free abelian subgroup of rank 2 (since they do so in $H_1$). If $E \cap E'$
reducible, that is, \( \mathcal{A}_{V/E} \oplus \mathcal{A}'_{V/E} \) is a decomposition of \( \mathcal{A}_{V/(E \cap E')}' \), then for appropriate choices of base points we find parabolic subgroups \( P \) and \( P' \) such that \( Z_P \) and \( Z_{P'} \) commute. However, in general, it is not clear whether all edges of \( C_{\text{alg}} \) arise in these two situations.

\subsection*{1.2. Blowing up subspaces}

Definition of a manifold with faces. A topological \( n \)-manifold with boundary is a smooth manifold with corners if it is locally differentiably modeled on open sets in \([0, \infty)^n\). Suppose that \( X \) is an \( n \)-manifold with corners. If a point \( x \in X \) has local coordinates \((x_1, \ldots, x_n) \in [0, \infty)^n\), then denote by \( c(x) \) the number of indices \( i \) such that \( x_i = 0 \). (This number is independent of the choice of local coordinates.) A “stratum” of \( X \) of codimension \( k \) means a connected component of \( \{ x \in X \mid c(x) = k \} \). So, a codimension-zero stratum of \( X \) is a component of the interior \( X - \partial X \) and \( \partial X \) is the union of the strata of \( X \) of codimension \( \geq 1 \). A point \( x \in X \) lies in the closures of at most \( c(x) \) strata of codimension one. Call \( X \) a manifold with faces if each point \( x \in X \) is in the closure of exactly \( c(x) \) codimension-one strata. When this is the case, the closure of a codimension-\( k \) stratum is a face of \( X \) of codimension \( k \). A face of \( X \) is itself a manifold with faces. A covering space of a manifold with faces is naturally a manifold with faces. A prototypical example of an \( n \)-manifold with faces is a \( n \)-dimensional simple convex polytope \( P \) where a “face” of \( P \) has its usual meaning.

A closed subset \( Y \subset X \) is a submanifold with faces if the induced smooth structure on \( Y \) is that of a manifold with corners (say, of dimension \( m \)) and if for any codimension-\( k \) face \( F \) of \( X \), \( Y \) intersects \( F \) transversely in a disjoint union of codimension-\( k \) faces of \( Y \). It follows that \( Y \) is itself an \( m \)-dimensional manifold with faces. In particular, taking \( k = 0 \) we see that \( Y - \partial Y \) is an \( m \)-dimensional submanifold of \( X - \partial X \).

Let \( \mathcal{V}(X) \) denote the set of codimension-one faces of \( X \). Consider the nerve \( \mathcal{N} (= \mathcal{N}(X)) \) of the cover of \( \partial X \) by the codimension-one faces of \( X \). It is a simplicial complex with vertex set \( \mathcal{V}(X) \) where a \((k - 1)\)-simplex \( \alpha \) of \( \mathcal{N} \) corresponds to a collection of \( k \) codimension-one faces with nonempty intersection. Any such intersection is a disjoint union of codimension-\( k \) faces. There is a related cell complex \( \Delta(X) \) which differs from \( \mathcal{N} \) in that it can have “multiple simplices.” For example, if \( X \) has two codimension-one faces \( \partial_0 X \) and \( \partial_1 X \) and \( \partial_0 X \cap \partial_1 X \neq \emptyset \), then \( \mathcal{N}(X) \) consists of a single edge connecting 0 to 1; however, in \( \Delta(X) \) there is an edge for each component of the intersection. In general, the poset of faces in \( \partial X \) is anti-isomorphic to the poset of cells in a cell complex \( \Delta(X) \). The vertex set of \( \Delta(X) \) is \( \mathcal{V}(X) \) and each codimension \( k \) face determines a \((k - 1)\)-simplex in \( \Delta(X) \). So, there is a natural map \( \Delta(X) \to \mathcal{N}(X) \) whose restriction to each simplex is a homeomorphism. However, since multiple simplices can have the same vertex set, we see that \( \Delta(X) \) is only a \( \Delta \)-complex in the sense of [35].

Say that \( X \) has the connected intersection property if each intersection of codimension-one faces is either empty or contains a single face. When this holds, the natural map \( \Delta(X) \to \mathcal{N}(X) \) is an isomorphism and so, \( \Delta(X) \) is a simplicial complex. Note, however, that it might happen that \( X \) has the connected intersection property, while a covering space \( Y \) does not. This is the issue we shall be concerned with in Subsection 1.4.

Blowing up subspaces and submanifolds. In this paragraph we explain a method for canonically “removing an open tubular neighborhood” of a submanifold \( Y \) in a manifold \( M \) without mentioning the phrase “\( e \) neighborhood.” The resulting manifold with boundary \( M \odot Y \) is a bordification of \( M - Y \) called the blowup of \( M \) along \( Y \). We consider some simple examples of this process. First consider the case where \( M \) is a vector space \( V \) and \( Y \) is the zero subspace \( 0 \). The sphere in \( V \) can be defined as the quotient space \( SV := (V - 0)/\mathbb{R}_+ \), where the positive real numbers \( \mathbb{R}_+ \) act on \( V - 0 \) via scalar multiplication. Define the blowup \( V \odot 0 \) by

\[
(V \odot 0) := (V - 0) \times_{\mathbb{R}_+} [0, \infty) \cong SV \times [0, \infty).
\]
Note that \( \partial(V \odot 0) = SV \times 0 \). A slight generalization is the case where \( M = V \) and \( Y = E \) is a linear subspace of \( V \). Then \( V - E = E \times (V/E - 0) \) and
\[
(V \odot E) := E \times \{(V/E - 0) \times \mathbb{R}_+ [0, \infty)\} = E \times S(V/E) \times [0, \infty).
\]
(1.6)

There is another approach to the definition of the blowup \( V \odot E \), which we shall generalize in the next subsection. Define a map \( \rho : V - E \to V \times S(V/E) \) as follows. The first component of \( \rho \) is the inclusion \( V - E \to V \). Its second component is the composition of projections \( V - E \to (V/E) - (E/E) \to S(V/E) \). One sees that the closure of the image of \( \rho \) can be identified with the blowup, that is,
\[
V \odot E \cong \overline{\text{Im} \rho}.
\]
(1.7)

Essentially, the blowup \( V \odot E \) is the only case with which we need be concerned; however, there are some slightly more general situations. If \( N \) is a vector bundle over a smooth manifold \( Y \), then its sphere bundle \( SN \) is defined by \( SN = (N - Y)/\mathbb{R}_+ \), where \( \mathbb{R}_+ \) acts on the complement of the 0-section \( N - Y \) via fiberwise scalar multiplication. The cylinder bundle \( CN \) is then defined by
\[
CN := (N - Y) \times \mathbb{R}_+ [0, \infty) = SN \times [0, \infty).
\]
Thus, \( N \odot Y := CN \) is a bordification of \( N - Y \). In general, suppose that \( Y \) is a smooth submanifold of a manifold \( M \) and that \( N \) is its normal bundle. Our discussion follows [37] or [15]. By a tubular map we mean a diffeomorphism \( T : N \to M \) onto an open neighborhood of \( Y \) such that (1) the restriction of \( T \) to the 0-section is the inclusion and (2) at any \( y \in Y \), under the natural identification \( T_y N = T_y M \), the differential of \( T \) is the identity map. A tubular map \( T \) induces a function \( T' : CN \to (M - Y) \sqcup SN \) and there is a unique structure of a smooth manifold with boundary on \((M - Y) \sqcup SN\) which agrees with the original structure on \( M - Y \) so that \( T' \) takes \( CN \) onto a collared neighborhood of \( SN \). We denote this manifold with boundary, \( M \odot Y \), and call it the blowup of \( M \) along \( Y \). It is diffeomorphic to a complement of an open tubular neighborhood of \( Y \) in \( M \). Note that \( \partial(M \odot Y) = SN \).

Finally, suppose that \( Y \) is a submanifold with faces of a manifold with faces \( X \). Then the previous paragraph goes through mutatis mutandis. First, there is a normal vector bundle \( N \) over \( Y \) such that for any face \( F \) of \( X \), the restriction \( N|_{Y \cap F} \) is the normal bundle of \( Y \cap F \) in \( F \). As before, we get a new manifold with faces \( X \odot Y \) that has acquired a new codimension-one face, namely, \( SN \). Moreover, each face \( F \) of \( X \) with \( F \cap Y \neq \emptyset \) has a bordification \( F \odot (Y \cap F) \) that also has acquired a new codimension-one face, namely, \( SN|_{Y \cap F} \). Thus, \( F \odot (Y \cap F) \) is a submanifold with faces of \( X \odot Y \). This generality will allow us, in the next subsection, to iterate the blowing up procedure to certain sequences of submanifolds.

### 1.3. Attaching a boundary to the complement of a hyperplane arrangement

Our goal in this subsection is to construct a bordification of \( \mathcal{M}(\mathcal{A}) \), where, as usual, \( \mathcal{M}(\mathcal{A}) \) is the complement of an arrangement \( \mathcal{A} \) of linear hyperplanes in a complex vector space \( V \). The idea is to blow up the subspaces belonging to some subset \( \mathcal{S} \) of \( \mathcal{Q}(\mathcal{A}) \). In order for the result to be a manifold with faces, this subset \( \mathcal{S} \) must be a “building set” as defined in [25], [21], or [29]. One of the main requirements for a subset to be a building set is that it contains all the irreducible elements in \( \mathcal{Q}(\mathcal{A}) \). One possible choice is to take the building set to be all of \( \mathcal{Q}(\mathcal{A}) \). Another possible choice is to take the building set to be \( \mathcal{I}^{(0)}(\mathcal{A}) \), the set of irreducibles in \( \mathcal{Q}(\mathcal{A}) \). This second choice is the one we make throughout this paper.

**Method 1: The closure of an embedding.** This method is the easiest to define. Its disadvantage is that it is not so clear that it actually results in a smooth manifold with corners.
The simplest definition of the blowup is similar to one in [25, p. 461], see also [32]. Let $S$ be a collection of linear subspaces of $V$. Consider the embedding

$$\rho : V - \left( \bigcup_{E \in S} E \right) \to V \times \prod_{E \in S} S(V/E),$$

where the first component of $\rho$ is the inclusion and the component in $S(V/E)$ is the natural projection (which is defined since $V - E \subset V - (\bigcup_{E \in S} E)$). Note that if $S$ contains all hyperplanes $H \in \mathcal{A}$, then the domain of $\rho$ is $M(\mathcal{A})$. In a similar fashion, one can define

$$\rho_S : SV - \left( \bigcup_{E \in S} SE \right) \to SV \times \prod_{E \in S} S(V/E).$$

**Definition 1.15.** As in (1.7), define $V \odot S$ (respectively, $SV \odot S$) to be the closure of the image of $\rho$ (respectively, $\rho_S$). If $S = \mathcal{T}(0)$, we write simply $V \odot$ (respectively, $SV \odot$) instead of $V \odot S$ (respectively, $SV \odot S$).

**Remark 1.16.** In [25] De Concini and Procesi use complex projective spaces $\mathbb{P}(V/E)$ rather than spheres $S(V/E)$ so that $M(\mathcal{A})$ is partially compactified by adding a divisor with normal crossings to $M(\mathcal{A})$ rather than a boundary.

Now we introduce the notion of building set, cf. [32, Definition 2.1], which goes back to [25]. Let $\mathcal{Q}(S)$ be the collection of subspaces of $V$ formed by intersection of elements of $S$. In this paper we will be only interested in the case when $\mathcal{Q}(S) = \mathcal{Q}(\mathcal{A})$ (that is, $S$ is a subset of $\mathcal{Q}(\mathcal{A})$ which contains all the hyperplanes in $\mathcal{A}$). For subspaces $F, F' \in \mathcal{Q}(\mathcal{A})$, put

$$S_F := \{ E \in S | F \leq E \},$$

$$S^F := \{ F \cap B | B \in S - S_F \},$$

$$S^E_{F'} := \{ B \cap F | B \in S_{F'} - (S_{F'} \cap S_F) \}.$$

Choose an inner product on $V$. Then for any $F \in \mathcal{Q}(\mathcal{A})$ we can identify with its orthogonal complement $F^\perp$ with $V/F$. The set $S$ is a building set if for any $E \in \mathcal{Q}(\mathcal{A})$, we have a decomposition

$$E = E_1 \cap \cdots \cap E_k \quad \text{and} \quad \mathcal{A}_{V/E} \cong \bigoplus_{i=1}^k \mathcal{A}_{V/E_i},$$

where $E_1, \ldots, E_k$ are the minimal elements of $S_F$ (with respect to the partial order on $\mathcal{Q}(\mathcal{A})$). It follows that any building set $S$ must contain the set of irreducibles $\mathcal{T}(0)$. It also follows that $\mathcal{T}(0)$ is a building set.

The following lemma is an immediate consequence of the definition.

**Lemma 1.17.** Suppose that $S$ is a building set. For each $E \in \mathcal{Q}(\mathcal{A})$, both $S^E_F$ and $S^E_{F'}$ are buildings sets (with respect to $\mathcal{Q}(\mathcal{A}^E)$ and $\mathcal{Q}(\mathcal{A}_{V/E})$, respectively).

**Theorem 1.18** (Gaiffi [32, Theorem 4.5]). Suppose that $S$ is a building set. Then $V \odot S$ (respectively, $SV \odot S$) are smooth manifolds with faces. In particular, when $S = \mathcal{T}(0)$, this applies to $V_\odot$ and $SV_\odot$. 
By Theorem 1.18 and Lemma 1.17, the blowups \( S(V/E) \circ S_E^{k+} \), \((SE) \circ S^E\), and \( E \circ S^E\) are smooth manifolds with faces. Before describing the faces of \( SV_\circ\) in detail, we consider an example which might clarify the picture.

**Example 1.19 (Line arrangements in \( \mathbb{CP}^2\)).** Suppose that \( \mathcal{A} \) is an irreducible arrangement in a 3-dimensional vector space \( V \) and that we plan to blow up \( SV \) along the building set of irreducibles to get a 5-manifold with corners \( SV_\circ\). Projectivizing \( \mathcal{A} \) we get a projective arrangement \( PA \) of lines in the 2-dimensional projective space \( PV \). Take the corresponding blowup of \( PV \) to get a 4-manifold with corners \( Z = PV_\circ\). Since \( SV_\circ = S^1 \times Z \), it suffices to describe \( Z \). There are two types of irreducible subspace in \( Q(PA) \): (a) lines (that is, projective hyperplanes in \( PA \)) and (b) intersection points where at least 3 lines intersect. (A double point corresponds to a reducible subspace.) In either case, the corresponding codimension-one face of \( Z \) is the product of \( S^1 \) and a surface with boundary of genus 0 (that is, a 2-sphere with holes). These are glued together along the codimension-two faces (= boundary tori). Hence, \( \partial Z \) is a graph manifold. The JSJ-decomposition of \( \partial Z \) corresponds to the decomposition of \( \partial Z \) into its codimension-one faces. Hence, \( \partial(SV_\circ) \) is the product of \( S^1 \) with a 3-dimensional graph manifold.

Next we describe the strata of \( V \circ S \) for a building set \( S \). Its codimension-zero stratum is \( \mathcal{M}(\mathcal{A}) \). Each element \( E \in S \) gives rise to a codimension-one stratum of \( V \circ S \) as follows. Let \( p : V \circ S \to V \) (respectively, \( p_S : SV_\circ \to SV \)) be the projection to the first factor in the definition of \( \rho \) (respectively, \( \rho_S \)). Define

\[
\partial_E(V \circ S) := p^{-1}(E - \bigcup_{F \in S^E} F),
\]

and

\[
\partial_E(SV \circ S) := p_S^{-1}(S^E - \bigcup_{F \in S^E} SF).
\]

**Proposition 1.20 (Gaiffi [32, Theorem 5.1]).** For any \( E \) in the building set \( S \) there are diffeomorphisms, \( \partial_E(V \circ S) \cong (S(V/E) \circ S_E^{k+}) \times (E \circ S^E) \) and \( \partial_E(SV \circ S) \cong (S(V/E) \circ S_E^{k+}) \times (S^E \circ S^E) \).

The diffeomorphism arises as follows. Let \( K_1 \) be the interior of \( E \circ S^E \) and \( K_2 \) be the interior of \( S(V/E) \circ S_E^{k+} \). By considering small line segments emanating from \( K_1 \), orthogonal to \( E \) and going in the direction of \( K_2 \), we clearly see a copy of \( K_2 \times K_1 \) in \( V_\circ \). The closure of this set gives \( \partial_EV \circ S \).

From now on we will only be interested in the case where \( S = \mathcal{I}^{(0)} \), the collection of irreducible elements in \( Q(\mathcal{A}) \). For any \( F \in Q(\mathcal{A}) \), define \( F_\circ \) to be \( F \circ S^E \) and \( S(V/F)_\circ \) to be \( S(V/F) \circ (S_E^{k+}) \). It is shown in [32, Section 5] that \( \{\partial_EV_\circ\} \) is the set of codimension-one strata of \( V_\circ \); moreover, the union is \( \partial V_\circ \). By Proposition 1.20, \( \partial_EV_\circ \) is connected, and hence, is a codimension-one face of \( V_\circ \).

Next we describe intersections of codimension-one faces that give rise to faces of higher codimension. Let \( \alpha \) be a subset of \( \mathcal{I}^{(0)} \). Define

\[
\partial_\alpha V_\circ := \bigcap_{E \in \alpha} \partial_EV_\circ, \quad \partial_\alpha SV_\circ := \bigcap_{E \in \alpha} \partial_ESV_\circ.
\]

Let \( K_\alpha \) be the forest as in Definition 1.6. For \( E \in \text{Vert} \alpha \), let \( \{E_0, E_1, \ldots, E_k\} \) be vertices of \( K_\alpha \) in the next level. Set \( \hat{E} = \bigcap_{i=0}^k E_i \) (if there are no vertices in the next level, then \( \hat{E} = V \). As
$E$ is irreducible, $E \subseteq \hat{E}$. Define $S(\hat{E}/E)_{\circ}$ to be $S(\hat{E}/E) \cap S_{\hat{E}/E}^{E}$. Let $E_{\alpha}$ be the intersection of subspaces of $V$ arising from vertices of $\alpha$ at level 0. Define $(E_{\alpha})_{\circ}$ to be $E_{\alpha} \cap (S_{E}^{E})_{\circ}$.

Suppose that $\alpha$ is nested. By Lemma 1.17, for each $E \in V/F$, $S_{E}^{E} \cap E$ is a building set and $S_{E}^{E \cap E}$ is a building set. Hence, $S(\hat{E}/E)_{\circ}$ and $(E_{\alpha})_{\circ}$ are smooth manifolds with faces.

