

Lecture 4

(4.0) Recall : we need to prove Frobenius Thm and Monodromy principle in order to finish the proof of Lie's Theorems.

Proof of Frobenius Theorem is by induction. We begin by proving the local version (see (3.3) of Lecture 3 , page 3).

(4.1) Let M be a smooth m -dim'l manifold , $p \in M$ and let X be a smooth vector field defined in an open set containing p , s.t. $X_p \neq 0$. Then we can find a coordinate nhbd. $(u_1, \dots, u_m) : U \rightarrow \text{Cube}_r(\underline{0}) \subset \mathbb{R}^m$ s.t. (a) $u_j(p) = 0 \quad \forall j=1, \dots, m$ (b) X is defined on U and $X = \frac{\partial}{\partial u_i}$ on U .

Proof. Let us start with any coordinate nhbd. of p where X is

$$\text{defined : } (z_1, \dots, z_m) : W \xrightarrow{\psi} \text{Cube}_t(\underline{0}) \subset \mathbb{R}^m$$

$$\downarrow_p \xrightarrow{\psi_p} (0, \dots, 0)$$

s.t. $X_p z_i \neq 0$. We want to construct a change of coordinates $\underline{\varphi} = (\varphi_1(a_1, \dots, a_m), \dots, \varphi_m(a_1, \dots, a_m))$ on $\text{Cube}_r(\underline{0}) \subset \mathbb{R}^m$ s.t. (for some $r < t$)

$$W \xrightarrow[\text{Given}]{(z_1, \dots, z_m)} \text{Cube}_t(\underline{0})$$

$$\downarrow \quad \downarrow \quad \underline{\varphi} = (\varphi_1, \dots, \varphi_m) \leftarrow \text{To construct}$$

$$U \xrightarrow{(u_1, \dots, u_m)} \text{Cube}_r(\underline{0}) \quad \text{and} \quad X = \frac{\partial}{\partial u_i} \text{ on } U$$

(define using \underline{z} and $\underline{\varphi}$)

Let $F_j(b_1, \dots, b_m)$ be real valued functions on m real variables $(1 \leq j \leq m)$ $(b_1, \dots, b_m) \in \text{Cube}_t(\underline{0})$ defined by:

$$F_j(z_1(q), \dots, z_m(q)) = X_q z_j \quad \forall q \in W.$$

Claim: If $\frac{\partial \varphi_j}{\partial a_i} = F_j(\varphi_1, \dots, \varphi_m)$ ($1 \leq j \leq m$) , with initial conditions $\varphi_i(0, a_2, \dots, a_m) = 0$, $\varphi_i(0, a_2, \dots, a_m) = a_i$ ($2 \leq i \leq m$) then $X = \frac{\partial}{\partial u_i}$.

For $q \in U$ and $\underline{b} = (b_1, \dots, b_m) = (u_1(q), \dots, u_m(q))$ we have

$$\begin{aligned} \frac{\partial \varphi_j}{\partial a_i}(\underline{b}) &= F_j(\varphi_1(\underline{b}), \dots, \varphi_m(\underline{b})) = F_j(z_1(q), \dots, z_m(q)) \\ &= X z_j(q) \end{aligned}$$

$$\Rightarrow X z_j(q) = \frac{\partial \varphi_j}{\partial a_i}(u_1(q), \dots, u_m(q)) = \left. \frac{\partial z_j}{\partial u_i} \right|_q \text{ as claimed.}$$

We still have to show that $(\varphi_1, \dots, \varphi_m)$ is a change of coordinates.

i.e. $\det \left[\frac{\partial \varphi_i}{\partial a_j} \right] \neq 0$ at $(0, \dots, 0)$. $\frac{\partial \varphi_1}{\partial a_1}(0) = F_1(0) = X_p z_1 \neq 0$ by assumption

$\frac{\partial \varphi_i}{\partial a_j}(0) = \delta_{ij}$ ($2 \leq i, j \leq m$) by initial conditions. So

$$\left[\frac{\partial \varphi_i}{\partial a_j} \right]_{1 \leq i, j \leq m} = \left[\begin{array}{cccc} F_1(0) & * & \dots & * \\ * & & & \\ \vdots & & & \\ * & & & \end{array} \right]_{m-1 \times m-1} \rightsquigarrow \det = F_1(0) \neq 0.$$

□

(4.2) Induction step. Now we have n smooth vector fields, X_1, \dots, X_n defined on an open set W containing p s.t. $\{X_1(q), \dots, X_n(q)\}$ form a basis of $\mathcal{X}(q)$ ($\forall q \in W$) and $[X_i : X_j] = \sum_{k=1}^n g_{ij}^k X_k$ for some smooth fns. g_{ij}^k on W .

