

Lecture 20

①

(20.0) Our next theorem is Peter-Weyl Theorem. For a compact Lie group G , the theorem states

$$L^2(G) \cong \bigoplus_{\lambda \in \Lambda} V_\lambda^{\oplus m_\lambda}$$

\uparrow
square-integrable
 \mathbb{C} -valued fns. on G

$\{V_\lambda\}_{\lambda \in \Lambda}$ set of iso. classes of
irreducible finite-dim'l
representations of G

$$m_\lambda = \text{multiplicity of } V_\lambda = \dim V_\lambda$$

In order to define L^p -spaces associated to G , we need a measure on G (wrt Borel σ -algebra), or what is equivalent, by Riesz representation theorem, an integral

$$\int_G : C(G) \longrightarrow \mathbb{C}$$

(continuous
 \mathbb{C} -valued fns.
on G)

We want this integration to be invariant under left-translations of G . This will lead us to constructing invariant differential forms on G .

(20.1) Recall: for an m -dim'l smooth manifold M , we (2)

defined TM (tangent bundle) and T^*M (cotangent bundle)

A 1-form ω on M is a section of T^*M , i.e. a smooth

function $\omega: M \rightarrow T^*M$ s.t. $\pi \circ \omega = \text{Id}_M$.

For any r , $1 \leq r \leq m$, a (smooth) r -form on M is a section of

$\wedge^r T^*M$ (r^{th} exterior product). We usually denote by

\downarrow
 M

$\Omega^r(M) =$ space of r -forms on M .

(module over $C^\infty(M)$ - algebra of smooth functions $M \rightarrow \mathbb{R}$)

Locally, for $p \in M$ and a coordinate neighbourhood $U \xrightarrow{\sim} \text{Cube}_r(0) \subset \mathbb{R}^m$
 (x_1, \dots, x_m)

dx_1, \dots, dx_m are 1-forms on U

For $1 \leq i_1 < \dots < i_r \leq m$, $dx_{i_1} \wedge \dots \wedge dx_{i_r}$ is an r -form on U .

Change of coordinates, say near p we have 2 coordinates

$p \in U \xrightarrow{\sim (x_1, \dots, x_m)} \text{Cube}_r(0) \subset \mathbb{R}^m$

$\xrightarrow{\sim (y_1, \dots, y_m)} \text{Cube}_{r'}(0) \subset \mathbb{R}^m$

We get $y_j = F_j(x_1, \dots, x_m) \quad (\forall 1 \leq j \leq m)$. Here (3)

F_1, \dots, F_m are \mathbb{R} -valued fns. of m real variables and $\forall q \in U$

$$y_j(q) = F_j(x_1(q), \dots, x_m(q)).$$

Thus $dy_j = \sum_{i=1}^m \frac{\partial F_j}{\partial x_i} dx_i$. Similarly for an r -form

$$dy_{j_1} \wedge \dots \wedge dy_{j_r} = \left(\sum_{i=1}^m \frac{\partial F_{j_1}}{\partial x_i} dx_i \right) \wedge \dots \wedge \left(\sum_{i=1}^m \frac{\partial F_{j_r}}{\partial x_i} dx_i \right)$$

$$= \sum_{1 \leq i_1 < \dots < i_r \leq m} \left\{ \sum_{\sigma \in S_r} (-1)^\sigma \frac{\partial F_{j_{\sigma(1)}}}{\partial x_{i_1}} \dots \frac{\partial F_{j_{\sigma(r)}}}{\partial x_{i_r}} \right\} dx_{i_1} \wedge \dots \wedge dx_{i_r}$$

(use $dx_i \wedge dx_j = -dx_j \wedge dx_i$)

In particular, for $r=m$, we get

$$dy_1 \wedge \dots \wedge dy_m = \det \left(\frac{\partial F_i}{\partial x_j} \right)_{1 \leq i, j \leq m} dx_1 \wedge \dots \wedge dx_m$$

(20.2) Orientability. An orientation on M is a choice of ordering the coordinate functions on coordinate neighbourhoods of M s.t. the choices on overlapping coordinate open sets

are consistent. That is, for every $U \subset M$, with (4)

homeo. $U \xrightarrow{\sim} \text{Cube}_r(\mathcal{Q}) \subset \mathbb{R}^m$ we fix an order on the m -components of this homeo. (equivalently an ordered basis of \mathbb{R}^m).

If $U_1 \cap U_2 \neq \emptyset$

$$\begin{array}{ccc}
 & \nearrow U_1 & \xrightarrow{x_1 \dots x_m} \text{Cube}_r(\mathcal{Q}) \\
 U_1 \cap U_2 & & \\
 & \searrow U_2 & \xrightarrow{y_1 \dots y_m} \text{Cube}_r(\mathcal{Q})
 \end{array}$$

We require $\det \left(\frac{\partial y_j}{\partial x_i} \Big|_q \right) > 0 \quad \forall q \in U_1 \cap U_2$.

More systematically, an orientation on M is a choice of nowhere vanishing m -form, say $\phi \in \Omega^m(M)$. Such a choice determines an ordering (up to even permutations) of coordinate functions

$U \xrightarrow{x_1 \dots x_m} \text{Cube}_r(\mathcal{Q}) \subset \mathbb{R}^m$ by: $x_1 \dots x_m$ is oriented (wrt. ϕ) if

$$dx_1 \wedge \dots \wedge dx_m = F \cdot \phi \Big|_U \quad \text{and} \quad F(q) > 0 \quad \forall q \in U.$$

Examples. Spheres are orientable. \mathbb{P}^2 is not orientable.

