

LECTURE 41

I. Simultaneous Diagonalization of Two Quadratic Forms

A. General Coupled System

B. Normal Modes

C. Eigenvalue Problem

- (1) Eigenvalue equation
- (2) Eigenvectors
- (3) B-orthonormality

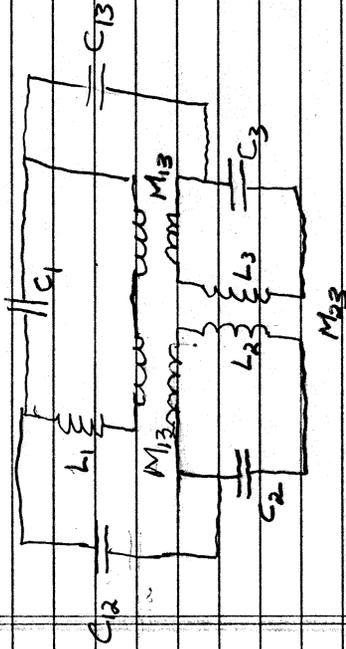
D. Change of Variables for
Diagonalization.

41.1

I. SIMULTANEOUS DIAGONALIZATION OF TWO QUADRATIC FORMS.

A) General Coupled System:
Consider the equation of motion for

the following system of inductively coupled networks



The equations of motion for this system are

$$\begin{bmatrix} L_1 & M_{12} & M_{13} \\ M_{12} & L_2 & M_{23} \\ M_{13} & M_{23} & L_3 \end{bmatrix} \frac{d^2}{dt^2} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} + \begin{bmatrix} \frac{1}{C_1} & 0 & 0 \\ 0 & \frac{1}{C_2} & 0 \\ 0 & 0 & \frac{1}{C_3} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = 0$$

Here $\{L_{ij}\}$ are the self-inductances

$\{M_{ij} = M_{ji}\}$ are the mutual inductances

41.2

$\{C_{ij}\}$ are capacitances

$\{C_{ij} = C_{ji}\}$ are mutual capacitances.

$\{I_i\}$ are the currents.

More generally, we consider the

following generalization of Eq. (4) on P. 320

$$B \ddot{q} + A q = 0.$$

Here $A^T = A$,

$$B^T = B,$$

A vectors q .

that is B is a positive definite matrix.

Normal Modes

The key to understanding the dynamics

of this time-invariant linear

system is by means of its normal

modes

$$q(t) = f(t) x$$

41.3

Each one satisfies

$$\ddot{f} B x = -A x$$

independent $\Rightarrow \ddot{f} = \text{const} = -\lambda$
of time

Thus one has

a) $\ddot{f} + \lambda f = 0$

b) $A x = \lambda B x$

c) Eigenvalue Problem

(1) The eigen value equation

$$(A - \lambda B) x = 0$$

has non-trivial solutions only for

those values of λ which are the roots

$$\lambda = \lambda_1, \lambda_2, \dots, \lambda_n$$

of the secular polynomial

$$\det |A - \lambda B| = 0$$

41.4

(2) The corresponding eigen vectors are

the elements of the nullspaces

$$N(A - \lambda_i B) \quad i = 1, 2, \dots, n$$

They satisfy

$$A \vec{x}_i = \lambda_i B \vec{x}_i \quad i = 1, 2, \dots, n$$

Question: Are the vectors \vec{x}_i and \vec{x}_j

orthogonal

$$\langle \vec{x}_i, \vec{x}_j \rangle = 0$$

when $\lambda_i \neq \lambda_j$?

Answer: NO; in general $x_i^H x_j \neq 0$

However, let us introduce the

Definition:

$$\langle \vec{x}, \vec{y} \rangle_B = x^H B y,$$

is an inner product, the B-inner product,

whenever B is positive definite,

i.e. $B^H = B$ and $X^H B X > 0 \quad \forall x \neq 0$

(3) B-orthonormality
 Consider two different eigen values

$\lambda_i \neq \lambda_j$ of the eigenvalue equation

$$A X = \lambda B X$$

One has the following

Theorem

Let $A x_i = \lambda_i B x_i$ and $A x_j = \lambda_j B x_j$ and $\lambda_i \neq \lambda_j$

Then $x_j^H B x_i = 0$ whenever $\lambda_i \neq \lambda_j$.

