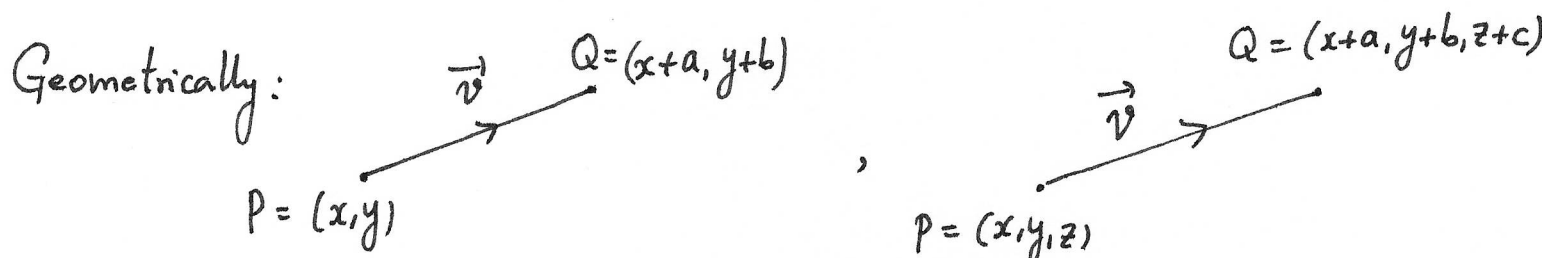


(10.0) Recall: last time we discussed vectors in 2 & 3 dimensions geometrically.

Algebraically: $\vec{v} = \begin{bmatrix} a \\ b \end{bmatrix}$ in \mathbb{R}^2 , $\vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ in \mathbb{R}^3

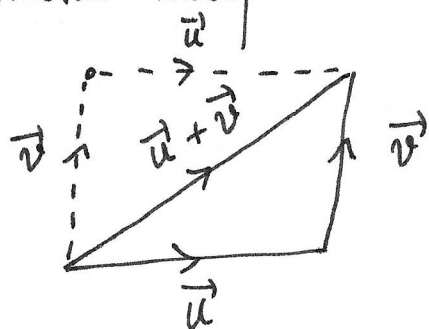


We discussed: magnitude, or length, or norm of a vector

$$\vec{v} = \begin{bmatrix} a \\ b \end{bmatrix}, \quad \|\vec{v}\| = \sqrt{a^2 + b^2} \quad \text{in } \mathbb{R}^2.$$

$$\vec{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}, \quad \|\vec{v}\| = \sqrt{a^2 + b^2 + c^2} \quad \text{in } \mathbb{R}^3.$$

• geometric interpretation of addition and scalar multiplication:



(triangle/parallelogram law)

$$\|c\vec{v}\| = |c| \cdot \|\vec{v}\| \quad (c \in \mathbb{R})$$

$$\text{Direction of } c\vec{v} = \begin{cases} \text{same as } \vec{v} & \text{if } c > 0 \\ \text{opposite to } \vec{v} & \text{if } c < 0 \\ \text{unspecified} & \text{if } c = 0 \end{cases}$$

• Basic unit vectors: $\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $\vec{e}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ in \mathbb{R}^2 .

$$\vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \quad \vec{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \quad \vec{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad \text{in } \mathbb{R}^3.$$

- (2)
- Given a non-zero vector \vec{v} , there is a unique unit vector in the direction same as \vec{v} , namely $\frac{1}{\|\vec{v}\|} \cdot \vec{v}$.

