

0. Summary of the last few lectures.

R : finite irreducible root system. $\{\alpha_i\}_{i \in I}$ a choice of base
- simple roots

$$R = R_+ \cup R_- ; R_- = -R_+$$

$$\mathfrak{h}^* \xrightarrow{\nu} \mathfrak{h} ; h_i := \nu(\alpha_i) \cdot \frac{2}{(\alpha_i, \alpha_i)} \quad (\text{Notation } d_\alpha = \frac{(\alpha, \alpha)}{2})$$

$$= \frac{\nu(\alpha_i)}{d_i} \quad \forall i \in I.$$

$$A = \left(a_{ij} = \frac{2(\alpha_i, \alpha_j)}{(\alpha_i, \alpha_i)} \right)_{i, j \in I} \quad \text{(Cartan Matrix)}$$

$W =$ Weyl group,
generated by $\{s_i\}_{i \in I}$

$$[s_i^2 = 1 ; (s_i s_j)^{m_{ij}} = 1]$$

We defined a Lie algebra

$\mathfrak{g}(A)$: generators $\{e_i, f_i, h_i\}_{i \in I}$

$$\left[\begin{array}{c|c|c|c} a_{ij} a_{ji} & 0 & 1 & 2 & 3 \\ \hline m_{ij} & 2 & 3 & 4 & 6 \end{array} \right]$$

relations: (1) $[h_i, h_j] = 0 \quad \forall i, j \in I.$

(2) $[h_i, e_j] = a_{ij} e_j ; [h_i, f_j] = -a_{ij} f_j$

(3) $[e_i, f_j] = \delta_{ij} h_i \quad \forall i, j \in I$

(4) $\forall i \neq j \in I ; (\text{ad } e_i)^{1-a_{ij}} f_j = 0 = (\text{ad } f_i)^{1-a_{ij}} e_j.$

1. Remarks. $\mathfrak{h} = \mathbb{C}$ -span of $\{h_i : i \in I\}$. (1) $\Leftrightarrow \mathfrak{h}$ is an

abelian Lie algebra: $[h, h'] = 0 \quad \forall h, h' \in \mathfrak{h}.$

(2): $\mathfrak{g} \supset \mathfrak{h}$ is semi-simple \Rightarrow simultaneous eigenspaces
via ad $\mathfrak{g}_{\alpha_i} = \mathbb{C} e_i \quad \& \quad \mathfrak{g}_{-\alpha_i} = \mathbb{C} f_i.$

i.e. $[h, e_j] = \alpha_j(h) e_j$ and $[h, f_j] = -\alpha_j(h) f_j$

(recall: $\alpha_j(h_i) = \frac{1}{d_i} (\alpha_i, \alpha_j) = a_{ij} \quad \forall i, j \in I$.)

(3) Every $i \in I$ gives a copy of $\mathfrak{sl}_2 - \{e_i, f_i, h_i\}$; denoted by $\mathfrak{sl}_2^{(i)} \subset \mathfrak{g}$.

(4) For every $i \neq j \in I$; $\mathfrak{sl}_2^{(i)} \hookrightarrow \bigoplus_{k \geq 0} \mathfrak{g}_{\alpha_j + k\alpha_i}$

Then this is an irreducible repn. of $\mathfrak{sl}_2^{(i)} \cong L_{-\alpha_j}$ (recall $a_{ij} \in \mathbb{Z}_{\leq 0}$)

