

(11.0) Definition of line integrals. Let $\Omega \subset \mathbb{C}$ be an open set,

$\gamma: [a, b] \rightarrow \Omega$ a path. We will assume that γ is piecewise smooth meaning there exist $c_1, c_2, \dots, c_n \in (a, b)$;

$$c_0 = a < c_1 < c_2 < \dots < c_n < b = c_{n+1}$$

such that $\gamma'(t)$ exists and is continuous $\forall t \in (c_j, c_{j+1})$; $j=0, 1, \dots, n$.

For a continuous function $f: \Omega \rightarrow \mathbb{C}$ define

$$\int_{\gamma} f(z) dz := \int_a^b f(\gamma(t)) \gamma'(t) dt \quad - \text{for smooth } \gamma.$$

For piecewise smooth γ ; $\int_{\gamma} f(z) dz = \sum_{j=0}^n \int_{c_j}^{c_{j+1}} f(\gamma(t)) \gamma'(t) dt$; where

$c_0 = a < c_1 < \dots < c_n < b = c_{n+1}$ are as above.

(11.1) Real and imaginary parts. - If $f = u + iv$ and $\gamma(t) = x(t) + y(t)i$

$$\text{then } \int_{\gamma} f(z) dz = \int_a^b \left(u(x(t), y(t)) + i v(x(t), y(t)) \right) \left(x'(t) + i y'(t) \right) dt$$

$$\Rightarrow \operatorname{Re} \int_{\gamma} f(z) dz = \int_a^b \left(u(x(t), y(t)) \cdot x'(t) - v(x(t), y(t)) \cdot y'(t) \right) dt$$

$$\operatorname{Im} \int_{\gamma} f(z) dz = \int_a^b \left(u(x(t), y(t)) \cdot y'(t) + v(x(t), y(t)) \cdot x'(t) \right) dt$$

(11.2) Properties of $\int_{\gamma} f(z) dz$. $\left[\begin{array}{l} \Omega \subset \mathbb{C} \\ \text{open} \end{array} ; f: \Omega \rightarrow \mathbb{C} \text{ continuous} \right]$ (2)

(1) Independence from parametrization. If $\gamma: [a, b] \rightarrow \Omega$ is a piecewise smooth path and $\tau: [c, d] \rightarrow [a, b]$ is differentiable on (c, d) with continuous derivative, we can consider $\mu: [c, d] \rightarrow \Omega$ given by $\mu(t) = \gamma(\tau(t))$.

Then $\int_{\mu} f(z) dz = \int_{\gamma} f(z) dz$ (we are assuming $\tau(c) = a$ and $\tau(d) = b$)

Proof. $\int_{\mu} f(z) dz = \int_c^d f(\mu(t)) \mu'(t) dt = \int_c^d f(\gamma(\tau(t))) \gamma'(\tau(t)) \tau'(t) dt$

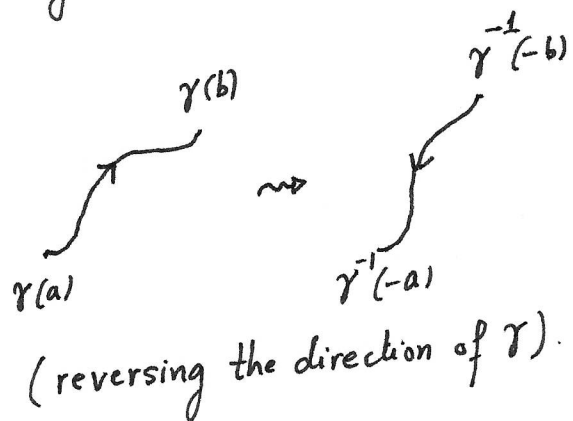
Set $\tau(t) = s$ to get $\int_{\tau(c)=a}^{\tau(d)=b} f(\gamma(s)) \gamma'(s) ds = \int_{\gamma} f(z) dz$ \square

(2) Note: $\int_{\gamma} f(z) dz$ depends on the direction of γ . If $\gamma: [a, b] \rightarrow \Omega$

we can define $\gamma^{-1}: [-b, -a] \rightarrow \Omega$ by $\gamma^{-1}(s) = \gamma(-s)$ ($-b \leq s \leq -a$)
(opposite or inverse of γ)

Then

$$\int_{\gamma^{-1}} f(z) dz = - \int_{\gamma} f(z) dz$$



(3) Let $f_1, f_2: \Omega \rightarrow \mathbb{C}$ be two continuous functions; $\alpha_1, \alpha_2 \in \mathbb{C}$.

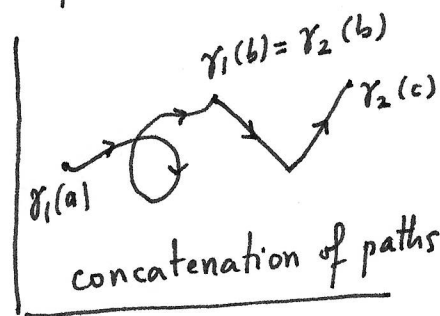
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Then
$$\int_{\gamma} (\alpha_1 f_1(z) + \alpha_2 f_2(z)) dz = \alpha_1 \int_{\gamma} f_1(z) dz + \alpha_2 \int_{\gamma} f_2(z) dz.$$

(4) Concatenation of paths. - Let $\gamma_1: [a, b] \rightarrow \Omega$ and $\gamma_2: [b, c] \rightarrow \Omega$ be two (piecewise smooth) paths. Define $\gamma = \gamma_1 \cdot \gamma_2: [a, c] \rightarrow \Omega$

$$\gamma(t) = \begin{cases} \gamma_1(t); & a \leq t \leq b \\ \gamma_2(t); & b \leq t \leq c \end{cases} \quad \text{— concatenation of } \gamma_1 \text{ and } \gamma_2.$$

Then
$$\int_{\gamma = \gamma_1 \cdot \gamma_2} f(z) dz = \int_{\gamma_1} f(z) dz + \int_{\gamma_2} f(z) dz$$



(5) Assume that there exists a \mathbb{C} -differentiable $F: \Omega \rightarrow \mathbb{C}$ such that $F'(z) = f(z)$ for every $z \in \Omega$. In this case, we say that f admits an antiderivative or primitive on Ω . Then

$$\int_{\gamma} f(z) dz = F(\gamma(b)) - F(\gamma(a)). \quad \text{In particular, this}$$

integral only depends on the endpoints of γ and not on the path connecting them. This is analogous to the fundamental theorem of calculus.

Proof Let $f = u + iv: \Omega \rightarrow \mathbb{C}$, $F = U + iV: \Omega \rightarrow \mathbb{C}$
(continuous) (\mathbb{C} -differentiable)

and $F' = f$; meaning
$$\begin{aligned} u &= U_x = V_y \\ v &= -U_y = V_x \end{aligned} \quad \left(\begin{array}{l} \text{Cauchy-Riemann} \\ \text{eqns for } F \end{array} \right)$$

(4)

By (11.1) above, $\operatorname{Re} \int_{\gamma} f(z) dz = \int_a^b (u(x(t), y(t)) x'(t) - v(x(t), y(t)) y'(t)) dt$

$$= \int_a^b (U_x(x(t), y(t)) x'(t) + U_y(x(t), y(t)) y'(t)) dt$$

$$= \int_a^b \frac{d}{dt} (U(x(t), y(t))) dt = U(x(b), y(b)) - U(x(a), y(a))$$

(by the fundamental Thm. of Calculus)

Similarly $\operatorname{Im} \int_{\gamma} f(z) dz = V(x(b), y(b)) - V(x(a), y(a)) \quad \square$

(11.3) Example I. Let $f(x+iy) = x$ (i.e. $f(z) = \operatorname{Re}(z)$).

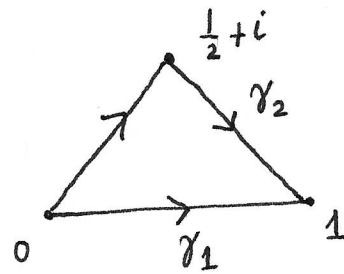
Consider two paths joining 0 to 1:

$$\gamma_1(t) = t \quad (0 \leq t \leq 1)$$

$$\gamma_2(t) = \begin{cases} t + 2ti; & 0 \leq t \leq \frac{1}{2} \\ t + 2(1-t)i; & \frac{1}{2} \leq t \leq 1 \end{cases}$$

$$\int_{\gamma_1} f(z) dz = \int_0^1 f(t) \cdot \overset{\gamma_1'(t)}{1} dt$$

$$= \int_0^1 t dt = \left[\frac{t^2}{2} \right]_0^1 = \frac{1}{2}$$



$$\int_{\gamma_2} f(z) dz = \int_0^{1/2} f(t+2ti) \cdot \underset{\gamma_2'(t)}{(1+2i)} dt + \int_{1/2}^1 f(t+(2-2t)i) \cdot \underset{\gamma_2'(t)}{(1-2i)} dt$$

