

Lecture 4

①

(4.0) Recall that our main objective in this course is to study functions of a complex variable: $f: \Omega \rightarrow \mathbb{C}$, where $\Omega \subseteq \mathbb{C}$. We will always take Ω to be open and connected. Today's lecture contains definitions of these topological concepts.

(4.1) Notation for discs. Given $\alpha \in \mathbb{C}$ and $r \in \mathbb{R}_{>0}$, define

$$D(\alpha; r) = \{z \in \mathbb{C} : |z - \alpha| < r\} \text{ - (open) disc of radius } r, \text{ centered at } \alpha.$$

$$D^*(\alpha; r) = \{z \in \mathbb{C} : 0 < |z - \alpha| < r\} = D(\alpha; r) \setminus \{\alpha\}$$

(punctured disc of radius r , centered at α)

$$\bar{D}(\alpha; r) = \{z \in \mathbb{C} : |z - \alpha| \leq r\} \text{ - (closed) disc.}$$

(do not confuse \bar{D} with complex conjugation)

(4.2) Definition (1): A subset $U \subseteq \mathbb{C}$ is said to be open if for every $\alpha \in U$, there exists $r \in \mathbb{R}_{>0}$ such that $D(\alpha; r) \subset U$.

- In logical symbols: $\forall \alpha \in U, \exists r \in \mathbb{R}_{>0}$ s.t. $D(\alpha; r) \subset U$.
- $U = \emptyset$ empty set is considered to be open.

This definition signifies that any point in an open set U can be approached along an arbitrary direction, while still staying in U . This is a crucial



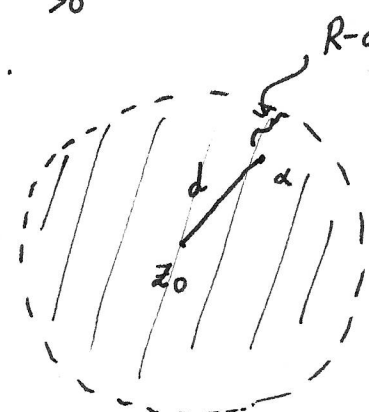
requirement for studying differentiability of a function defined on U .

(2)

Definition (2): A subset $A \subseteq \mathbb{C}$ is said to be closed if its complement is open (i.e. $A^c := \mathbb{C} - A$ is open).

(4.3) Examples. (1) Let $z_0 \in \mathbb{C}$ and $R \in \mathbb{R}_{>0}$. Then $D(z_0; R)$ is open. To prove this, let $\alpha \in D(z_0; R)$.

Then $d = |z_0 - \alpha| < R$.



Choose r ; $0 < r < R - d$. We claim that $D(\alpha; r) \subset D(z_0; R)$.

Proof of the claim: if $\beta \in D(\alpha; r)$, then

$$|z_0 - \beta| = |z_0 - \alpha + \alpha - \beta| \leq |z_0 - \alpha| + |\alpha - \beta| < d + r < R.$$

Hence, $\beta \in D(z_0; R)$. □

(2) $\bar{D}(z_0; R)$ is closed. Since $\mathbb{C} - \bar{D}(z_0; R) = \{|z - z_0| > R\}$, we need to show that $|z - z_0| > R$ defines an open set.

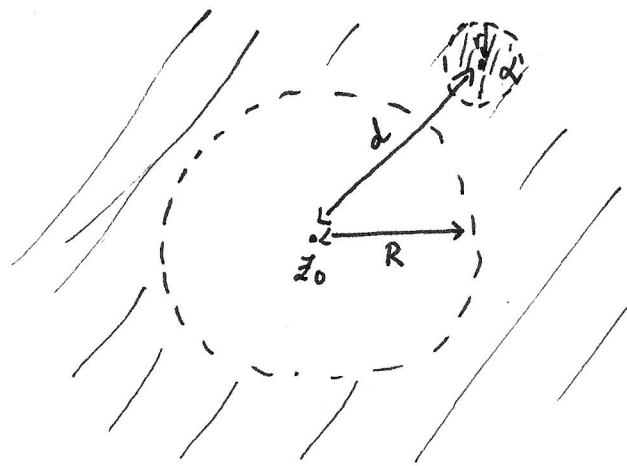
Proof. Let $\alpha \in \mathbb{C} - \bar{D}(z_0; R)$, i.e.