**Theorem 1.21** (Gaiffi [32, Theorems 5.2 and 5.3]). The intersection $\partial_{E}V_{\circ}$ is nonempty if and only if $\alpha$ is nested. Moreover, there are diffeomorphisms of smooth manifolds with faces: $\partial_{E}V_{\circ} \cong (E_{\alpha})_{\circ} \times \prod_{E \in E} S(\hat{E}/E)_{\circ}$ and $\partial_{E}SV_{\circ} \cong S(E_{\alpha})_{\circ} \times \prod_{E \in E} S(\hat{E}/E)_{\circ}$.

Now we explain the diffeomorphism in Theorem 1.21 in the case of $|\alpha| = 2$, general cases are similar [32]. Suppose $\alpha = \{E, F\}$ is nested. First case to consider is that $E \subseteq F$ or $F \subseteq E$ (assume the former). Use the inner product on $V$, we have the identification $V = E \oplus (F/E) \oplus (V/F)$. Let $SM(S_{E}^{E \cap E})$ denotes the interior of $S(F/E) \cap S_{E}^{E \cap E}$. Let $x_{1}, x_{2}, x_{3}$ be elements in $M(S^{E}), SM(S_{E}^{E \cap E})$, and $SM(S_{E}^{E \cap E})$, respectively. Consider the curve in $V$ represented by $t \to x_{1} + tx_{2} + tx_{3}$, where $x_{2}$ and $x_{3}$ are unit vectors in $F/E$ (respectively, $V/F$). When $t$ is small enough, this curve is in $M(A)$, and as $t \to 0^{+}$, we obtain a point in $\partial(V \cap S)$. This gives a injective map

$$
M(S_{E}^{E}) \times SM(S_{E}^{E \cap E}) \times SM(S_{E}^{E \cap E}) \to \partial(V \cap S).
$$

The closure of the image of this map turns out to be $\partial_{E}(V \cap S) \cap \partial_{F}(V \cap S)$ [32]. The second case is that $E \not\subseteq F$ and $F \not\subseteq E$. Let $U = E \cap F$. Then $A_{V/U} \cong A_{V/E} \oplus A_{V/F}$. The inner product of $V$ induces $V = U \oplus E_{\perp} + F_{\perp} = U \oplus (V/E) \oplus (V/F)$. Consider the curve in $V$ represented by $t \to x_{1} + tx_{2} + tx_{3}$, where $x_{1} \in M(S^{U}), x_{2} \in SM(S_{E}^{E \cap E}),$ and $x_{3} \in SM(S_{E}^{E \cap E})$, which gives a map

$$
M(S^{U}) \times SM(S_{E}^{E \cap E}) \times SM(S_{E}^{E \cap E}) \to \partial(V \cap S).
$$

The closure of the image of this map is $\partial_{E}(V \cap S) \cap \partial_{F}(V \cap S)$.

We summarize part of the above discussion as follows.

**Lemma 1.22.** For each $E$ in the building set $S$, the arrangement of subspaces $S_{E}^{E \cap E} \subset S^{E}$ in $\mathcal{Q}(A_{V/E} \oplus A^{E})$ is also a building set. The face $\partial_{E}(V \cap S)$ can be naturally identified with a codimension-one face of $((V/E) \oplus E) \cap (S_{E}^{E \cap E} \oplus S^{E})$. For a nested subset $\{E, F\}$ of $S$, $\partial_{E}(V \cap S) \cap \partial_{F}(V \cap S)$ can be identified as a codimension two face of $((V/E) \oplus E) \cap (S_{E}^{E \cap E} \oplus S^{E})$.

**Method 2: Iterated blowups.** We now describe an alternative definition of $V_{\circ}$. Linearly order the elements of $\mathcal{I}^{(0)}$: $E_{1}, \ldots, E_{p}$ in some fashion compatible with the partial order (here $p = \text{Card} \mathcal{I}^{(0)}$). In other words, $E_{i} < E_{j} \Rightarrow i < j$. The idea is to blow up $V$ along the $E_{i}$ in succession. We shall inductively define a sequence of manifolds with faces:

$$
V = V_{\circ}(1), V_{\circ}(2), \ldots, V_{\circ}(p) = V_{\circ},
$$

where, roughly speaking, $V_{\circ}(k)$ is obtained by blowing up $V_{\circ}(k - 1)$ along $E_{k}$. More precisely, let $E_{k}$ denote the closure of $M(A^{E_{k}})$ in $V_{\circ}(k - 1)$. (Since $E_{k}$ has not yet been removed from $V_{\circ}(k - 1)$, the restriction arrangement complement $M(A^{E_{k}})$ is a submanifold in the interior of $V_{\circ}(k - 1)$.) By induction we can assume that $E_{k}$ is a submanifold with faces of $V_{\circ}(k - 1)$. Define $V_{\circ}(k) = V_{\circ}(k - 1) \ominus E_{k}$, where the blowup along $E_{k}$ is as defined in the final paragraph of Subsection 1.2. The bordification of $M(A)$ is the manifold with faces defined by

$$
V_{\circ} := V_{\circ}(p).
$$

The bordification is well-defined modulo the following two issues:
(1) for each \( k \), we need to verify that \( \overline{E}_k \) is a submanifold with faces of \( V_\circ(k - 1) \);

(2) choosing a different linear order on \( T^{(0)} \) will result the same \( V_\circ \) (up to diffeomorphism between manifolds with corners).

We refer to [32, Sections 7–10] for the details of (1) and (2). The arguments rely on the fact that \( T^{(0)} \) is a building set. (As before, the results of [32] are proved in the more general setting of blowing up along building sets.) For (2), it is shown in [32, Proposition 10.2] that the identity map between the interior of the two blowups arising from different linear orders of \( T^{(0)} \) extends to a diffeomorphism of the blowups. One can use Method 2 to give an independent description of Proposition 1.20 and Theorem 1.21 (see [32, Section 11]). We leave the equivalence of Methods 1 and 2 to the reader.

**Remark 1.23 (Deleting tubular neighborhoods).** Although Methods 1 and 2 might seem to be complicated, the concept underlying both methods is simple. As explained in Subsection 1.2, given a submanifold \( Y \) of a manifold \( M \), the blowup \( M \circ Y \) is diffeomorphic to the complement of an open tubular neighborhood of \( Y \) in \( M \). In this subsection we have started with a more complicated situation, a collection \( \mathcal{S} \) of linear subspaces. Under either Methods 1 or 2 the blowup is diffeomorphic to the complement of an open regular neighborhood of the union of subspaces in \( \mathcal{S} \). One can try to remove the tubular neighborhoods directly, one at a time. Although this method is the easiest to visualize, technical difficulties could be encountered. For example, one needs to choose carefully radial functions on the normal bundles in order to specify the size of tubular neighborhoods to be removed. Also, in order for the blowup to be a well-defined manifold with corners, we need \( \mathcal{S} \) to be a building set. The point is that if a stratum is the transverse intersection of subspaces, then there is no reason to remove it first: it will be deleted when we remove the tubular neighborhoods of the subspaces and since their normal sphere bundles will intersect transversely, we will get a manifold with corners. However, if the stratum is not a transverse intersection of subspaces, then we must remove it first. This will have the effect that the intersections of various subspaces with the normal sphere bundle of the stratum will be disjoint submanifolds. So, the elements of \( \mathcal{S} \) that are not transverse intersections must be blown up first. This is exactly what it means for \( \mathcal{S} \) to be a building set. Finally, one removes neighborhoods of the strata in the same order as was done in Method 2. Our conclusion is that blowing up can be accomplished by the naive method of removing tubular neighborhoods, provided that \( \mathcal{S} \) is a building set.

**Definition 1.24 (The compact core).** Suppose that \( \mathcal{A} \) has an irreducible decomposition \( \mathcal{A} = \mathcal{A}_1 \times \cdots \times \mathcal{A}_\ell \) and corresponding vector space decomposition \( V = V_1 \oplus \cdots \oplus V_\ell \). Then \( V_\circ = (V_1)_\circ \times \cdots \times (V_\ell)_\circ = [0, \infty)^\ell \times S(V_1)_\circ \times \cdots \times S(V_\ell)_\circ \) (cf. (1.5)). The **compact core** \( X \) (or \( X(\mathcal{A}) \)) of \( V_\circ \) is defined by omitting the interval factors, that is,

\[
X = \prod_{i=1}^\ell S(V_i)_\circ.
\]

If \( X^\circ := \mathcal{M}(\mathcal{A}) \cap \prod S(V_i) \), then \( X \) is a bordification of \( X^\circ \). So, \( X \) is homotopy equivalent to \( V_\circ \) (or to \( \mathcal{M}(\mathcal{A}) \)). The faces of \( S(V_i)_\circ \) of codimension \( \geq 1 \) are indexed by the simplices of \( \mathcal{I}_0(\mathcal{A}_i) \) whose vertices are the nonzero irreducible subspaces in \( V_i \). In general define \( \mathcal{I}_0(\mathcal{A}) \) by

\[
\mathcal{I}_0(\mathcal{A}) \cong \mathcal{I}_0(\mathcal{A}_1) \ast \cdots \ast \mathcal{I}_0(\mathcal{A}_\ell).
\]

Since \( X(\mathcal{A}) = \prod_{i=1}^\ell X(\mathcal{A}_i) \), the faces of \( X \) are indexed by \( \mathcal{I}_0(\mathcal{A}) \). So, the face structure on \( X \) reduces to the case where \( \mathcal{A} \) is irreducible. When \( \mathcal{A} \) is irreducible a codimension-one face of \( X \) has the form \( \partial_X X = S E_\circ \times S(V/E)_\circ \). When \( \mathcal{A} \) has more than one factor, a codimension-one
face of $X$ has one factor of the form $\partial E X(\mathcal{A}_i)$ and the others are of the form $X(\mathcal{A}_j)$, with $j \neq i$.

1.4. The curve complex

Let $Y$ denote the universal cover of $X$ and $\pi : Y \to X$ the covering projection. Then $Y$ is a manifold with faces. Each face of $Y$ is a connected component of $\pi^{-1}(\partial \alpha X)$ for some $\alpha \in \mathcal{I}_0$.

The goals in this subsection are (1) to describe the bordification $Y$ of the universal cover of $X$, (2) to give the definition of the topological curve complex $C_{\text{top}}$ associated to the manifold with faces $Y$ (cf. Definition 1.25 below), and (3) to describe some properties of $Y$ which are needed to insure that $C_{\text{top}}$ is naturally isomorphic to $C_{\text{alg}}$ in Definition 1.14.

As in Subsection 1.2, let $\mathcal{N}(X)$ be the nerve of the cover of $\partial X$ by the set of its codimension-one faces, that is, by $\{ \partial E X \}_{E \in \text{Vert} \mathcal{I}_0}$. By Theorem 1.21, the $\mathcal{N}(X) = \mathcal{I}_0$. It also follows that $X$ has the connected intersection property (that is, each nonempty intersection of codimension-one faces is connected). Hence, the $\Delta$-complex $\Delta(X)$ is also equal to the simplicial complex $\mathcal{I}_0$.

**Definition 1.25.** The topological curve complex $C_{\text{top}} (= C_{\text{top}}(\mathcal{A}))$ is the $\Delta$-complex $\Delta(Y)$ as in Subsection 1.2. In other words, a $(k-1)$-simplex in $C_{\text{top}}$ corresponds to a codimension-$k$ face of $Y$.

Each vertex of $C_{\text{top}}$ has a well-defined type, which is a subspace in $\mathcal{I}^{(0)}$.

We have $\partial E X = SE \times (SV/E)$. By Lemma 1.9, the composition of inclusions $SV/E \hookrightarrow \partial E X \hookrightarrow X$ is $\pi_1$-injective and the image of $\pi_1(SV/E)$ in $G (= \pi_1(X))$ is an irreducible parabolic subgroup of type $E$. The composition of inclusions $SE \hookrightarrow \partial E X \hookrightarrow X$ induces a homomorphism $\pi_1(SE) \to G$.

**Properties A, B, C, and D.** Next we introduce four group theoretic properties that can be used to guarantee that $C_{\text{top}}$ and $C_{\text{alg}}$ are isomorphic. These properties will be proved later for complexifications of real simplicial arrangements, although we expect the properties to hold in greater generality.

**Property A.** For each $E \in \mathcal{Q}(\mathcal{A})$, the inclusion $SE \hookrightarrow SE \times (SV/E) = \partial E X \hookrightarrow X$ is $\pi_1$-injective.

By Theorem 1.21, each face $\partial \alpha X$ is a product of blown up spheres $S(E'/E)\times$ in subnormal arrangements. By Lemma 1.9, $S(E'/E)\times$ is a retract, and hence, is $\pi_1$-injective. Property A states that $S(E'/E)\times \hookrightarrow X$ is $\pi_1$-injective. So, $\pi_1(S(E'/E)\times) \to \pi_1(X)$, being the composition of two injections, also is injective. Therefore, Property A implies the following.

**Property A'.** For each $\alpha \in \mathcal{I}_0$, the inclusion $\partial \alpha X \hookrightarrow X$ is $\pi_1$-injective.

**Property B.** For each simplex $\alpha$ of $\mathcal{I}_0$, we have

$$
\pi_1(\partial \alpha X, x) = \bigcap_{v \in \text{Vert}\alpha} \pi_1(\partial v X, x)
$$

for a base point $x \in \partial \alpha X$.

**Property B'.** Suppose that $\{ \partial v Y \}$ is a collection of codimension-one faces of $Y$ such that the intersection of any subcollection is nonempty. Then $\{ \partial v Y \}$ has the connected intersection property (see Subsection 1.2).
The fibration of $S(V/E)$ by $S^1$ naturally extends to a fibration of $S(V/E)_\circ$ by $S^1$, which we will call the Hopf fibration of $S(V/E)_\circ$. For any base point $p \in S(V/E)_\circ$, $\pi_1(S(V/E)_\circ, p)$ gives a parabolic subgroup $P$ of $G$ (cf. Definition 1.11) and the Hopf fiber passing through $p$ represents the central $\mathbb{Z}$-subgroup $Z_P$.

**PROPERTY C.** For each $E \in T^{(0)}$ and a basepoint $p \in \partial E X$, the image of $\pi_1(\partial E X, p)$ in $\pi_1(X, p) = G$ is equal to the normalizer of $Z_E$ in $G$ where $Z_E$ is represented by the Hopf fiber of $S(V/E)_\circ$ passing through $p$.

Before we formulate the next property, we record the following lemma, which is a straightforward consequence of the relevant definitions.

**Lemma 1.26.** Let $\alpha$ be a simplex of $T_0$. Take $p \in \partial_\alpha X$. For each $E \in \text{Vert} \alpha$, consider the Hopf fiber for each $S(V/E)_\circ$ passing through $p$. This gives rise to a collection of mutually commuting $\mathbb{Z}$-subgroups in $G$ (and hence, a free abelian subgroup of rank $= \dim \alpha + 1$).

**Property D.** For $k \geq 2$ and for any collection $\{L_1, L_2, \ldots, L_k\}$ of $k$ commuting $\mathbb{Z}$-subgroups such that each of $L_i$ is the central $\mathbb{Z}$-subgroup of some parabolic subgroup of $G$, there exists $g \in G$ so that $g\{L_1, L_2, \ldots, L_k\}g^{-1}$ arises from a simplex of $T_0$ as described in Lemma 1.26.

**Proposition 1.27.** Suppose that $A$ is an essential complex arrangement in an $n$-dimensional complex vector space. Suppose that $A$ satisfies properties A, B, C, and D. Then the following statements are true.

1. $C_{\text{top}}$ is naturally isomorphic to $C_{\text{alg}}$.
2. The action of fundamental group on $C = C_{\text{top}} = C_{\text{alg}}$ has no inversions (that is, the pointwise stabilizer of each simplex equal to its setwise stabilizer), and the quotient complex is naturally isomorphic to the complex $T_0$ of irreducible subspaces.
3. If $\partial_\alpha X$ is aspherical for each simplex $\alpha$ of $T_0$, then $C$ has the same homology as a wedge of spheres of dimension $n - k - 1$, where $k$ is the number of irreducible components of $A$.
4. If $\dim C \leq 1$, then $C$ is homotopy equivalent to a wedge of spheres. If $\dim C > 1$ and if $C$ is simply connected, then $C$ is homotopic to a wedge of spheres.

**Proof.** First we define a map $f : C_{\text{top}}^{(0)} \to C_{\text{alg}}^{(0)}$. Each vertex $v$ of $C_{\text{top}}^{(0)}$ corresponds to a face $\partial_v \tilde{X}$ with a product decomposition

$$\partial_v \tilde{X} \cong \overline{SE_\circ} \times S(V/E)_\circ,$$

where $E$ is the type of $v$. The setwise stabilizer of each $S(V/E)_\circ$ fiber is the same, namely, a parabolic subgroup of $G$ and $f(v)$ is defined to be the center of this parabolic subgroup. As this parabolic subgroup cannot correspond to an irreducible factor of $A$, we know that $f(v)$ gives a vertex in $C_{\text{alg}}^{(0)}$. Note that $f$ is surjective, $G$-equivariant, and type preserving. Suppose for vertices $v_1$ and $v_2$ we have $f(v_1) = f(v_2)$. Then $v_1$ and $v_2$ have the same type. Thus there exists $g \in G$ such that $g\partial_{v_1} \tilde{X} = \partial_{v_2} \tilde{X}$. Suppose that $Z_{v_1}$ is the $Z$-subgroup associated with $f(v_1)$. If $f$ is $G$-equivariant, $g$ normalizes $Z_{v_1}$. By Property C, $g$ stabilizes $\partial_{v_1} \tilde{X}$. Thus, $v_1 = v_2$ and $f$ is injective. For two adjacent vertices $v_1$ and $v_2$ in $C_{\text{top}}$, we have $\partial_{v_1} \tilde{X} \cap \partial_{v_2} \tilde{X} \neq \emptyset$. So, $\partial_{E_1} X \cap \partial_{E_2} X \neq \emptyset$ where $E_i$ is the type of $v_i$. By Theorem 1.21, $\{E_1, E_2\}$ is a nested set. By Lemma 1.26, $f(v_1)$ and $f(v_2)$ commute. So, if a collection of vertices of $C_{\text{top}}$ spans a simplex, then their $f$-images span a simplex. By Property D, the converse of this statement also holds. So to show that $f$ extends to an isomorphism from $C_{\text{top}}$ to $C_{\text{alg}}$, it suffices to prove that $C_{\text{top}}$ is a simplicial complex. Equivalently, we need to prove if $\{v_i\}_{i=1}^k$ is a collection of vertices of $C_{\text{top}}$.
spanning a simplex, then \( \bigcap_{i=1}^{k} \partial_i X \) is connected. The case \( k = 2 \) follows from Properties \( A' \) and \( B \) and Lemma 1.29 below. We can use Property \( B \) to reduce the general case to the case \( k = 2 \) by noticing that \( \bigcap_{i=1}^{k} \partial_i X = (\bigcap_{i=1}^{k-1} \partial_i X) \cap (\bigcap_{i=2}^{k} \partial_i X) \). This finishes the proof of the first assertion.

