#### Math 2568 Homework 4

Dr. Golubitsky Due: Monday, September 16, 2019

## Problem 1

§2.4, Exercise 15. Consider the augmented matrix

$$A = \left(\begin{array}{cc|c} 1 & -r & 1 \\ r & -1 & 1 \end{array}\right)$$

where r is a real parameter.

1 Find all r so that rank(A) = 2.

2 Find all r for which the corresponding linear system has

(a) no solution,

(b) one solution, and

(c) infinitely many solutions.

**Solution:** Subtracting r times the first row of A from the second row of that matrix yields

$$\left(\begin{array}{cc|c} 1 & -r & 1 \\ 0 & r^2-1 & 1-r \end{array}\right) = \left(\begin{array}{cc|c} 1 & -r & 1 \\ 0 & (r+1)(r-1) & 1-r \end{array}\right)$$

So the reduced row echelon form of A is

$$RREF(A) = \begin{cases} \begin{pmatrix} 1 & 0 & \frac{1}{1+r} \\ 0 & 1 & -\frac{1}{1+r} \\ 1 & -1 & 1 \\ 0 & 0 & 0 \end{pmatrix} & r \neq \pm 1 \\ \begin{pmatrix} 1 & -1 & 1 \\ 0 & 0 & 0 \end{pmatrix} & r = 1 \\ \begin{pmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} & r = -1 \end{cases}$$

 $1 \operatorname{rank}(A) = 2 \text{ if } r \neq 1.$ 

2 The linear system corresponding to the augmented matrix A has

(a) no solution if r = -1,

(b) one solution if  $r \neq \pm 1$ , and

(c) infinitely many solutions if r = 1.

# Problem 2

§3.1, Exercise 12. Let A be a  $2 \times 2$  matrix. Find A so that

$$A \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$
$$A \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 3 \end{pmatrix}.$$

**Answer:** The equations are valid when

$$A = \left(\begin{array}{cc} 3 & -1 \\ 1 & -2 \end{array}\right).$$

Solution: Let

$$A = \left(\begin{array}{cc} a_{11} & a_{12} \\ a_{21} & a_{22} \end{array}\right)$$

Then

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -1 \end{pmatrix} \quad \text{and} \quad \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 3. \end{pmatrix}$$

These matrix equations yield the linear system

which can be written as an augmented matrix and row-reduced to yield the values  $a_{ij}$ :

$$\begin{pmatrix} 1 & 1 & 0 & 0 & 2 \\ 0 & 0 & 1 & 1 & -1 \\ 1 & -1 & 0 & 0 & 4 \\ 0 & 0 & 1 & -1 & 3 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 0 & 0 & 3 \\ 0 & 1 & 0 & 0 & -1 \\ 0 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 2 \end{pmatrix}.$$

#### Problem 3

Determine whether the given transformation is linear.

§3.3, Exercise 7.  $T: \mathbb{R}^2 \to \mathbb{R}^2$  defined by  $T(x_1, x_2) = (x_1 + x_1 x_2, 2x_2)$ .

**Answer:** The transformation T(x,y)=(x+xy,2y) is not linear.

**Solution:** If T is a linear transformation, then

$$T(x_1 + x_2, y_1 + y_2) = T(x_1, y_1) + T(x_2, y_2)$$

for any real numbers  $x_1, x_2, y_1, y_2$ . However,

$$T(1,1) = (2,2)$$
  

$$T(1,0) + T(0,1) = (1,0) + (0,2) = (1,2).$$

Therefore  $T(1,1) \neq T(1,0) + T(0,1)$  and T is not linear.

#### Problem 4

Determine whether the given transformation is linear.

§3.3, Exercise 9.  $T: \mathbb{R}^2 \to \mathbb{R}^3$  defined by  $T(x_1, x_2) = (1, x_1 + x_2, 2x_2)$ 

The transformation T(x,y)=(1,x+y,2y) is not linear because  $T(0,0)=(1,0,0)\neq 0.$ 

### Problem 5

§3.3, Exercise 14. Let  $\sigma: \mathbb{R}^3 \to \mathbb{R}^3$  permute coordinates cyclically; that is,

$$\sigma(x_1, x_2, x_3) = (x_2, x_3, x_1).$$

Find the  $3 \times 3$  matrix A such that  $\sigma = L_A$ .

