

Lecture 13

①

Lie algebras and their representations

0. Basic definitions. A Lie algebra (over \mathbb{C}) is a vector space \mathfrak{g} , over \mathbb{C} , together with a bilinear map (called commutator, or just Lie bracket) $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ satisfying

• (skew symmetry) $[x, y] = -[y, x] \quad \forall x, y \in \mathfrak{g}$.

• (Jacobi identity) $\forall x, y, z \in \mathfrak{g}$ we have

$$[[x, y], z] + [[y, z], x] + [[z, x], y] = 0.$$

Let \mathfrak{g} be a Lie algebra. A representation of \mathfrak{g} is a vector space V over \mathbb{C} , together with a linear map $\mathfrak{g} \xrightarrow{\pi} \text{End}_{\mathbb{C}}(V)$ s.t.

$$\pi([x, y]) = \pi(x)\pi(y) - \pi(y)\pi(x) \quad \forall x, y \in \mathfrak{g}.$$

A homomorphism of Lie algebras $f : \mathfrak{g} \rightarrow \mathfrak{g}'$ (where \mathfrak{g} and \mathfrak{g}' are Lie algebras) is a linear map satisfying $f([x, y]_{\mathfrak{g}}) = [f(x), f(y)]_{\mathfrak{g}'}$.
($\forall x, y \in \mathfrak{g}$).

1. Remarks. - (i) Given any vector space V over \mathbb{C} , the space of all linear endomorphisms $V \rightarrow V$, denoted by $\text{End}_{\mathbb{C}}(V)$ above, has a natural structure of a Lie algebra:

$$A, B \in \text{End}(V) \rightsquigarrow [A, B] := AB - BA.$$

We will denote this Lie algebra by $\mathfrak{gl}(V)$; or $\mathfrak{gl}_n(\mathbb{C})$ if V is n -dimensional and we have chosen a basis of V .

(ii) A representation of \mathfrak{g} (on a vector space V) is nothing but a homomorphism of Lie algebras $\mathfrak{g} \longrightarrow \mathfrak{gl}(V)$.

(iii) For any $x \in \mathfrak{g}$, consider the linear map:

$$\text{ad}(x) : \begin{array}{ccc} \mathfrak{g} & \longrightarrow & \mathfrak{g} \\ \psi & & \psi \\ y & \longmapsto & [x, y] \end{array} \quad (\text{called } \underline{\text{adjoint}})$$

which gives rise to $\text{ad} : \mathfrak{g} \longrightarrow \mathfrak{gl}(\mathfrak{g})$. The Jacobi identity
 $x \longmapsto \text{ad}(x)$

is then equivalent to requiring that ad is a homomorphism of Lie algebras and hence defines a representation of \mathfrak{g} on itself.

2. Operations on representations.

Let \mathfrak{g} be a Lie algebra over \mathbb{C} . Given V_1, V_2 two representations of \mathfrak{g}

$$\pi_j : \mathfrak{g} \longrightarrow \mathfrak{gl}(V_j) ; j=1, 2,$$

we define:

• Direct Sum $V_1 \oplus V_2 =$ direct sum of vector spaces (as a vector space)

$$\pi_{V_1 \oplus V_2} : \begin{array}{ccc} \mathfrak{g} & \longrightarrow & \mathfrak{gl}(V_1 \oplus V_2) \\ \psi & & \psi \\ x & \longmapsto & \left[\begin{array}{c|c} \pi_1(x) & 0 \\ \hline 0 & \pi_2(x) \end{array} \right] \end{array}$$

• Tensor product: $\pi : \mathfrak{g} \longrightarrow \mathfrak{gl}(V_1 \otimes_{\mathbb{C}} V_2)$ is defined by:

$$\pi(x) \cdot (v_1 \otimes v_2) = \pi_1(x)(v_1) \otimes v_2 + v_1 \otimes \pi_2(x)(v_2)$$

$$\forall x \in \mathfrak{g}, v_1 \in V_1 \text{ and } v_2 \in V_2$$

[This is often written as $\pi(x) = \pi_1(x) \otimes \text{Id}_{V_2} + \text{Id}_{V_1} \otimes \pi_2(x)$.]