For (2), as the action of \( G \) on \( C_{\text{alg}} \) is type preserving, and different vertices in a simplex have different types, the action does not have inversions. As \( C_{\text{top}} = \Delta(X) \) and the \( (k-1) \)-simplices of \( \Delta(X) \) are in one-to-one correspondence with codimension-\( f \) faces of \( X \), we know that the \( G \)-orbits of simplices in \( C_{\text{top}} \) are in one-to-one correspondence with the simplices of \( I_0 \). This proves (2).

In order to prove (3) we begin with the fact that \( M(A) \) is homotopy equivalent to a CW complex of dimension \( n \). It is proved in [20] that for any \( A \) that is essential and central, \( H^*(M(A); ZG) \) is concentrated in degree \( n \) and it is a free abelian group in that degree. (This is a generalization a result of Squier [54], where this is proved in the case of the complexification of a reflection arrangement.) Since \( M(A) \) is homotopy equivalent to the compact space \( X \), we have \( H^*(X; ZG) \cong H^*_c(\tilde{X}) \). Since each face of \( \partial X \) is contractible and since \( C \) is the nerve of covering of \( X \) by its codimension-one faces, \( \tilde{X} \) is homotopy equivalent to \( C \). Note that \( \dim C = \dim I_0 = n - k - 1 \) since \( I_0 \) is the join of \( k \) factors of the form \( I_0(A_i) \). Since \( (X, \partial X) \) is a manifold with boundary of dimension \( 2n - k \), Poincaré duality gives:

\[
H^*_c(\tilde{X}) \cong H_{2n-k-*}(\tilde{X}, \partial \tilde{X})
\]

\[
\cong \check{H}_{2n-k-*-1}(\partial \tilde{X}) \cong \check{H}_{2n-k-*-1}(C),
\]

where the second equation holds since \( \tilde{X} \) is contractible. Since \( H^*_c(\tilde{X}) \) is concentrated in degree \( n \), \( H_k(\tilde{X}, \partial \tilde{X}) \) is concentrated in degree \( n - k \), and hence, \( \check{H}_k(C) \) is concentrated in degree \( n - k - 1 \) (\( = \dim C \)). This proves (3). Equation (4) follows immediately from (3).

**Remark 1.28.** Suppose that \( A \) satisfies properties A, B, C, and D. When \( \dim C_{\text{top}} > 1 \), the condition that \( C \) is simply connected is equivalent to the condition that the map \( \partial X \to X \) induces an isomorphism on the fundamental groups. However, this is always true. Since \( \partial X \) is homeomorphic to the boundary \( M \) of a closed regular neighborhood (cf. [28]) of \( SV \cap \bigcup_{H \in A} H \) in \( SV \) and since \( M \to SV \cap M(A) \) induces isomorphism on the fundamental group whenever \( V \) is irreducible and \( \dim V \geq 4 \) (see [27, Proposition 5.2.31]). So, in Proposition 1.27(4) we can drop, the assumption \( C \) is simply connected.

**Lemma 1.29.** Suppose \( B = B_0 \cup B_1 \), where \( B, B_0, B_1 \), and \( C = B_0 \cap B_1 \) are path connected. Take base point \( x_0 \in C \). Let \( h : \pi_1(B, x_0) \to G \) be a homomorphism to some group \( G \) such that

1. for \( i = 0, 1 \), \( \pi_1(B_i, x_0) \to \pi_1(B, x_0) \to G \) is injective (denote the image of \( \pi_1(B_i, x_0) \) in \( G \) by \( G_i \)) and \( \pi_1(C, x_0) \to \pi_1(B, x_0) \to G \) is injective (denote the image in \( G \) by \( H \)),
2. \( G_0 \cap G_1 = H \).

Let \( \pi : \tilde{B} \to B \) be a regular covering space with group of deck transformations \( \text{Im} h \). Then if \( C' \) is a component of \( \pi^{-1}(C) \) and if \( B'_i \) is a component of \( \pi^{-1}(B_i) \) that contains \( C' \), then \( B'_0 \cap B'_1 = C' \).

**Proof.** Assume \( G = \text{Im} h \) for simplicity. Suppose that \( B'_0 \cap B'_1 \) contain a connected component \( C'' \) which is different from \( C' \). Let \( x' \in C' \) and \( x'' \in C'' \), be lift of \( x_0 \in C \). For \( i = 1, 2 \), let \( \omega_i \) be a path from \( x' \) to \( x'' \) inside \( B'_i \). Let \( g_i \in H_i \) be the element represented by \( \pi(\omega_i) \). As \( \omega_i \omega_i^{-1} \) is a loop in \( \tilde{B} \), \( g_0 g^{-1} \) represents the trivial element in \( G \). So, \( g_0 = g_1 \). By condition (2), \( g_0 \in H_i \), which contradicts that \( C' \neq C'' \). The lemma follows. □
Admissible families of arrangements.

**Definition 1.30.** Let $\mathcal{C}$ be a collection of complex hyperplane arrangements. We say that $\mathcal{C}$ is *admissible* if the following conditions hold.

1. if $\mathcal{A} \in \mathcal{C}$ is an arrangement in vector space $V$ and $E \in Q(\mathcal{A})$, then $\mathcal{A}_{V/E} \in \mathcal{C}$ and $\mathcal{A}_E \in \mathcal{C}$;
2. if $\mathcal{A}_1, \mathcal{A}_2 \in \mathcal{C}$, then $\mathcal{A}_1 \oplus \mathcal{A}_2 \in \mathcal{C}$.

For example, the collection of all complex hyperplane arrangements that are complexifications of simplicial real arrangements is admissible [26]. The collection of supersolvable arrangements is also admissible (see [14, Section 2] for a summary).

**Proposition 1.31.** Suppose that $\mathcal{C}$ is an admissible collection of complex hyperplane arrangements. Suppose that each element in $\mathcal{C}$ satisfies Properties A, C, and D. Then the following statements are true.

1. Suppose $\mathcal{A} \in \mathcal{C}$. Then the stabilizer of each simplex in $C_{\text{alg}}$ is isomorphic to $\pi_1(\mathcal{M}(\mathcal{A}'))$ for some $\mathcal{A}' \in \mathcal{C}$.
2. Each element of $\mathcal{C}$ satisfies properties A, B, C, and D.

**Proof.** We prove (1). Suppose that the simplex has vertex set $\{v_i\}_{i=1}^k$. Let $Z_i$ be the central $Z$-subgroup of the parabolic subgroup associated with $v_i$ of type $E_i$. By Property D, $\{Z_i\}_{i=1}^k$ is a nested subset. Let $H_i$ be the stabilizer of $v_i$. Then $H_i = N_G(Z_i) = C_G(Z_i)$ by property C. Suppose that $E_1$ does not properly contain any other $E_i$. There is a natural map $f_G : G_1 := \pi_1(\mathcal{M}(\mathcal{A}_{V/E_1} \oplus \mathcal{A}_{E_1})) \to H_1$, which is an isomorphism by Properties A and C. Note that $\bigcap_{i=1}^k C_G(Z_i) = \bigcap_{i=2}^k C_{H_1}(Z_i)$. It follows from Property D that if $E_1 \subset E_i$, then $f^{-1}_G(Z_i)$ is a central $Z$-subgroup of a parabolic subgroup in $\pi_1(\mathcal{M}(\mathcal{A}_{V/E_1}))$ that is irreducible. The case $\mathcal{A}_{V/(E_i \cap E_1)} \cong \mathcal{A}_{V/E_1} \oplus \mathcal{A}_{E_1}$ is similar, where $f^{-1}_G(Z_i)$ is a central $Z$-subgroup of an irreducible parabolic subgroup in $\pi_1(\mathcal{M}(\mathcal{A}_{E_1}))$. Thus, we are reduced to the stabilizer of a simplex with $k-1$ vertices in the curve complex for $\mathcal{A}_{V/E_1} \oplus \mathcal{A}_{E_1}$. The arrangement $\mathcal{A}_{V/E_1} \oplus \mathcal{A}_{E_1}$ is in $\mathcal{C}$. So we are done by induction. Next we prove (2). We use the same notation as before. By Lemma 1.22 and Properties A and C for $\mathcal{A}_{V/E_1} \oplus \mathcal{A}_{E_1}$, the inclusion $\partial E_1 \cap \partial E_i X \to \partial E_i X$ induces an injective map on fundamental groups and its $\pi_1$-image is $C_{H_1}(Z_i)$. The case $k = 2$ follows. The more general case can be proved by induction as in (1). \qed

2. Zonotopes, Salvetti complexes, and Deligne groupoids

This section deals with some complexes associated to a real, simplicial arrangement of hyperplanes. So, $\mathcal{A}$ denotes an essential, central arrangement of hyperplanes in a real vector space $A$.

### 2.1. Real arrangements and their dual zonotopes

The hyperplanes in $\mathcal{A}$ cut $A$ into a collection of convex polyhedral cones, called the *fan* of $\mathcal{A}$, denoted by $\text{Fan}(\mathcal{A})$. The intersection of these polyhedral cones with the sphere $SA$ defines a cellulation of $SA$ by totally geodesic spherical polytopes. This gives rise $SA$ to a piecewise linear cellulation of $SA$, and we denote the associated cell complex by $\partial \text{Fan}(\mathcal{A})$. We define the *dual zonotope* of $\mathcal{A}$, denoted by $Z(\mathcal{A})$, to be $SA$ with the cell structure dual to $\partial \text{Fan}(\mathcal{A})$. The real arrangement is *simplicial* if $\partial \text{Fan}(\mathcal{A})$ is a simplicial complex.

**Example 2.1.** If $\mathcal{A}$ is the braid arrangement corresponding to the action of the symmetric group $S_{n+1}$ on $A = \mathbb{R}^n$, then $\partial \text{Fan}(\mathcal{A})$ is the Coxeter complex and $Z(\mathcal{A})$ is the permutohedron.
We denote the barycentric subdivision of \( Z(A) \) by \( bZ(A) \), which is a simplicial complex (the “\( b \)” indicates “barycentric subdivision”). Note that \( bZ(A) \) and \( \partial \operatorname{Fan} (A) \) can be naturally identified. One can realize \( Z(A) \) as a convex polytope in the dual space \( A^* \) of \( A \). However, in this paper, we would like to embed \( Z(A) \) (and \( bZ(A) \)) as a (not necessarily convex) piecewise linear subset of \( A \) as follows.

For each cone \( U \in \operatorname{Fan}(A) \), choose a point \( x_U \) in the relative interior of \( U \). The partial order on \( \operatorname{Fan}(A) \) is defined by \( U_1 \prec U_2 \) if \( U_1 \) is contained in the closure of \( U_2 \) and in this case, we also write \( x_{U_1} < x_{U_2} \). Each chain \( x_{U_1} < x_{U_2} \prec \cdots \prec x_{U_k} \) determines a simplex in \( A \) with vertex set \( \{x_{U_i}\}_{i=1}^k \). This defines an embedding of the simplicial complex \( bZ(A) \) as a subset of \( A \). The simplices of \( bZ(A) \) can be assembled into cells in two different ways to obtain the cell structure on \( \partial \operatorname{Fan}(A) \) and \( Z(A) \). The faces of the zonotope \( Z(A) \) are in one-to-one correspondence with vertices of \( bZ(A) \). We identify the face of \( Z(A) \) associated with vertex \( x_U \in bZ(A) \) with the union of all simplices of \( bZ(A) \) corresponding to chains whose smallest element is \( x_U \). In this way each vertex of \( bZ(A) \) can also be regarded as the barycenter of a face of \( Z(A) \).

Suppose that \( B \) is a subspace in \( Q(A) \). A face \( F \) of \( Z(A) \) is dual to \( B \) if \( F \cap B = \{b_F\} \), where \( b_F \) denotes the barycenter of \( F \). It follows that \( F \) is isomorphic to the zonotope dual to the real arrangement \( A_{A/B} \). Note that \( \operatorname{Fan}(A^B) \subset \operatorname{Fan}(A) \). So, our previous choices of the \( x_U \), yield an embedding \( bZ(A^B) \to B \). Therefore, we can treat \( bZ(A^B) \) as a subcomplex of \( bZ(A) \), that is, \( bZ(A^B) = bZ(A) \cap B \).

Two faces \( F_1 \) and \( F_2 \) of \( Z(A) \) are parallel if they are dual to the same subspace in \( Q(A) \): we write \( F_1 \parallel F_2 \). When \( Z(A) \) is realized as a convex polytope in \( A^* \) dual to \( \operatorname{Fan}(A) \), then \( F_1 \) and \( F_2 \) actually are parallel faces of \( Z(A) \). Parallel classes of faces of \( Z(A) \) are in one-to-one correspondence with subspaces of \( Q(A) \). For example, the duals to a hyperplane in \( A \) form a parallel class of edges in \( Z(A) \).

Given two faces \( F_1 \) and \( F_2 \) of \( Z(A) \) both dual to \( B \in Q(A) \), define \( p : \operatorname{Vert} F_1 \to \operatorname{Vert} F_2 \) as follows. Let \( A_B \) be the collection of hyperplanes of \( A \) containing \( B \). For \( x \in \operatorname{Vert} F_1 \), define \( p(x) \) to be the unique vertex in \( F_2 \) such that \( x \) and \( p(x) \) are not separated by any hyperplanes in \( A_B \). The map \( p \) is called parallel translation. (When \( F_1 \) and \( F_2 \) are regarded as actual parallel faces of the zonotope \( Z(A) \), the map \( p \) is the restriction of the parallel translation taking \( F_1 \) to \( F_2 \).)

Define \( F_1 \) to be orthogonal to \( F_2 \), denoted by \( F_1 \perp F_2 \), if there is another face \( F \) of \( Z(A) \) containing \( F_1 \) and \( F_2 \) such that \( F \cong F_1 \times F_2 \) (and consequently, \( F_1 \cap F_2 \) will be a vertex). Note that \( F_1 \perp F_2 \) if and only if \( A_{A/B_1} \times A_{A/B_2} = A_{A/(B_1 \cap B_2)} \) where \( B_i \) is the subspace dual to \( F_i \).

The 1-skeleton of \( Z(A) \) is endowed with a path metric \( d \) such that each edge has length 1. Given \( x, y \in \operatorname{Vert} Z(A) \), it turns out that \( d(x, y) \) is the number of hyperplanes separating \( x \) and \( y \) (cf. [26, Lemma 1.3]). In the next lemma we collect some basic facts which will be used in Sections 3 and 5.

**Lemma 2.2.** Let \( x \) be a vertex in \( Z(A) \) and \( F \) be a face of \( Z(A) \).

1. There exists a unique vertex \( x_F \in F \) such that \( d(x, x_F) \leq d(x, y) \) for any vertex \( y \in F \). The vertex \( x_F \) is called the projection of \( x \) to \( F \), and is denoted by \( \operatorname{Proj}_F(x) \).

2. For any vertex \( y \in F \), there exists a shortest edge path \( \omega \) in the 1-skeleton of \( Z(A) \) from \( x \) to \( y \) so that \( \omega \) passes through \( x_F \) and so that the segment of \( \omega \) between \( x_F \) and \( y \) is contained in \( F \).

3. Let \( H_F \) be the collection of hyperplanes in \( A \) dual to some edge of \( F \). Then \( x_F \) can be characterized as the unique vertex in \( F \) such that no element in \( H_F \) separates \( x \) from \( x_F \).

4. Let \( F' \) be another face parallel to \( F \) and let \( p : F' \to F \) be parallel translation. Let \( y \in F' \). Then \( \operatorname{Proj}_F(y) = p(y) \).

Statements (1) and (2) are proved in [49, Lemma 3], Statements (3) and (4) follow immediately from (1) and (2).
Lemma 2.3. Suppose that $A$ is finite, central, simplicial arrangement. Then the following statements are true.

1. Given edges $e_1, \ldots, e_k$ of $Z(A)$ sharing a vertex $x$, let $F$ be the smallest face of $Z(A)$ containing each $e_i$. Then any edge of $F$ containing $x$ has to be one of the $e_i$. This $F$ is called the face spanned by $\{e_i\}^{k}_{i=1}$.

2. Let $F \subset Z(A)$ be a face containing a given vertex $x$. Let $\{e_1, \ldots, e_l\} \subset Z(A)$ be a set of distinct edges that contain $x$ but do not lie in $F$. Then there is a unique face $F' \subset Z(A)$ containing $F$ and $\{e_1, \ldots, e_l\}$ such that dim($F'$) = dim($F$) + 1. This $F'$ is called the face spanned by $F$ and $\{e_1, \ldots, e_l\}$.

This lemma follows immediately from the fact that the link of each vertex of $Z(A)$ is a simplex (since $A$ is simplicial). Also, with regard to assertion (2), suppose that $\{e_i^{\prime}\}^{k}_{i=1}$ is the set of edges of $F$ that contain $x$. Then $F'$ is the face spanned by $\{e_1^{\prime}, \ldots, e_k^{\prime}, e_1, \ldots, e_l\}$.

Remark 2.4. Suppose that $A$ is finite, central, and simplicial. Let $E \in Q(A)$ be a subspace. Then both $A^E$ and $A_{V/E}$ are simplicial, cf. [14, Lemma 2.17].

2.2. The Salvetti complex

Suppose that $A$ is a real arrangement in a vector space $A \cong \mathbb{R}^n$ and that $Z(=Z(A))$ is the dual zonotope. Consider the set of pairs $(F, v) \in \mathcal{P}(Z) \times \text{Vert } Z$. Define an equivalence relation $\sim$ on this set by

$$(F, v) \sim (F', v') \iff F = F'$ and $\text{Proj}_F(v') = \text{Proj}_F(v).$$

Denote the equivalence class of $(F, v')$ by $[F, v']$ and let $\mathcal{E}(A)$ be the set of equivalence classes. Note that each equivalence class $[F, v']$ contains a unique representative of the form $(F, v)$, with $v \in \text{Vert } F$. The partial order on $\mathcal{P}(Z)$ induces a partial order on $\mathcal{E}(A)$. In [49] the Salvetti complex $\text{Sal}(A)$ of $A$ is defined as the regular CW complex given by taking $Z \times \text{Vert } Z$ (that is, a disjoint union of copies of $Z$) and then identifying faces $F \times v$ and $F \times v'$ whenever $[F, v] = [F, v']$, that is,

$$\text{Sal}(A) = (Z \times \text{Vert } Z)/\sim.$$  (2.1)

For example, for each edge $F \in \text{Edge } Z \cong Z(1)$ with endpoints $v_0$ and $v_1$, we get two 1-cells $[F, v_0]$ and $[F, v_1]$ of $\text{Sal}(A)$ glued together along their endpoints $[v_0, v_0]$ and $[v_1, v_1]$. So, the 0-skeleton of $\text{Sal}(A)$ is equal to the 0-skeleton of $Z$, while its 1-skeleton is formed from the 1-skeleton of $Z$ by doubling each edge.