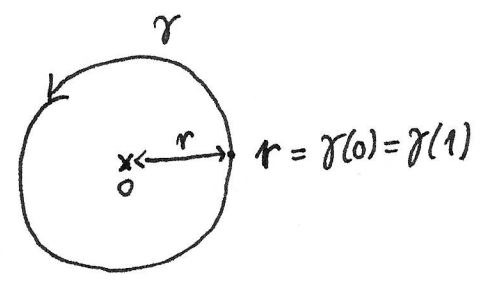
$$= (1+2i) \int_0^{1/2} t dt + (1-2i) \int_{1/2}^1 t dt = (1+2i) \frac{1}{8} + (1-2i) \frac{3}{8}$$

$$= \frac{1}{2} - \frac{1}{2}i$$

This example illustrates that $\int_{\gamma} f(z) dz$ is not always independent of the path joining $\gamma(a)$ to $\gamma(b)$. As we will see later, the problem with $f(z) = \text{Re}(z)$ is that it is not \mathbb{C} -differentiable.

(11.4) Example II. $f(z) = \frac{1}{z} : \Omega \rightarrow \mathbb{C}$ (here $\Omega = \mathbb{C} - \{0\}$).

Let γ be counterclockwise oriented circle of radius $r > 0$, centered at 0. $\gamma(t) = r \cdot e^{it}$ ($0 \leq t \leq 2\pi$)



$$\int_{\gamma} f(z) dz = \int_0^{2\pi} \underbrace{\frac{1}{r \cdot e^{it}}}_{f(\gamma(t))} \cdot \underbrace{r \cdot i \cdot e^{it}}_{\gamma'(t)} dt$$

$$= i \int_0^{2\pi} dt = 2\pi i.$$

If $\mu : [0, 1] \rightarrow \Omega$ is the constant path connecting r to itself ($\mu(t) = r \forall 0 \leq t \leq 1$), then $\int_{\mu} f(z) dz = 0$ (simply because $\mu'(t) = 0$)

Here, again, we see that $\int_{\gamma} f(z) dz \neq \int_{\mu} f(z) dz$ (the answer depends on the path joining r to itself)

though $f(z) = \frac{1}{z}$ is \mathbb{C} -differentiable.

The problem here is that the region enclosed by γ , $D(0; r)$, is not in the domain of f ($D(0; r) \not\subset \Omega = \mathbb{C} - \{0\}$).

(11.5) Example III. $f(z) = z^3 : \Omega \rightarrow \mathbb{C}$ ($\Omega = \mathbb{C}$). (6)

Let γ be any path joining 1 to $2+i$. Then (by property (5).

- page 3 above)

$$\int_{\gamma} f(z) dz = \left[\frac{z^4}{4} \right]_1^{2+i} = \frac{(2+i)^4 - 1}{4} = \frac{-8 + 24i}{4} = -2 + 6i.$$

(11.6) Theorem*. Let $\Omega \subset \mathbb{C}$ be an open and connected set, $f: \Omega \rightarrow \mathbb{C}$ be a continuous function. Then the following conditions are equivalent.

(1) f admits an antiderivative.

(2) $\int_{\gamma} f(z) dz$ depends only on the endpoints of γ - for every piecewise smooth path γ in Ω .

(3) $\int_{\gamma} f(z) dz$ depends only on the endpoints of γ - for every zig-zag path γ in Ω .

Proof. (1) \Rightarrow (2) by Property (5) on page 3 above.

(2) \Rightarrow (3) is clear since a zig-zag path is piecewise smooth.

(3) \Rightarrow (1). The idea of the proof is exactly the same as for functions of a real variable. Namely given $g(x)$ we find its primitive by

fixing a point x_0 on the real line and $G(x) := \int_{x_0}^x g(t) dt$. While over \mathbb{R} there is only one way to go from x_0 to x ; over \mathbb{C} - there are many paths

* This result is often attributed to Giacinto Morera (18/7/1856 - 8/2/1907)

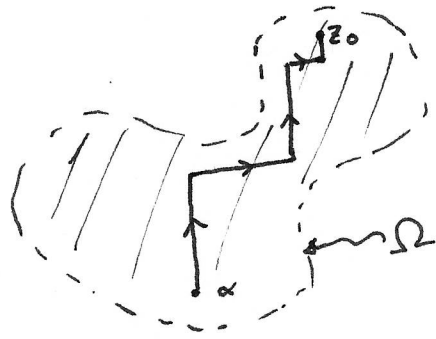
joining two given points - and we need to make the assumption as in (3) to remove the dependence on the path chosen. (7)

So, choose $\alpha \in \Omega$, and define $F: \Omega \rightarrow \mathbb{C}$ by ($z_0 \in \Omega$)

$$F(z_0) := \int_{\gamma} f(z) dz \quad ; \quad \gamma \text{ is any zig-zag path joining } \alpha \text{ to } z_0.$$

Such path exists since Ω is open & connected (see Prop. 6.5 - Lecture 6).

