

Lecture 1

(1.0) Sketch of a proof of Lemma (0.3) from Lecture 0, page 7.

Recall: $M =$ smooth m -dim'l manifold. $p \in M$.

$$C^\infty(M)_p / \sim = \frac{\{(f, U) : p \in U \subset M \text{ and } f: U \rightarrow \mathbb{R} \text{ is smooth}\}}{}$$

$$(f, U) \sim (f', U') \text{ if } f = f' \text{ on } U \cap U'$$

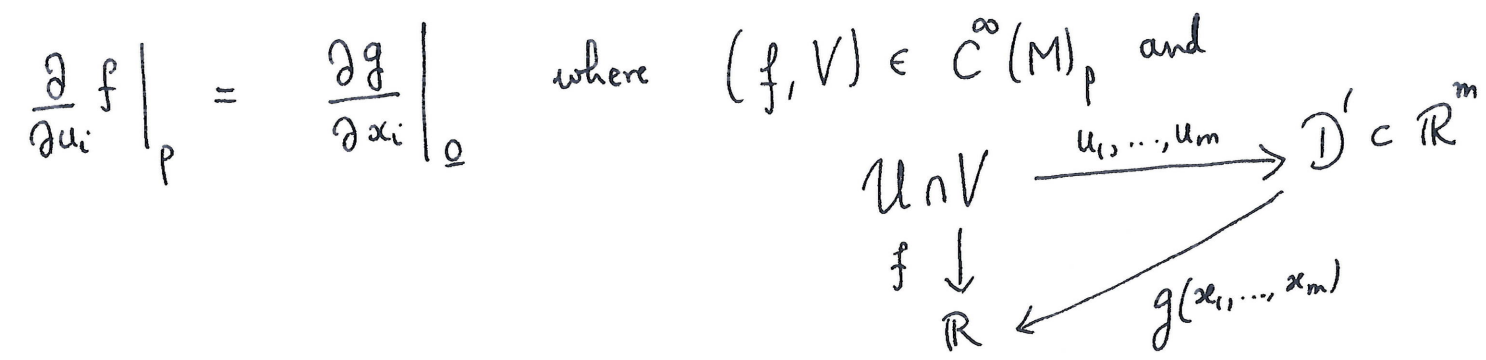
$\mathcal{U}_p =$ equivalence classes of functions vanishing at p .

$\mathcal{U}_p^2 =$ linear span of $[f \cdot g]$ where $f, g \in \mathcal{U}_p$.
equivalence class

Pick a coordinate neighbourhood $U \xrightarrow{(u_1, \dots, u_m)} D \subset \mathbb{R}^m$ of p . We

assumed $\underline{0} = (\underbrace{0, \dots, 0}_m) \in D$ and $u_i(p) = 0$ for each $i=1, \dots, m$.

$du_i|_p := [u_i] \in \mathcal{U}_p / \mathcal{U}_p^2$ and $\frac{\partial}{\partial u_i}|_p \in T_p M$ is defined as



Easy part: (a) $\left\{ \frac{\partial}{\partial u_i}|_p \right\}_{1 \leq i \leq m}$ and $\{du_i\}_{1 \leq i \leq m}$ are dual to each other.

(b) $\forall L \in T_p M, f \in \mathcal{U}_p^2, L(f) = 0$ (by product rule)

We have the following lemma from Calculus (proof left as an exercise) (2)

Lemma. Let $g(x_1, \dots, x_m)$ be a smooth function defined in an open disc $D_{\underline{0}}(r) = \{(a_1, \dots, a_m) \in \mathbb{R}^m : \sum_{j=1}^m a_j^2 < r\}$. If $g(\underline{0}) = 0$ and

$$\left. \frac{\partial g}{\partial x_i} \right|_{\underline{0}} = 0 \quad \text{for } 1 \leq i \leq m, \quad \text{then}$$

$$g(a_1, \dots, a_m) = \sum_{i < j} a_i a_j \int_0^1 (1-t) \left. \frac{\partial^2 g}{\partial x_i \partial x_j} \right|_{\substack{x_i = ta_i \\ \vdots \\ x_m = ta_m}} dt$$

Hence we get :

(c) if $f \in \mathcal{U}_p$, and $\left. \frac{\partial f}{\partial u_i} \right|_p = 0$ for $1 \leq i \leq m$, then $f \in \mathcal{U}_p^2$

(d) $\forall f \in \mathcal{U}_p$, $[f] = \sum_{i=1}^m \left. \frac{\partial f}{\partial u_i} \right|_p du_i|_p$ in $\mathcal{U}_p / \mathcal{U}_p^2$

$$\Rightarrow \dim T_p M = \dim \mathcal{U}_p / \mathcal{U}_p^2 = m (= \dim M).$$

Lemma (0.3) is now proved.

$\mathcal{U}_p / \mathcal{U}_p^2$ is also denoted by $T_p^* M$ (cotangent space).

We will now define tangent and cotangent bundles. First

we need to introduce the notion of a vector bundle.

(1.1) Vector bundle (of rank r) on M is the data of a smooth manifold E and a surjective smooth map $\pi: E \rightarrow M$ such that M admits an open cover $\{V_\alpha\}_{\alpha \in J}$ satisfying

(i) $\forall \alpha \in J$, we have homeomorphisms $\pi^{-1}(V_\alpha) \xrightarrow{\psi_\alpha} V_\alpha \times \mathbb{R}^r$
 s.t. $\text{pr}_1 \circ \psi_\alpha = \pi$

(ii) $\forall \alpha, \beta \in J$ s.t. $V_\alpha \cap V_\beta \neq \emptyset$, and $p \in V_\alpha \cap V_\beta$, the map $g_{\alpha\beta}(p): \mathbb{R}^r \rightarrow \mathbb{R}^r$ is linear (here $g_{\alpha\beta}(p) \cdot v = \psi_\alpha \circ \psi_\beta^{-1}(p, v)$)
 iso.

(iii) $g_{\alpha\beta}: V_\alpha \cap V_\beta \rightarrow GL_r(\mathbb{R})$ is smooth.
 $p \mapsto g_{\alpha\beta}(p)$

(1.2) TM and T^*M . As a set $TM = \bigcup_{p \in M} T_p M$ and

$$\begin{array}{ccc} TM & \supset & T_p M \\ \pi \downarrow & & \downarrow \\ M & \ni & p \end{array}$$

There is one and only one way to put a topology on TM which makes it a vector bundle (of rank m) on M .

Idea: • Open cover needed is ~~the~~ open cover of M by coordinate neighbourhoods $\{(U_\alpha, (u_1^\alpha, \dots, u_m^\alpha))\}_{\alpha \in I}$.

• ψ_α are given by $U_\alpha \times \mathbb{R}^m \rightarrow \bigcup_{p \in U_\alpha} T_p M$
 $(q, (a_1, \dots, a_m)) \mapsto \sum_{j=1}^m a_j \frac{\partial}{\partial u_j^\alpha} \Big|_q \in T_q M$

• put the same topology on $\bigcup_{p \in U_\alpha} T_p M$ as that on $U_\alpha \times \mathbb{R}^r$ via ψ_α . ⁽⁴⁾

Remark: This idea works for T^*M or any tensor or exterior powers of these

Definition: Smooth Vector fields on M = set of smooth maps $X: M \rightarrow TM$ such that $\pi \circ X = \text{Identity}_M$. (denoted by $\text{Vect}(M)$)

1-forms on M = $\{ \omega: X \rightarrow T^*M : \pi \circ \omega = \text{Identity}_M \}$
(denoted by $\Omega^1(M)$)

$\text{Vect}(M)$ acts on $C^\infty(M)$, i.e. $\forall X \in \text{Vect}(M)$, we have a linear map, also denoted by $X: C^\infty(M) \rightarrow C^\infty(M)$ defined as follows:

$\forall f \in C^\infty(M), p \in M; (Xf)(p) = X_p(f)$ ($X_p \in T_p M$ is the value of X at p).

Leibniz rule holds: $X(f \cdot g) = X(f) \cdot g + f \cdot X(g)$.

Thus we can take composition of vector fields. However, for $X, Y \in \text{Vect}(M)$, $X \circ Y$ does not belong to $\text{Vect}(M)$.

e.g. $M = \mathbb{R}^m$, $X = \frac{\partial}{\partial x_i}$, $Y = \frac{\partial}{\partial x_j} \Rightarrow X \circ Y = \frac{\partial^2}{\partial x_i \partial x_j}$

does not satisfy Leibniz rule.

Nevertheless, $[X, Y] := X \circ Y - Y \circ X$ is again a vector field.