Since $\text{Sal}(A)$ is a union of cells of the form $(Z(A), v)$ with $v$ ranging over vertices of $Z(A)$, there is a natural map $\text{Sal}(A) \to Z(A)$ defined by ignoring the second coordinate. A standard subcomplex of $\text{Sal}(A)$ is the inverse image of a face of $Z(A)$ under this map. A standard subcomplex is proper if it is associated with a positive dimensional proper face of $Z(A)$, that is, a face which is neither a vertex nor the entire zonotope $Z(A)$.

Remark 2.5. Each edge of $\text{Sal}(A)$ has a natural orientation, namely, if $F = \{v_0, v_1\}$ is an edge of $Z$, then $[F, v_0]$ is oriented so that $[v_0, v_0]$ is its initial vertex and $[v_1, v_1]$ is its terminal vertex. An edge path in the $\text{Sal}(A)$ is positive if each of its edges is positively oriented. (Positive paths are related to the Deligne groupoid defined in Section 2.3 below.)

For example, if $Z(A)$ is a hexagon, then $\text{Sal}(A)$ is a CW complex with six vertices, twelve edges and six 2-cells.

There is a natural projection $\pi : \text{Sal}(A) \to Z(A)$.
The main property of $\text{Sal}(\mathcal{A})$ is that it has the homotopy type of the complement of the complexified arrangement $\mathcal{A} \otimes \mathbb{C}$.

We write a simplex in the barycentric subdivision $b\text{Sal}(\mathcal{A})$ of $\text{Sal}(\mathcal{A})$ as a pair $(\Delta, v)$, where $\Delta$ is a simplex of $bZ(\mathcal{A})$ and $v$ is a vertex of $Z(\mathcal{A})$.

**Remark 2.6.** Suppose $\Delta = [b_{F_0}, b_{F_1}, \ldots, b_{F_k}]$ where each $F_i$ is a face of $Z(\mathcal{A})$ and $b_{F_i}$ is the barycenter of $F_i$. We assume $F_k \subset F_{k-1} \subset \cdots \subset F_0$. Let $v_1$ and $v_2$ be two vertices of $Z(\mathcal{A})$. Note that if $\text{Proj}_{F_i}(v_1) = \text{Proj}_{F_i}(v_2)$, then $\text{Proj}_{F_j}(v_1) = \text{Proj}_{F_j}(v_2)$ for any $j < i$. Then $(\Delta, v_1) \cap (\Delta, v_2) = (\Delta', v)$, where $\Delta' = [b_{F_0}, b_{F_1}, \ldots, b_{F_m}]$ where $m \leq k$ is the largest possible number such that $\text{Proj}_{F_m}(v_1) = \text{Proj}_{F_m}(v_2)$ and $v = \text{Proj}_{F_m}(v_2)$. (If $\text{Proj}_{F_0}(v_1) \neq \text{Proj}_{F_0}(v_2)$, then $(\Delta, v_1) \cap (\Delta, v_2) = \emptyset$.)

2.3. The Deligne groupoid

We recall the definition of the “Deligne groupoid” from [26, 47]. A chamber of $\mathcal{A}$ is a connected component of $\mathcal{A} \setminus (\bigcup_{H \in \mathcal{A}} H)$. In other words, a chamber is the interior of a top-dimensional cone in $\text{Fan}(\mathcal{A})$. Two chambers $C$ and $D$ are adjacent if there exists exactly one hyperplane in $\mathcal{A}$ separating $C$ from $D$. The chambers of $\mathcal{A}$ are in bijective correspondence with the vertices of $Z(\mathcal{A})$ and two chambers are adjacent if there is an edge of $Z(\mathcal{A})$ connecting the corresponding vertices. Let $\Gamma(\mathcal{A})$ be the directed graph whose vertices are the chambers, and whose arrows are pairs $(C, D)$ of adjacent chambers ($(C, D)$ and $(D, C)$ are distinct oriented edges). Then $\Gamma(\mathcal{A})$ can be identified with the 1-skeleton of the Salvetti complex $\text{Sal}(\mathcal{A})$ with edge orientations as in Remark 2.5. We identify the vertices of $\Gamma(\mathcal{A})$ with the vertices of $Z(\mathcal{A})$. (A vertex of $\Gamma(\mathcal{A})$ is identified with the vertex $[v, v]$ of $\text{Sal}(\mathcal{A})$, and then with the vertex $v$ of $Z(\mathcal{A})$.) So, there is a natural map $\pi: \Gamma(\mathcal{A}) \to Z(\mathcal{A})$ whose image is the 1-skeleton of $Z(\mathcal{A})$. (We think of $\Gamma(\mathcal{A})$ as the “doubled 1-skeleton of $Z(\mathcal{A})”). Given an edge $e$ of $\Gamma(\mathcal{A})$, write $\bar{e}$ for $\pi(e)$.

Let $E(\Gamma)$ be the collection of edges of $\Gamma(\mathcal{A})$. Since the edges of $\Gamma(\mathcal{A})$ are directed, each element $e \in E(\Gamma)$ has a source, denoted by $s(e)$, and a target, denoted by $t(e)$. Introduce a formal inverse of $a$, denoted as $a^{-1}$. It can be thought as traveling the same edge but in the opposite direction. Thus, $t(a^{-1}) = s(a)$ and $s(a^{-1}) = t(a)$.

A path of $\Gamma$ is an expression $g = a_{i_1}^{\epsilon_1}a_{i_2}^{\epsilon_2} \cdots a_{i_n}^{\epsilon_n}$ where $a_i \in E(\Gamma)$, $\epsilon_i \in \{\pm 1\}$, and $t(a_{i+1}^{\epsilon_1}) = s(a_{i+1}^{\epsilon_1})$. Define $s(g) = s(a_1^{\epsilon_1})$ and $t(g) = t(a_n^{\epsilon_n})$. The length of $g$ is $n$. A vertex is a path of length 0. The path $g$ is positive if $\epsilon_i = 1$ for each $1 \leq i \leq n$. The path $g$ is minimal if any path from $s(g)$ to $t(g)$ has length $\geq n$.

Let $\sim$ be the smallest equivalence relation on the set of paths such that

(a) $ff^{-1} \sim s(f)$ for any path $f$;
(b) if $f \sim g$, then $f^{-1} \sim g^{-1}$;
(c) if $f \sim g$, and $h_1$ is a path with $t(h_1) = s(f) = s(g)$, and $h_2$ is a path with $s(h_2) = t(g) = t(f)$, then $h_1fh_2 \sim h_1gh_2$;
(d) if $f$ and $g$ are both minimal positive paths with $s(f) = s(g)$ and $t(f) = t(g)$, then $f \sim g$.

Let $[f]$ be the collection of all paths equivalent to $f$. Define another equivalence relation on the set of positive paths, called positive equivalence and denoted as $\sim_+$: it is the smallest equivalence relation generated by conditions (c) and (d) above. If $f$ is positive, let $[f]_+$ be the set of all positive paths that are positively equivalent to $f$. Note that the elements of $[f]_+$ all have the same length; so, $[f]_+$ has a well-defined length.

Define $G_+(\mathcal{A})$ (respectively, $G^+(\mathcal{A})$) to be the collection of all equivalence (respectively, positive equivalence) classes of paths (respectively, positive paths). The category $G_+(\mathcal{A})$ (respectively, $G^+(\mathcal{A})$) has the structure of a groupoid (respectively, a category), whose objects are vertices of $\Gamma(\mathcal{A})$, whose morphisms are equivalence classes of paths (respectively, positive paths) with compositions given by concatenation of paths. Then $G_+(\mathcal{A})$ is called the Deligne groupoid of $\mathcal{A}$. The object $G^+(\mathcal{A})$ is the set of chambers of $\mathcal{A}$.
groupoid. Put $G = G(A)$ and $G^+ = G^+(A)$. For objects $x, y \in G^+$, let $G^+_{x \to y}$ denote the collection of morphisms whose source is $x$. Define $G^+_{x \to y}$ and $G^+_{x \to y}$ similarly. These notions can be defined for $G$ (that is, without using the superscript $^+$) in the same way. Note that the collection of morphisms of $G$ with source and target both equal to $x$ is a group, called the isotropy group at $x$ denoted by $G_x$.

For two morphisms (that is, for two positive equivalence classes of positive paths) $f$ and $g$ in $G^+$, define the prefix order in such a way that $f \prec g$ if there is a morphism $h$ such that $g = fh$. Similarly, define the suffix order so that $g \succ f$ if there is a morphism $h$ such that $g = hf$. Then $(G^+_{x \to y}, \prec)$ and $(G^+_{x \to y}, \succ)$ are posets.

**Theorem 2.7** [26]. Suppose that the real hyperplane arrangement $A$ is a finite, central, and simplicial. Then the following statements are true.

1. The natural map $G^+ \to G$ is injective. In other words, two positive path are positively equivalent if and only if they are equivalent. Moreover, left and right cancellation laws both hold in $G^+$.

2. For any vertex $x \in \Gamma(A)$, the posets $(G^+_{x \to y}, \prec)$ and $(G^+_{x \to y}, \succ)$ are lattices.

3. For any vertex $x \in \Gamma(A)$, the posets $(G^+_{x \to y}, \prec)$ and $(G^+_{x \to y}, \succ)$ are lattices.

For two morphisms $f$ and $g$ with $s(f) = s(g)$ (respectively, $t(f) = t(g)$), we write $f \vee_p g$ and $f \wedge_p g$ (respectively, $f \vee s$ and $f \wedge s$) for the join and meet of $f$ and $g$ with respect to the prefix order (respectively, suffix order). (Here, as usual, the words “join” and “meet” mean “least upper bound” and “greatest lower bound,” respectively).

For paths $f$ and $g$, write $f \ast g$ if $[f] = [g]$.

**Lemma 2.8.** Given any path $f$ on $\Gamma(A)$, there exist positive paths $a$ and $b$ such that $f \ast ab^{-1}$ and $a \wedge b = t(a)$. Moreover, if $f \ast cd^{-1}$ where $c$ and $d$ are positive paths with $c \wedge d = t(c)$, then $a \ast c$ and $b \ast d$. Thus if $f \ast a_1b_1^{-1}$ for $a_1$ and $b_1$ positive, then $a \preceq a_1$ and $b \preceq b_1$.

In the above lemma $t(a)$ denotes the identity morphism at the vertex $t(a)$. The proof of Lemma 2.8 is identical to that of [8, Theorem 2.6]. The decomposition $f \ast ab^{-1}$ is called the pm-normal form of $f$.

Given a path $f = a_1^{e_1}a_2^{e_2} \cdots a_n^{e_n}$, define the signed intersection number, denoted as $i(f, H)$, to be the sum of all the $e_i$ such that $a_i$ is dual to $H$. In the special case when $f$ is positive, $i(f, H)$ is the number of times the edge path $\pi(f)$ crosses $H$. Two positive minimal paths with the same end points cross the same collection of hyperplanes (and each hyperplane is crossed exactly once). This gives the following lemma.

**Lemma 2.9** [26, Proposition 1.11]. Let $f$ and $g$ be paths on $\Gamma(A)$ such that $f \sim g$. Then $i(f, H) = i(g, H)$ for any $H \in A$.

2.4. Some facts about irreducible arrangements

Let $Z(A)$ be the dual zonotope of $A$ and $x$ a vertex in $Z(A)$. Following [14], the Coxeter graph of $A$ at $x$, denoted by $\Gamma_x$, is defined as follows. Let $\{e_i\}_{i=1}^k$ be the collection of edges of $Z(A)$ containing $x$, and let $H_i$ be the hyperplane of $A$ dual to $e_i$. Let $B_{ij} = H_i \cap H_j$. The vertices of $\Gamma_x$ are in one-to-one correspondence with $\{e_i\}_{i=1}^k$. Two distinct vertices are joined by an edge if $A_{A/B_{ij}}$ is irreducible (that is, if it contains more than two lines).

**Lemma 2.10** [14, Lemma 3.5]. Let $A$ and $Z(A)$ be as above. Then the following statements are equivalent.
(1) The arrangement $\mathcal{A}$ is an irreducible.
(2) The Coxeter graph $\Gamma_x$ is connected for some vertex $x \in Z(\mathcal{A})$.
(3) The Coxeter graph $\Gamma_x$ is connected for any vertex $x \in Z(\mathcal{A})$.

A face $F$ of $Z(\mathcal{A})$ that is dual to a subspace $B \in Q(\mathcal{A})$ is irreducible if $\mathcal{A}_{A/B}$ is irreducible. Then we have the following corollary to Lemma 2.10.

Corollary 2.11. Let $x \in Z(\mathcal{A})$ be a vertex. Suppose that there exists a pair of irreducible faces $F_1$ and $F_2$ of $Z(\mathcal{A})$ such that

(1) any edge of $Z(\mathcal{A})$ containing $x$ is contained in either $F_1$ or $F_2$;
(2) there exists an edge $e$ such that $x \in e$ and $e \subset F_1 \cap F_2$.

Then $\mathcal{A}$ is irreducible.

Lemma 2.12 [14, Lemma 3.11]. Suppose that $\mathcal{A}$ is a finite, central, simplicial real arrangement. If $\mathcal{A}$ is irreducible, then $\mathcal{A}^B$ is irreducible and simplicial for any subspace $B \in Q(\mathcal{A})$.

3. Garside theoretic computations

In this section, $\mathcal{A}$ is, as before, an essential, simplicial arrangement of linear hyperplanes in a real vector space $A$. Let $V = A \otimes \mathbb{C}$ and let $\mathcal{A} \otimes \mathbb{C}$ be the complexification of $\mathcal{A}$.

3.1. Faces of zonotopes and words of longest length

Let $Z(\mathcal{A})$ be the zonotope dual to $\mathcal{A}$ and let $\Gamma(\mathcal{A})$, $G^+ = G^+(\mathcal{A})$, $G = G(\mathcal{A})$, and $\pi : \Gamma(\mathcal{A}) \to Z(\mathcal{A})$ be as in Subsection 2.3.

Definition 3.1. Suppose that $F$ is a face of $Z(\mathcal{A})$. An $F$-path of $\Gamma(\mathcal{A})$ is a path whose image under $\pi$ is contained in $F$.

Put $\Gamma(\mathcal{A}, F) = \pi^{-1}(F)$. We can identify $\Gamma(\mathcal{A}, F)$ with $\Gamma(\mathcal{A}_{A/B})$, where $B$ is the subspace dual to $F$. Let $G(F)$ denote the Deligne groupoid over $\Gamma(\mathcal{A}, F)$ so that $G(F)$ is isomorphic to $G(\mathcal{A}_{A/B})$. By Remark 2.4, $G(F)$ also satisfies Theorem 2.7.

Define a retraction $r_F : \Gamma(\mathcal{A}) \to \Gamma(\mathcal{A}, F)$ as follows. Given a vertex $x \in \Gamma(\mathcal{A})$, put $r_F(x) = \text{Proj}_F(x)$, where $\text{Proj}_F$ is the “nearest vertex projection” defined in Lemma 2.2. Let $e$ be an oriented edge $\Gamma(\mathcal{A})$. Suppose $H_e \in Q(\mathcal{A})$ denotes the hyperplane dual to $e$. If $H_e$ is not dual to any edge of $F$, then $r_F(s(e)) = r_F(t(e))$ and we define $r_F(e) := r_F(s(e))$. If $H_e$ is dual to an edge of $F$, then $r_F(e)$ is the oriented edge from $r_F(s(e))$ to $r_F(t(e))$. The map $r_F$ induces a map from the set of paths on $\Gamma(\mathcal{A})$ to the set of paths on $\Gamma(\mathcal{A}, F)$; moreover, $r_F$ takes positive paths to positive paths, and positive minimal paths to positive minimal paths.

Lemma 3.2 [26, Proposition 1.30]. The natural map $G(F) \to G$ is injective and preserves the lattice structure. Moreover, the image of $G^+(F)$ is contained in $G^+$.

The lemma follows from the existence of $r_F$. Although the preservation of the lattice structure is not mentioned explicitly in [26], it follows easily from existence of $r_F$ and the fact that a positive $F$-path cannot be equivalent to a path which is not an $F$-path (by Lemma 2.9).

For a vertex $x \in \Gamma(\mathcal{A})$ and a face $F$ of $Z(\mathcal{A})$, denote by $\Sigma_{x \to F}$ (respectively, $\Sigma_{\to x}(F)$) the collection of edges in $\Gamma(\mathcal{A})$ whose image under $\pi$ is contained in $F$ and whose source (respectively, target) is $x$. Let $\text{Ant}(x, F)$ denote the antipodal vertex to $x$ in $F$. (Any zonotope
is centrally symmetric.) For \( y = \text{Ant}(x, F) \) define \( \Delta^y(x) \) (respectively, \( \Delta_x(F) \)) to be the morphism represented by a minimal positive path from \( y \) to \( x \) (respectively, \( x \) to \( y \)). The equivalence classes of such positive paths of this form are called Garside elements. For an integer \( k \geq 1 \), define

\[
(\Delta_x(F))^k := \underbrace{\Delta_x(F)\Delta_y(F)\Delta_x(F)\cdots}_{k \text{ times}}
\]

To simplify notation, put

\[
\Delta^x = \Delta^x(Z(A)), \quad \Sigma_{x \rightarrow} = \Sigma_{x \rightarrow}(Z(A)),
\]

\[
\Delta_x = \Delta_x(Z(A)), \quad \Sigma_{\rightarrow x} = \Sigma_{\rightarrow x}(Z(A)),
\]

and set \( \text{Ant}(x) = \text{Ant}(x, Z(A)) \).

**Lemma 3.3** [26]. The following statements are true.

1. For any vertex \( x \in \Gamma(A) \) and for any path \( g \) from \( x \) to \( y \), we have \((\Delta_x)^2 g \stackrel{*}{=} g(\Delta_y)^2\).
2. Let \( y = \text{Ant}(x) \). Then \( \Delta_x \succ e \) for any \( e \in \Sigma_{y} \).
3. Suppose \( \Sigma_{x \rightarrow} = \{e_1, e_2, \ldots, e_k\} \) and \( \Sigma_{\rightarrow x} = \{e_1', e_2', \ldots, e_k'\} \). Then \( \Delta_x \equiv e_1 \lor_p e_2 \lor_p \cdots \lor_p e_k \) and \( \Delta^x \equiv e_1' \lor_s e_2' \lor_s \cdots \lor_s e_k' \).
4. Let \( f \) be any path with \( x = s(f) \). Then there is an integer \( k \geq 0 \) and positive path \( g \) such that \( f \equiv (\Delta_x)^{-2k} g \equiv g(\Delta_{\pi(f)})^{-2k} \).
5. Suppose that \( v \) is a positive path with \( x = s(v) \) and \( y = t(v) \). Then there is a positive path \( u \) such that \( \Delta^x v \equiv u \Delta^y \).

The next lemma is a consequence of Lemma 3.2 and Lemma 3.3 (3).

