

§1. Differential Equations. A differential equation of order $N \geq 1$

is an equation of the form

$$f^{(N)}(z) = P(z; f(z), f'(z), \dots, f^{(N-1)}(z)) \quad - \text{ (Diff'l Eq}^n \text{)}$$

where P is a polynomial in $f, f', \dots, f^{(N-1)}$ with coefficients rational functions of z (the nature of P can be obviously generalized).

e.g. $f''(z) = f(z)^2 + a(z)$ Order 2, degree 2.

$$f^{(3)}(z) = a(z) f'(z)^4 + b(z) f^{(2)}(z) f(z) \dots \text{ and so on.}$$

Frobenius method. - is to solve the differential eqⁿ locally - i.e., as a power series in z (for various algebraic relations, such methods were used earlier by Newton and Puiseux.). Our goals are:

- To determine the global nature of our solution; ← this is a problem of analytic continuation.
- Find better approximations to this solution.

§2. Linear differential equations. - Some examples

A linear differential eqⁿ is the one depending linearly on $f, f', \dots, f^{(N)}$.

$$\sum_{j=0}^N a_j(z) \frac{d^j}{dz^j} (f) = g \quad - (*)$$

We say (*) is homogeneous if $g \equiv 0$.

Remark. (1) Linear diff'l eqⁿs are special because of the "superposition principle": (let $L = \sum_{j=0}^N a_j \partial_z^j$).

$$\begin{aligned}
 L f_1 &= g \\
 L f_2 &= g
 \end{aligned}
 \Rightarrow L(f_1 - f_2) = 0 \quad ; \quad f_1, f_2 \text{ two solns. of } Lf = 0$$

hgs. eqⁿ

then $\alpha_1 f_1 + \alpha_2 f_2$ is another solution.

(2) Frobenius also observed that

Order N , linear hgs diff'l eqⁿ for $f: \Omega \rightarrow \mathbb{C}$

first order, linear hgs. eqⁿ for $N \times N$ matrix, whose entries are hol. fns. $\Omega \rightarrow \mathbb{C}$

$$f^{(N)}(z) = \sum_{j=0}^{N-1} a_j(z) f^{(j)}(z)$$

assume $a_0 \neq 0$.

$$\psi(z) = \begin{bmatrix} f \\ f' \\ \vdots \\ f^{(N-1)} \end{bmatrix} \in \Omega \rightarrow \mathbb{C}^N$$

$$\psi'(z) = A(z) \psi(z)$$

$$A(z) = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & & & \ddots & \vdots \\ 0 & \dots & & 0 & 1 \\ a_0 & a_1 & \dots & & a_{N-1} \end{bmatrix}$$

Companion matrix of $t^N - \sum_{j=0}^{N-1} a_j t^j$

$$\psi'(z) = \begin{bmatrix} f' \\ f'' \\ \vdots \\ \sum_{j=0}^{N-1} a_j f^{(j)} \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & & & \ddots & \vdots \\ 0 & \dots & 0 & 0 & 1 \\ a_0 & a_1 & \dots & & a_{N-1} \end{bmatrix} \begin{bmatrix} f \\ f' \\ \vdots \\ f^{(N-1)} \end{bmatrix}$$

§3. Examples. - (1) The simplest example is $f'(z) = g(z)$.

(1st order, linear, inhomogeneous)

Local solution. If $g(z) = \sum_{n=0}^{\infty} g_n (z-\alpha)^n$ near $\alpha \in \Omega$
($g: \Omega \rightarrow \mathbb{C}$)

then $F_{\alpha}(z) := \sum_{n=0}^{\infty} g_n \frac{(z-\alpha)^{n+1}}{n+1} \in \mathbb{C}\{z-\alpha\}$ is a local solution

near α . These are normalized to vanish at $z=\alpha$.

Global solution. For any simply-connected subset containing α ,
say $U \subset \Omega$, we can define (Choose $\alpha \in \Omega$ "base point")

$$F_U(z) = \int_{\gamma} g(w) dw.$$

$$\begin{aligned} \gamma: [0,1] &\rightarrow U \\ \gamma(0) &= \alpha \\ \gamma(1) &= z \end{aligned}$$

Note: $F_U = F_{\alpha}$ on $D(\alpha; r)$ for some $r > 0$.

For any $\beta \in U$,

$$F_U = F_{\beta} + F_U(\beta) \text{ on } D(\beta; r) \text{ for some } r > 0.$$

$F_U(\alpha) = 0 \leftarrow$ normalization.

The solution will in general be multivalued.

(2) Second simplest example

$$f'(z) = a(z) f(z).$$

$a: \Omega \rightarrow \mathbb{C}$ ($\Omega \subset \mathbb{C}$ open, connected).

Local soln. If $a(z) = \sum_{n=0}^{\infty} a_n (z-\alpha)^n$ near $\alpha \in \Omega$

then $f(z) = 1 + \sum_{n=1}^{\infty} f_n (z-\alpha)^n$ solves $f' = af$ if and only if:

$$(n+1) f_{n+1} = \sum_{j=0}^n a_j f_{n-j} \quad (f_0 = 1 \text{ normalization}).$$

($\forall n \geq 0$).

eg. $f_0 = 1$; $f_1 = a_0$; $f_2 = \frac{1}{2} (a_0 f_1 + a_1 f_0) = \frac{1}{2} (a_0^2 + a_1)$

and so on.

Ex. If $R =$ radius of convergence of $\sum_{j=0}^{\infty} a_j z^j$, then $f(z)$ defined as above also has radius of convergence $= R > 0$.

So, for any $\alpha \in \Omega$, we have a local solution; let us denote it

by $F_{\alpha} : D(\alpha; r) \rightarrow \mathbb{C} \quad (F_{\alpha}(\alpha) = 1).$

Global solns:

$$f(z) = \exp \int_{\alpha \rightarrow z} a(w) dw$$

If $f(z) = \exp(\varphi(z))$ then $f' = f \cdot \varphi'(z)$. So, we first

solve $\varphi' = a$ (remember - it may not be a global function)

$$\varphi(\alpha) = 0 \quad (\text{normalization})$$

and set $f = \exp(\varphi)$.

§4. First order, linear diff'l eqⁿ, hgs, matrix-valued.

(5)

Let $N \geq 1$. $\psi'(z) = A(z)\psi(z)$ $A: \Omega \rightarrow M_{N \times N}(\mathbb{C})$

i.e. $A = (a_{ij}(z))$
 $a_{ij}: \Omega \rightarrow \mathbb{C}$ hol. or mero.

Local Study $\alpha \in \Omega$ isolated sing. of A
 $A: \Omega \dashrightarrow M_{N \times N}(\mathbb{C})$ mero.

We say α is a regular point if A is hol. at α .

_____ regular singular point if A has a pole of order 1 at α .
 (or Fuchsian) (simple pole)

_____ irregular point if A has a pole of ord. $r \geq 2$ at α
 (or Poincaré rank r)

Example of irregular case. -

$\varphi'(z) = \frac{\varphi(z)}{z^2} - \frac{1}{z}$ can be solved formally

near 0 ; $\varphi(z) = z + \sum_{n=2}^{\infty} c_n z^n$ gives :

$$1 + \sum_{n=2}^{\infty} n c_n z^{n-1} = \sum_{m=2}^{\infty} c_m z^{m-2}$$

So, $c_2 = 1$; $c_3 = 2c_2 = 2$; $c_4 = 3c_3 = 3!$
 (coeff of z^0) (coeff of z^1) (coeff of z^2)

... $c_m = (m-1)!$

$$\varphi(z) = \sum_{n=1}^{\infty} (n-1)! z^n$$

divergent series.