(1.3) Let $f: M \rightarrow N$ be a smooth map. For every $p \in M$, (5)

we naturally get a linear map $Tf_p: T_p M \rightarrow T_{f(p)} N$:
(or $T_p f$)

let $X \in T_p M$,

$(g, V) \in C^\infty(N)_{f(p)}$ (ie. $V \subset N$ is an open set containing $f(p)$ and $g: V \rightarrow \mathbb{R}$ is a smooth function)

Then $(T_p f (X))(g) = X(g \circ f)$

$$g \circ f: \underbrace{f^{-1}(V)}_{\substack{\text{(again open} \\ \text{in } M)}} \xrightarrow{f} V \xrightarrow{g} \mathbb{R} \in C^\infty(M)_p$$

\Rightarrow We get a smooth map $Tf: TM \rightarrow TN$ such that:

$$\begin{array}{ccc} TM & \xrightarrow{Tf} & TN \\ \pi_M \downarrow & & \downarrow \pi_N \\ M & \xrightarrow{f} & N \end{array}$$

$$\pi_N \circ Tf = f \circ \pi_M.$$

(1.4) Back to Lie groups and Lie algebras.

$G =$ Lie group (manifold + group st. $G \times G \xrightarrow{\text{Multiplication}} G$ and $G \xrightarrow{\text{inverse}} G$ are smooth)

$\forall g \in G$, $l_g: G \rightarrow G$ is a diffeomorphism (smooth bijection with smooth inverse = $l_{g^{-1}}$)
 $h \rightarrow gh$
left-translation

Similarly we have r_g (right-translation); Conjugation $c_g(x) = gxg^{-1}$

Definition. A vector field $X \in \text{Vect}(G)$ is said to be left-invariant ⑥

$$\text{if } (Tl_g)(X(h)) = X(gh) \quad \forall g, h \in G.$$

$$T_h G \xrightarrow{\sim} T_{gh} G$$

$$G \xrightarrow[\text{lg}]{\text{diffeo}} G$$

$$\begin{array}{ccc} \psi & & \psi \\ h & \longmapsto & gh \end{array}$$

$\text{Vect}(G)^G =$ space of left-invariant vector fields

Easy check: $X, Y \in \text{Vect}(G)^G \Rightarrow [X, Y] \in \text{Vect}(G)^G$

Clearly any $X \in \text{Vect}(G)^G$ is determined by its value at $e \in G$

since $X(g) = (Tl_g)(X(e)).$

Conversely, given $L \in T_e G$, define $X \in \text{Vect}(G)$ by

$$X(g) = (Tl_g)(L).$$

$$\begin{aligned} X \in \text{Vect}(G)^G : \quad X(gh) &= (Tl_{gh})(L) = (Tl_g \circ Tl_h)(L) \\ &= (Tl_g)(X(h)) \quad (\forall g, h \in G). \end{aligned}$$

Prop. $\mathfrak{g} = T_e G \simeq \text{Vect}(G)^G$. Thus we have an

operation $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \longrightarrow \mathfrak{g}$. (called Lie bracket).

(Skew-symmetry) $[X, Y] + [Y, X] = 0$

(Jacobi Identity) $[X, [Y, Z]] = [[X, Y], Z] + [Y, [X, Z]].$

(1.5) Definition. A Lie algebra \mathfrak{a} (over a field - \mathbb{R} or \mathbb{C} for us) is a vector space, together with a bilinear map

$$[\cdot, \cdot] : \mathfrak{a} \times \mathfrak{a} \longrightarrow \mathfrak{a}$$

satisfying skew-symmetry and Jacobi identity.

Summarizing:

$$G : \text{Lie group} \implies \mathfrak{g} = \text{Te}G \stackrel{=}{=} \text{Lie}(G) : \text{Lie algebra}$$

$$f : G \longrightarrow H \implies \text{Lie}(f) = \text{Te}f : \mathfrak{g} \longrightarrow \mathfrak{h}$$

Caution: a smooth map $f : M \rightarrow N$ of manifolds does not induce a map between $\text{Vect}(M) \rightarrow \text{Vect}(N)$. Only $Tf : TM \rightarrow TN$. For Lie groups however, $\text{Lie}(f)$ is a map $\text{Vect}(G)^G \rightarrow \text{Vect}(H)^H$ (here $f : G \rightarrow H$).