

- (13.0) Set up:
- $\Omega \subseteq \mathbb{C}$ open, connected set
 - $f: \Omega \rightarrow \mathbb{C}$ continuous function
 - $\gamma: [a, b] \rightarrow \Omega$ piecewise smooth path.

Recall that we defined (Lecture 12, (12.3) Defn 2):

$$\int_{\gamma} f(z) dz = \int_a^b f(\gamma(t)) \gamma'(t) dt \quad (\text{if } \gamma \text{ is smooth})$$

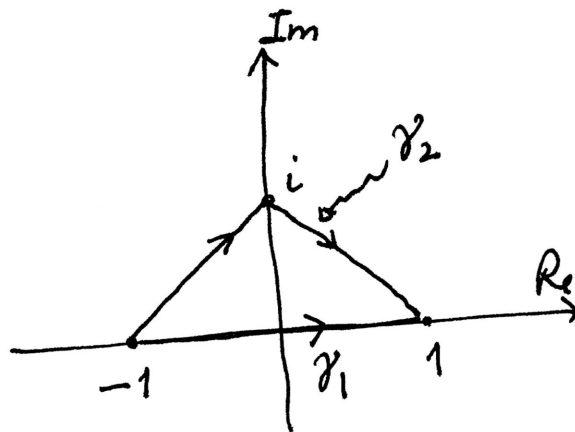
$$= \int_a^{c_1} f(\gamma(t)) \gamma'(t) dt + \int_{c_1}^{c_2} f(\gamma(t)) \gamma'(t) dt + \dots + \int_{c_{l-1}}^b f(\gamma(t)) \gamma'(t) dt$$

(if γ is piecewise smooth - smooth on each $[a, c_1], [c_1, c_2], \dots, [c_{l-1}, b]$).

(13.1) Three examples.

I. $f(z) = \operatorname{Re}(z)$. $\gamma_1(t) = t; (-1 \leq t \leq 1)$ ($\Omega = \mathbb{C}$.)

$$\gamma_2(t) = \begin{cases} (-1+t) + ti & ; 0 \leq t \leq 1 \\ (-1+t) + (2-t)i & ; 1 \leq t \leq 2 \end{cases}$$



$$\int_{\gamma_1} f(z) dz = \int_{-1}^1 \underbrace{t}_{f(\gamma_1(t))} \cdot \underbrace{1}_{\gamma_1'(t)} dt = \left[\frac{t^2}{2} \right]_{-1}^1 = 0.$$

$$\int_{\gamma_2} f(z) dz = \int_0^1 \underbrace{(-1+t)}_{f(\gamma_2(t))} \cdot \underbrace{(1+i)}_{\gamma_2'(t)} dt + \int_1^2 (-1+t) \cdot (1-i) dt$$

(for $0 \leq t \leq 1$)

$$= (1+i) \left[-t + \frac{t^2}{2} \right]_0^1 + (1-i) \left[-t + \frac{t^2}{2} \right]_1^2$$

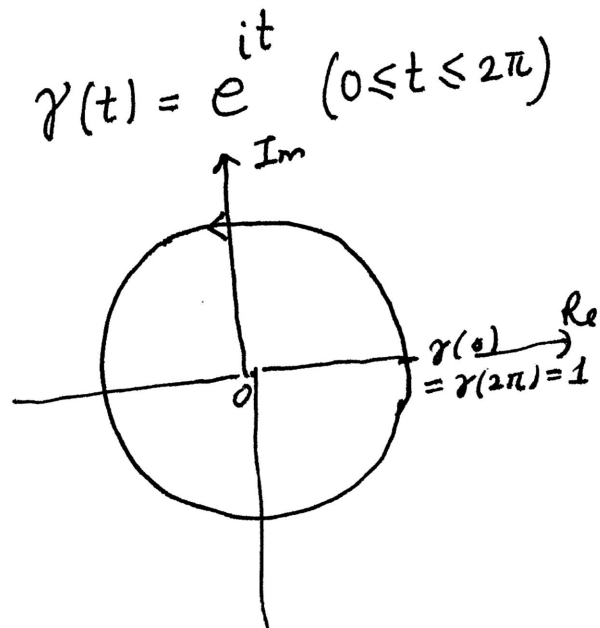
$$= (1+i) \left(-\frac{1}{2} - 0 \right) + (1-i) \left(0 - \left(-\frac{1}{2} \right) \right) = -i$$

(Moral of the story: the answer depends on how we go from -1 to 1 . Reason (as we will see later): $f(z) = \operatorname{Re}(z)$ is NOT \mathbb{C} -differentiable.)