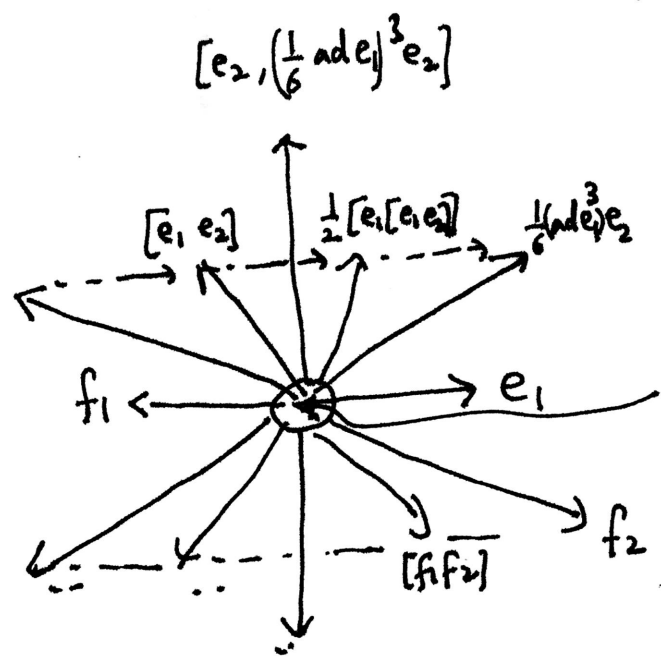
This allows us to compute the action of $\{\bar{s}_i\}_{i \in I} \subset \text{Aut}_{\text{linear}}(\mathfrak{g})$

(recall $\bar{s}_i = \exp(\text{ad } e_i) \exp(-\text{ad } f_i) \exp(\text{ad } e_i)$
 $\in \text{Aut}(\mathfrak{g}) \simeq \bar{s}_i : \mathfrak{g}_\alpha \xrightarrow{\sim} \mathfrak{g}_{\bar{s}_i(\alpha)}$)

2. Example G_2 . $A = \begin{bmatrix} 2 & -3 \\ -1 & 2 \end{bmatrix}$. $\mathfrak{h} = \mathbb{C}h_1 \oplus \mathbb{C}h_2$
 \mathfrak{g}^* - basis α_1, α_2 s.t.

$\alpha_i(h_i) = 2 ; i=1,2$
 $\alpha_1(h_2) = -1$
 $\alpha_2(h_1) = -3$

Positive part:
 $[h_1, e_2] = -3e_2$
 \mathbb{P}_2
 4-dim'l repn.



2-dim'l \mathfrak{g}
 Negative part.

3. (\cdot, \cdot) and Casimir element.

\mathfrak{g} has a unique, non-degenerate, symmetric, bilinear form $(\cdot, \cdot): \mathfrak{g} \times \mathfrak{g} \rightarrow \mathbb{C}$ s.t.

(i) $(\cdot, \cdot)|_{\mathfrak{h} \times \mathfrak{h}}$ is given by the original inner product on $\mathfrak{h} (= E \otimes_{\mathbb{R}} \mathbb{C})$.

(ii) $\forall i, j \in I; (e_i, f_j) = \frac{\delta_{ij}}{d_i}$

(So, e_i is dual to $d_i f_i$.)

(iii) Invariance property: $\forall x, y, z \in \mathfrak{g},$
 $([x, y], z) = (x, [y, z]).$

- Properties. -
- \mathfrak{g}_{α} and $\mathfrak{g}_{-\alpha}$ are dual to each other.
 - $(\mathfrak{g}_{\alpha}, \mathfrak{g}_{\beta}) = 0$ if $\alpha + \beta \neq 0$. (hint: use (iii) $y = h \in \mathfrak{h}$.)

Definition. Pick a basis (o.n.) of $\mathfrak{h} : \{x_i\}_{i \in I}$ (s.t. $(x_i, x_j) = \delta_{ij}$).

$C^0 := \sum_{i \in I} x_i^2$ (on a representation, say V)

$K_{\alpha} := d_{\alpha} (e_{\alpha} f_{\alpha} + f_{\alpha} e_{\alpha})$ where $e_{\alpha} \in \mathfrak{g}_{\alpha}$ and $f_{\alpha} \in \mathfrak{g}_{-\alpha}$ are chosen so that $(e_{\alpha}, f_{\alpha}) = \frac{1}{d_{\alpha}}$.

Casimir element. let $\mathfrak{g} \curvearrowright V$ be a representation

$$C_V := C_V^0 + \sum_{\alpha \in R_+} K_\alpha; V$$

$$= \sum_{i \in I} \alpha_i^2 + \sum_{\alpha \in R_+} d_\alpha (e_\alpha f_\alpha + f_\alpha e_\alpha)$$

Similarly we will define

$$\Omega = \boxed{\sum_{i \in I} \alpha_i \otimes \alpha_i} + \sum_{\alpha \in R_+} d_\alpha (e_\alpha \otimes f_\alpha + f_\alpha \otimes e_\alpha) \in \mathfrak{g} \otimes \mathfrak{g}.$$

This is nothing but the canonical tensor of (\cdot, \cdot) on \mathfrak{g} .