**Lemma 3.4.** For vertex \( x \in \Gamma(A) \), let \( \Sigma_{x \rightarrow}(F) = \{e_1, e_2, \ldots, e_k\} \) and \( \Sigma_{\rightarrow x}(F) = \{e_1', e_2', \ldots, e_k'\} \). Then

\[
\Delta_x(F) = e_1 \lor_p e_2 \lor_p \cdots \lor_p e_k \quad \text{and} \quad \Delta^x(F) = e_1' \lor_s e_2' \lor_s \cdots \lor_s e_k',
\]

where \( F \) is the face of \( Z(A) \) spanned by \( \{\bar{e}_1, \ldots, \bar{e}_k\} \), where the \( \bar{e}_i \) (\( = \pi(e_i) \)) are as defined in the first paragraph of Subsection 2.3.

### 3.2. Elementary \( B \)-segments

**Definition 3.5.** Parallel faces \( F \) and \( F' \) of \( Z(A) \) are adjacent if \( F \neq F' \) and if they are contained in a face \( F_0 \) with \( \dim(F_0) = \dim(F) + 1 \).

**Lemma 3.6.** Let \( F, F' \) and \( F_0 \) be as in Definition 3.5.

1. For any vertex \( x \in F \), \( \text{Ant}(x, F_0) \in F' \).
2. If \( p : F \to F' \) is parallel translation, then \( \text{Ant}(p(x), F') = \text{Ant}(x, F_0) \).

The following is a generalization of the notion of elementary conjugator in [46, Section 5].

**Definition 3.7.** Let \( B \in \mathcal{Q}(A) \). Let \( F \) and \( F' \) be two adjacent parallel faces of \( Z(A) \) that are dual to \( B \). An elementary \( B \)-segment, or an \((F,F')\)-elementary \( B \)-segment is a minimal positive path from a vertex \( x \in F \) to \( x' = p(x) \in F' \), where \( p : F \to F' \) is parallel translation.

**Lemma 3.8.** Let \( B, F, F', \) and \( F_0 \) be as in Definition 3.7.
(1) For any vertex $x \in F$ and $y = \text{Ant}(x, F_0) \in F'$, $\Delta_x(F_0)(\Delta^y(F'))^{-1} \circ \Delta^y(F_0)(\Delta^y(F'))^{-1}$ is an elementary $B$-segment.

(2) Any elementary $B$-segment can be written as $\Delta_x(F_0)(\Delta^y(F'))^{-1}$ for some vertex $x \in F$.

(3) Let $u$ be an elementary $B$-segment. Let $x' = t(u)$. Then $(\Delta_x(F))^k u \circ \Delta_x(F'')^k$ for any positive even integer $k$.

(4) Let $e \in \Sigma_x \rightarrow (F)$ (respectively, $e \in \Sigma_x \rightarrow (F')$) and let $e'$ be the oriented edge in $F'$ that is parallel to $e$. Then there is an elementary $B$-segment $v$ such that $ev = u e'$ (respectively, $eu = ve'$).

(5) A positive path representing an elementary $B$-segment does not cross any hyperplane dual to an edge of $F$.

Proof. Let $p : F \rightarrow F'$ be parallel translation. By Lemma 2.2, there is a minimal positive path from $x$ to $y$ passing through $p(x)$ such that the segment from $p(x)$ to $y$ is an $F'$-path. So, statements (1) and (2) follow from Lemma 3.6 (2). For (3), let $z = \text{Ant}(x, F)$ and $z' = \text{Ant}(z, F'')$. Then $z' = p(z)$. Let $v$ be an elementary $B$-segment from $z$ to $z'$. By Lemma 2.2, both $u \Delta_z(F'')$ and $\Delta_z(F')$ are minimal positive paths with the same endpoints. Thus, $u \Delta_z(F'') \circ \Delta_z(F')$. Similarly, $v \Delta_z(F'') \circ \Delta_z(F')$. Statement (3) now follows by repeatedly applying these two equations. Similarly, statement (4) can be deduced from Lemma 2.2. Statement (5) is immediate.

Lemma 3.9. Take two pairs of adjacent parallel faces $(F_1, F)$ and $(F_2, F)$ dual to the subspace $B$. For $i = 1, 2$, let $u_i$ be an $(F_i, F)$-elementary $B$-segment. Suppose $t(u_1) = t(u_2) = x$. Then $u_1 \vee u_2 \circ \Delta^y(F') \circ \Delta_y(F')$ for some vertex $e \in F_1$. Moreover, $\dim(F') = \dim(F) + 2$ unless $F_1 = F_2$.

In particular, $u_1 \vee u_2$ is represented by a minimal positive path which is a concatenation of elementary $B$-segments.

Proof. For $i = 1, 2$, let $F'_i$ be the face containing $F \cup F_1$ such that $\dim(F'_i) = \dim(F_i) + 1$. Let $e_i$ be the last edge of $u_i$. Then $F'_i$ is spanned by $F$ and $e_i$ (by Lemma 2.3). Moreover, $F'$ is the face spanned by $F, e_1$ and $e_2$. Also, $F' = F'_1 = F'_2$ if and only if $e_1 = e_2$; otherwise, $\dim(F') = \dim(F) + 2$. Let $y = \text{Ant}(x, F)$. By Lemma 3.4,

$$\Delta^y(F'_1) \vee \Delta^y(F'_2) \circ \Delta^y(F'_1) \vee \Delta^y(F'_2)$$

where $\vee : \Sigma_{\rightarrow y}(F'_i)$ denotes the least common multiple of all edges in $\Sigma_{\rightarrow y}(F'_i)$ (where “least” is with respect to the suffix order).

By Lemma 3.8 (1), $u_1 \Delta_x(F) \circ \Delta_x(F)$ for $i = 1, 2$. Thus,

$$(u_1 \vee u_2) \Delta_x(F) \circ \Delta_x(F) \circ \Delta_x(F) \circ \Delta_x(F) \circ \Delta_x(F)$$. 

The lemma follows.

3.3. Computation of centralizers

In this subsection, we modify some computations of centralizers of parabolic subgroups of spherical Artin groups from [46, Lemma 5.6 and Theorem 5.2] to the context of Deligne groupoids.

Lemma 3.10. Take a face $F' \subset Z(A)$. Let $f$ be a positive path in $\Gamma(A)$. For a positive integer $k$, consider $y = f(\Delta_x(F'))^k$ where $x' = t(f)$. Suppose $g \gg e$ for an edge $e$ with $e \not\subset F'$. Then there exists an elementary $B$-segment $u$ such that $f \gg u$. 

Proof. Let $x'_m = t(f(\Delta_{x'}(F'))^m)$. Let $F'_1$ be the face spanned by $F'$ and $\bar{e}$. We prove by induction on $i$ that if $1 \leq i \leq k$, then there exists a positive path $f_i$ and an elementary $B$-segment $v_i$ such that

$$f(\Delta_{x'}(F'))^{k-i} \overset{\ast}{=} f_i v_i$$

and $v_i \subset F'_1$.

First consider the case $i = 1$. Then $e \in \Delta_{x'}(F') \overset{\ast}{=} \Delta_{x'}(F'_1)$. Thus, $f(\Delta_{x'}(F'))^k \overset{\ast}{=} f_1 \Delta_{x'}(F'_1)$ for some positive path $f_1$. Then

$$f(\Delta_{x'}(F'))^{k-1} \overset{\ast}{=} f_1 \Delta_{x'}(F'_1)(\Delta_{x'}(F'))^{-1} \overset{\ast}{=} f_1 v_1.$$ 

Next suppose that $f(\Delta_{x'}(F'))^{k-i} \overset{\ast}{=} f_i v_i$. As $v_i$ ends with an edge $e_i$ such that $\bar{e}_i \subset F'_1$ and $\bar{e}_i \not\subset F''$, we have that $e_i \in \Delta_{x'}(F') \overset{\ast}{=} \Delta_{x'}(F'_1)$. Thus, $f_i(\Delta_{x'}(F'))^{k-i} \overset{\ast}{=} f_{i+1} \Delta_{x'}(F'_1)$ for a positive path $f_{i+1}$. Then

$$f_i(\Delta_{x'}(F'))^{k-i-1} \overset{\ast}{=} f_{i+1} \Delta_{x'}(F'_1)(\Delta_{x'}(F'))^{-1} \overset{\ast}{=} f_{i+1} v_{i+1}.$$ 

This completes the proof. \hfill \Box 

**Lemma 3.11.** Given two parallel faces $F$, $F'$ of $Z(A)$, let $f$ be a positive path in $\Gamma(A)$ from $x \in F$ to $x' \in F'$ satisfying the following.

1. $f(\Delta_{x'}(F'))^k \overset{\ast}{=} h f$, for an even integer $k \geq 2$ and a positive path $h$.

2. There does not exist an edge $e \in \Sigma_{x'}(F')$ such that $f \succ e$.

Then $f \overset{\ast}{=} u_1 u_2 \cdots u_n$ where each $u_i$ is an elementary $B$-segment and $B \in \mathcal{Q}(A)$ is dual to $F$. Moreover, $h = (\Delta_{x}(F))^k$.

Proof. We use induction on the length of $f$. Let $e$ be the last edge of $f$. By assumption, $\bar{e} \not\subset F$. Let $F'_1$ be the face spanned by $F'$ and $e$. By Lemma 3.10, $f \overset{\ast}{=} f_k v_k$ where $f_k$ is positive and $v_k$ is an elementary $B$-segment. Let $x'' = t(f_k)$ and let $F''$ be the face such that $F''$ is parallel to $F$ and $x'' \in F''$. By Lemma 3.8 (3),

$$f_k(\Delta_{x''}(F''))^k v_k \overset{\ast}{=} f_k v_k(\Delta_{x'}(F'))^k \overset{\ast}{=} f(\Delta_{x'}(F'))^k \overset{\ast}{=} h f \overset{\ast}{=} h f_k v_k.$$ 

Thus, $f_k(\Delta_{x''}(F''))^k \overset{\ast}{=} h f_k$. Moreover, there does not exist an edge $e \in \Sigma_{x''}(F')$ such that $f_k \succ e$, for otherwise, by Lemma 3.8 (4), we would have $f \succ e'$ for $e'$ parallel to $e$. The lemma follows by induction. The last statement of the lemma follows from Lemma 3.8 (3) and induction. \hfill \Box 

**Corollary 3.12.** Let $F \subset F'$ be two faces of $Z(A)$. Suppose $B \in \mathcal{Q}(A)$ is dual to $F$. Let $y \in F'$ be a vertex. Then $\Delta^y(F')(\Delta^y(F))^{-1}$ is equivalent to a concatenation of elementary $B$-segments.

Proof. Let $f = \Delta^y(F')(\Delta^y(F))^{-1}$ and $x = \text{Ant}(y,F)$. By Lemma 3.3, $f(\Delta^y(F))^2 f^{-1} = \Delta^y(F')\Delta_y(F)f^{-1} = \Delta^y(F')\Delta_y(F)\Delta^y(F)(\Delta^y(F))^{-1}$ is positive, so the first condition of Lemma 3.11 holds. As $\Delta^y(F') \overset{\ast}{=} f \Delta^y(F)$ is positive and minimal, $f$ cannot cross any hyperplane dual to $F$. So the second condition of Lemma 3.11 also holds. The corollary follows. \hfill \Box 

**Corollary 3.13.** Let $F$ be a face of $Z(A)$ and let $x \in F$ be a vertex. Let $f \in G_x$ be such that $f(\Delta_x(F))^2 = (\Delta_x(F))^2 f$. Let $G_{x,F}$ be the collection of $F$-paths with both source
and target equal to $x$. Then there exists an integer $k \geq 0$, and a collection of elementary $B$-segments (where $B \in Q(A)$ is dual to $F$) \{$(u_i)$\}_{i=1}^k and a positive path in $G_{x,F}$ such that $f = (\Delta_x)^{-2k}u_1u_2 \cdots u_kv$.

**Proof.** By Lemma 3.3, we have $f = (\Delta_x)^{-2k}g$ where $g$ is positive. Then $g(\Delta_x(F))^2 = (\Delta_x(F))^2g$. We can write $g = hv$ where $v$ is a positive $F$-path, $h$ is positive, and there does not exist edge $e$ with $\bar{e} \subset F$ and $h \geq e$. Let $x' = s(v) = t(h)$. Then $v(\Delta_x(F))^2 = (\Delta_x(F))^2h$. It follows that $h(\Delta_x(F))^2 = (\Delta_x(F))^2h$. By Lemma 3.11, $h$ is a concatenation of elementary $B$-segments. It follows from the definition of a $B$-segment that $x' = x$. Thus, $v \in G_{x,F}$. \hfill $\Box$

### 3.4. Injectivity of the restriction arrangement groupoid

In this subsection we study how the Deligne groupoid of a restriction arrangement sits inside the ambient Deligne groupoid. This will show how to push $\pi_1(M(A^B \otimes C))$ into $\pi_1(M(A \otimes C))$.

**Lemma 3.14.** Let $B \in Q(A)$.

1. There is a natural one-to-one correspondence between chambers of $A^B$ and the collection of faces of $Z(A)$ that are dual to $B$.

2. Two chambers of $A^B$ are adjacent if and only if the associated faces of $Z(A)$ (as in (1) above) are adjacent (see Definition 3.5).

**Definition 3.15.** We define a map $\phi : \Gamma(A^B) \to \Gamma(A)$ as follows. First choose a vertex $x \in \Gamma(A^B)$ and let $F$ be the face of $Z(A)$ associated with $x$ as in the previous lemma. Then choose a vertex $y$ in $F$ and set $\phi(x) = y$. For any other vertex $x' \in \Gamma(A^B)$, let $F'$ be the face of $Z(A)$ associated with $x'$ and let $p : F \to F'$ be parallel translation. Define $\phi(x')$ to be $p(y)$. Let $e$ be the edge of $\Gamma(A^B)$ from $x_1$ to $x_2$. Define $\phi(e)$ be a positive minimal path from $\phi(x_1)$ to $\phi(x_2)$. (Such a positive minimal path always exists; however, it might not be unique. If it is not, choose one arbitrarily.)

It is clear that $\phi : \Gamma(A^B) \to \Gamma(A)$ induces maps $G^+(A^B) \to G^+(A)$ and $G(A^B) \to G(A)$, both of which we also denote by $\phi$.

Let $y'$ be a vertex of $\Gamma(A)$ such that $y' = \phi(y)$ for some $y \in \Gamma(A^B)$ (such a $y$ is unique). Let $F_{y'}$ be the face of $Z(A)$ associated with $y$ as in Lemma 3.14 (1).

**Lemma 3.16.** The map $\phi : G(A^B) \to G(A)$ is injective.

**Proof.** We first show that $\phi : G^+(A^B) \to G^+(A)$ is injective. Let $f_1, f_2$ be two positive paths in $\Gamma(A^B)$ and let $f_1, f_2$ be their image under $\phi$. Then $f_1 = u_1u_2 \cdots u_n$, where each $u_i$ is an elementary segment coming from an edge of $f_1$. Similarly, $f_2$ can be written as $f_2 = v_1v_2 \cdots v_m$.

Suppose $f_1 = f_2$. We need to show that $f_1 = f_2$, where $f_1$ refers to equivalent paths in $\Gamma(A^B)$. This will be proved by induction on $c = \ell(f_1) + \ell(f_2)$, where $\ell(f)$ denotes the length of $f$. The case $c = 0$ is immediate, as $\ell(\phi(f)) > 0$ if and only if $\ell(f) > 0$. Next we consider the general case $c \geq 0$. Let $w = u_n \lor v_m$. Then there is positive path $p$ such that $f_1 = pw$ and $f_2 = f_2$. Let $w_1$ and $w_2$ be positive paths such that $w = w_1u_n = w_2v_m$. By Corollary 3.12 and Lemma 3.9, $w_1$ and $w_2$ are equivalent to concatenations of elementary $B$-segments. By Lemma 3.8 (3), both $f_1$ and $f_2$ satisfy condition (1) of Lemma 3.11; so, the same holds for the positive path $p$. By Lemma 3.8 (5), both $f_1$ and $w$ do not cross any hyperplane dual to $F$, and so, the same holds for $p$ by Lemma 29. By Lemma 3.11, $p$ is equivalent to a concatenation of elementary $B$-segments. Thus, we can find positive paths $\hat{w}_1$ and $\hat{p}$ of $\Gamma(A^B)$ such that $\phi(\hat{w}_1) = w_1$ and $\phi(\hat{p}) = p$. We delete the last edge $\hat{e}_1$ of $\hat{f}_1$ to obtain $\hat{f}_1$. Then $\phi(\hat{f}_1) = \phi(\hat{p}\hat{w}_1) = u_1u_2 \cdots u_{n-1}$.\hfill $\Box$
We can assume by induction that \( \hat{g}_1 = B \hat{p} \hat{w}_1 \). Define \( \hat{w}_2, \hat{e}_2 \), and \( \hat{g}_2 \) similarly and then conclude that \( \hat{g}_2 = B \hat{p} \hat{w}_2 \). By Lemma 3.9 both \( \hat{w}_1 \hat{e}_1 \) and \( \hat{w}_2 \hat{e}_2 \) are positive minimal paths in \( \Gamma(A^B) \). Thus, \( \hat{w}_1 \hat{e}_1 = B \hat{w}_2 \hat{e}_2 \). Then

\[
\hat{f}_1 = B \hat{g}_1 \hat{e}_1 \hat{w}_1 \hat{e}_1 = B \hat{p} \hat{w}_2 \hat{e}_2 = B \hat{g}_2 \hat{f}_2.
\]

Next take paths \( \hat{f}_1, \hat{f}_2 \) on \( \Gamma(A^B) \) not necessarily positive and let \( f_1, f_2 \) denote their \( \phi \)-images. Suppose \( f_1 \hat{=} f_2 \). By Lemma 3.3 and Remark 2.4, there is a \( k \geq 0 \) such that for \( i = 1, 2 \), \( f_i = B (\Delta_{x(f_i)})^{2k} \hat{g}_i \), with \( \hat{g}_i \) positive. Since \( f_1 \hat{=} f_2 \), we deduce that \( \phi(\hat{g}_1) \hat{=} \phi(\hat{g}_2) \). By the previous discussion, \( \hat{g}_1 = B \hat{g}_2 \). Hence, \( \hat{f}_1 = B \hat{f}_2 \), as required.

Let \( F \) be a face of \( Z(\mathcal{A}) \) and let \( \Gamma(\mathcal{A}, F) \) be the graph defined in Section 3.1. For the product arrangement \( \mathcal{A}_{A/B} \times \mathcal{A}^B \) (which is also simplicial by Remark 2.4), we can identify \( \Gamma(\mathcal{A}_{A/B} \times \mathcal{A}^B) \) with the 1-skeleton of \( \Gamma(\mathcal{A}, F) \times \Gamma(\mathcal{A}) \). Thus, each vertex of \( \Gamma(\mathcal{A}_{A/B} \times \mathcal{A}^B) \) corresponds to a vertex of \( \Gamma(\mathcal{A}) \). This induces a map

\[
\theta : \Gamma(\mathcal{A}_{A/B} \times \mathcal{A}^B) \to \Gamma(\mathcal{A})
\]

doing so that for each vertex \( x \in F \), the restriction of \( \theta \) to \( \{x\} \times \Gamma(\mathcal{A}) \) is equal to the map \( \phi \) in Definition 3.15.

