

0. Recall that we defined a root system as follows:

Let E be a finite-dimensional real vector space, together with a positive-definite form $(\cdot, \cdot): E \times E \rightarrow \mathbb{R}$. Using (\cdot, \cdot) we identified

$$v: E^* \xrightarrow{\sim} E \text{ according to the rule } (v(\alpha), \phi) = \alpha(\phi) \text{ and } (\forall \alpha \in E^*, \phi \in E)$$

transported (\cdot, \cdot) on E^* (i.e. $(\alpha, \beta) \stackrel{\text{def}}{=} (v(\alpha), v(\beta)) \forall \alpha, \beta \in E^*$).

Notation: $\forall \alpha \in E^*, \alpha \neq 0$, we define $\alpha^\vee \in E$ by:

$$\alpha^\vee = \frac{2 v(\alpha)}{(\alpha, \alpha)}. \quad (\text{Note: } \alpha(\alpha^\vee) = 2 \forall \alpha \in E^* \setminus \{0\}.)$$

Reflections: Let $\alpha \in E^*; \alpha \neq 0$. We have $s_\alpha \in GL(E)$ or $GL(E^*)$

$$\text{given by } s_\alpha: E \rightarrow E \quad ; \quad s_\alpha: E^* \rightarrow E^* \\ \phi \mapsto \phi - \alpha(\phi) \cdot \alpha^\vee \quad ; \quad \gamma \mapsto \gamma - \gamma(\alpha^\vee) \alpha$$

By a root system we mean a finite set $R \subset E^* \setminus \{0\}$ s.t.

$$(1) \quad R \text{ spans } E^*.$$

$$(2) \quad \alpha, c\alpha \in R \Rightarrow c = \pm 1.$$

$$(3) \quad \alpha, \beta \in R \Rightarrow \beta(\alpha^\vee) = \frac{2(\alpha, \beta)}{(\alpha, \alpha)} \in \mathbb{Z}.$$

$$(4) \quad \forall \alpha \in R; s_\alpha(R) \subset R.$$

In two-dimensions, we obtained the following classification:

* cf - Bourbaki - Lie groups & Lie algebras Ch 4, 5, 6.

$$(A_1 \times A_1) \quad R = \{ \pm \alpha, \pm \beta \}, \quad (\alpha, \beta) = 0.$$

$$(A_2) \quad R = \{ \pm \alpha_1, \pm \alpha_2, \pm (\alpha_1 + \alpha_2) \}; \quad |\alpha_1|^2 = |\alpha_2|^2$$

and $\alpha_1(\alpha_2^\vee) = \alpha_2(\alpha_1^\vee) = -1.$

$$(B_2) \quad R = \{ \pm \alpha_1, \pm \alpha_2, \pm (\alpha_1 + \alpha_2), \pm (2\alpha_1 + \alpha_2) \};$$

$|\alpha_2|^2 = 2|\alpha_1|^2$ and $\alpha_1(\alpha_2^\vee) = -1$
 $\alpha_2(\alpha_1^\vee) = -2$

$$(G_2) \quad R = \{ \pm \alpha_1, \pm \alpha_2, \pm (\alpha_1 + \alpha_2), \pm (2\alpha_1 + \alpha_2),$$

$\pm (3\alpha_1 + \alpha_2), \pm (3\alpha_1 + 2\alpha_2) \};$

$|\alpha_2|^2 = 3|\alpha_1|^2$ and $\alpha_1(\alpha_2^\vee) = -1$
 $\alpha_2(\alpha_1^\vee) = -3$

1. Positive and negative roots.

For $\alpha \in E^* \setminus \{0\}$, let $H_\alpha = \text{Ker}(\alpha) \subset E$ be the corresponding hyperplane in E . Consider the disconnected space

$$E^0 = E \setminus \bigcup_{\alpha \in R} H_\alpha \quad (\text{Note: } H_\alpha = H_{-\alpha})$$

The connected components of E^0 are called chambers. Let us choose a chamber, say $C^0 \subset E^0$, and refer to it as the fundamental chamber. This choice defines the notion of positive and negative roots as follows.