Proof:

Following Properties 1 and 2 on page 356

one has

- $x^H A x$ is real
- $x^H B x$ is real and positive

2. $A X = \lambda B X$ has real eigenvalues.

Indeed, using item 1. above, one

finds $x^H A x = \lambda x^H B x \Rightarrow \lambda$ is real

$$3. \quad x_j^H A x_i = \lambda_i x_j^H B x_i; \quad x_i^H A x_j = \lambda_j x_i^H B x_j \quad (*)$$

$$(A^H x_j)^H x_i = \lambda_i x_j^H B x_i$$

$$(A x_j)^H x_i = "$$

$$x_i^H A x_j = \lambda_i x_j^H B x_i$$

$$= \lambda_i (B^H x_j)^H x_i$$

$$= \lambda_i x_i^H B x_j$$

$$x_i^H A x_j = \lambda_i x_i^H B x_j \quad (**)$$

Subtract Eq. (***) from Eq. (*) above and

obtain

$$0 = \underbrace{(\lambda_j - \lambda_i)}_{\neq 0} x_i^H B x_j$$

$$x_i^H B x_j = \langle x_i, x_j \rangle_B$$

i.e. x_i and x_j are B-orthogonal.

Using B-normalization, one obtains

$$x_i^H B x_j = \delta_{ij}$$

i.e. $\{x_i\}$ form a B-orthonormal eigenbasis

LECTURE 41

I. Simultaneous Diagonalization of Two Quadratic Forms

A. General Coupled System

B. Normal Modes

C. Eigenvalue Problem

(1) Eigenvalue equation

(2) Eigenvectors

(3) B-orthonormality

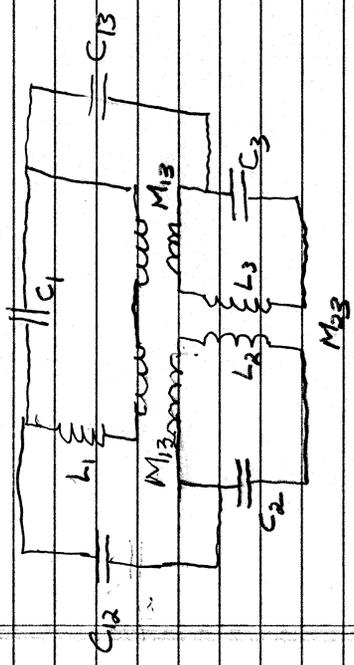
D. Solution to the Eigenvalue Problem:
Its Matrix Formulation

E. Geometrization via Concentric
Ellipses.

I. SIMULTANEOUS DIAGONALIZATION OF TWO QUADRATIC FORMS.

A) General Coupled System:
Consider the equation of motion for

the following system of inductively coupled networks



The equations of motion for this system are

$$\begin{bmatrix} L_1 & M_{12} & M_{13} \\ M_{12} & L_2 & M_{23} \\ M_{13} & M_{23} & L_3 \end{bmatrix} \frac{d^2}{dt^2} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} + \begin{bmatrix} \frac{1}{C_1} & 0 & 0 \\ 0 & \frac{1}{C_2} & 0 \\ 0 & 0 & \frac{1}{C_3} \end{bmatrix} \begin{bmatrix} I_1 \\ I_2 \\ I_3 \end{bmatrix} = 0$$

Here $\{L_i\}$ are the self-inductances

$\{M_{ij} = M_{ji}\}$ are the mutual inductances

$\{C_{ij}\}$ are capacitances

$\{C_{ij} = C_{ji}\}$ are mutual capacitances.

$\{I_i\}$ are the currents.

More generally, we consider the

following generalization of Eq. (6) on p. 32.9

$$B \ddot{q} + A q = 0.$$

Here $A^T = A,$

$$B^T = B,$$

$q^T B q > 0,$ \forall vectors $q.$

That is B is a positive definite matrix.