All Lie groups are orientable as we will see later.

For an orientable manifold M , with a choice of nowhere vanishing m -form ϕ , we can define integration of compactly supported

continuous (\mathbb{R} -valued, or \mathbb{C} -valued) functions on M .

(5)

(20.3) M, ϕ : oriented Manifold of dimension m .

$$C_c(M) = \left\{ f : M \rightarrow \mathbb{R} \text{ continuous such that } \overline{\text{Supp}(f)} \text{ is compact} \right\}$$

Here $\text{Supp}(f) = \{ p \in M : f(p) \neq 0 \}$

Definition of $\int_M f \phi$: Step 1. Assume $\text{Supp}(f) \subset$ a coord. nhd.

say $U \xrightarrow{\sim} \text{Cube}_r(\underline{0}) \subset \mathbb{R}^m$. Then we get ~~two~~ real-valued functions of m real variables \tilde{f} and F such that:

$$f(q) = \tilde{f}(x_1(q), \dots, x_m(q)) \quad \forall q \in U$$

$$\phi(q) = F(x_1(q), \dots, x_m(q)) dx_1 \wedge \dots \wedge dx_m \Big|_q$$

(here $F > 0$).

$$\int_M f \phi = \int_{\text{Cube}_r(\underline{0})} \tilde{f}(u_1, \dots, u_m) F(u_1, \dots, u_m) du_1 \wedge \dots \wedge du_m$$

Use change of coordinate formulae and change of variables for integrals to prove independence from the choice of (x_1, \dots, x_m) :

$$U \xrightarrow{\sim} \text{Cube}_r(\underline{0})$$

Step 2. By step 1 we know how to integrate functions (6)

$f \in C_c(M)$ s.t. $\overline{\text{Supp}(f)} \subset \mathcal{U}$ a coord. nhd. \mathcal{U} . We have the usual properties of $\int_M \phi$ restricted to such functions (i.e. fix a coord. nhd. \mathcal{U} and consider $C_c(M)_\mathcal{U} = \{f \in C_c(M) : \overline{\text{Supp} f} \subset \mathcal{U}\}$)

Then
$$\int_M (a_1 f_1 + a_2 f_2) \phi = a_1 \int_M f_1 \phi + a_2 \int_M f_2 \phi.$$
$$\forall f_1, f_2 \in C_c(M)_\mathcal{U}$$

Now, if $f \in C_c(M)$ is arbitrary, we use the following Lemma. Let $K \subset M$ be a compact subset. Then there exists a continuous function η on M such that

- (1) $\eta = \eta_1 + \dots + \eta_l$ finite sum of functions $\eta_j \in C_c(M)_{\mathcal{U}_j}$ with each $\mathcal{U}_j \subset M$ a coord. nhd.
- (2) $\eta(q) = 1 \quad \forall q \in K.$

Then (assuming the lemma for now), take $K = \overline{\text{Supp}(f)}$ and let η be the continuous function given by the lemma.

Define
$$\int_M f \phi = \sum_{i=1}^l \int_M f \cdot \eta_i \phi$$
 (note $f = f \cdot \eta$
since $f = 0$ outside K
 $\eta = 1$ inside K)

(20.4) Proof of independence from η . (7)

More generally, if $f = \sum_{j=1}^r f_j = \sum_{k=1}^s g_k$ where each

f_j and g_k have compact support in a coord. open set, we will prove that $\sum_{j=1}^r \int f_j \phi = \sum_{k=1}^s \int g_k \phi$. To see this,

let η be the function coming from Lemma (20.3) above, with

$K = \bigcup_{j=1 \dots r} \text{Supp}(f_j) \cup \bigcup_{k=1 \dots s} \text{Supp}(g_k)$. Then we get (say

$$\eta = \eta_1 + \dots + \eta_t) \quad f \eta_i = \sum_j f_j \eta_i = \sum_k g_k \eta_i$$

$$\Rightarrow \sum_j \int f_j \eta_i \phi = \sum_k \int g_k \eta_i \phi$$

(by Step 1)

Summing over i and using $f_j = \sum_i f_j \eta_i$ (same w/ g 's)

$$\text{we get } \sum_j \int f_j \phi = \sum_k \int g_k \phi$$

(20.5) Proof of Lemma (20.3) page 6:

$K \subset M$ compact. We can cover $K \subset \bigcup_{j=1}^l V_j =: \mathcal{U}$

$$V_j \xrightarrow[\substack{\sim \\ x_i^j \dots x_m^j}]{} \text{Cube}_r(\underline{0}) \subset \mathbb{R}^m \quad (8)$$

Define $\mu_j(q) = \begin{cases} 1 - \frac{\text{Max}_{1 \leq i \leq m} |x_i^j(q)|}{r} & \text{if } q \in V_j \\ 0 & \text{o/w} \end{cases}$

(by shrinking V_j if necessary we can assume $V_j \cap \tilde{V}_j$ another coord. nhd.)

Let $\mu = \sum_{j=1}^l \mu_j$ (> 0 on \mathcal{U}) continuous fn
($= 0$ on $M \setminus \mathcal{U}$)

Let $m = \min \{ \mu(p) : p \in K \} > 0$ since K is cpct.

We just need to average μ , by $s(p) = \text{Max} \{ m, \mu(p) \}$
($= \mu(p)$ on K)

Thus $\eta = \frac{\mu}{s} = \sum_{j=1}^l \left(\frac{\mu_j}{s} \right) \leftarrow \eta_j$ is the desired

function. □