(10.1) Today we are going to talk about dot product.

$$\text{In } \mathbb{R}^2 : \vec{u} = \langle a_1, b_1 \rangle \text{ (Calculus notation)}, \vec{v} = \begin{bmatrix} a_2 \\ b_2 \end{bmatrix} \\ = \begin{bmatrix} a_1 \\ b_1 \end{bmatrix} \text{ (matrix notation)}$$

$$\boxed{\vec{u} \cdot \vec{v} = a_1 a_2 + b_1 b_2}$$

$$\text{In } \mathbb{R}^3 : \vec{u} = \begin{bmatrix} a_1 \\ b_1 \\ c_1 \end{bmatrix}, \vec{v} = \begin{bmatrix} a_2 \\ b_2 \\ c_2 \end{bmatrix}$$

$$\boxed{\vec{u} \cdot \vec{v} = a_1 a_2 + b_1 b_2 + c_1 c_2}$$

Note - We saw that this formula generalizes to any dimension, and can be written as matrix multiplication:

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}, \vec{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \Rightarrow \boxed{\vec{u}^T \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3 + \dots + u_n v_n}$$

for now, we will stick to Calculus notation $\vec{u} \cdot \vec{v}$, but later in the course we will solely use $\vec{u}^T \vec{v}$ for this quantity.

(10.2) Properties of the dot product.

(i) $\|\vec{u}\|^2 = \vec{u} \cdot \vec{u}$

(ii) $\vec{u} \cdot \vec{v} = \vec{v} \cdot \vec{u}$

(iii) $\vec{u} \cdot (\vec{v}_1 + \vec{v}_2) = \vec{u} \cdot \vec{v}_1 + \vec{u} \cdot \vec{v}_2$

For any vectors
 $\vec{u}, \vec{v}, \vec{v}_1, \vec{v}_2$

These follow directly from the definition.

Example. - $\|\vec{u} + \vec{v}\|^2 = (\vec{u} + \vec{v}) \cdot (\vec{u} + \vec{v})$ (using (i))
 $= \vec{u} \cdot \vec{u} + \vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{u} + \vec{v} \cdot \vec{v}$ (using (iii))
 $= \|\vec{u}\|^2 + 2\vec{u} \cdot \vec{v} + \|\vec{v}\|^2$ (using (ii) & (i))

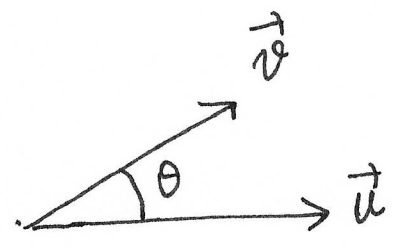
$$\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2\vec{u} \cdot \vec{v}$$

(10.3) Geometric formula for the dot product.

If $\theta =$ angle between \vec{u} and \vec{v} ($0 \leq \theta \leq \pi$)

Then

$\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos(\theta)$



Proof We are going to compute $\|\vec{u} + \vec{v}\|^2$ geometrically and compare it with the formula written on the last page

$$\|\vec{u} + \vec{v}\|^2 = |PR|^2$$

$$= |PS|^2 + |RS|^2$$

$$= (\|\vec{u}\| + \|\vec{v}\| \cos \theta)^2 + (\|\vec{v}\| \sin \theta)^2$$

$$= \|\vec{u}\|^2 + \|\vec{v}\|^2 (\cos^2 \theta + \sin^2 \theta)$$

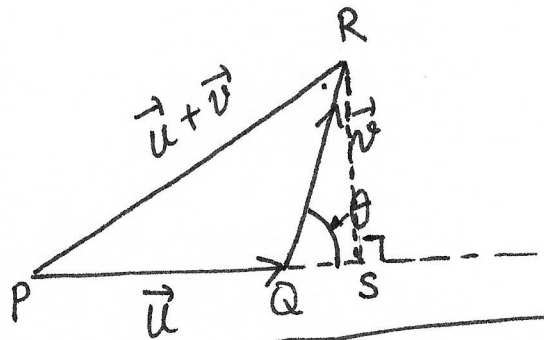
$$+ 2 \|\vec{u}\| \|\vec{v}\| \cos(\theta)$$

$$= \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2 \|\vec{u}\| \|\vec{v}\| \cos(\theta)$$

$$= \|\vec{u}\|^2 + \|\vec{v}\|^2 + 2 \vec{u} \cdot \vec{v} \quad (\text{from last page})$$