II. $f(z) = \frac{1}{z}$. $\Omega = \mathbb{C} \setminus \{0\}$. $\gamma(t) = e^{it}$ ($0 \leq t \leq 2\pi$)

$$\int_{\gamma} f(z) dz = \int_0^{2\pi} \frac{1}{e^{it}} \cdot \underbrace{i \cdot e^{it}}_{\gamma'(t)} dt$$

$$= i \cdot \int_0^{2\pi} 1 \cdot dt = 2\pi i.$$



Moral of the story. - the answer still depends on the path

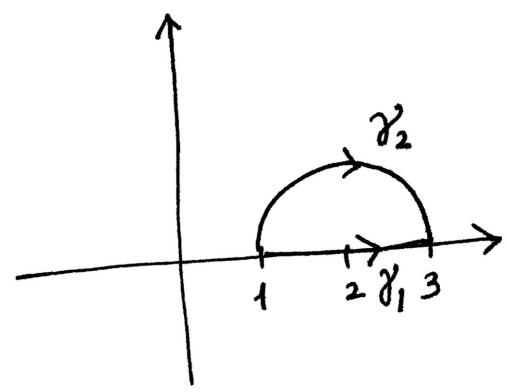
chosen (for $\gamma(t) = e^{it}$ ($0 \leq t \leq 2\pi$) - we get $2\pi i$) , even when
for $\gamma_2(t) = 1$ ($0 \leq t \leq 2\pi$) - we get 0.)

$f(z)$ is \mathbb{C} -differentiable. Reason (again as we will see later)
the whole interior of γ is not in the domain of f .

III. $f(z) = z$; $\Omega = \mathbb{C}$.

$\gamma_1(t) = t$; $1 \leq t \leq 3$.

$\gamma_2(t) = 2 - e^{-it}$; $0 \leq t \leq \pi$.



$\int_{\gamma_1} f(z) dz = \int_1^3 t \cdot 1 \cdot dt = \left[\frac{t^2}{2} \right]_1^3 = 4.$

$\int_{\gamma_2} f(z) dz = \int_0^\pi (2 - e^{-it}) \cdot (-1)(-i)e^{-it} dt$
Labels: $f(\gamma_2(t))$ under $(2 - e^{-it})$, $\gamma_2'(t)$ under $(-1)(-i)e^{-it}$

$= i \left[\int_0^\pi 2 e^{-it} dt - \int_0^\pi e^{-2it} dt \right]$

$= 2 \cdot i \cdot \left[\frac{e^{-it}}{-i} \right]_0^\pi - i \cdot \left[\frac{e^{-2it}}{-2i} \right]_0^\pi = -2(-1-1) = 4.$

(13.2) Theorem. Let $f: \Omega \rightarrow \mathbb{C}$ be a continuous function, where $\Omega \subseteq \mathbb{C}$ is an open and connected subset. Assume that there exists a \mathbb{C} -differentiable $F: \Omega \rightarrow \mathbb{C}$ such that

$$F'(z) = f(z). \quad (\text{i.e., } F \text{ is an antiderivative of } f \text{ ; on } \Omega.)$$

Then for any piecewise smooth path $\gamma: [a, b] \rightarrow \Omega$, we have:

$$\int_{\gamma} f(z) dz = F(\gamma(b)) - F(\gamma(a))$$

(this means that the answer only depends on the starting and finishing points of γ - and not on γ itself. - see Ex. III of (13.1) above.)

Proof. - Let us write $f(z) = u(x, y) + v(x, y)i$,
 $F(z) = U(x, y) + V(x, y)i$, $\gamma(t) = x(t) + y(t)i$.