$$d = |z_0 - \alpha| > R.$$

Take $0 < r < d - R$. We have to show that $D(\alpha; r) \subset \mathbb{C} - \bar{D}(z_0; R)$,

that is

(To show) $|\alpha - \beta| < r \Rightarrow |z_0 - \beta| > R.$



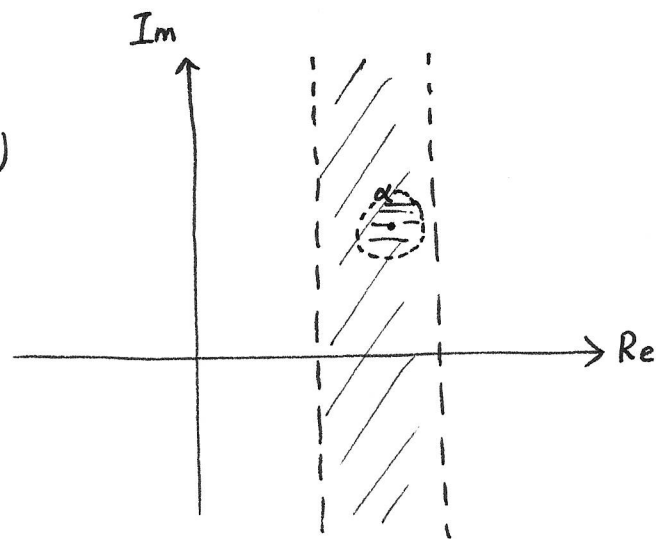
Complement of $\bar{D}(z_0; R)$

We can check this by contradiction. If $|z_0 - \beta| \leq R$, then

$$d = |z_0 - \alpha| \leq |z_0 - \beta| + |\beta - \alpha| < R + r < d. \text{ Contradiction. } \square$$

(3) $U = \{1 < \text{Re}(z) < 2\}$ is open.

Let $\alpha \in U$. If $\alpha \in \mathbb{R}$ $a = \text{Re}(\alpha)$
 then $1 < a < 2$. Take $r > 0$ to be
 smaller than $a-1$ and $2-a$.
 $0 < r < \text{Min}(a-1, 2-a)$.



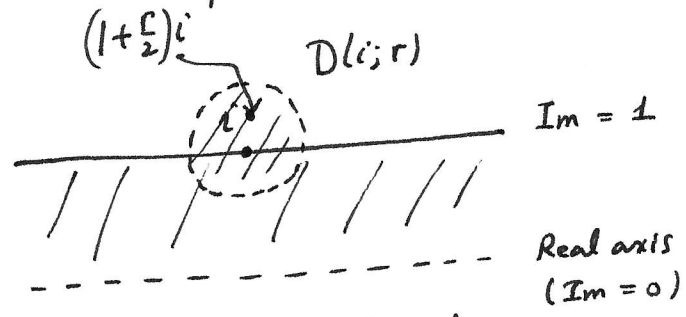
Check: $D(\alpha; r) \subset U$.

(4) $A = \{0 < \text{Im}(z) \leq 1\}$ is neither open, nor closed.

• A is not open.

Pick $\alpha \in \mathbb{C}$ on $\text{Im} = 1$ line,
 for example $\alpha = i$.

Claim: for every $r \in \mathbb{R}_{>0}$, $D(\alpha; r) \not\subset A$.