**Corollary 3.17.** The map \( \theta \) satisfies the following.

1. The homomorphism of groupoids \( \theta_* : \mathcal{G}(\mathcal{A}_{A/B} \times \mathcal{A}^B) \to \mathcal{G}(\mathcal{A}), \) that is induced by \( \theta \), is injective.
2. Let \( x' \in \Gamma(\mathcal{A}_{A/B} \times \mathcal{A}^B) \) be a vertex. Let \( x = \theta(x') \) and let \( F_x \) be the face containing \( x \) and parallel to \( F \). Then \( \theta_*((\mathcal{G}_{x'}(\mathcal{A}_{A/B} \times \mathcal{A}^B))) \) is the centralizer of \( (\mathcal{D}_{x}(F_x))^2 \) in \( \mathcal{G}_{x}(\mathcal{A}) \).
3. Let \( U = \langle (\mathcal{D}_{x}(F_x))^2 \rangle \) and \( G = \mathcal{G}_{x}(\mathcal{A}) \). Then \( C_G(U) = N_G(U) = \theta_*((\mathcal{G}_{x'}(\mathcal{A}_{A/B} \times \mathcal{A}^B))). \)

The centralizer \( U \) in \( G \) is denoted by \( C_G(U) \) and the normalizer denoted by \( N_G(U) \).

**Proof.** Note that \( \theta \) takes minimal positive paths to minimal positive paths; so, \( \theta_* \) is well defined. Moreover, \( \mathcal{G}(\mathcal{A}_{A/B} \times \mathcal{A}^B) \cong \mathcal{G}(\mathcal{A}_{A/B}) \times \mathcal{G}(\mathcal{A}^B) \). So, the first assertion follows from Lemmas 3.2 and 3.16. By Lemma 3.3 (1), \( \theta_*((\mathcal{G}_{x'}(\mathcal{A}_{A/B} \times \mathcal{A}^B))) \) is contained in the centralizer of \( (\mathcal{D}_{x}(F_x))^2 \). The containment in the other direction follows from Corollary 3.13. For (3), we need to show that \( (\mathcal{D}_{x}(F_x))^2 \) is not conjugate to its inverse; however, this follows from Lemma 2.9 since two conjugate paths have the same intersection number with each hyperplane in \( \mathcal{A} \).

3.5. Simultaneously conjugating mutually commuting Dehn twists

**Definition 3.18.** Take a base vertex \( x_0 \in \Gamma(\mathcal{A}) \). Let \( F \) be an irreducible face of \( Z(\mathcal{A}) \) and let \( x_F = \text{Proj}_F(x) \) (defined in Lemma 2.2). Let \( h_F \) be a minimal positive path from \( x_0 \) to \( x_F \). The **standard Dehn twist** associated with \( F \), denoted by \( \mathcal{Z}_F \), is defined to be \( h_F(\mathcal{D}_{x_F}(F))^2 h^{-1}_F \).

**Lemma 3.19.** Let \( h \) be a positive path from \( x_0 \) to \( x_F \). We write \( f = h \mathcal{Z}_F h^{-1} \) in its \( p \)-normal form \( ab^{-1} \). Then there is a \( F' \) parallel to \( F \) such that \( b^{-1} f b = (\mathcal{D}_{x}(F'))^2 \) for a vertex \( x \in F' \).

This observation is taken from [12, Theorem 4] in the case of spherical Artin groups. The same proof given there also works for the Deligne groupoid and we give it below.
Proof. Let $g = hh_F$. Then $f = g(\Delta_{x_F}(F))^2g^{-1}$. If there does not exist an edge $e$ such that $g(\Delta_{x_F}(F))^2 \parallel e$ and $g \parallel e$, then we are done by Lemma 2.8. Suppose that such $e$ exists. If $e \subset F$, then $e(\Delta_{x_F}(F))^2 e^{-1} = (\Delta(e)(F))^2$ by Lemma 3.3 and we can shorten $g$. If $e \not\subset F$, then Lemma 3.10 implies that $g = g_1u$ where $g_1$ is positive and $u$ is an elementary $B$-segment where $B$ is the subspace dual to $F$. By Lemma 3.8 (3), $u(\Delta_{t(e)}(F))^2u^{-1} = (\Delta_{h(u)}(F_1))^2$ for a face $F_1 \parallel F$. So again, we can shorten $g$ again. The lemma follows by repeatedly applying this procedure.

Alternatively, one could define $Z_F$ by taking an arbitrary vertex $x \in F$ (not necessarily $x_F$), taking a minimal positive path $h$ from $x_0$ to $x$, and considering $h(\Delta_x(F))^2 h^{-1}$. We claim that $Z_F \cong h(\Delta_x(F))^2 h^{-1}$. Indeed, by [26, Section 2], there exists a minimal path $h' = h_1h_2$ such that $h \cong h'$, $t(h_1) = s(h_2) = x_F$ and $h_2 \subset F$. We can then use the same argument as in the proof of Lemma 3.19 to deduce the claim.

The following lemma is proved in [13] for spherical Artin groups, where the argument is based on solution of the conjugacy problem for Garside groups. We give a shorter proof based on arguments from [46].

**Lemma 3.20.** Let $\{F_i\}_{i=1}^k$ be a collection of faces of $Z(A)$. Consider a mutually commuting collection \( \{g_i := h_i Z_{F_i} h_i^{-1}\}_{i=1}^k \) where $h_i \in G_{x_0}$. Then there exist an element $g \in G_{x_0}$ such that for each $i$, $g g_i g^{-1} = Z_{F_i}$ for some face $F_i \subset Z(A)$ parallel to $F_i$. Moreover, there is a vertex $x \in \Gamma(A)$ such that $x \in \bigcap_{i=1}^k F_i$.

**Proof.** The proof is by induction on $k$. The case $k = 1$ is clear. Assume by induction that $h_i$ is the trivial element for $1 \leq i \leq k - 1$, and assume, moreover, that there is a vertex $x \in \Gamma(A)$ and a minimal positive path $h$ from $x_0$ to $x$ such that $Z_{F_i} = h(\Delta_x(F_i))^2 h^{-1}$ for each $1 \leq i \leq k - 1$. Define $S_0 = \{Z_{F_1}, \ldots, Z_{F_{k-1}}, h_k Z_{F_k} h_k^{-1}\}$. Then any two elements from the set $S_1 = \{(\Delta_x(F_1))^2, \ldots, (\Delta_x(F_{k-1}))^2, h^{-1} h_k Z_{F_k} h_k^{-1}\}$ commute.

By Lemma 3.3, we can assume $f := h^{-1} h_k$ is positive. Let $ab^{-1}$ be the $pn$-normal form of $f Z_{F_k} F^{-1}$. For each $i$ with $1 \leq i \leq k - 1$, we have $(\Delta_x(F_i))^2 a b^{-1} = ab^{-1} (\Delta_x(F_i))^2$. Thus, $(\Delta_x(F_i))^2 a \cdot (\Delta_x(F_i))^2 b^{-1} = a \cdot b^{-1}$. It follows from Lemma 2.8 that $a^{-1}(\Delta_x(F_i))^2 a = b^{-1}(\Delta_x(F_i))^2 b$ is positive. Decompose $b$ as $b = b_1 b_2$, where $b_2$ is a maximal positive $F_i$-path. By applying Lemma 3.3 (3) to $b_2$ and Lemma 3.11 to $b_1$, we deduce that $b^{-1}(\Delta_x(F_i))^2 b \cong (\Delta_y(F'_i))^2$ where $F'_i \parallel F_i$ and $y = t(b)$. By Lemma 3.19, $b^{-1}(f Z_{F_k} F^{-1}) b \cong (\Delta_y(F'_i))^2$ with $F'_i$ parallel to $F_k$. Thus, $b^{-1} h^{-1} S_0 h b^{-1} S_1 b = ((\Delta_y(F'_i))^2)_{i=1}^k$. Take a minimal positive path $h'$ from $x$ to $y$ and let $g = h' b^{-1} h^{-1}$. Then $g S_0 g^{-1} = \{Z_{F_i}\}_{i=1}^k$.

**Lemma 3.21.** Let $F_1$ and $F_2$ be two irreducible faces of $Z(A)$. Then $Z_{F_1}$ and $Z_{F_2}$ commute if and only if $F_1 \perp F_2$ or if $F_1$ and $F_2$ are comparable.

**Proof.** By Lemma 3.20, $F_1 \cap F_2 \neq \emptyset$. We assume without loss of generality that the base point $x_0$ is contained in $F_1 \cap F_2$, and that $Z(A)$ is spanned by $F_1$ and $F_2$. Let $f = (\Delta_{x_0}(F_1))^2(\Delta_{x_0}(F_2))^2 \cong (\Delta_{x_0}(F_2))^2(\Delta_{x_0}(F_1))^2$. By Lemma 3.3, $e \cong f$ for any $e \in \Sigma_{x_0 \rightarrow}$; hence, $\Delta_{x_0} \cong f$. Let $H$ (respectively, $H_i$) be the collection of hyperplanes dual to edges of $Z(A)$ (respectively, $F_i$). Let $H_f$ be the collection of hyperplanes crossed by $f$. Then $H_f = H_1 \cup H_2$.

By Lemma 3.9, $H_{\Delta_{x_0}} \subset H_f$. As $H_{\Delta_{x_0}} = H$, we have that $H = H_1 \cup H_2$. Thus, if $F_1 \cap F_2$ is a vertex, then $H = H_1 \cup H_2$, which implies $F_1 \perp F_2$.

Next assume $F := F_1 \cap F_2$ contains an edge, then $Z(A)$ is irreducible by Corollary 2.11. Suppose that $B$ is the subspace dual to $F$. Let $\theta : \Gamma(A_B / F) \to \Gamma(A)$ be the map defined.
before Corollary 3.17. Let \( x_0 \) be such that \( \theta(x_0) = x_0 \). Let \( \Delta_{x_0}(A_{A/B}) \) be the Garside element of the \( A_{A/B} \)-factor.

An edge \( e \) of \( \Sigma_{x_0}(F_1) - \Sigma_{x_0}(F) \) gives rise to an elementary \( B \)-segment contained in the face spanned by \( e \) and \( F \) that corresponds to an edge \( \bar{e} \) in \( \Gamma(A^B) \). Let \( F'_1 \) be the face of \( Z(A^B) \) spanned by all such edges coming from elements of \( \Sigma_{x_0}(F_1) - \Sigma_{x_0}(F) \). Define \( F'_2 \) similarly. Then \( F'_1 \cap F'_2 \) is a vertex, and \( Z(A^B) \) is spanned by \( F'_1 \) and \( F'_2 \).

It is readily verified that \( \theta((\Delta_{x_0}(A_{A/B}))^2(\Delta_{x_0}(F'_i)))^2 \equiv (\Delta_{x_0}(F_i))^2 \) for \( i = 1, 2 \). By Corollary 3.17 (1), \( (\Delta_{x_0}(F'_i))^2(\Delta_{x_0}(F'_2))^2 \equiv (\Delta_{x_0}(F'_2))^2(\Delta_{x_0}(F'_i))^2 \) in \( \Gamma(A^B) \). By the argument in the previous paragraph, \( Z(A^B) \cong F'_1 \times F'_2 \). By Lemma 2.12, either \( F'_1 \) or \( F'_2 \) has to be a point. Thus, \( F_1 \subset F_2 \), or \( F_2 \subset F_1 \).

\[ \square \]

4. The Deligne groupoid, the Deligne complex, and simple connectivity of the curve complex

Throughout the this section we assume that \( A \) is irreducible. To prove the main theorem, we need to know that one of \( C_{\text{gro}}(A) \) or \( C_{\text{top}}(A) \) is simply connected when \( \dim V \geq 4 \). Simple connectivity of \( C_{\text{top}}(A) \) follows from Remark 1.28. On the other hand, it is possible to prove that \( C_{\text{gro}}(A) \) is simply connected via a direct elementary argument, which is given in this section. Readers who are comfortable with Remark 1.28 can slip this section. Alternatively, the material in this section offers an independent route to the main theorem without relying on Remark 1.28.

4.1. From the Deligne complex to the curve complex

Here we define a version of the curve complex without using bordifications; instead, it is defined in terms of the Deligne groupoid. Choose a base vertex \( x_0 \in \Gamma(A) \) and let \( G = G_{x_0} \) denote the isotropy group at \( x_0 \). A standard \( Z \)-subgroup of \( G \) is a conjugate of a standard Dehn twist associated to a proper irreducible face of \( Z(A) \) (cf. Definition 3.18). The groupoidal curve complex \( C_{\text{gro}}(= C_{\text{gro}}(A)) \) is defined as follows. The vertices of \( C_{\text{gro}} \) are in one-to-one correspondence with standard \( Z \)-subgroups of \( G \) and a set of vertices spans a simplex if the associated \( Z \)-subgroups mutually commute. From this we see that \( C_{\text{gro}} \) is a flag complex. The group \( G \) acts by conjugation on the set of standard \( Z \)-subgroups and this induces \( G \curvearrowright C_{\text{gro}} \).

**Remark 4.1.** In this section we only need to consider \( C_{\text{gro}}(A) \) when \( A \) is irreducible. However, if \( A \) has more than one irreducible factor, say \( A = A_1 \oplus \cdots \oplus A_l \), then, by Definition 1.4, \( Z_0(A) = Z_0(A_1) \ast \cdots \ast Z_0(A_l) \). By analogy, in the general case, it would make sense to define \( C_{\text{gro}}(A) \) as \( C_{\text{gro}}(A_1) \ast \cdots \ast C_{\text{gro}}(A_l) \), although we never use this definition.

**Definition 4.2.** The spherical Deligne complex associated with \( A \), denoted as \( \text{Del}'(A) \), is defined as follows. Let \( \partial \text{Fan}(A) \) denote the cellulation of the unit sphere in \( A \) cut out by the hyperplanes of \( A \). For each vertex \( y \in \Gamma(A) \), let \( C_y \) be chamber containing \( y \) (so that \( C_y \) is a top-dimensional closed cell of \( \partial \text{Fan}(A) \)). For each vertex \( x \in \text{Sal}(A) \), put \( C_x = C_{k(x)} \), where \( k : \text{Sal}(A) \to \text{Sal}(A) \) is the covering projection. The *spherical Deligne complex* associated with \( A \), denoted as \( \text{Del}'(A) \), is defined by:

\[
\text{Del}'(A) = \bigsqcup_{x \in \text{Vert(Sal}(A))} (x, C_x) / \sim .
\]

Here \( \sim \) is the equivalence relation which glues adjacent chambers along codimension-one faces. To be more explicit, suppose that \( F_i \) is a face of \( C_{x_i} \) for \( i = 1, 2 \). We identify \((x_1, F_1)\) with
$(x_2, F_2)$ if $x_1$ and $x_2$ are adjacent in $\widehat{\text{Sal}(A)}$ and $F_1 = F_2$; the equivalence relation $\sim$ is generated by such identifications. There is an action $G \acts \text{Del}'(A)$.

The union of all $(x, C_x)$, with $x$ ranging over the vertices of a top-dimensional face of $\widehat{\text{Sal}(A)}$, gives rise to an embedded sphere in $\text{Del}'(A)$ called an apartment of $\text{Del}'(A)$. The Deligne complex, denoted as $\text{Del}(A)$, is obtained from $\text{Del}'(A)$ by filling in independently each apartment of $\text{Del}'(A)$ by a disk of dimension equal to $\dim(A)$.

**Lemma 4.3.** Suppose that $A$ is a central arrangement of hyperplanes in a real vector space $A$. Then $\text{Del}(A)$ is simply connected.

The above lemma follows from [26] (see also [45, p. 49]) since the Deligne complex (up to subdivision) is isomorphic to the nerve of an open cover of the universal cover of $\mathcal{M}(A \otimes \mathbb{C})$ where each open set of the cover is connected.

Each face of $\text{Del}'(A)$ can be written as $(x, F)$ where $x \in \text{Vert}(\widehat{\text{Sal}(A)})$ and $F$ being a simplex of $\partial \text{Fan}(A)$. For a simplex $F$ of $\partial \text{Fan}(A)$, we define $K_F$ to be the standard subcomplex of $\widehat{\text{Sal}(A)}$ associated with the face of $Z(A)$ dual to $F$ (cf. Subsection 2.2). A standard subcomplex of $\widehat{\text{Sal}(A)}$ is proper if it is neither a vertex nor the entire zonotope $Z(A)$. Similarly, a proper standard subcomplex of $\widehat{\text{Sal}(A)}$ is a connected component of the inverse image of a proper standard subcomplex in $\widehat{\text{Sal}(A)}$ under the covering map $k : \text{Sal}(A) \to \text{Sal}(A)$. A standard subcomplex is nontrivial if it is not a point. Then $(x, F) = (y, F)$ if and only if $x$ and $y$ are in the same standard subcomplex of $\widehat{\text{Sal}(A)}$ that projects to $K_F$. Thus, the vertices of the barycentric subdivision $b \text{Del}'(A)$ of $\text{Del}'(A)$ are in one-to-one correspondence with standard subcomplexes of $\widehat{\text{Sal}(A)}$. This gives rise to an alternative description of the simplicial complex $b \text{Del}'(A)$: the vertices of $b \text{Del}'(A)$ are in one-to-one correspondence with standard subcomplexes of $\text{Sal}(A)$, and a simplex in $b \text{Del}'(A)$ corresponds to a chain of standard subcomplexes in $\text{Sal}(A)$.

Now suppose that $A$ is irreducible. Let $\text{D}(A)$ be the full subcomplex of $b \text{Del}'(A)$ spanned by vertices that correspond to proper standard subcomplexes. In other words, $\text{D}(A)$ can be identified with the barycentric subdivision of $(n - 2)$-skeleton of $\text{Del}'(A)$, where $n = \dim A$; that is to say, the interiors of top-dimensional simplices of $\text{Del}'(A)$ have been deleted. Thus, $\text{D}(A)$ is simply connected whenever $n \geq 4$ (that is, when $n - 2 \geq 2$).

We define a $G$-equivariant map $\rho : \text{D}(A) \to C_{\text{gro}}$ as follows. Let $v \in \text{D}(A)$ be a vertex. Then $v$ corresponds to a standard subcomplex $K \subset \widehat{\text{Sal}(A)}$. Let $K = \prod_{i=1}^m K_i$ be the decomposition of $K$ into irreducible standard subcomplexes. Then stabilizer of each $K_i$ is an irreducible parabolic subgroup, whose centralizer gives rise to a vertex $w_i \in C_{\text{gro}}$. The vertices $\{w_i\}_{i=1}^m$ span a simplex in $C_{\text{gro}}$ and $\rho$ sends $v$ to the barycenter of this simplex. Suppose that $\{v_{ij}\}_{i=1}^k$ is a collection of vertices of $\text{D}(A)$ spanning a simplex $\sigma$. Let $K_1 \subset K_2 \subset \cdots \subset K_k$ be the associated chain of standard subcomplexes of $\text{Sal}(A)$. Then $\{\rho(v_{ij})\}_{i=1}^k$ is contained in a simplex of $C_{\text{gro}}$ (the simplex associated with the product decomposition of $K_k$). Thus, we can extend $\rho$ linearly to a map into $C_{\text{gro}}$. N.B. $\rho$ is usually not a simplicial map.