**Answer:** The matrix A of the linear mapping  $L_A$  is

$$A = \left(\begin{array}{ccc} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{array}\right).$$

**Solution:** Note that if  $\sigma = L_A$ , then  $\sigma(e_j) = Ae_j$  is the  $j^{th}$  column of matrix A. Thus A is determined by

$$\sigma(e_1) = \sigma(1, 0, 0) = (0, 0, 1)$$

$$\sigma(e_2) = \sigma(0, 1, 0) = (1, 0, 0)$$

$$\sigma(e_3) = \sigma(0,0,1) = (0,1,0).$$

# Problem 6

§3.3, Exercise 16. Let  $P: \mathbb{R}^n \to \mathbb{R}^m$  and  $Q: \mathbb{R}^n \to \mathbb{R}^m$  be linear mappings.

(a) Prove that  $S: \mathbb{R}^n \to \mathbb{R}^m$  defined by

$$S(x) = P(x) + Q(x)$$

is also a linear mapping.

(b) Theorem 3.3.5 states that there are matrices A, B and C such that

$$P = L_A$$
 and  $Q = L_B$  and  $S = L_C$ .

What is the relationship between the matrices A, B, and C?

**Solution:** The mapping L is linear if L(x+y) = L(x) + L(y) and if cL(x) = L(cx).

(a) We can use the assumption that P(x) and Q(x) are linear mappings to show:

$$S(x+y) = P(x+y) + Q(x+y)$$

$$= P(x) + P(y) + Q(x) + Q(y)$$

$$= [P(x) + Q(x)] + [P(y) + Q(y)]$$

$$= S(x) + S(y)$$

and

$$cS(x) = cP(x) + cQ(x)$$
  
=  $P(cx) + Q(cx)$   
=  $S(cx)$ .

(b) Assume that  $S = L_C$ ,  $P = L_A$  and  $Q = L_B$  for  $m \times n$  matrices A, B, C. We claim that A = B + C. By definition,  $A(e_j) = L_A(e_j) = L_B(e_j) + L_C(e_j) = (B + C)(e_j)$ . Lemma 3.3.4 implies that the  $j^{th}$  column of C is the sum of the  $j^{th}$  column of A and the  $j^{th}$  column of B for all columns j, so C = A + B.

# Problem 7

§3.4, Exercise 3.

(a) Find all solutions to the homogeneous equation Ax = 0 where

$$A = \left(\begin{array}{ccc} 2 & 3 & 1 \\ 1 & 1 & 4 \end{array}\right).$$

(b) Find a single solution to the inhomogeneous equation

$$Ax = \begin{pmatrix} 6 \\ 6 \end{pmatrix}. \tag{1}$$

- (c) Use your answers in (a) and (b) to find all solutions to (1).
- (a) **Answer:** All solutions to the homogeneous equation are of the form

$$x = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = s \begin{pmatrix} -11 \\ 7 \\ 1 \end{pmatrix}.$$

**Solution:** Row reduce the matrix of the homogeneous system Ax = 0 to obtain:

$$\left(\begin{array}{ccc} 1 & 0 & 11 \\ 0 & 1 & -7 \end{array}\right).$$

So  $x_1 = -11s$ ,  $x_2 = 7s$  and  $x_3 = s$ .

(b) **Answer:** One possible solution is

$$\left(\begin{array}{c} x_1 \\ x_2 \\ x_3 \end{array}\right) = \left(\begin{array}{c} 1 \\ 1 \\ 1 \end{array}\right).$$

**Solution:** Assign a value to  $x_3$ , then substitute into the two equations of the inhomogeneous system to obtain values for  $x_1$  and  $x_2$ .