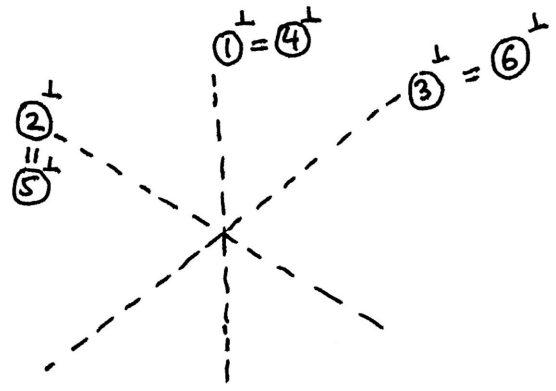
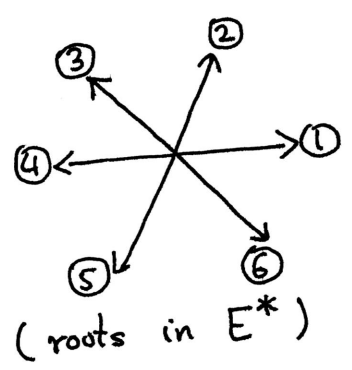
[Note: for any connected component $\mathcal{C} \subset E^\circ$, and $\alpha \in R$, either $\alpha(x) > 0 \forall x \in \mathcal{C}$; or $\alpha(x) < 0 \forall x \in \mathcal{C}$. Since otherwise, H_α will cross through \mathcal{C} .]

$$R_+ := \{ \alpha \in R \mid \alpha(x) > 0 \forall x \in \mathcal{C}^\circ \},$$

$$R_- := \{ \alpha \in R \mid \alpha(x) < 0 \forall x \in \mathcal{C}^\circ \}. \text{ Then we have}$$

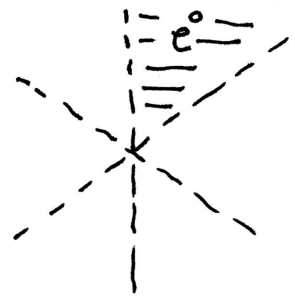
$$R = R_+ \sqcup R_- \text{ and } R_- = -R_+.$$

Example
(A_2)



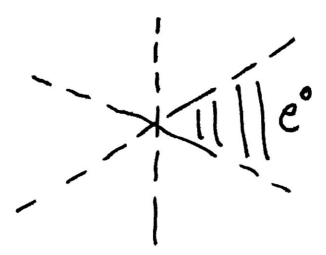
hyperplanes in E . E° has 6 connected components

If we choose \mathcal{C}° to be



then
 $\{1, 2, 3\} = R_+$
 $\{4, 5, 6\} = R_-$

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2. Simple roots.

Given $e \subset E^0$ and $\alpha \in R$, we say α is a
(a connected component)

wall of e if $\left\{ \begin{array}{l} \cdot \alpha(x) > 0 \quad \forall x \in e \quad \text{and} \\ \cdot \bar{e} \cap H_\alpha \text{ is of dimension} = \dim E - 1 \end{array} \right.$
↑
closure in standard topology of \mathbb{R}^n

Having chosen a fundamental chamber e^0 , let $\Delta \subset R_+$ be the set of walls of e^0 . To preserve notation we will write

$$\{\alpha_i\}_{i \in I} = \Delta. \quad (\text{called } \underline{\text{simple roots}}).$$

(I : indexing set)

Lemma. Let $i, j \in I$ and assume $i \neq j$. Let $c \in \mathbb{R}_{>0}$.

Then $\alpha_i - c\alpha_j$ is not a root.

Proof. As α_i and α_j are not proportional; if $\alpha = \alpha_i - c\alpha_j \in R$,

then either $\alpha \geq 0$ on \bar{e}^0

or $\alpha \leq 0$ on \bar{e}^0 . However, α is < 0 on $H_{\alpha_i} \cap \bar{e}^0$

and $\alpha > 0$ on $H_{\alpha_j} \cap \bar{e}^0$. This is a contradiction. \square

Corollary. - For $i \neq j$; $i, j \in I$, let $a_{ij} := \frac{2(\alpha_j, \alpha_i)}{(\alpha_i, \alpha_i)} = \alpha_j(\alpha_i^\vee)$.

Then $a_{ij} \in \mathbb{Z}_{\leq 0}$.

Proof. $a_{ij} \in \mathbb{Z}$ by axiom of integrality (3) of root systems.