For a representation V of \mathfrak{g} , $\pi : \mathfrak{g} \longrightarrow \mathfrak{gl}(V)$, its dual representation $(\mathfrak{g} \curvearrowright V^*)$ is defined by $\mathfrak{g} \xrightarrow{\pi^*} \mathfrak{gl}(V^*)$:

$$(\pi^*(x)(\xi))(v) = -\xi(\pi(x)(v)) \quad \forall x \in \mathfrak{g}; \xi \in V^*; v \in V.$$

3. Let \mathfrak{g} be a Lie algebra and V a representation of \mathfrak{g} . We say

V is irreducible if 0 and V are the only invariant subspaces under \mathfrak{g} action. That is, $\left\{ \begin{array}{l} V' \subseteq V \\ \pi(x)(V') \subseteq V', \forall x \in \mathfrak{g} \end{array} \right\} \Rightarrow V' = 0 \text{ or } V.$

[0 is not considered irreducible.]

V is said to be indecomposable if $V \cong V_1 \oplus V_2$ as \mathfrak{g} -reps

(for $V_1, V_2 \subset V$ subreps.) implies that either $V_1 = 0$ or $V_2 = 0$.

[We will mostly work with finite-dimensional representations.]

Given two representations V_1, V_2 of \mathfrak{g} ; a linear map $f : V_1 \rightarrow V_2$ is said to be a homomorphism of \mathfrak{g} -representations (or, \mathfrak{g} -intertwiner,

or just \mathfrak{g} -linear) if $f(\pi_1(x)(v)) = \pi_2(x)(f(v))$
 $\forall x \in \mathfrak{g}$ and $v \in V$.

Remarks (i) If $\mathfrak{g} \curvearrowright V_1, V_2$, then we can define $\mathfrak{g} \curvearrowright \text{Hom}_{\mathbb{C}}(V_1, V_2)$

by $(x \cdot A)(v_1) = \pi_2(x)(A(v_1)) - A(\pi_1(x)(v_1))$
 $\forall x \in \mathfrak{g}, A \in \text{Hom}_{\mathbb{C}}(V_1, V_2), v_1 \in V_1$.

Thus $\text{Hom}_{\mathfrak{g}}(V_1, V_2) = \{ A \in \text{Hom}_{\mathbb{C}}(V_1, V_2) \mid x \cdot A = 0 \ \forall x \in \mathfrak{g} \}$

(ii) $\mathfrak{g} \curvearrowright V$. We define $V^{\mathfrak{g}}$ (\mathfrak{g} -invariants) to be

$V^{\mathfrak{g}} = \{ v \in V \mid x \cdot v = 0 \ \forall x \in \mathfrak{g} \}$.

4. Schur's Lemma. Let V_1 and V_2 be two irreducible representations of \mathfrak{g} and let $f: V_1 \rightarrow V_2$ be a morphism of \mathfrak{g} -representations.

Then: either $f \equiv 0$, or f is an isomorphism.

[Proof: $\text{Ker}(f) = \{ v_1 \in V_1 : f(v_1) = 0 \} \subseteq V_1$ is a subrepresentation
 \Rightarrow $\text{Ker } f = V_1$ (ie. $f \equiv 0$) or $\text{Ker } f = 0$. If $\text{Ker } f = 0$, we get
(V_1 irred.)

$f(V_1) \subseteq V_2$ subrepr. Since V_2 is irreducible & $V_1 \neq 0$, $f(V_1) = V_2$.

Hence f is both injective & surjective,]

Schur's Lemma continued. Assume V is a finite-dimensional irreducible representation of \mathfrak{g} ; and let $f: V \rightarrow V$ be a \mathfrak{g} -intertwiner.

Then $\exists \lambda \in \mathbb{C}$ s.t. $f = \lambda \cdot \text{Id}_V$.

Proof. As $f \in \text{End}_{\mathbb{C}}(V)$ and V is finite-dimensional (and \mathbb{C} is algebraically closed); we can find an eigenvector of f :

(i.e., $\exists v \in V$ and $\lambda \in \mathbb{C}$ s.t. $f(v) = \lambda v$, $v \neq 0$)

Now $\text{Ker}(f - \lambda \cdot \text{Id}_V) \subset V$ is a subrepr. since f is a \mathfrak{g} -intertwiner and $0 \neq v \in \text{Ker}(f - \lambda \cdot \text{Id}_V)$ - so it cannot be zero. By irreducibility of V ; $\text{Ker}(f - \lambda \cdot \text{Id}_V) = V$. □

5. Lie algebra $\mathfrak{sl}_2(\mathbb{C})$ is the Lie algebra of 2×2 matrices with trace zero. Thus, it is 3-dimensional with basis

$$h = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad e = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad \text{and} \quad f = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

Commutators: $[h, e] = 2e$ $[e, f] = h$
 $[h, f] = -2f$

Therefore, a representation of \mathfrak{sl}_2 is nothing but a vector space V together with 3 linear maps $\pi(h), \pi(e), \pi(f) \in \text{End}_{\mathbb{C}}(V)$

satisfying $[\pi(h), \pi(e)] = 2\pi(e)$

$$[\pi(h), \pi(f)] = -2\pi(f) \quad \text{and} \quad [\pi(e), \pi(f)] = \pi(h).$$

Proposition. Let V be a finite-dimensional, irreducible representation of \mathfrak{sl}_2 . Let $\dim V = n+1$ where $n \in \mathbb{Z}_{\geq 0}$. Then there exists a basis of V $\{v_0, v_1, \dots, v_n\}$ s.t.

$$h \cdot v_i = (n-2i)v_i \quad ; \quad f \cdot v_i = (i+1)v_{i+1} \quad ; \quad e \cdot v_i = (n-i+1)v_{i-1}$$

$\forall 0 \leq i \leq n$; with the convention that $v_{-1} = v_{n+1} = 0$.

Proof. Since $h \in \text{End}_{\mathbb{C}}(V)$, and V is f.d., we can find an eigenvector $v \neq 0$; $v \in V$ of h with eigenvalue $\lambda \in \mathbb{C}$. That is, $h \cdot v = \lambda \cdot v$.

Note: $h \cdot e = e \cdot (h+2)$ \Rightarrow $e^k \cdot v$ is an eigenvector of h with eigenvalue $\lambda + 2k$.
 $(h \cdot f = f \cdot (h-2))$

[Remark.- vectors with distinct eigenvalues \leadsto linearly independent.]

Since V is finite-dim'l, we can find k s.t. $e^k \cdot v \neq 0$ and $(k \geq 0)$

$e^{k+1} \cdot v = 0$. Set $v_0 = e^k \cdot v$ and let $\mu \in \mathbb{C}$ be its h -eigenvalue
 $(\mu = \lambda + 2k)$

For each $l \geq 0$; define $v_l = \frac{f^l}{l!} v_0$. Then we have

$$h \cdot v_l = (\mu - 2l) v_l \quad \text{and} \quad f \cdot v_l = (l+1) v_{l+1}.$$

We will prove (by induction on l) that $e \cdot v_l = (\mu - l + 1) v_{l-1}$
(Note $e \cdot v_0 = 0$)

$$l=1. \quad e \cdot v_1 = e \cdot (f \cdot v_0) = \underset{0}{f \cdot (e \cdot v_0)} + h \cdot v_0 = \mu \cdot v_0.$$

$$\begin{aligned} l > 1. \quad e \cdot v_l &= \frac{1}{l!} (e f^l) v_l = \frac{1}{l!} (f e + h) f^{l-1} v_l \\ &= \frac{1}{l} f \cdot (e \cdot v_{l-1}) + \frac{1}{l} (\mu - 2(l-1)) v_{l-1} \\ &= \frac{1}{l} f \cdot ((\mu - l + 2) v_{l-1}) + \frac{1}{l} (\mu - 2l + 2) v_{l-1} \\ &= \frac{1}{l} \left((l-1)(\mu - l + 2) + \mu - 2l + 2 \right) v_{l-1} \\ &= \frac{1}{l} \left(l \cdot \mu - l(l-1) \right) v_{l-1} = (\mu - l + 1) v_{l-1}. \end{aligned}$$

Let n be smallest ($n \in \mathbb{Z}_{\geq 0}$) s.t. $v_n \neq 0$ and $v_{n+1} = 0$.
(exists by finite-dimensionality of V).

Then (i) $0 = e \cdot v_{n+1} = (\mu - n) v_n \Rightarrow \mu = n \in \mathbb{Z}_{\geq 0}$.

(ii) $\text{Span} \{v_0, \dots, v_n\} \subseteq V$ is a subrepr. hence $= V$ by irreducibility of V .