Proof. Let $r \in \mathbb{R}_{>0}$. Then $(1 + \frac{r}{2})i \in D(i; r)$ but not in A . \square

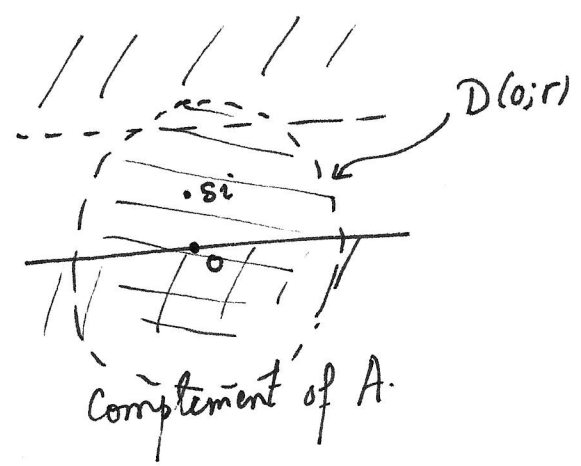
• A is not closed. That is, we need to show

$$A^c = \{z \in \mathbb{C} : \text{Im}(z) \leq 0 \text{ or } \text{Im}(z) > 1\} \text{ is not open}$$

So, pick α on the real line, say $\alpha = 0$.
 Let $r > 0$. As before we must produce an
 element of $D(0; r)$ not in A .

Take $0 < s < \text{Min}(r, 1)$.

Then $si \in D(0; r)$, $si \notin A$. \square



(5) ϕ and \mathbb{C} are both open and closed.

(4.4) Proposition. (i) Let $\{U_j\}_{j \in J}$ be a set of open subsets of \mathbb{C} (J is just an indexing set). Then $U = \bigcup_{j \in J} U_j$ is again open.

[In words: (arbitrary) union of open sets is open.]

(ii) Let U_1, U_2, \dots, U_n be a finite collection of open subsets of \mathbb{C} . ($n \in \mathbb{Z}; n \geq 1$). Then $U = \bigcap_{j=1}^n U_j$ is open.

[In words: finite intersection of open sets is open.]

(Taking complements we get - (i) Arbitrary intersection of closed sets is closed; (ii) finite union of closed sets is closed.)

Proof. (i) If $U = \phi$ (i.e. each $U_j = \phi$) there is nothing to prove.

Otherwise, let $\alpha \in U$. That means there exists a $j_0 \in J$ such that $\alpha \in U_{j_0}$. As U_{j_0} is open, there exists $r > 0$ such that $D(\alpha; r) \subset U_{j_0}$.

Hence, $D(\alpha; r) \subset \bigcup_{j \in J} U_j = U$, proving that U is open.

(ii) Again it is enough to consider the case when $\bigcap_{j=1}^n U_j \neq \phi$.

Let $\alpha \in U = \bigcap_{j=1}^n U_j$. That is, $\alpha \in U_j$ for each $j = 1, \dots, n$.

\Rightarrow there exists $r_j \in \mathbb{R}_{>0}$ s.t. $D(\alpha; r_j) \subset U_j$ ($j = 1, \dots, n$).

Take $r = \text{Min}\{r_1, \dots, r_n\}$. Then $D(\alpha; r) \subset D(\alpha; r_j) \subset U_j \forall j = 1, \dots, n$

$\Rightarrow D(\alpha; r) \subset \bigcap_{j=1}^n U_j = U$. Hence, U is open. \square

(4.5) Remark* - The abstract definition of a "topological space" is modeled on the property established above. Namely, a topological space is a set X, together with a set of subsets of X, $\mathcal{C} \subset 2^X$ (= set of all subsets of X), such that (0) $\phi \in \mathcal{C}$; $X \in \mathcal{C}$.

(1) If $\{U_j \in \mathcal{C}\}_{j \in J}$ then $\bigcup_{j \in J} U_j \in \mathcal{C}$.

(2) If $U_1, \dots, U_n \in \mathcal{C}$, then $\bigcap_{j=1}^n U_j \in \mathcal{C}$.

(4.6) For $z_0 \in \mathbb{C}$, the singleton $A = \{z_0\} \subset \mathbb{C}$ is a closed set.

Using the finite union property of closed sets, any finite subset $A \subset \mathbb{C}$, $|A| < \infty$ is closed.