Hence $\boxed{\vec{u} \cdot \vec{v} = \|\vec{u}\| \|\vec{v}\| \cos(\theta)}$

□



$$|RS| = |RQ| \sin \theta$$

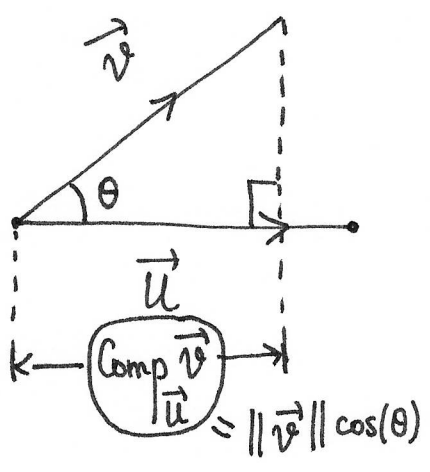
$$|QS| = |RQ| \cos \theta$$

(10.4) Orthogonal ~~projection~~ vectors and projection.

We say two vectors \vec{u} and \vec{v} are orthogonal (or perpendicular), denoted by $\vec{u} \perp \vec{v}$, if

$$\boxed{\vec{u} \cdot \vec{v} = 0}$$

In physical problems, we sometimes have to compute "Component of \vec{v} along \vec{u} ", or "projection of \vec{v} onto \vec{u} "



Component of \vec{v} along \vec{u}
 $= \text{Comp}_{\vec{u}} \vec{v} = \|\vec{v}\| \cos(\theta)$
 $= \|\vec{v}\| \left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} \right)$

$$\text{Comp}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|}$$

Projection of \vec{v} onto $\vec{u} = \left(\text{Component of } \vec{v} \text{ along } \vec{u} \right) \cdot \left(\text{Unit vector along } \vec{u} \right)$

$$\text{Proj}_{\vec{u}} \vec{v} = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|} \left(\frac{1}{\|\vec{u}\|} \vec{u} \right)$$

$$\text{Proj}_{\vec{u}} \vec{v} = \left(\frac{\vec{u} \cdot \vec{v}}{\vec{u} \cdot \vec{u}} \right) \vec{u}$$

(10.5) Examples. (i) Show that $\vec{u} = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$ and $\begin{bmatrix} -2 \\ 3 \\ 1 \end{bmatrix} = \vec{v}$ are orthogonal to each other. (Soln: $\vec{u} \cdot \vec{v} = 1(-2) + 0(3) + 2(1) = 0$. $\Rightarrow \vec{u} \perp \vec{v}$.)

(ii) Find the angle between $\vec{u} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$ & $\vec{v} = \begin{bmatrix} 2 \\ -1 \\ 2 \end{bmatrix}$

$$\cos(\theta) = \frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\| \|\vec{v}\|} = \frac{1(2) + 1(-1) + 0(2)}{\sqrt{1^2 + 1^2 + 0^2} \sqrt{2^2 + (-1)^2 + 2^2}} = \frac{1}{3\sqrt{2}}$$

$$\theta = \cos^{-1}\left(\frac{1}{3\sqrt{2}}\right) (= 76.37^\circ \text{ or } 1.33 \text{ radians}).$$

(iii) Let $\vec{u} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $\vec{v} = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$.

Compute the projection of \vec{v} onto \vec{u} .

$$\text{Proj}_{\vec{u}}(\vec{v}) = \left(\frac{\vec{u} \cdot \vec{v}}{\|\vec{u}\|^2} \right) \vec{u}$$

$$= \frac{1(3) + 1(5)}{1^2 + 1^2} \vec{u}$$

$$= \frac{8}{2} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 4 \end{bmatrix}$$