→ Assume that γ is smooth. Then:

(i) $F(z)$ is \mathbb{C} -differentiable and $F'(z) = f(z)$

$$\begin{aligned} U_x &= V_y = u \\ V_x &= -U_y = v \end{aligned}$$

(Cauchy-Riemann)

(ii) Unfolding $\int_a^b f(\gamma(t)) \gamma'(t) dt$ (see Lecture 12, §12.4, Remark (2)) (5)

we get:

$$\begin{aligned} \bullet \operatorname{Re} \left(\int_{\gamma} f(z) dz \right) &= \int_a^b (u(x(t), y(t)) \cdot x'(t) - v(x(t), y(t)) \cdot y'(t)) dt \\ &= \int_a^b \underbrace{(U_x(x(t), y(t)) \cdot y'(t) + U_y(x(t), y(t)) \cdot x'(t))}_{\frac{d}{dt} (U(x(t), y(t))) \text{ by Chain rule.}} dt \\ &= \left[U(x(t), y(t)) \right]_a^b = \operatorname{Re} (F(\gamma(b)) - F(\gamma(a))). \end{aligned}$$

$$\begin{aligned} \bullet \operatorname{Im} \left(\int_a^b f(z) dz \right) &= \int_a^b (u(x(t), y(t)) y'(t) + v(x(t), y(t)) x'(t)) dt \\ &= \int_a^b \underbrace{(V_y(x(t), y(t)) y'(t) + V_x(x(t), y(t)) x'(t))}_{\frac{d}{dt} (V(x(t), y(t)))} dt \\ &= \left[V(x(t), y(t)) \right]_a^b \\ &= \operatorname{Im} (F(\gamma(b)) - F(\gamma(a))). \end{aligned}$$

Hence, $\int_{\gamma} f(z) dz = F(\gamma(b)) - F(\gamma(a))$ for smooth γ .

→ If γ is only piecewise smooth, say smooth on $[a, c_1], [c_1, c_2], \dots, [c_{\ell}, b]$, then (by the previous argument):

$$\int_{\gamma} f(z) dz = (F(\gamma(c_1)) - F(\gamma(a))) + (F(\gamma(c_2)) - F(\gamma(c_1)))$$

$$+ \dots + (F(\gamma(c_{\ell})) - F(\gamma(c_{\ell-1}))) + (F(\gamma(b)) - F(\gamma(c_{\ell})))$$

$$= F(\gamma(b)) - F(\gamma(a)). \quad \square$$

(13.3) Remarks. - (1) In view of this theorem, and Example II of (13.1) above, we conclude that $\frac{1}{z}$ ($\Omega = \mathbb{C} - \{0\}$) does not have an antiderivative on the whole of Ω . This is consistent with the fact that we could not define a logarithm on $\mathbb{C} - \{0\}$, but only on $\mathbb{C} - \mathbb{R}_{\leq 0}$ (Lecture 9; (9.2); page 3).

(2) This theorem will allow us to compute $\int_{\gamma} f(z) dz$ for a lot of functions whose antiderivative is easy to write down: e.g.

- $f(z) = a_0 + a_1 z + \dots + a_n z^n$; $F(z) = a_0 z + a_1 \frac{z^2}{2} + \dots + a_n \frac{z^{n+1}}{n+1}$
polynomial; $\Omega = \mathbb{C}$

(13.4) Converse of Theorem (13.2) above is also true. Namely: ⑦

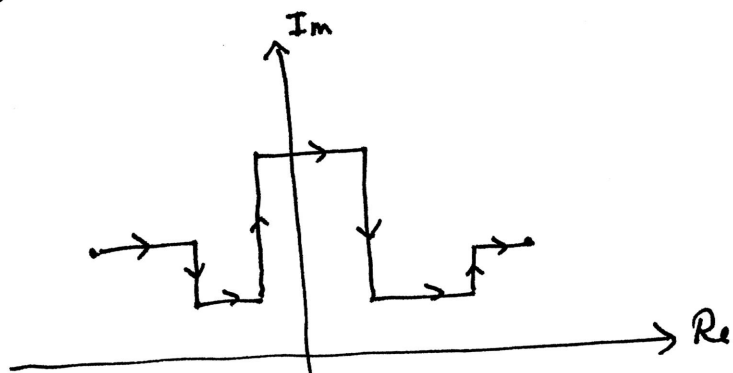
If $f: \Omega \rightarrow \mathbb{C}$ is continuous; ($\Omega \subseteq \mathbb{C}$ open & connected)

such that $\int_{\gamma_1} f(z) dz = \int_{\gamma_2} f(z) dz$ for any two piecewise smooth paths in Ω , with same end points

Then there exists a \mathbb{C} -differentiable $F: \Omega \rightarrow \mathbb{C}$ such that $F'(z) = f(z)$.