Pick a coordinate system around p , say $Z \subset W$, with $(z_1, \dots, z_m) : Z \rightarrow \text{Cube}_s(\underline{0}) \subset \mathbb{R}^m$ s.t. $X_1 = \frac{\partial}{\partial z_1}$. Replace X_j by $X_j - (X_j \cdot z_1) X_1$ so that $X_j \cdot z_1 = 0 \quad \forall j = 2, \dots, n$.

$\bar{Z} = \{q \in Z : z_1(q) = 0\}$ has $(n-1)$ smooth vector fields X_2, \dots, X_n with the same properties. By induction, choose coordinate system around $p \in \bar{Z}$, $(w_2, \dots, w_m) : W \rightarrow \text{Cube}_r(\underline{0}) \subset \mathbb{R}^{m-1}$ s.t. the statement of theorem holds: i.e. $\forall b_{n+1}, \dots, b_m \in (-r, r)$, the slice $\overline{S_b} \subset W$ defined by $w_l(q) = b_l \quad (n+1 \leq l \leq m)$ has the property $T_q \overline{S_b} = \text{span}$ of $\{X_2(q), \dots, X_n(q)\} \quad \forall q \in \overline{S_b}$.

$$\begin{array}{ccc}
 \bar{Z} & \xrightarrow{(z_1, \dots, z_m)} & \text{Cube}_s(\underline{0}) \subset \mathbb{R}^m \\
 \downarrow & & \downarrow \\
 \{z_1=0\} \supset W & \xrightarrow{(w_2, \dots, w_m)} & \text{Cube}_r(\underline{0}) \subset \mathbb{R}^{m-1}
 \end{array}$$

Take U to be open subset in Z defined by

$q \in U \Leftrightarrow (0, z_2(q), \dots, z_m(q)) \in \text{Cube}_r(0) \subset \text{Cube}_s(0)$ and (4)

$$|z_i(q)| < r$$

Coordinates $u_1 = z_1, u_2 = w_2, \dots, u_m = w_m$.

Claim: $X_i u_e = 0 \quad \forall 1 \leq i \leq n \text{ and } n+1 \leq l \leq m$.

True for $i=1$ by construction. For $i \geq 2$, we have

$$\frac{\partial}{\partial u_1} (X_i u_e) = X_1 X_i u_e = [X_1, X_i] u_e = \sum_{j=2}^n g_{1i}^{ij} X_j u_e$$

Since on $u_1=0$ the functions $X_i u_e$ vanish, this eqⁿ implies that the fns $\psi_i = X_i u_e$ are solns. of homogeneous diff'l eqⁿs

($2 \leq i \leq n$)

$$\frac{\partial \psi_i}{\partial u_1} = \sum_{j=2}^n g_{1i}^{ij} \psi_j \quad \text{w/ initial condition } \psi_i = 0 \quad 2 \leq i \leq n \\ (\text{on } u_1=0)$$

By uniqueness, $\psi_j = 0 \quad \forall 2 \leq j \leq n$ and we are done.

□

(4.3) Global statement.

We define a new topological space $M(\mathcal{X})$ which is same as M (as a set) with a base of topology given by

$$\mathcal{B} = \{S \subset M \text{ s.t. } S \text{ is an integral submanifold wrt. } \mathcal{X}\}$$

That is, a subset $O \subset M(\mathcal{X})$ is open iff it is a union of integral submanifolds.

The local statement can be used to prove that

- \mathcal{B} is a base of a topology on $M(\mathfrak{X})$ (i.e. $\bigcup_{S \in \mathcal{B}} S = M$)

and $\forall S_1, S_2 \in \mathcal{B}, p \in S_1 \cap S_2, \exists S_3 \in \mathcal{B}$ s.t. $p \in S_3 \subset S_1 \cap S_2$

- $M(\mathfrak{X})$ is a manifold.

Then $\forall p \in M$, the connected component of p in $M(\mathfrak{X})$ is the maximal integral submanifold $W(p)$ claimed in (Global Statement) of Frobenius Theorem (Thm (3.3) of Lecture 3 page 4).

(4.4) Proof of Lie's Theorem (Thm (3.0) of Lecture 3, part (2)).

Let $\mathfrak{o}_G = \text{Lie}(G)$ and $i: \mathfrak{h} \hookrightarrow \mathfrak{o}_G$ be a subalgebra. Define

$$\mathcal{X}_{\mathfrak{h}}(\sigma) := \left\{ X(\sigma) : X \in \mathfrak{h} \subset \mathfrak{o}_G = \text{Vect}(G)^G \right\} \subset T_\sigma G.$$

$\mathcal{X}_{\mathfrak{h}}$ satisfies the hypotheses of Frobenius' Thm. (being a subalgebra $\Rightarrow \mathcal{X}_{\mathfrak{h}}$ is involutive).

Let $H \xrightarrow{\varphi} G$ be the max'l integral submanifold passing through $e \in G$ (in the notation of Frobenius' Thm $H = W(e)$).

Claim: H is a subgroup.

Since $\mathfrak{h} \subset \mathfrak{o}_G$, $\forall \sigma \in G$, l_σ leaves $\mathcal{X}_{\mathfrak{h}}$ invariant

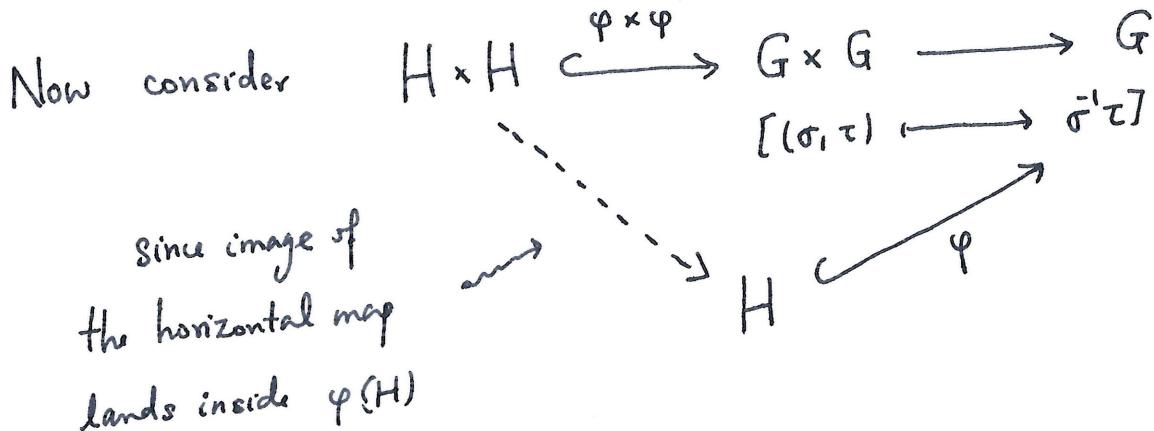
$\underset{\parallel}{\text{left-mv. vector fields}}$

i.e. ℓ_σ permutes the max'l integral submanifolds of \mathcal{K}_G . ⑥

Now let $\sigma \in H$. Then $\ell_{\bar{\sigma}^{-1}}(H)$ is the max'l integral submanifold and $e \in \ell_{\bar{\sigma}^{-1}}(H) \Rightarrow \ell_{\bar{\sigma}^{-1}}(H) = H$

So $\bar{\sigma}^{-1} \in H$ and H is stable under left multiplication.
(since $e \in H$)

$\Rightarrow H$ is a subgroup of G .



The fact that the resulting map $H \times H \rightarrow H$ is smooth, is
 $(\sigma, \tau) \longmapsto \bar{\sigma}^{-1}\tau$

a consequence of countability axiom (from HW1). (See Optional
problem 4(c))

Reading A for a proof).

□

(4.5) Proof of Lie's Theorem part (3).

Set up: $\mathfrak{g} = \text{Lie}(G)$ when G is connected & simply-conn.
 $\mathfrak{g}' = \text{Lie}(G')$

$\xi: \mathfrak{g} \rightarrow \mathfrak{g}'$ hom of Lie algebras.

To prove: $\exists \psi: G \rightarrow G'$ s.t. $\xi = T_e \psi$ (or $\text{Lie}(\psi)$)

(Existence) Let $\Omega = \{(x, \xi(x)) : x \in \mathfrak{g}\} \subset \mathfrak{g} \times \mathfrak{g}'$
 Subalgebra since ξ
 is hom. of Lie algebras

By (4.4) we get a Lie subgroup

$$A \xrightarrow{\psi} G \times G' \quad \psi_1 = \text{pr}_1 \circ \psi: A \rightarrow G$$

$$\begin{array}{ccc} & \text{pr}_1 \swarrow & \searrow \text{pr}_2 \\ G & & G' \end{array}$$

$$\text{Note: } \text{Lie}(\psi_1) = \Omega \subset \mathfrak{g} \times \mathfrak{g}'$$

$$\begin{array}{ccc} & \nearrow & \downarrow \text{pr}_1 \\ & \sim & \mathfrak{g} \end{array}$$

$\Rightarrow \exists$ a nhd. $V \underset{\text{open}}{\subset} G$ of e s.t. ψ_1 admits an inverse
 $\lambda: V \rightarrow A$. Clearly $\lambda(e) = e \in A$ and if $a, b, ab \in V$

$$\text{then } \lambda(ab) = \lambda(a)\lambda(b).$$

G simply-connected $\Rightarrow \lambda$ extends to a unique hom (\star)
 $G \xrightarrow{\lambda} A$. Let $\varphi = \text{pr}_2 \circ \lambda: G \rightarrow G'$. By construction

$$\text{Lie}(\varphi) = \xi.$$

(Uniqueness) $\text{Lie}(\text{graph of } \varphi) \subset \text{Lie}(G \times G') = \mathfrak{g} \times \mathfrak{g}'$

depends only on ξ . Hence, graph of φ , and therefore φ ,
 is uniquely determined by ξ .