Arbitrary intersections of open sets need not be open. For example,

let $U_n = D(0; \frac{1}{n}) =$ (open) disc of radius $\frac{1}{n}$ centered at 0 ($n \geq 1$).

Then $\bigcap_{n=1}^{\infty} U_n = \{0\}$ is not open.

(4.7) Definition. - A subset $A \subseteq \mathbb{C}$ is said to be path connected if for every $\alpha, \beta \in A$, there exists a continuous function

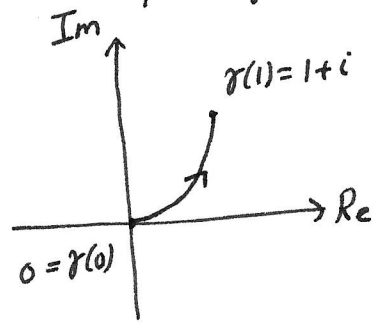
$$\gamma: [0, 1] \rightarrow A$$

such that $\gamma(0) = \alpha$ and $\gamma(1) = \beta$.

* Optional

• A continuous function $\gamma: [0,1] \rightarrow \mathbb{C}$ is called a path (or a parametric curve) joining $\gamma(0)$ and $\gamma(1)$. Writing real and imaginary parts, $\gamma(t) = x(t) + y(t)i$, and continuity refers to both $x(t)$ and $y(t)$ being continuous.

e.g. • $\gamma(t) = t + t^2 i$ ($0 \leq t \leq 1$) is part of the parabola $y = x^2$ joining 0 to $1+i$.



• $\gamma(t) = e^{it}$ ($0 \leq t \leq 2\pi$) is the unit circle $|z|=1$ traversed counterclockwise going 1 to itself

(4.8) Formal definition of continuity of $\gamma: [0,1] \rightarrow \mathbb{C}$. - γ is said to be continuous at $t_0 \in [0,1]$ if for every $\epsilon > 0$, we can find $\delta > 0$ such that

$$\begin{aligned} t \in [0,1] \\ |t - t_0| < \delta \end{aligned} \text{ implies } |\gamma(t) - \gamma(t_0)| < \epsilon.$$

γ is continuous if it is continuous at every $t_0 \in [0,1]$.

Remark. - Using the inequalities (for $\gamma(t) = x(t) + y(t)i$):
 $|\gamma(t) - \gamma(t_0)| = |(x(t) - x(t_0)) + (y(t) - y(t_0))i| \leq |x(t) - x(t_0)| + |y(t) - y(t_0)|$
 and $|x(t) - x(t_0)|, |y(t) - y(t_0)| \leq \sqrt{(x(t) - x(t_0))^2 + (y(t) - y(t_0))^2}$
 one can easily show that γ is continuous $\iff x(t)$ and $y(t)$ are.

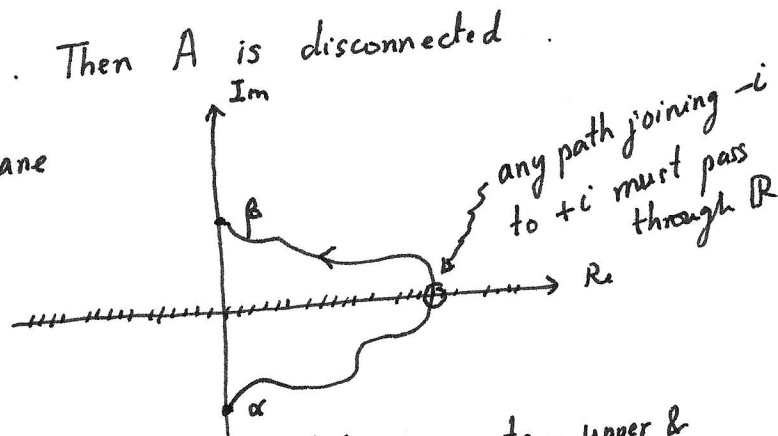
Remark. - The definition of continuity of $\gamma: [0,1] \rightarrow \mathbb{C}$ is equivalent

to
$$\lim_{t \rightarrow t_0} \gamma(t) = \gamma(t_0) \quad [\text{review the definition of limit}].$$

$$(0 \leq t \leq 1)$$

(4.9) Example. Let $A = \mathbb{C} - \mathbb{R}$. Then A is disconnected.