The definition of $F(z_0)$ is independent of the choice of γ (i.e. F is well-defined) by our assumption (3).



We have to prove that F is \mathbb{C} -differentiable, and $F' = f$. For this, it is enough to prove (by Thm 9.1 - Lecture 9 - applied to F):

$$\left[\begin{array}{l} F = U + iV \\ f = u + iv \end{array} \text{ below} \right]$$

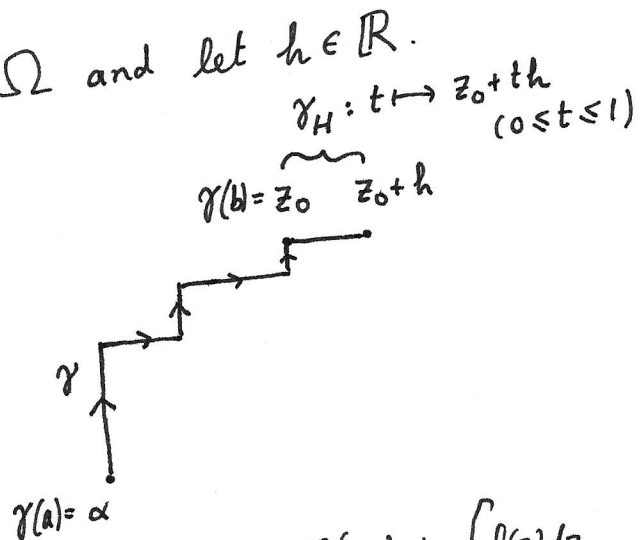
$$(i) \quad U_x = V_y = u \quad (ii) \quad -U_y = V_x = v$$

(since u & v are assumed to be continuous - the hypotheses of Thm 9.1 for U and V will hold - once (i) & (ii) are proved).

Proof of $U_x = u$ & $V_x = v$. Let $z_0 \in \Omega$ and let $h \in \mathbb{R}$.

Let γ be a zig-zag path joining α to z_0 .

$\gamma_H(t) = z_0 + th$ horizontal segment joining z_0 to $z_0 + h$ ($0 \leq t \leq 1$)



$$\text{Then } F(z_0 + h) = \int_{\gamma \cdot \gamma_H} f(z) dz = \int_{\gamma} f(z) dz + \int_{\gamma_H} f(z) dz = F(z_0) + \int_{\gamma_H} f(z) dz$$

$$\Rightarrow F(z_0+h) - F(z_0) = \int_{\gamma_H} f(z) dz = \int_0^1 f(z_0+th) \cdot \underbrace{h}_{\gamma_H'(t)} dt$$

$$\Rightarrow \frac{F(z_0+h) - F(z_0)}{h} = \int_0^1 f(z_0+th) dt.$$

Claim: $\lim_{h \rightarrow 0} \int_0^1 f(z_0+th) dt = f(z_0)$. This claim proves that

$$\lim_{\substack{h \rightarrow 0 \\ (h \in \mathbb{R})}} \frac{F(z_0+h) - F(z_0)}{h} = U_x(x_0, y_0) + i V_x(x_0, y_0) \text{ exists, and } \begin{cases} U_x(x_0, y_0) = u(x_0, y_0) \\ V_x(x_0, y_0) = v(x_0, y_0). \end{cases}$$

The proof of $-U_y(x_0, y_0) = v$ & $V_y(x_0, y_0) = u$ is similar (replace γ_H (horizontal) by γ_V (vertical)) and is left as an easy check.

Proof of the claim: Let $\epsilon > 0$ be given. We need to find $\delta > 0$ such that $|h| < \delta \Rightarrow \left| \int_0^1 f(z_0+th) dt - f(z_0) \right| < \epsilon$.

Since f is continuous, there is $\delta > 0$ so that $|f(z) - f(z_0)| < \epsilon$ for every z s.t. $|z - z_0| < \delta$.

This δ works for us:

$$\begin{aligned} \text{for } |h| < \delta, \text{ we get } & \left| \int_0^1 f(z_0+th) dt - f(z_0) \right| = \left| \int_0^1 (f(z_0+th) - f(z_0)) dt \right| \\ & \leq \int_0^1 |f(z_0+th) - f(z_0)| dt \quad (\text{triangle inequality}) \\ & < \int_0^1 \epsilon \cdot dt = \epsilon. \quad \left(\begin{array}{l} \text{since } |h| < \delta \text{ and } 0 \leq t \leq 1 \\ \Rightarrow |th| < \delta \end{array} \right) \quad \square \end{aligned}$$