(c) All solutions to (1) can be found by adding a single solution of the inhomogeneous system to all solutions of the homogeneous system, so:

$$x = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + s \begin{pmatrix} -11 \\ 7 \\ 1 \end{pmatrix}.$$

#### Problem 8

**§3.4**, Exercise 4. How many solutions can a homogeneous system of 4 linear equations in 7 unknowns have?

**Answer:** The system must have infinitely many solutions.

The system must have a solution because homogeneous systems are always consistent. The system cannot have a unique solution because the rank of the corresponding augmented matrix cannot exceed 4 which is less than the number of variables 7.

### Problem 9

Compute the given matrix product.

§3.5, Exercise 8. 
$$\begin{pmatrix} 2 & -1 & 3 \\ 1 & 0 & 5 \\ 1 & 5 & -1 \end{pmatrix} \begin{pmatrix} 1 & 7 \\ -2 & -1 \\ -5 & 3 \end{pmatrix}.$$

$$\begin{pmatrix} 2 & -1 & 3 \\ 1 & 0 & 5 \\ 1 & 5 & -1 \end{pmatrix} \begin{pmatrix} 1 & 7 \\ -2 & -1 \\ -5 & 3 \end{pmatrix} = \begin{pmatrix} 2+2-15 & 14+1+9 \\ 1-25 & 7+15 \\ 1-10+5 & 7-5-3 \end{pmatrix} = \begin{pmatrix} -11 & 24 \\ -24 & 22 \\ -4 & -1 \end{pmatrix}.$$

### Problem 10

§3.6, Exercise 4. Let

$$I = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$
 and  $J = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$ .

- (a) Show that  $J^2 = -I$ .
- (b) Evaluate (aI + bJ)(cI + dJ) in terms of I and J.
- (a) Verify  $J^2 = -I$  by computation:

$$J^2 = \left(\begin{array}{cc} 0 & -1 \\ 1 & 0 \end{array}\right) \left(\begin{array}{cc} 0 & -1 \\ 1 & 0 \end{array}\right) = \left(\begin{array}{cc} -1 & 0 \\ 0 & -1 \end{array}\right) = -I.$$

(b) **Answer:** (aI + bJ)(cI + dJ) = (ac - bd)I + (ad + bc)J.

**Solution:** Evaluate (aI + bJ)(cI + dJ), yielding  $acI^2 + adIJ + bcJI + bdJ^2$ . Then, use the identities IJ = JI = J,  $I^2 = I$ , and  $J^2 = -I$  to rewrite the expression in terms of I and J.

### Problem 11

§3.7, Exercise 1. Verify by matrix multiplication that the following matrices are inverses of each other:

$$\left(\begin{array}{ccc} 1 & 0 & 2 \\ 0 & -1 & 2 \\ 1 & 0 & 1 \end{array}\right) \quad \text{and} \quad \left(\begin{array}{ccc} -1 & 0 & 2 \\ 2 & -1 & -2 \\ 1 & 0 & -1 \end{array}\right).$$

If two matrices are inverses of each other, then their product is the identity matrix. So:

$$\left(\begin{array}{ccc} 1 & 0 & 2 \\ 0 & -1 & 2 \\ 1 & 0 & 1 \end{array}\right) \left(\begin{array}{ccc} -1 & 0 & 2 \\ 2 & -1 & -2 \\ 1 & 0 & -1 \end{array}\right) = \left(\begin{array}{ccc} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{array}\right).$$

# Problem 12 (MATLAB)

§3.6, Exercise 10 (MATLAB). (MATLAB) Experimentally, find two symmetric  $2 \times 2$  matrices A and B for which the matrix product AB is *not* symmetric.

Let

$$A = \begin{pmatrix} 1 & 2 \\ 2 & -1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}$$

be symmetric matrices. Then

$$AB = \left(\begin{array}{cc} 0 & 3\\ 5 & -4 \end{array}\right)$$

is not symmetric. In general, for

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{12} & a_{22} \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} b_{11} & b_{12} \\ b_{12} & b_{22} \end{pmatrix},$$

AB is symmetric if  $a_{12}b_{11} + a_{22}b_{12} = a_{11}b_{12} + a_{12}b_{22}$ .