4.2. $C_{\text{gro}}$ is simply connected

In this subsection we study the map $\rho$ in more detail in order to prove that $C_{\text{gro}}$ is simply connected when $n \geq 4$. As before, $A$ is assumed to be irreducible.

**Lemma 4.4.** Let $v$ and $v'$ be two vertices in $\text{D}(A)$ corresponding to irreducible proper standard subcomplexes $K$ and $K'$ of $\widehat{\text{Sal}(A)}$ such that $\rho(v) = \rho(v')$. Then there exists a finite
sequence of vertices \( \{v_i\}_{i=1}^k \subset D(A) \) with associated standard subcomplexes \( \{K_i\}_{i=1}^k \) such that

1. \( v_1 = v \) and \( v_k = v' \);
2. for any \( i \), \( \rho(v_i) = \rho(v) \);
3. \( K_i \) and \( K_{i+1} \) are contained in a common standard subcomplex \( C \) with \( \dim(C) = \dim(K_i) + 1 \).

Proof. Let \( F \) (respectively, \( F' \)) be the irreducible face of \( Z(A) \) corresponding to \( K \) (respectively, \( K' \)). Let \( \tilde{g} \) be an edge path in \( \widetilde{Sal}(A) \) connecting a vertex \( \tilde{x} \in K \) and vertex \( \tilde{x}' \in K' \). Let \( g \) be the projection of \( \tilde{g} \) into \( \Gamma(A) \) to get an edge path from \( x \) to \( x' \). As \( \rho(v) = \rho(v') \), we have \( (\Delta_x(F))^2 g = g(\Delta_x(F'))^2 \). By the same argument as in Corollary 3.13, up to changing \( x \) and \( x' \) (which corresponds to replace \( \tilde{x} \) and \( \tilde{x}' \) by other vertices in the same standard subcomplex), we can assume that \( g \) is a positive path and that there does not exist edge \( e \) of \( \Gamma(A) \) with \( e \in F' \) and \( g \not\supset e \). By Lemma 3.11, \( F \) and \( F' \) are parallel and \( g = g_1g_2 \cdots g_k \), where each \( g_i \) is an elementary \( B \) segment (\( B \) is the subspace dual to \( F' \)). For \( 1 \leq i \leq k-1 \), define \( F_i \) to be the face of \( Z(A) \) that is parallel to \( F \) and contains \( s(g_i) \). Let \( \tilde{g} = \tilde{g}_1\tilde{g}_2 \cdots \tilde{g}_{k-1} \) be the induced decomposition. For \( 1 \leq i \leq k-1 \), define \( K_i \) to be the standard subcomplex of \( \widetilde{Sal}(A) \) associated to \( F \) and containing the initial vertex of \( \tilde{g}_i \). It follows from Lemma 3.8 (3) that \( \rho(v_i) = \rho(v_{i+1}) \) for \( 1 \leq i \leq k-1 \). This implies assertion (2) of the lemma. For assertion (3), note that \( F_i \) and \( F_{i+1} \) are contained in a common face \( F \) of one higher dimension. Let \( C \) be the standard subcomplex of \( \widetilde{Sal}(A) \) associated with \( F \) such that \( K_i \subset C \). Then clearly \( K_{i+1} \subset C \).

Corollary 4.5. Let \( v \) and \( v' \) be as in Lemma 4.4 with \( \rho(v) = \rho(v') = w \). Suppose \( \dim(A) \geq 4 \). Then there is an edge path \( \omega \) in \( D(A) \) connecting \( v \) and \( v' \) such that \( \rho(\omega) \) is a loop representing the trivial element in \( \pi_1(C_{gro}, w) \).

Proof. Suppose \( \dim(A) = n \). Let \( \{K_i\}_{i=1}^k \) be as in Lemma 4.4. Put \( n' = \dim(K_i) \). If \( n' < n - 1 \), then the standard subcomplex \( C \) in Lemma 4.4 (3) is proper. Hence, by Lemma 4.4 (3), there is an induced edge path \( \omega \) in \( D(A) \) connecting \( v \) and \( v' \). By Lemma 4.4 (2), the image \( \rho(\omega) \) is trivial in \( \pi_1(C_{gro}, w) \) due to its multiple back-tracking. Suppose \( n' = n - 1 \). We claim that there are irreducible proper standard subcomplexes \( \hat{K} \) and \( \hat{K}' \) of \( \widetilde{Sal}(A) \) such that

1. \( \hat{K} \subset K \) and \( \hat{K}' \subset K' \);
2. \( \rho(\hat{v}) = \rho(\hat{v}') \) where \( \hat{v} \) and \( \hat{v}' \) are vertices of \( D(A) \) associated with \( \hat{K} \) and \( \hat{K}' \).

To establish this claim, let \( F, F', g, \) and \( \tilde{g} \) be as in Lemma 4.4. Since \( F \) is irreducible, it follows from Lemma 2.10 that there is a 2-dimensional irreducible face \( \tilde{F} \subset F \). Note that \( \tilde{F} \neq F \) since \( \dim(A) \geq 4 \). Let \( \tilde{F}' \) be the face of \( F' \) parallel to \( \tilde{F} \). Let \( \hat{K} \) (respectively, \( \hat{K}' \)) be the standard subcomplex of \( K \) (respectively, \( K' \)) associated with \( \tilde{F} \) (respectively, \( \tilde{F}' \)) such that \( s(\tilde{g}) \subset \hat{K} \) (respectively, \( t(\tilde{g}) \subset \hat{K}' \)). As \( g \) is a concatenation of elementary \( B \) segments, it follows from Lemma 3.8 that \( (\Delta_x(\tilde{F}))^2 g = g(\Delta_x(\tilde{F}'))^2 \). Thus, \( \rho(\hat{v}) = \rho(\hat{v}') \).

By the previous case when \( n' < n - 1 \), there is an edge path \( \omega' \) connecting \( \hat{v} \) and \( \hat{v}' \) such that \( \rho(\omega') \) is trivial in \( \pi_1(C_{gro}, \rho(\hat{v})) \). Defining \( \omega \) to be the concatenation of the edge \( \vec{\hat{v}v} \), \( \omega' \), and the edge \( \vec{v'v} \), we see that it satisfies the requirements of the corollary.

Proposition 4.6. Suppose \( A \) an irreducible, central, simplicial real arrangement in \( A \). If \( \dim A \geq 4 \), then \( C_{gro} \) is simply connected.
Proof. Let \( \tilde{\mathcal{C}}_{gro} \) be the universal cover of \( \mathcal{C}_{gro} \) and \( \pi : \tilde{\mathcal{C}}_{gro} \to \mathcal{C}_{gro} \) the covering projection. The proposition will be proved by showing that \( \pi \) is a homeomorphism. Let \( \rho : D(A) \to \tilde{\mathcal{C}}_{gro} \) be the \( G \)-equivariant map defined previously. Since \( \dim A \geq 4 \), \( D(A) \) is simply connected. Hence, there is a lift \( \tilde{\rho} : D(A) \to \tilde{\mathcal{C}}_{gro} \) of \( \rho \). Next we construct a section of \( \rho : \mathcal{C}_{gro} \to \tilde{\mathcal{C}}_{gro} \) of \( \pi \). Choose a vertex \( v \in \mathcal{C}_{gro} \). Since \( \tilde{\rho} \) is a lift of \( \rho \), it follows from Corollary 4.5 that if two vertices \( v_1 \), \( v_2 \) of \( D(A) \) satisfy \( \rho(v_1) = \rho(v_2) = w \) where \( w \) is a vertex of \( \mathcal{C}_{gro} \), then \( \tilde{\rho}(v_1) = \tilde{\rho}(v_2) \). Define \( s(w) = \tilde{\rho}(v_1) \), and note that this does not depend on the choice of \( v_1 \) in the preimage of \( w \). Taking two adjacent vertices \( w_1 \) and \( w_2 \), we claim that \( s(w_1) \) and \( s(w_2) \) are adjacent. By Lemma 3.20, one of the following holds:

1. There are proper standard subcomplexes \( K_1 \) and \( K_2 \) in \( Sal(A) \) with one contained in the other so that for \( i = 1, 2 \), \( \rho(v_{K_i}) = w_i \), where \( v_{K_i} \) is the vertex of \( D(A) \) associated to \( K_i \).
2. There are proper standard subcomplexes \( K_1, K_2, K \) in \( Sal(A) \) with \( K = K_1 \times K_2 \) and with \( \rho(v_{K_i}) = w_i \) for \( i = 1, 2 \).

In either case, \( \tilde{\rho}(v_{K_1}) \) and \( \tilde{\rho}(v_{K_2}) \) are adjacent, which establishes the claim. Therefore, we can extend the map \( s \) to 1-skeleton of \( \mathcal{C}_{gro} \). Since both \( \mathcal{C}_{gro} \) and \( \tilde{\mathcal{C}}_{gro} \) are flag simplicial complexes, \( s \) extends to a section \( \mathcal{C}_{gro} \to \tilde{\mathcal{C}}_{gro} \); hence, \( \mathcal{C}_{gro} \) is simply connected. \( \square \)

5. The fundamental groups of the faces of a blowup

Throughout this section, \( A \) denotes an essential arrangement of linear hyperplanes in a real vector space \( A, V = A \otimes \mathbb{C} \), \( Z = Z(A) \) is the zonotope associated to \( A \), and \( bZ \) denotes the barycentric subdivision of \( Z \). We treat \( Z \) as an embedded subset of \( A \) as indicated in Subsection 2.1. The barycenter of a face \( F \) of \( Z \) is denoted by \( b_F \). Let \( Sal(A) \) be the Salvetti complex associated with \( A \) as defined in Subsection 2.2.

5.1. Salvetti’s embedding

We recall the definition from [49] of an embedding of \( Sal(A) \) into \( \mathcal{M}(A \otimes \mathbb{C}) \). A simplex in \( bSal(A) \) is represented by a pair \( (\Delta, v) \), where \( \Delta = [b_{F_0}, b_{F_1}, \ldots, b_{F_k}] \) is a simplex of \( bZ \) where each \( F_i \) a face of \( Z \), and \( v \) is a vertex of \( Z \). Write barycentric coordinates of a point \( x \in \Delta \) as \( x = \sum_{i=0}^{k} \lambda_{F_i} b_{F_i} \). Then the Salvetti’s embedding \( \Psi(x, v) \) is defined by

\[
\Psi : (x, v) \mapsto x + i \left( \sum_{i=0}^{k} \lambda_{F_i} [p_{F_i}(v) - b_{F_i}] \right),
\]

(5.1)

where \( i = \sqrt{-1} \). By Remark 2.6, the definitions of \( \Psi \) on each simplex of \( bSal(A) \) fit together to give a continuous map \( \Psi : bSal(A) \to V \).

Theorem 5.1 (cf. [49]). The map \( \Psi \) is injective; its image is contained in \( \mathcal{M}(A \otimes \mathbb{C}) \); and \( \Psi : Sal(A) \to \mathcal{M}(A \otimes \mathbb{C}) \) is a homotopy equivalence.

Let \( (\Delta, v) \) be as before and let \( x \in \Delta \). We also consider a modified version \( \Psi' \) of Salvetti’s embedding, defined by:

\[
\Psi' : (x, v) \mapsto x + i \left( \sum_{i=0}^{k} \lambda_{F_i} p_{F_i}(v) \right).
\]

(5.2)
Lemma 5.2. The map $\Psi'$ is an embedding. Let $J$ be the straight line homotopy between $\Psi$ and $\Psi'$. Then the image of $J$ is contained in $\mathcal{M}(A \otimes \mathbb{C})$. Hence, $\Psi' : b\text{Sal}(A) \to \mathcal{M}(A \otimes \mathbb{C})$ is a homotopy equivalence.

Proof. The first statement follows from the description of intersection of two simplices in $b\text{Sal}(A)$ as in Remark 2.6. For the second statement, we follow the argument in [49, pp. 609–611]. Suppose that $x$ is in the relative interior of $\Delta$ and that there is a hyperplane $H \in A$ such that $x \in H$. Then $\Delta \subset H$ and $b_{F_i} \in H$ for each $i$. By [49, Lemma 3], the $p_{F_i}(v)$ all lie on the same side of $H$. So, $\{p_{F_i}(v) - tb_{F_i}\}_{0 \leq i \leq k}$ and $\{p_{F_i}(v)\}$ lie on the same side of $H$. Hence, the image of $J$ is contained in $\mathcal{M}(A \otimes \mathbb{C})$. The final statement of the lemma follows from Theorem 5.1. \hfill \Box

Although both $\Psi$ and $\Psi'$ depend on a choice of points in the fan (that is, on the choice of the $b_{F_i}$), different choices lead to maps $\Psi$ and $\Psi'$ that are homotopic inside $\mathcal{M}(A \otimes \mathbb{C})$ via a straight line homotopy.

Let $G_x$ and $\Gamma(A)$ be as in Subsection 2.3. By combining Lemma 5.2 with results of [26, 44, 49], one can prove the following theorem.

Theorem 5.3. Suppose that $A$ is a finite, central, real arrangement. Let $x \in \Gamma(A)$ be a vertex. Consider the embeddings $\Gamma(A) \to \text{Sal}(A)$ and $\Gamma(A) \to \mathcal{M}(A \otimes \mathbb{C})$ (where the second map is induced by the modified Salvetti’s embedding of (5.2)). These embeddings induce well-defined homomorphisms $G_x \to \pi_1(\text{Sal}(A),x)$ and $G_x \to \pi_1(\mathcal{M}(A \otimes \mathbb{C}),x)$ both of which are isomorphisms.

5.2. Standard subcomplexes and parabolic subgroups

Let $B \in \mathcal{Q}(A)$ be a subspace and let $C_B$ be a face of $Z(A)$ dual to $B$. The standard complex $K$ of $\text{Sal}(A)$ associated to $C_B$ was defined in Subsection 4.1. Alternatively, it can be characterized as the union of all cells of $\text{Sal}(A)$ of form $(C_B,v)$ with $v$ ranging over vertices of $C_B$. Note that $K$ is isomorphic to $\text{Sal}(A_{A/B})$.

Let $\Psi_0 : K \to \mathcal{M}(A \otimes \mathbb{C})$ be the restriction of the modified Salvetti embedding (5.2) to $K$, that is, if $\Delta = [b_{F_0}, b_{F_1}, \ldots, b_{F_k}]$ is a simplex of $bC_B$, and if $v$ is a vertex of $C_B$, we have the map,

$$\Psi_0 : (x,v) \mapsto x + i \left( \sum_{i=0}^{k} \lambda_{F_i}p_{F_i}(v) \right). \tag{5.3}$$

Note that the barycenter $b$ of $C_B$ lies in $B$.

We perturb the choice of point in each fan in the definition of $\Psi_0$ to obtain another embedding $\Psi_1 : K \to \mathcal{M}(A \otimes \mathbb{C})$ such that $bF - b$ is orthogonal to $B$ for any face $F \subset C_B$. Let $J_1$ be the straight line homotopy between $\Psi_0$ and $\Psi_1$. Define $\Psi_2 : K \to V = A + iA$ to be the constant map with image $b + ib$. Let $J_2$ be the straight line homotopy between $\Psi_1$ and $\Psi_2$. Let $J$ denote the concatenation of $J_1$ and $J_2$.

The complexifications of the real vector spaces $A$ and $B$ are denoted by $V = A \otimes \mathbb{C}$ and $E = B \otimes \mathbb{C}$. The complex vector spaces $V$ and $E$ are identified with $A + iA$ and $B + ib$. As before, let $V_{\odot}$ be the blowup of $V$ along $A \otimes \mathbb{C}$. Let $\partial_E V_{\odot} = E_{\odot} \times S(V/E)_{\odot}$ denote the codimension one face of $V_{\odot}$ associated with $E$.

We claim that $J$ induces a homotopy $\tilde{J} : K \times [0,1] \to V_{\odot}$. Since the interior of $V_{\odot}$ is identified with $\mathcal{M}(A \otimes \mathbb{C})$ and $J(\cdot,t) \in \mathcal{M}(A \otimes \mathbb{C})$ for $t < 1$, we can define $\tilde{J}(\cdot,t)$ to be $J(\cdot,t)$ when $0 \leq t < 1$. Note that $\Psi_1(x,v) - \Psi_2(x,v)$ is a vector orthogonal to $E$, so this vector defines a point $\mu(x,v)$ in the interior of $S(V/E)_{\odot}$. We can extend $\tilde{J}$ to $t = 1$ by $\tilde{J}((x,v),1) := (b + ib, \mu(x,v)) \in$
\[\partial E \cap = E \times S(V/E) \cap (note that \(b + ib \in \mathcal{M}(A^B \otimes \mathbb{C})\), which is the interior \(E \cap\)). One checks that \(J\) is continuous.

Let \(B^\perp\) be the orthogonal complement to \(B\) in \(A \subset b\). Taking \(D\) to be a small enough open disk in \(B^\perp\) centered at \(b\), the arrangement \(A\) induces an arrangement in \(D\) which can be identified with \(A_{A/B}\). We can assume without loss of generality that the image of \(\Psi_1\) is contained in \(D \times D\). By Lemma 5.2, \(\Psi_1 : K \to (D \times D) - (\bigcup_{H \in A} H \times H)\) is a homotopy equivalence. Thus, the map \(K \to S(V/E)\cap\), defined by \(\tilde{J}(\cdot, 1)\), is a homotopy equivalence. We summarize the above discussion in the following proposition.

**Proposition 5.4.** Let \(B\) be a subspace of \(A\). Let \(C_B\) be a face of \(Z(A)\) dual to \(B\) and let \(b = bC_B = C_B \cap B\). Suppose that \(K\) is the standard subcomplex of \(\text{Sal}(A)\) associated with \(C_B\). Let \(\Psi_0 : K \to \mathcal{M}(A \otimes \mathbb{C})\) be the restriction of the modified Salvetti embedding of (5.2).

Let \(D\) be small open disk orthogonal to \(B\) at \(b\) of complementary dimension. Let \(E = B \otimes \mathbb{C}\) and let \(\partial E \cap = E \times S(V/E) \cap\) be the codimension one face of \(E \cap\) associated with \(E\). Then

1. the map \(\Psi_0\) is homotopic in \(\mathcal{M}(A \otimes \mathbb{C})\) to a map \(\Psi_1 : K \to (D \times D) - (\bigcup_{H \in A} H \times H)\); moreover, \(\Psi_1\) is a homotopy equivalence;
2. the map \(\Psi_0\) is homotopic in \(E \cap\) to \(\Psi_2 : K \to \{x\} \times S(V/E)\cap\) for some \(x \in E \cap\); moreover, \(\Psi_2\) is a homotopy equivalence.