(If V is a f.d. vector space / \mathbb{C} and $(\cdot, \cdot) : V \times V \rightarrow \mathbb{C}$ a non-degenerate, symmetric bilinear form, we can define a natural element of $V \otimes V$ - pick a basis of V : $\{v_i\}_i$.

$\{v^i\} :=$ dual basis
Canonical tensor of $(\cdot, \cdot) \rightarrow \Omega := \sum_i v^i \otimes v_i$
depends only on (\cdot, \cdot) and not the choice of a basis.)

let $\mathfrak{g} \curvearrowright V$ be a repr.

• For any $x \in \mathfrak{g}$; we get $[x \otimes 1 + 1 \otimes x, \Omega_V] = 0$.
 $[x, C_V] = 0$. } we will see a proof of this later. (next lecture).

4. Finite-dimensional representations of \mathfrak{g} .

Let V be a f.d. vector space / \mathbb{C} ; and $\mathfrak{g} \curvearrowright V$.

Prop. $\mathfrak{h} \curvearrowright V$ is diagonalizable

Proof $\forall i \in I$; $\mathfrak{sl}_2^{(i)} \curvearrowright V \Rightarrow h_i$ is diagonalizable

$[h_i, h_j] = 0$ (a set of commuting; diagonalizable matrices can be simultaneously diagonalized.)

$\Rightarrow \mathfrak{h} \curvearrowright V$ is diagonalizable. \square

$\forall \mu \in \mathfrak{h}^*$, define $V[\mu] := \{v \in V \mid h \cdot v = \mu(h)v \ \forall h \in \mathfrak{h}\}$.
 (called " μ -weight space" of V)

Thus, by Prop. above, $V = \bigoplus_{\mu \in \mathfrak{h}^*} V[\mu]$.

5. Weight lattice. $\mathfrak{g} \curvearrowright V$ (f.d. repn). $\mathfrak{sl}_2^{(i)} \curvearrowright V$

implies $V[\mu] \neq 0 \Rightarrow \mu(h_i) \in \mathbb{Z} \ \forall i \in I$.

Define $P := \{\mu \in \mathfrak{h}^* \mid \mu(h_i) \in \mathbb{Z} \ \forall i \in I\} \subset \mathfrak{h}^*$.
 (weight lattice).

Thus $V = \bigoplus_{\mu \in P} V[\mu]$. $P(V) := \{\mu \in P \mid V[\mu] \neq 0\}$
 set of weights of V .

6. Now we assume that $\rho \subset V$ is an irreducible finite-dim'l representation. (6)

Proposition. ~ There is $\lambda \in P_+$ (i.e. $\lambda(h_i) \in \mathbb{Z}_{\geq 0}$) and a

unique up to scalar vector $v_\lambda \in V$ s.t. $h_i v_\lambda = \lambda(h_i) v_\lambda \forall h_i \in \mathfrak{h}$
 i.e. $v_\lambda \in V[\lambda]$ $e_i v_\lambda = 0 \forall i \in I$.

Then, $V[\lambda]$ is 1-dim'l; and $\forall i \in I$

$$f_i^{\lambda(h_i)+1} v_\lambda = 0$$

Proof Pick $\lambda \in P$ s.t. $V[\lambda] \neq 0$ & $V[\lambda + \alpha_i] = 0 \forall i \in I$
 (exists by finite-dimensionality)

Let $v \in V[\lambda]; v \neq 0$. Then $h_i \cdot v = \lambda(h_i) v \forall h_i \in \mathfrak{h}$; and
 $e_i v \in V[\lambda + \alpha_i] = (0) \forall i \in I$.

V' = subrepr. generated by $v = \mathbb{C}$ -span of $\{f_{i_1} \dots f_{i_r} v\}_{r \geq 0, i_1, \dots, i_r \in I}$
 = V by irreducibility
 ($V' \neq (0)$ since $r=0, v \in V'$).