We are going to need a stronger version of this, which we will prove later, where we only consider zig-zag paths.

(13.5) Zig-zag path. Let $\gamma: [a, b] \rightarrow \Omega$ be a piecewise smooth path. We say γ is a zig-zag path if every smooth component of γ is either a horizontal line; or a vertical line.



(example of a zig-zag path)

More precisely, $[a, b] = [a, c_1] \cup [c_1, c_2] \cup \dots \cup [c_l, b]$

($a \underset{\parallel}{=} c_0 < c_1 < c_2 < \dots < c_l < \underset{\parallel}{=} c_{l+1} = b$ as before.)

and for each subinterval

$[c_j, c_{j+1}]$ ($0 \leq j \leq l$; $c_0 = a, c_{l+1} = b$)

either $\text{Re}(\gamma(t)) = \text{constant} \quad \forall t \in [c_j, c_{j+1}]$ (vertical)

or $\text{Im}(\gamma(t)) = \text{constant} \quad \forall t \in [c_j, c_{j+1}]$ (horizontal)

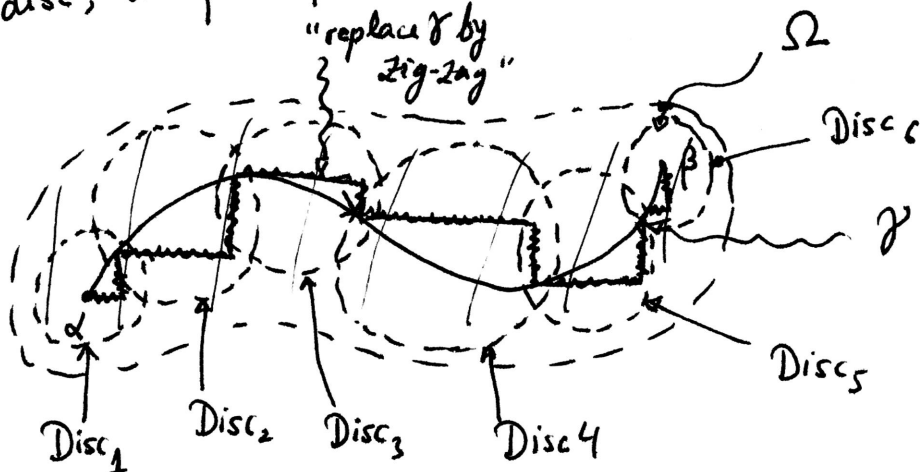
Fact: (I will write a proof of this separately in "Optional Reading" material)

If $\Omega \subseteq \mathbb{C}$ is open and connected, then any two points can be joined by a zig-zag path.

Idea of the proof: Let $\alpha, \beta \in \Omega$. Since Ω is connected, there is some path $\gamma: [a, b] \rightarrow \Omega$ with $\gamma(a) = \alpha, \gamma(b) = \beta$.

$\left[\begin{array}{l} \Omega : \text{open} \\ \gamma \text{ closed \& bounded} \end{array} \right] \Rightarrow$ we can cover γ by a finite number of discs. (open)
Within each open disc, the part of γ can be replaced by a zig-zag

Illustration:



(13.6) We will prove the following theorem next time.

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Theorem. Let $\Omega \subseteq \mathbb{C}$ be open and connected subset and $f: \Omega \rightarrow \mathbb{C}$ a continuous function. Then, the following three assertions are equivalent.

(1) There exists a \mathbb{C} -differentiable function $F: \Omega \rightarrow \mathbb{C}$ such that $F'(z) = f(z)$.

(2) Given any two piecewise smooth paths $\gamma_1, \gamma_2: [a, b] \rightarrow \Omega$ such that $\gamma_1(a) = \gamma_2(a)$ and $\gamma_1(b) = \gamma_2(b)$;

$$\int_{\gamma_1} f(z) dz = \int_{\gamma_2} f(z) dz$$

(3) - same statement as (2) - but γ_1 and γ_2 are only assumed to be zig-zag paths.