B) Normal Modes

The key to understanding the dynamics

of this time-invariant linear

system is by means of its normal

modes

$$q(t) = f(t) \times$$

41.3

Each one satisfies

$$\ddot{\mathbf{f}} + B\mathbf{x} = -A\mathbf{x}$$

independent $\Rightarrow \ddot{\mathbf{f}} = \text{const} = -\lambda \mathbf{f}$
of time

Thus one has

$$a) \ddot{\mathbf{f}} + \lambda \mathbf{f} = 0$$

$$b) A\mathbf{x} = \lambda B\mathbf{x}$$

c) Eigenvalue Problem

(i) The eigen value equation

$$(A - \lambda B)\mathbf{x} = 0$$

has non-trivial solutions only for

those values of λ which are the roots

$$\lambda = \lambda_1, \dots, \lambda_n$$

of the secular polynomial

$$\det |A - \lambda B| = 0$$

41.4

(a) The corresponding eigenvectors are

the elements of the nullspaces

$$\mathcal{N}(A - \lambda_i B) \quad i = 1, 2, \dots, n$$

They satisfy

$$A\vec{x}_i = \lambda_i B\vec{x}_i \quad i = 1, 2, \dots, n$$

Question: Are the vectors \vec{x}_i and \vec{x}_j

orthogonal,

$$\langle \vec{x}_i, \vec{x}_j \rangle = 0$$

when $\lambda_i \neq \lambda_j$?Answer: NO; in general $\vec{x}_i^H \vec{x}_j \neq 0$

However, let us introduce the

Definition:

$$\langle \vec{x}, \vec{y} \rangle_B = \vec{x}^H B \vec{y},$$

is an inner product, the B-inner product,

whenever B is positive definite,

4/5

i.e. $B^H = B$ and $X^H B X > 0 \quad \forall x \neq 0$

(3) B-orthonormality

Consider two different eigen values

$\lambda_i \neq \lambda_j$ of the eigenvalue equation

$$A X = \lambda B X$$

One has the following

Theorem

Let $A x_i = \lambda_i B x_i$ and $A x_j = \lambda_j B x_j$ and $\lambda_i \neq \lambda_j$

Then $x_j^H B x_i = 0$ whenever $\lambda_i \neq \lambda_j$.

Proof:

Following Properties 1 and 2 on page 356

one has

Step 1. $x^H A x$ is real

$x^H B x$ is real and positive

Step 2. $A X = \lambda B X$ has real eigenvalues.

Indeed, using item 1. above, one

finds $x^H A x = \lambda x^H B x \Rightarrow \lambda$ is real

4/6.

Step 3. $x_j^H A x_i = \lambda_i x_j^H B x_i$; $x_i^H A x_j = \lambda_j x_i^H B x_j$ (*)

$$(A^H x_j)^H x_i = \lambda_i x_j^H B x_i$$

$$(A x_j)^H x_i = "$$

$$x_i^H A x_j = \lambda_i x_j^H B x_i$$

$$= x_i^H (B^H x_j)^H x_i$$

$$= x_i^H x_i^H B x_j$$

$$x_i^H A x_j = \lambda_i x_i^H B x_j \quad (**)$$

Subtract Eq. (***) from Eq. (*) above and

obtain

$$0 = (\lambda_j - \lambda_i) x_i^H B x_j$$

∴

$$x_i^H B x_j = \langle x_i, x_j \rangle_B$$

i.e. x_i and x_j are B-orthogonal.

Using B-normalization, one obtains

$$x_i^H B x_j = \delta_{ij}$$

i.e. $\{x_i\}$ form a B-orthonormal eigenbasis

41.7

Solution to the Eigenvalue Problem:
Its Matrix Formulation

The B-orthonormal eigenvectors

x_i of the eigenvalue problem

$$Ax = \lambda Bx \quad (*)$$

lead to the diagonalizing matrix

$$S = [x_1 \dots x_n] \quad (**)$$

Its columns are B-orthonormal. Consequent-

ly it satisfies

$$S^T B S = I \quad (***)$$

It also diagonalizes A. Indeed it

satisfies

$$AS = BS \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_n \end{bmatrix} = BSA$$

which is Eq. (*) written in terms of the

eigenvectors in Eq. (**). Multiplying

41.8

on the left by S^T one finds with the

help of Eq. (***) on page 41.7 that

$$S^T A S = \Lambda \quad (**)$$

41.9

E) Geometrization via Concentric Ellipses.

