

Simple Matroids

Def: Let M be a matroid on E .

- Wednesday, Exercise 4: $e \in E$ is a loop if $\{e\}$ is a circuit.
- Today, Exercise 1: $e, f \in E$ are parallel if $e \neq f$ and $\{e, f\}$ is a circuit.

A matroid is simple if it has no loops and no pairs of parallel edges.

Ex: $M(G)$ is simple $\Leftrightarrow G$ is a simple graph.

There is a natural simplification process

matroid $M \rightsquigarrow$ simple matroid $\tilde{M} = \text{si}(M)$

such that $\tilde{M} = M \Leftrightarrow M$ is simple.

Informally, construct \tilde{M} from M by deleting loops and collapsing parallel elements.

More precisely, the relation on $E = E(M)$

$e \sim f \Leftrightarrow e = f$ or e and f are parallel

is an equivalence relation (Ex. 1)

A non-loop equivalence class of \sim is a parallel class.

Define \tilde{M} on ground set

$$\tilde{E} = \{ \text{parallel classes of } M \} = E \setminus \{ \text{loops} \} / \sim$$

and with independence defined by taking representatives:

If $P_1, \dots, P_k \in \tilde{E}$ are distinct parallel classes and $e_i \in P_i$, then

$$\{P_1, \dots, P_k\} \in \mathcal{I}(\tilde{M}) \Leftrightarrow \{e_1, \dots, e_k\} \in \mathcal{I}(M).$$

Check: (I1) - (I3) hold.

Ex 1(a): $e \sim f$ and $I \in \mathcal{I}(M)$ with $e \in I$
 $\Rightarrow (I \setminus e) \cup f \in \mathcal{I}(M)$

Prop: If P_1, \dots, P_k are distinct parallel classes,
then

$\{P_1, \dots, P_k\}$ is a flat of $\tilde{M} \Leftrightarrow P_1 \perp \dots \perp P_k \perp \{ \text{loops of } M \}$
is a flat of M .

Representable matroids

Let $A = \{v_e \mid e \in E\}$ be a configuration in a K -vector space V . Then $M(A)$ is simple if and only if

- $v_e \neq 0$ for all $e \in E$
- $e \neq f \Rightarrow \text{span}(v_e) \neq \text{span}(v_f)$.

If $M(A)$ is simple, then we may projectivize A :

$$V \setminus \{0\} \longrightarrow \mathbb{P}V = \{\text{lines in } V\} = V \setminus \{0\} / K^\times$$
$$v \longmapsto [v] := \text{span}(v)$$

Main fact: If $W \subseteq V$ subspace def. by lin. forms f_1, \dots, f_k , then $\mathbb{P}W \subseteq \mathbb{P}V$ is defined by the same forms.

- $\dim \mathbb{P}V = \dim V - 1$

points in $\mathbb{P}V \leftrightarrow$ 1-dim subspaces of V

lines in $\mathbb{P}V \leftrightarrow$ 2-dim subspaces of V

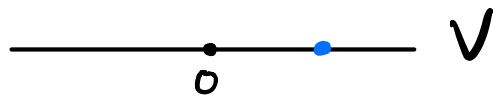
etc.

If $M(A)$ is simple, define $\mathbb{P}A = \{[v_e] \mid e \in E\}$.

Examples: A conf. in V s.t. $M(A)$ is simple.

$$\text{WLOG assume } A \text{ spans } V \Rightarrow \text{rk}(M(A)) = \dim V \\ = \dim \mathbb{P}V + 1$$

Rank 1:



$A =$ one non-zero vector

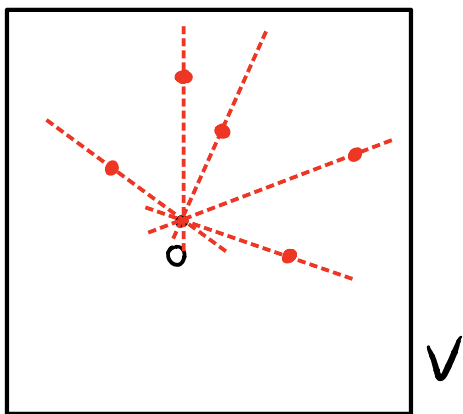


• $\mathbb{P}V$

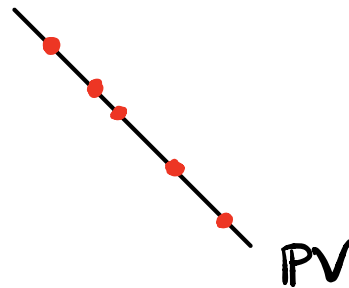
$\mathbb{P}A = \mathbb{P}V =$ one point

$$\Rightarrow M(A) = U_{1,n}$$

Rank 2:



$A =$ finite set of pairwise lin. indep. vectors in a plane



$\mathbb{P}A =$ finite set of collinear points

$$\Rightarrow M(A) = U_{2,n}$$

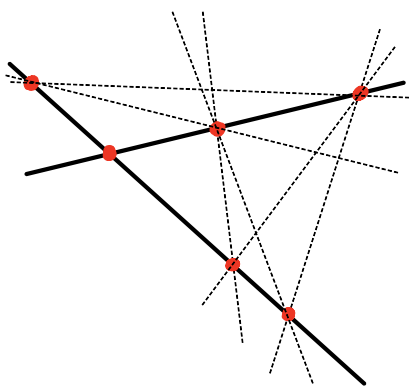
Rank 3:

A = finite set of vectors in 3-space s.t. each pair of vectors spans a plane

$\rightsquigarrow PA$ = finite set of points in a projective plane

Convention: In PA , only draw the lines containing ≥ 3 points

Ex:



Many possibilities

$\mathcal{B}(M(A)) \leftrightarrow$ sets of 3 non-collinear points

$\mathcal{L}(M(A)) \leftrightarrow$ sets of 3 collinear points

and sets of 4 points, no 3 of which are collinear

Rank 0 flat = \emptyset

Rank 1 flats \leftrightarrow points \leftrightarrow ground set

Rank 2 flats \leftrightarrow lines

Rank 3 flat = E

Rank 4: similar - convention is to draw only "interesting" lines + planes