Proof. - Pick α in the lower half plane
(i.e. $\text{Im}(\alpha) < 0$)
and β in the upper half plane
(i.e. $\text{Im}(\beta) > 0$)



e.g. $\alpha = -i$, $\beta = i$.

(A has 2 connected components - upper & lower half planes)

Claim. There is no continuous $\gamma: [0,1] \rightarrow A$ s.t. $\gamma(0) = -i$
 $\gamma(1) = +i$.

Proof of the claim: Assume $\gamma: [0,1] \rightarrow \mathbb{C}$ is any path joining $-i$ to i .
Then $y(t) = \text{Im}(\gamma(t))$ is a continuous function $[0,1] \rightarrow \mathbb{R}$ with
 $y(0) = -1$ and $y(1) = +1$. By intermediate value theorem, there must
exist $t_0 \in (0,1)$ s.t. $y(t_0) = 0$. That is, $\gamma(t_0) \in \mathbb{R}$. \square

(4.10) More examples of connected (via paths) subsets.

\mathbb{C} , $\mathbb{C} - \{0\}$, $\mathbb{C} - \mathbb{R}_{\leq 0}$, \mathbb{R} , $D(z_0; R)$,
 $D^x(z_0; R)$, $\overline{D}(z_0; R)$, $\mathbb{C} - D(z_0; R)$ [here $z_0 \in \mathbb{C}$ & $R \in \mathbb{R}_{>0}$].
are all connected (via paths).

A subset $S \subset \mathbb{C}$ ($S \neq \emptyset$) is called convex if for any $\alpha, \beta \in S$,
the line segment joining α & β is in S . That is $t\alpha + (1-t)\beta \in S$
for every $0 \leq t \leq 1$. Every convex subset of \mathbb{C} is clearly (path) connected.

(4.11) Remark* - There is a more general notion of "connectedness" (8)

from topology (path-connected as defined in (4.7) above implies connected, but converse is not true, in general). For the sake of mentioning it - here is the general definition. A subset $A \subset \mathbb{C}$ is said to be disconnected if there exist two open sets $U_1, U_2 \subset \mathbb{C}$ such that (i) $U_1 \cap U_2 = \emptyset$, (ii) $A \cap U_1 \neq \emptyset$, $A \cap U_2 \neq \emptyset$ and (iii) $A \subset U_1 \cup U_2$. (e.g. in the example of (4.9), take $U_1 = \{Im(z) > 0\}$ and $U_2 = \{Im(z) < 0\}$). A is connected if it is not disconnected.

For our purposes, the restrictive notion of path-connectedness will suffice. In fact, it is known that for open sets in \mathbb{C} , the two notions are equivalent.

(4.12) Example. Let $\gamma: [0,1] \rightarrow \mathbb{C}$ be a path in \mathbb{C} . Then its image $C = \{\gamma(t) : 0 \leq t \leq 1\} \subset \mathbb{C}$ is closed.

Proof. Let $z_0 \in \mathbb{C}$ be a point not on C .

Define $D(t) = |\gamma(t) - z_0|^2 \in \mathbb{R}_{>0}$.

Then $D(t)$ is a continuous function $[0,1] \xrightarrow{D} \mathbb{R}_{>0}$

(if $z_0 = x_0 + y_0 i$, $\gamma(t) = x(t) + y(t) i$; then $D(t) = (x(t) - x_0)^2 + (y(t) - y_0)^2$ is continuous - since $x(t)$ & $y(t)$ are).

By extreme value theorem, D attains its absolute min. for some $t_0 \in [0,1]$ say, $D(t_0) = d^2 > 0$ (since $\gamma(t_0) \neq z_0$). Choose $0 < r < d$ and check that

$D(z_0; r) \subset \mathbb{C} \setminus C$. □



*Optional