### 5.3. Orthogonal complements of standard subcomplexes

Let \(A, A, B, V, E, C_B\), and \(b = bC_B\) be as in the previous subsection. Suppose \(Z = Z(A)\) and \(Z' = Z(A^B)\). Let \(P (Z')\) denote the set of faces of \(Z'\). For each \(F \in P (Z')\) there is a unique face \(\tilde{F}\) of \(Z\) such that \(B \cap \tilde{F} = F\). If \(v\) is a vertex of \(Z'\), then \(F(v) := \tilde{v}\) is a dual face to \(B\). If \(v, v'\) are vertices of \(Z'\), then \(F(v)\) and \(F(v')\) are parallel faces of \(Z\). Hence, parallel translation defines a bijection from \(Vert F(v)\) to \(Vert F(v')\). For each \(v \in \text{Vert } Z'\) choose a vertex \(u(v) \in F(v)\) so that \(u(v)\) corresponds to \(u(v')\) under parallel translation. Since we can also treat \(b\) as a vertex of \(Z'\), the meaning of \(u(b)\) is clear.

**Lemma 5.5.** Let \(F\) be a face of \(Z'\) and let \(v\) be a vertex of \(Z'\). Then \(u(\text{Proj}_F(v)) = \text{Proj}_F(u(v))\).

**Proof.** Let \(H_F\) (respectively, \(H'_F\)) be the collection of hyperplanes of \(A\) which intersect an edge of \(F\) (respectively, \(\tilde{F}\)) in one point. Then \(H_F \subset H'_F\). Since each element of \(\text{Hom}_{H_F}\) contains \(b_F = b_F\), each element of \(H'_F = H_F \setminus H_F\) contains \(b\). By Lemma 2.3 (3), for any \(H \in H_F\), \(v\) and \(\text{Proj}_F(u)\) are on the same side of \(H\). Since no hyperplane of \(A\) separates \(v\) from \(u(v)\), \(u(v)\) and \(u(\text{Proj}_F(v))\) are on the same side of \(H\) for any \(H \in H_F\). The same statement holds if \(H \in A'\), since each element of \(A'\) contains \(B\). The lemma follows after applying Lemma 2.3 (3) to \(\tilde{F}\).

**Definition 5.6.** For each face \(F\) of \(Z'\), choose a homeomorphism \(\Phi_F : C_B \times F \to \tilde{F}\) such that

1. For each vertex \(v \in Z'\), \(\Phi_v\) maps \(C_B \times \{v\}\) to the face of \(Z'\) which is parallel to \(C_B\) and contains \(v\) (we regard \(Z'\) as a subset of \(Z\)); moreover, \(\Phi_v\) is a simplicial isomorphism induced by parallel translation;
2. For each edge \(e \subset Z'\) endpoints \(v_1\) and \(v_2\), \(\Phi_e(\{u(b)\} \times e)\) is an edge path in \(Z^{(1)}\) of the shortest length from \(\Phi_{v_1}(\{u(b)\} \times \{v_1\})\) to \(\Phi_{v_2}(\{u(b)\} \times \{v_2\})\);
3. For two faces \(F_1 \subset F_2\) of \(Z'\), the maps \(\Phi_{F_1}\) and \(\Phi_{F_2}\) agree on \(C_B \times F_1\);
4. We have \(\Phi_{F}(\{b\} \times F) = F\) (where the \(F\) on the right-hand side is understood to be a subset of \(F\)).

Define \(\text{TSal}(A^B)\) to be \(C_B \times \text{Sal}(A^B)\).
Lemma 5.7. The homeomorphisms $\Phi_F$ defined above fit together to induce a map $\Phi: \text{TSal}(A^B) \to \text{Sal}(A)$. Moreover, the image of $\Phi$ is $\bigcup_{v \in \text{Vert} Z'} (Z, u(v))$.

Proof. A face of $\text{TSal}(A^B)$ is represented by $(F, v)$ where $F$ is a face of $Z'$ and $v$ is a vertex of $F$. Define $\Phi$ on $C_B \times (F, v)$ by taking $C_B \times (F, v)$ to $(\tilde{F}, u(v))$ via $\Phi_F$. Recall that for two cells $(F_1, v_1)$ and $(F_2, v_2)$ in $Z'$, $(F_1, v_1) \subset (F_2, v_2)$ if and only if $F_1 \subset F_2$ and $\text{Proj}_{F_1}(v_2) = v_1$. So, by Lemma 5.5, $\tilde{F}_1 \subset \tilde{F}_2$ and $\text{Proj}_{\tilde{F}_1}(u(v_2)) = u(\text{Proj}_{F_1}(v_2)) = u(v_1)$. Therefore, $(\tilde{F}_1, u(v_1)) \subset (\tilde{F}_2, u(v_2))$ as cells of $\text{Sal}(A)$. This shows that $\Phi$ is well defined. The final statement in the lemma follows from the definition of $\Phi$. □

Let $\Psi_B: \text{Sal}(A^B) \to E$ and $\Psi_A: \text{Sal}(A) \to V$ be two modified Salvetti embeddings (cf. (5.2)). Define $f_0$ to be the composition,

$$\text{Sal}(A^B) \overset{j}{\to} \text{TSal}(A^B) \overset{k}{\to} \text{Sal}(A) \overset{\Psi_A}{\to} V,$$

where $j$ sends $\text{Sal}(A^B)$ to $\{b\} \times \text{Sal}(A^B)$. Perturb the choice of points in each fan in the definition of $\Psi_A$ so that

1. for each vertex $v \in Z'$, the vector $u(v) - v$ is orthogonal to $B$;
2. for any two vertices $v_1, v_2 \in Z'$, the vectors $u(v_1) - v_1$ and $u(v_2) - v_2$ are parallel.

The perturbation of $\Psi_A$ leads to a perturbation of $f_0$. Denote the resulting map by $f_1$. Let $H_1$ be the straight line homotopy between $f_0$ and $f_1$. Define $f_2$ to be the composition, $\text{Sal}(A^B) \overset{\Psi_B}{\to} E \overset{\Psi_A}{\to} V$, where the second map is the inclusion. Next, we compare $f_1$ and $f_2$.

Recall that any simplex in $b\text{Sal}(A^B)$ has the form $(\Delta, v)$ where $\Delta$ is a simplex in $bZ'$, and $v$ is a vertex of $Z'$. Let $\Delta = [b_{F_0}, b_{F_1}, \ldots, b_{F_k}]$, where each $F_i$ is a face of $Z'$. Note that $b_{F_i} = b_{F_i}$. Then

$$f_2((b_{F_i}, v)) = b_{F_i} + i(p_{F_i}(v)).$$

Note that $\Phi$ sends $(\Delta, v)$ to $(\Delta, u(v))$, which is a simplex of $b\text{Sal}(A)$. Thus,

$$f_1((b_{F_i}, v)) = b_{F_i} + i(p_{F_i}(u(v))) = b_{F_i} + i(u(p_{F_i}(v))),$$

where the second inequality follows from Lemma 5.5.

By our choice of points in each fan, it follows that there is a unit vector $\vec{\mu} \in A$ orthogonal to $B$ such that for each vertex $v \in Z'$, $u(v) - v$ is the vector $\alpha_v \vec{\mu}$, where $\alpha_v$ is some positive number. So, for each vertex $x$ of $b\text{Sal}(A^B)$, $H_1(x) - H_0(x)$ is proportional to $i\vec{\mu}$. Since $H_1$ and $H_0$ are linear on each simplex of $b\text{Sal}(A^B)$, the same holds for any $x \in b\text{Sal}(A^B)$. Let $H_2$ be the straight line homotopy between $f_1$ and $f_2$, and let $H$ be the concatenation of $H_1$ and $H_2$. Note that $H(\cdot, t) \in \mathcal{M}(A \otimes \mathbb{C})$ whenever $t < 1$.

Then $H(\cdot, t)$ induces a homotopy $\tilde{H}: b\text{Sal}(A^B) \times [0, 1] \to V_\circ$ as follows. As the interior of $V_\circ$ is identified with $\mathcal{M}(A \otimes \mathbb{C})$, put $\tilde{H}(x, t) = H(x, t)$ when $t < 1$ and define $\tilde{H}(x, 1) = (\Psi_B(x), \mu) \in \partial E V_\circ = E_\circ \times S(V/E)_\circ$. Again, the interior of $E_\circ$ is equal to $\mathcal{M}(A^B \otimes \mathbb{C})$ in which the image of $\Psi_B$ lies, and the point $\mu \in S(V/E)_\circ$ is determined by the vector $i\vec{\mu}$ (note that $i\vec{\mu} \perp E$). One checks that $\tilde{H}$ is continuous. Moreover, by Lemma 5.2, $\tilde{H}(\cdot, 1): \text{Sal}(A^B) \to E_\circ$ is a homotopy equivalence.

Lemma 5.8. Let $K$ be the standard subcomplex of $\text{Sal}(A)$ associated with $C_B$. Put $K^\perp = \Phi(\{b\} \times \text{Sal}(A^B))$. Then

1. the restriction of $\Phi$ to $\{b\} \times \text{Sal}(A^B)$ is an embedding;
2. the intersection $K \cap K^\perp$ is single vertex of $b\text{Sal}(A)$ represented by the point $(b, u(b))$.

(Here we treat $b$ as a vertex of $Z'$; hence, $u(b)$ makes sense.)
Proof. Let $\Delta$ be a simplex of $bZ'$. Let $v_1, v_2$ be vertices of $Z'$. It follows from Remark 2.6 and Lemma 5.5 that if $(\Delta, v_1) \cap (\Delta, v_2) = (\Delta', v)$, then $(\Delta, u(v_1)) \cap (\Delta, u(v_2)) = (\Delta', u(v))$. As $\Phi$ maps $(\Delta, v)$ to $(\Delta, u(v))$, statement (1) follows. Note that the unique top-dimensional cell of $K$ that has nonempty intersection with $K^\perp$ is of the form $(C_B, u(b))$. Statement (2) follows. □

**Definition 5.9.** The subcomplex $K^\perp$ of $b\text{Sal}(A)$ in the above lemma can be described directly as follows: it is the union of all simplices of form $(\Delta, u(v))$ with $(\Delta, v)$ ranging over simplices of $b\text{Sal}(A^B)$. We call $K^\perp$ the orthogonal complement of $K$ at $(b, u(b))$.

Take a copy of $K$ and a copy of $K^\perp$ and glue them together at $b^* := (b, u(b))$ to obtain a space $K^\ast$. So, $K^\ast$ is the wedge of $b\text{Sal}(A)$ and $b\text{Sal}(A^B)$, and there is a natural embedding $K^\ast \to \text{Sal}(A)$. Let $g_0 : K^\ast \to V_\odot$ be the map induced by the modified Salvetti embedding $\text{Sal}(A) \to \mathcal{M}(A \otimes \mathbb{C})$ (cf. (5.2)). Let $J^1, J_1$, and $J_2$ be the homotopies defined in Subsection 5.2. Since $J_1$ and $H_1$ arise by perturbing the choice of points in fans and since this can be done simultaneously and consistently, we can assume that these homotopies fit together to give a homotopy $K^\ast \times [0, 1] \to \mathcal{M}(A \otimes \mathbb{C})$. Moreover, the restrictions of $J_2$ and $H_2$ to $(b, u(b)) \times [0, 1]$ agree (they both give a segment from $(b, u(b))$ to $(b, b)$). By Lemma 5.8 (2), $\tilde{H}$ and $J$ together induce a homotopy $K^\ast \times [0, 1] \to V_\odot$ from $g_0$ to $g_1$, where $g_1$ is obtained by gluing together $H(-, 1)$ and $\tilde{J}(-, 1)$. We summarize the above discussion in the following proposition.

**Proposition 5.10.** Let $B \subset A$ be a subspace in $\mathcal{Q}(A)$. Let $C_B$ be a face of $Z(A)$ dual to $B$ and let $K$ be the standard subcomplex of $\text{Sal}(A)$ associated with $C_B$. For a top-dimensional cell $C$ of $K$, let $b^* := \text{barycenter}$ of $C$ and let $K^\perp := K^\ast$ be the orthogonal complement to $K$ at $b^*$. As in the preceding paragraph, glue $K$ to $K^\perp$ at $b^*$ to obtain $K^\ast$. Then the map $g_0 : K^\ast \to V_\odot$ induced by the modified Salvetti embedding is homotopic (in $V_\odot$) to a continuous map $g_1 : K^\ast \to \partial E V_\odot = E_\odot \times S(V/E)_\odot$ satisfying the following conditions.

1. There exists a point $y$ in the interior of $E_\odot$ such that $g_1(K^\perp) \subset E_\odot \times \{y\}$ and $(g_1)|_{K^\perp} : K^\perp \to E_\odot \times \{y\}$ is a homotopy equivalence.
2. There exists a point $y'$ in the interior of $S(V/E)_\odot$ such that $g_1(K) \subset \{y'\} \times S(V/E)_\odot$ and $(g_1)|_K : K \to \{y'\} \times S(V/E)_\odot$ is a homotopy equivalence.

5.4. The isomorphism between $C_{\text{alg}}$ and $C_{\text{top}}$

**Proposition 5.11.** Suppose that $A$ is a finite, central, simplicial real arrangement in a real vector space $A$ and let $V = A \otimes \mathbb{C}$. Let $B$ be a subspace in $\mathcal{Q}(A)$ and let $E = B \otimes \mathbb{C}$.

1. The inclusion map $i : \partial E V_\odot = E_\odot \times S(V/E)_\odot \to V_\odot$ induces an injective map of fundamental groups. Hence, any component of the inverse image of $\partial E V$ in the universal cover $\tilde{V}_\odot$ is contractible.
2. Let $U$ be the center of $\pi_1(S(V/E)_\odot)$. Then $i_\ast(\pi_1(\partial E V_\odot))$ is the centralizer of $i_\ast(U)$ in $\pi_1(V_\odot)$, and this also is equal to the normalizer of $i_\ast(U)$ in $\pi_1(V_\odot)$.

**Proof.** Let $\Phi$ be the map from Lemma 5.7 and let $\phi : \Gamma(A^B) \to \Gamma(A)$ be the map from Definition 3.15. Let $\Gamma(A^B)$ and $\Gamma(A)$ be the graphs defined in Section 3. We identify $\Gamma(A)$ as the 1-skeleton of $\text{Sal}(A)$ and $\Gamma(A^B)$ as a subset of $T\text{Sal}(A^B) = C_B \times \text{Sal}(A^B)$ of the form $\{u(b)\} \times (\text{Sal}(A^B))^1$ (where the edges of $\text{Sal}(A)$ and $\text{Sal}(A^B)$ are oriented as in Remark 2.5).

It follows from Definition 5.6 (2) that we can assume that $\phi$ is the restriction of $\Phi$ to $\Gamma(A^B)$. Theorem 5.3 implies that the morphism induced by $\Phi : \{u(b)\} \times \text{Sal}(A^B) : \{u(b)\} \times \text{Sal}(A^B) \to \text{Sal}(A)$ is described, on the level of fundamental groups, by a morphism of groupoids $\phi : \mathcal{G}(A^B) \to \mathcal{G}(A)$. Take a vertex $v$ of $\text{Sal}(A^B)$ and let $x = \Phi((u(b), v))$. Let $K \cong \text{Sal}(A_{A/B})$ be as before. Let $h_1 : \pi_1(K, x) \to \pi_1(\text{Sal}(A), x)$ be the map induced by the inclusion $K \to \text{Sal}(A)$, and let $C^\ast_{\phi}(v)$ be the 1-skeleton of $\text{Sal}(A)$. Then $h_1$ is an isomorphism.
Let \( h_2 : \pi_1(\text{Sal}(A^B), v) \to \pi_1(\text{Sal}(A), x) \) be the map induced by \( \Phi_{\{\alpha(b)\} \times \text{Sal}(A^B)} \). By Corollary 3.17,

1. \( \text{Im} h_1 \) and \( \text{Im} h_2 \) commute;
2. \( h = h_1 \times h_2 : \pi_1(K, x) \times \pi_1(\text{Sal}(A^B), v) \to \pi_1(\text{Sal}(A), x) \) is injective;
3. if \( U \) denotes the center of \( \pi_1(\text{Sal}(A^B), v) \), then both the centralizer and normalizer of \( h_1(U) \) in \( \pi_1(\text{Sal}(A), x) \) are generated by \( \text{Im} h_1 \) and \( \text{Im} h_2 \).

The existence of the map \( \Phi \) implies that these properties still hold if we choose as base point \( \Phi((b, v)) \) instead of \( x \) in the definition of \( h_1 \), and let \( h_2 \) be induced by \( \Phi_{\{\alpha(b)\} \times \text{Sal}(A^B)} \). Proposition 5.10 can be used to complete the proof. \( \square \)

Let \( C_{\text{alg}}(A) \) be as in Definition 1.14. By Proposition 5.4(1), when \( A \) is irreducible, \( C_{\text{gr}}(A) \) is isomorphic \( C_{\text{alg}}(A) \).

**Theorem 5.12.** Suppose that \( A \) is the complexification of a finite, central real simplicial arrangement of hyperplanes in an \( n \)-dimensional vector space and let \( l \) be the number of irreducible components of \( A \). As in Definition 1.24 let \( X \) be the compact core of \( V_\cap \) and let \( \tilde{Y} \) be the universal cover of \( X \). Then Properties A, C, and D in Section 1.4 hold and the following statements are true.

1. The algebraic and topological versions of the curve complex \( C_{\text{alg}} \) and \( C_{\text{top}} \) are identical (and we denote this simplicial complex by \( C \)).
2. The faces in \( \partial X \) are indexed by the set of simplices in a complex \( \mathcal{T}_0 \) which is defined in Definition 1.4 in Section 1.1. The faces of \( Y \) are indexed by \( C \) and the group \( \Gamma = \pi_1(X) \) acts on \( C \) with quotient space \( \mathcal{T}_0 \).
3. The simplicial complex \( C \) is homotopy equivalent to a wedge of \((n-l-1)\)-spheres (where \( \dim C = n - l - 1 \)).
4. Each face of \( X \) is aspherical and its fundamental group injects into \( \Gamma \).
5. The fundamental group of each codimension-one face of \( X \) is the normalizer of an irreducible parabolic subgroup.
6. The stabilizer of each simplex of \( C \) is the fundamental group of \( M(A') \) where \( A' \) is also the complexification of some real simplicial arrangement.

**Proof.** Once we verify Properties A, C, and D, the theorem follows from Propositions 1.27, 1.31 (or alternatively Propositions 1.27 and 1.31 and Remark 1.28). Property A follows from Proposition 5.11(1). Property C is follows from Proposition 5.11(2). Property D follows from Lemma 3.20. \( \square \)

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