Now $s_i(\alpha_j) = \alpha_j - a_{ij}\alpha_i \in R$ and hence, by the lemma above, $a_{ij} \leq 0$.

3. Proposition. - $\{\alpha_i\}_{i \in I}$ forms a basis of E^* .

Proof. - let us first prove that this set is linearly independent.

Assume a linear relation existed $\sum_{t=1}^p c_t \alpha_{i_t} = 0$ where all c_t 's are non-negative, and, say $c_1 = 1$. Then $-\alpha_{i_1} = \sum_{t=2}^p c_t \alpha_{i_t}$. The left-hand side of this equation is < 0 on E° while the right-hand side is ≥ 0 - contradiction.

Thus if a linear relation existed, among $\{\alpha_i\}_{i \in I}$, it must be of the form $\beta = \sum_{j=1}^p c_j \alpha_{i_j} = \sum_{k=p+1}^q d_k \alpha_{i_k}$; $c_1, \dots, c_p \in \mathbb{R}_{>0}$
 d_{p+1}, \dots, d_q

and $\alpha_{i_1}, \dots, \alpha_{i_p}$ are distinct from $\alpha_{i_{p+1}}, \dots, \alpha_{i_q}$.

But then $(\beta, \beta) = \sum_{j,k} c_j d_k (\alpha_{i_j}, \alpha_{i_k}) \leq 0$, contradicting positive definiteness, unless $\beta = 0$ - in which case we obtain a linear relation with $\mathbb{R}_{>0}$ coefficients - the case we already excluded.

Now we claim that $\{\alpha_i\}_{i \in I}$ spans E^* . As R spans E^* , it is enough to show that $\forall \alpha \in R, \{\alpha\} \cup \{\alpha_i\}_{i \in I}$ is linearly dependent. Assume, on the contrary, that there exists $\alpha \in R$ such that $\{\alpha\} \cup \{\alpha_i\}_{i \in I}$ is linearly independent. Then we can find $x, y \in E$ s.t. $\alpha_i(x) > 0; \alpha_i(y) > 0 \forall i \in I$
 $\alpha(x) > 0$ and $\alpha(y) < 0$

$\Rightarrow H_\alpha$ passes through E° , a contradiction. □

4. Cartan matrix and Dynkin diagram. -

Let $A = (a_{ij})_{i,j \in I}$ be the integer matrix where

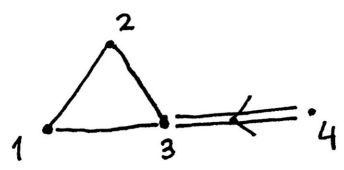
$$a_{ij} = \frac{2(\alpha_i, \alpha_j)}{(\alpha_i, \alpha_i)} = \alpha_j(\alpha_i^\vee) = \begin{cases} 2 & \text{if } i=j \\ \in \mathbb{Z}_{\leq 0} & \text{if } i \neq j \end{cases}$$

By our rank 2 classification, $\forall i \neq j$, we have the following possibilities for (a_{ij}, a_{ji}) (up to switching the role of i & j).

- $(a_{ij}, a_{ji}) = (0, 0)$ - draw as $i \quad j$ not connected.
- $(a_{ij}, a_{ji}) = (-1, -1)$ - " " $i \text{ --- } j$ 'simple edge'
- $(a_{ij}, a_{ji}) = (-2, -1)$ - " " $i \text{ \leftarrow } j$ 'double edge and $|\alpha_j|^2 > |\alpha_i|^2$ '
- $(a_{ij}, a_{ji}) = (-3, -1)$ - " " $i \text{ $\leftarrow\leftarrow$ } j$ 'triple edge and $|\alpha_j|^2 > |\alpha_i|^2$ '

The Dynkin diagram associated to the root system R is then a graph on the vertex set I and edges drawn according to the rule given above.

e.g. $A = \begin{bmatrix} 2 & -1 & -1 & 0 \\ -1 & 2 & -1 & 0 \\ -1 & -1 & 2 & -2 \\ 0 & 0 & -1 & 2 \end{bmatrix} \longleftrightarrow$ Dynkin diagram



(Note - This "Cartan matrix" does not arise from any root system, since it is not positive-definite $A \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$.)

5. Root systems are completely classified by their Dynkin diagrams:

