

Lecture 7

(1)

(7.0) Recall : $G =$ connected Lie group $\mathfrak{g} = \text{Lie}(G)$. Last time we introduced

• $\exp : \mathfrak{g} \rightarrow G$ smooth map, diffeo. near $0 \in \mathfrak{g}$. This was defined

using $\mathbb{R} \times \mathfrak{g} \rightarrow G$ where for fixed $X \in \mathfrak{g}$, $\mathbb{R} \rightarrow G$
 $(t, X) \mapsto \exp(tX)$ $t \mapsto \exp(tX)$ is

the unique 1-parameter subgroup s.t. $\left. \frac{d}{dt} \exp(tX) \right|_{t=0} = X$.

• $\mathfrak{gl}(\mathfrak{g})$ or $\text{End}(\mathfrak{g}) =$ vector space of all \mathbb{R} -linear maps $\mathfrak{g} \rightarrow \mathfrak{g}$
(Lie algebra under $[A, B] = AB - BA$).

\cup

$\text{Der}(\mathfrak{g}) = \{ f : \mathfrak{g} \rightarrow \mathfrak{g} \text{ s.t. } f([A, B]) = [f(A), B] + [A, f(B)] \}$
(derivations : Lie subalgebra of $\mathfrak{gl}(\mathfrak{g})$)

$\text{Aut}(\mathfrak{g})$ or $GL(\mathfrak{g}) =$ group of all invertible linear maps $\mathfrak{g} \rightarrow \mathfrak{g}$

\cup

$\text{Aut}_{\text{L.A.}}(\mathfrak{g}) = \{ \varphi \in GL(\mathfrak{g}) : \varphi([A, B]) = [\varphi(A), \varphi(B)] \}$

We defined a hom. of Lie groups $G \xrightarrow{\text{Ad}} \text{Aut}_{\text{L.A.}}(\mathfrak{g})$

(Ad is smooth by HW2, at $e \in G$ and hence everywhere \leftarrow using left translations).

Lie algebra of $\text{Aut}_{\text{L.A.}}(\mathfrak{g}) = \text{Der}(\mathfrak{g})$ (also by HW2)

and $\text{Lie}(\text{Ad}) = \text{ad}$

Recall $\text{Ad}(\sigma) : \mathfrak{g} \rightarrow \mathfrak{g}$ is the derivative at e of conjugation map

$\alpha \mapsto \sigma \alpha \sigma^{-1}$ from $G \rightarrow G$. $\text{ad}(X) : \mathfrak{g} \rightarrow \mathfrak{g}$
 $Y \mapsto [X, Y]$

(7.1) One application of exp. (G : connected Lie group $\mathfrak{g} = \text{Lie}(G)$) ②

Let $\{X_1, \dots, X_n\}$ be a basis of \mathfrak{g} . Since exp is a local diffeo. we can find a coord. neighbourhood U of $e \in G$ and inverse to exp on U , in other words:

• $\exists r > 0$ st. $\exp\left(\sum_{i=1}^n a_i X_i\right) \in U \iff |a_i| < r \ \forall 1 \leq i \leq n.$

• $u_i \left(\exp \sum_{j=1}^n a_j X_j\right) = a_i$ are the coordinates in U

$(u_1, \dots, u_n) : U \longrightarrow \text{Cube}_r(\underline{0}) \subset \mathbb{R}^n \xrightarrow{\cong} \mathfrak{g}$
↑
by fixing basis $\{X_1, \dots, X_n\}$

We refer to (u_1, \dots, u_n) as coordinates adapted to basis $\{X_1, \dots, X_n\}$.

Prop. Let $\varphi: G \rightarrow G'$ be a continuous group hom of two Lie groups. Then φ is smooth.

Proof Step 1: Prove the proposition for $G = \mathbb{R}$, $G' = H$. i.e. given a continuous gp. hom. $\eta: \mathbb{R} \rightarrow H$, we claim that η is smooth.

In fact we will prove that we can find $X \in \mathfrak{h}$ st. $\eta(t) = \exp(tX)$.

Choose a coord. system near $e \in H$ adapted to a basis $\{X_1, \dots, X_n\}$ of \mathfrak{h}

($n = \dim \mathfrak{h}$), say $(u_1, \dots, u_n) : U \xrightarrow{\sim} \text{Cube}_r(\underline{0}) \subset \mathbb{R}^n \cong \mathfrak{h}.$

$U' \xrightarrow{\sim} \text{Cube}_{r'}(\underline{0})$ (choose some $0 < r' < r$)

Let $t_0 \in \mathbb{R}$ be such that $\eta(t_0) \in U'$ and fix $X_0 \in \mathfrak{h}$ st

$\eta(t_0) = \exp(X_0)$ (here $X_0 = \sum_{j=1}^n u_j(\eta(t_0)) \cdot X_j$ by defn of U)

We claim that $\eta(t) = \exp\left(\frac{t}{t_0} X_0\right)$. We write this as

$$\eta(r \cdot t_0) = \exp(r X_0) \quad \forall r \in \mathbb{R}. \text{ The idea is to prove this for rational}$$

$r \in \mathbb{Q}$ of size < 1 .