$sl_2^{(i)} \subset V$ and $h_i v_\lambda = \lambda(h_i) v_\lambda \Rightarrow f_i^{\lambda(h_i)+1} v_\lambda = 0$ □

7. Conversely, starting from $\lambda \in P_+$, we can define

$L_\lambda =$ representation of \mathfrak{g} generated by a (non-zero) vector v_λ , subject to the following list of relations:

$$\left. \begin{aligned} h \cdot v_\lambda &= \lambda(h) v_\lambda \quad \forall h \in \mathfrak{h}. \\ e_i \cdot v_\lambda &= 0 \quad \forall i \in I \end{aligned} \right\} (*)$$

$$\boxed{f_i^{\lambda(h_i)+1} v_\lambda = 0 \quad \forall i \in I} - (**)$$

Theorem (Harish-Chandra) L_λ is a finite-dimensional irreducible representation of \mathfrak{g} .

Idea of the proof of finite-dimensionality:

- use (**) to prove that e_i, f_i act locally nilpotently on L_λ ; $\forall i \in I$. This gives $\bar{s}_i \in GL(L_\lambda)$ s.t.

$$\forall \mu \in P(L_\lambda); \quad \bar{s}_i : L_\lambda[\mu] \rightarrow L_\lambda[s_i \mu].$$

Hence $P(L_\lambda) \subset P$ is W -stable subset.

- Use (*) to prove that $P(L_\lambda) \subset \lambda - Q_+$ where

$$Q_+ = \sum_{i \in I} \mathbb{Z}_{\geq 0} \alpha_i$$

- Since W acts transitively on the set of chambers

we conclude that $|P(L_\lambda)| < \infty$; hence $\dim L_\lambda = \sum_{\mu \in P(L_\lambda)} \dim L_\lambda[\mu] < \infty$. \square

8. Characters.

$$\mathfrak{g} \curvearrowright V \Rightarrow V = \bigoplus_{\mu \in \mathcal{P}} V[\mu].$$

(f.d.)

Define $\chi_V = \sum_{\mu \in \mathcal{P}} (\dim V[\mu]) e^\mu \in \mathbb{Z}[e^{\pm \omega_i} : i \in I]$

(ring of Laurent poly-s in $|I|$ variables).

Properties

(i) $\chi_{V_1 \oplus V_2} = \chi_{V_1} + \chi_{V_2}$

(ii) $\chi_{V_1 \otimes V_2} = \chi_{V_1} \cdot \chi_{V_2}$

$\text{Rep}_{\text{fd}}(\mathfrak{g})$ is a semisimple category - i.e., every f.d. ~~irreducible~~ repr. of \mathfrak{g} is a direct sum of irreducible ones.

Character formula of Hermann Weyl:

$$\chi_{L_\lambda} = \frac{\sum_{w \in W} (-1)^{l(w)} e^{w(\lambda + \rho) - \rho}}{\prod_{\alpha \in R_+} (1 - e^{-\alpha})}; \text{ where}$$

$\rho = \frac{1}{2} \sum_{\alpha \in R_+} \alpha$ is the unique element of P_+ s.t. $\rho(h_i) = 1 \forall i \in I$.

9. Example: $\mathfrak{g} = \mathfrak{sl}_2 \hookrightarrow L_n$.

(9)

Direct computation: L_n has a basis $\{v_0, v_1, \dots, v_n\}$ and $h \cdot v_j = (n-2j)v_j$

$$\begin{aligned} \Rightarrow \chi_{L_n} &= e^{n\frac{\alpha}{2}} + e^{(n-2)\frac{\alpha}{2}} + \dots + e^{-n\frac{\alpha}{2}} \\ &= z^n + z^{n-2} + \dots + z^{-n} \quad \text{when } z = e^{\alpha/2} \end{aligned}$$

Weyl Character formula,

$$\begin{aligned} \chi_{L_n} &= \frac{e^{n\frac{\alpha}{2}} - e^{(-n-2)\frac{\alpha}{2}}}{1 - e^{-\alpha}} = \frac{z^n - z^{-n-2}}{1 - z^{-2}} \\ &= \frac{z^{n+1} - z^{-n-1}}{z - z^{-1}} = z^n + z^{n-2} + \dots + z^{-n}. \end{aligned}$$

□