The diagonalizing matrix S also

geometrizes $Ax = \lambda Bx$. It does this by

furnishing the transformation which

relates the given coordinates $\{x^i\}$ to the

new ones $\{y^i\}$,

$$X \equiv \begin{bmatrix} x^1 \\ \vdots \\ x^m \end{bmatrix} = S \begin{bmatrix} y^1 \\ \vdots \\ y^m \end{bmatrix} \equiv Sy$$

This coordinate transformation diagonalizes both quadratic forms

$x^T Ax$ and $x^T Bx$

$$x^T Ax \text{ and } x^T Bx$$

simultaneously. Indeed one has

$$\begin{aligned} x^T Ax &= y^T S^T A S y = y^T \Lambda y \\ &= \lambda_1 (y^1)^2 + \lambda_2 (y^2)^2 + \dots + \lambda_m (y^m)^2, \end{aligned}$$

41.10

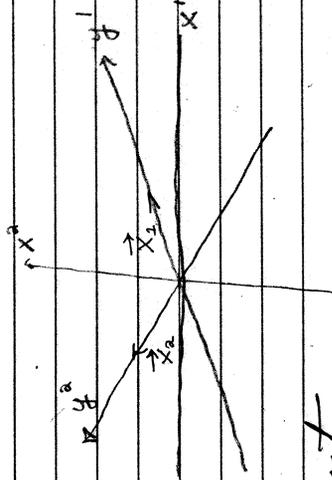
$$x^T B x = y^T S^T B S y = (y^1)^2 + (y^2)^2 + \dots + (y^m)^2$$

The columns of

$$S = \begin{bmatrix} | & | & | \\ x_1 & \dots & x_m \\ | & | & | \end{bmatrix}$$

are the vectors which point along the

new coordinate axes



Comment

Note that the y^1 -axis and the y^2 -axis are

not orthogonal in the standard sense.

This is because w.r.t. the standard inner product $x^T x_j \neq \delta_{ij}$.

In fact, relative to the old coordinate system $\{x^i\}$ the new coordinate system

4/1/11

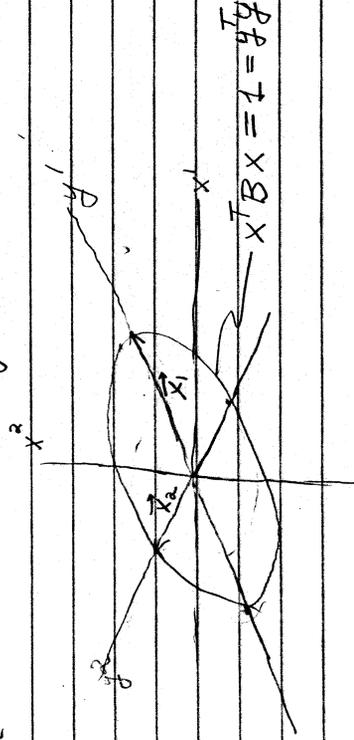
$\{y^i\}$ is one which is oblique. However, the y^1 -axis and the y^2 -axis are orthogonal with respect to the B-inner product. This is because

$$x_i^T B x_j = \delta_{ij}$$

The $x^T B x = 1$ isogram of

$$x^T B x = \sum_i x^i B_{ij} x^j$$

is an ellipse relative to the old $\{x^i\}$ coordinate system.



4/1/12

However, it is a circle with respect to the B-inner product because

$$x^T B x = y^T y.$$

The isograms

$$x^T A x = \lambda_1$$

$$x^T A x = \lambda_2$$

of

$$x^T A x = \sum_i \sum_j x^i A_{ij} x^j$$

are also ellipses (relative to $\{x^i\}$

coordinate system) when A is positive definite.