eg. if $r = \frac{1}{N}$ then let $\sigma = \eta\left(\frac{t_0}{N}\right)$. As $\sigma^N \in \mathcal{U}$, we know that

$$u_i(\sigma^k) = k u_i(\sigma) \quad \text{are all in } \mathcal{U} \quad (0 \leq k \leq N) \text{ and hence}$$

$$u_i(\sigma^N) = N u_i(\sigma) \Rightarrow u_i(\sigma) = \frac{1}{N} u_i(\sigma^N) \text{ and thus } u_i(\sigma^k) = \frac{k}{N} u_i(\sigma^N)$$

$$\text{i.e. } u_i\left(\eta\left(\frac{k}{N} t_0\right)\right) = \frac{k}{N} u_i(\eta(t_0)) \quad (0 \leq k \leq N). \text{ The same is true}$$

for $\exp\left(\frac{k}{N} X_0\right)$. Thus $\eta(r \cdot t_0) = \exp(r \cdot X_0)$ for rat'l r of size < 1

By continuity $\eta(r \cdot t_0) = \exp(r \cdot X_0) \quad \forall r \in \mathbb{R}, |r| \leq 1$. Since both sides are gp. hom $\eta(t \cdot t_0) = \exp(t \cdot X_0) \quad \forall t \in \mathbb{R}$ and we are done.

Step 2. General case. $\varphi: G \rightarrow G'$ is a continuous gp. hom.

Let $\{X_1, \dots, X_m\}$ be a basis of \mathfrak{g} ($m = \dim \mathfrak{g}$).

We get $\mathbb{R} \xrightarrow{\varphi} G'$. By previous part $\exists Y_i \in \mathfrak{g}'$ s.t.
 $\forall 1 \leq i \leq m: \quad t \longmapsto \varphi(\exp(t X_i))$

$$\varphi(\exp(t X_i)) = \exp(t Y_i) \quad (1 \leq i \leq m)$$

and $\varphi(\exp(t_1 X_1) \dots \exp(t_n X_n)) = \exp(t_1 Y_1) \dots \exp(t_n Y_n)$ since φ

is a group hom.

Let $(u_1, \dots, u_m): \mathcal{U} \rightarrow \text{Cube}_r(\underline{0}) \subset \mathbb{R}^m \cong \mathfrak{g}$ be coord. adapted to $\{X_1, \dots, X_n\}$

For a smaller open nhd of $\underline{0} \in \text{Cube}_r(\underline{0})$, the map

$$(t_1, \dots, t_m) \longmapsto \exp(t_1 X_1) \dots \exp(t_n X_m) \in \mathcal{U}$$

and $f_j(t_1, \dots, t_m) = u_j(\exp(t_1 X_1) \dots \exp(t_n X_m))$ are smooth with

$$\left. \frac{\partial f_i}{\partial t_j} \right|_{\underline{0}} = \delta_{ij} \text{ (by defn. of } u_1, \dots, u_m \text{)}. \text{ This allows us to introduce}$$

t_1, \dots, t_m as local coordinates near $e \in G$, and in these coordinates the hom φ has the form

$$(t_1, \dots, t_m) \longmapsto \exp(t_1 Y_1) \dots \exp(t_m Y_m) \text{ which is}$$

smooth. Since φ is smooth near $e \in G$ and a gp. hom. it is smooth everywhere □

(7.2) Cor. If G is a topological group then there is at most one smooth structure on G making it a Lie group.

(7.3) One more example. $Sp(n)$. skew-symmetric ↓ didn't cover

Introduce a non-degenerate symplectic form on \mathbb{C}^{2n} in terms of a basis $\{\epsilon_1, \dots, \epsilon_n; \eta_1, \dots, \eta_n\}$:

$$(\epsilon_i, \epsilon_j) = 0 = (\eta_i, \eta_j) \quad (\epsilon_i, \eta_j) = \delta_{ij} = -(\eta_j, \epsilon_i)$$

$$Sp(n; \mathbb{C}) := \left\{ A \in M_{2n \times 2n}(\mathbb{C}) : (Av, Aw) = (v, w) \forall v, w \in \mathbb{C}^{2n} \right\}$$

$Sp(n) := Sp(n; \mathbb{C}) \cap U(2n)$ closed subgroup of $U(2n)$, (5)

hence compact.

Lemma $\{Sp(n)\}_{n \geq 1}$ are simply connected.

Proof: $Sp(1) = \begin{bmatrix} \alpha & -t\bar{\beta} \\ \beta & t\bar{\alpha} \end{bmatrix} = A$ s.t. $A^T \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$

a typical matrix in $U(2)$
here $|\alpha|^2 + |\beta|^2 = 1, |t| = 1$

Last condⁿ $\Rightarrow \det A = 1 = t$

Hence $Sp(1) \cong SU(2) \cong S^3$ simply-connected.

Claim: $Sp(n) / Sp(n-1) \cong S^{4n-1}$ ($n \geq 2$)

Proof left as an exercise.

Hence by results of Lecture 5, each $Sp(n)$ is simply-connected \square

(7.4) Examples we have seen so far (all compact)

