Week 8 Lectures, Math 6451, Tanveer

1 Green's function as a distribution

1.1 Laplace Operator

For the Poisson-Problem with homogeneous boundary condition:

$$\Delta u = f \quad \text{for} \quad \mathbf{x} \in \Omega \quad , \quad u = 0 \quad \text{on} \quad \partial \Omega \tag{1}$$

we know that

$$u(\mathbf{x}_0) = \int_{\Omega} G(\mathbf{x}, \mathbf{x}_0) f(\mathbf{x}) d\mathbf{x}$$
(2)

On the other and, if u is a test function with support inside Ω , we have from using corollary 4 of week 7 notes that

$$u(\mathbf{x}_0) = \int_{\Omega} G(\mathbf{x}, \mathbf{x}_0) \Delta u(\mathbf{x}) d\mathbf{x} = (u, \Delta G(., \mathbf{x}_0))$$
(3)

Therefore, in the sense of distribution,

$$\Delta G(\mathbf{x}, \mathbf{x}_0) = \delta(\mathbf{x} - \mathbf{x}_0) \tag{4}$$

Therefore, we view solution (24) as a principle of linear superposition. In the physical context (n = 3), it means that the potential caused by charge density f in a domain Ω with boundary at zero potential is given by a linear superposition of point charge potentials satisfying the same boundary conditions, with a weighting proportional to the infinitesimal charge $f(\mathbf{x})d\mathbf{x}$ present in a volume element $d\mathbf{x}$ at \mathbf{x} .

Further, note that $G(\mathbf{x}, \mathbf{x}_0) = G_0(|\mathbf{x} - \mathbf{x}_0|) + H(\mathbf{x}, \mathbf{x}_0)$, where H is harmonic in \mathbf{x} . It follows that

$$\Delta G_0(|\mathbf{x} - \mathbf{x}_0|) = \delta(\mathbf{x} - \mathbf{x}_0) \tag{5}$$

More generally if we have a linear constant coefficient PDE in the form

$$Lu = f$$
, for $x \in \Omega \subset \mathbb{R}^n$, with $u = 0$ on $\partial \Omega$ (6)

then if we can find Greens function satisfying

$$LG = \delta(\mathbf{x} - \mathbf{x}_0)$$
 , with $G = 0$ on $\partial\Omega$ (7)

then, we can show that

$$u(\mathbf{x}_0) = \int_{\Omega} G(\mathbf{x}, \mathbf{x}_0) f(\mathbf{x}) d\mathbf{x}$$
(8)

1.2 Heat Equation

Recall from last class that the source function:

$$S = \left(\frac{1}{4\pi\kappa t}\right)^{n/2} \exp\left[-\frac{|\mathbf{x}|^2}{4\kappa t}\right]$$
(9)

satisfies

$$S_t = \kappa \Delta S$$
 for $\mathbf{x} \in \mathbb{R}^n$, $t > 0$, with $S(\mathbf{x}, 0^+) = \delta(\mathbf{x})$ (10)

It can be shown (exercise) that

$$R(\mathbf{x}, t) = S(\mathbf{x} - \mathbf{x}_0, t - t_0) \text{ for } t > t_0 \text{ and } R(\mathbf{x}, t) = 0 \text{ for } t < t_0$$
(11)

satisfies

$$R_t - \kappa \Delta R = \delta(\mathbf{x} - \mathbf{x}_0)\delta(t - t_0) \tag{12}$$

2 Eigen Function Expansion for Green's Function

2.1 Heat Equation

Consider Source solution to heat equation bounded domain $\Omega \subset \mathbb{R}^n$ with homogeneous Dirichlet Boundary conditions:

$$S_t = \kappa \Delta S \text{ for } \mathbf{x} \in \Omega \text{ and } S = 0 \text{ on } \partial \Omega, \text{ with } S(\mathbf{x}, 0) = \delta(\mathbf{x} - \mathbf{x}_0)$$
 (13)

In terms of the $S(\mathbf{x}, \mathbf{x}_0, t)$ the solution to the initial value problem

$$u_t = \kappa \Delta u \text{ for } \mathbf{x} \in \Omega \text{ and } u = 0 \text{ on } \partial \Omega, \text{ with } u(\mathbf{x}, 0) = \phi(\mathbf{x})$$
 (14)

is given by

$$u(\mathbf{x},t) = \int_{\Omega} S(\mathbf{x},\mathbf{y},t)\phi(\mathbf{y})d\mathbf{y}$$
(15)

On the other hand, if we denote the orthonormalized eigenfunctions $\{X_n\}_{n=1}^{\infty}$ and corresponding eigenvalues $\{\lambda_n\}_{n=1}^{\infty}$ of the operator $-\Delta$ with homogenous boundary conditions on $\partial\Omega$, we know that solution to heat equation has the form

$$u(\mathbf{x},t) = \sum_{n=1}^{\infty} \exp\left[-\lambda_n \kappa t\right] X_n(\mathbf{x})$$
(16)

where

$$c_n = (\phi, X_n) = \int_{\Omega} \phi(\mathbf{x}) X_n(\mathbf{x}) d\mathbf{x}$$
(17)

Then,

$$u(\mathbf{x},t) = \sum_{n=1}^{\infty} \left(\int_{\Omega} \phi(\mathbf{y}) X_n(\mathbf{y}) d\mathbf{y} \right) \exp\left[-\lambda_n \kappa t \right] X_n(\mathbf{x}) = \left(\int_{\Omega} \phi(\mathbf{y}) \left\{ \sum_{n=1}^{\infty} X_n(\mathbf{y}) X_n(\mathbf{x}) e^{-\lambda_n \kappa t} \right\} d\mathbf{y} \right)$$
(18)

Therefore, it follows that under the assumption that the summation converges absolutely and uniformly,

$$S(\mathbf{x}, \mathbf{y}, t) = \sum_{n=1}^{\infty} X_n(\mathbf{y}) X_n(\mathbf{x}) e^{-\lambda_n \kappa t}$$
(19)

Note, that this implies that in the sense of distribution, we must have

$$\delta(\mathbf{x} - \mathbf{y}) = \sum_{n=1}^{\infty} X_n(\mathbf{y}) X_n(\mathbf{x})$$

This is true for any complete ortho-normal basis.

Fourier Transform 3

Notation: For multi-index $\alpha = (\alpha_1, \alpha_2, ..., \alpha_n)$, with each $\alpha_j \in \mathbb{N}$, it is convenient to introduce operator

$$D^{\alpha} \equiv \partial_{x_1}^{\alpha_1} \partial_{x_2}^{\alpha_2} \dots \partial_{x_n}^{\alpha_n}$$

The order of this operator is denoted by $|\alpha| \equiv \alpha_1 + \alpha_2 + ... + \alpha_n$.

Definition 1 $\mathcal{S}(\mathbb{R}^n)$ be the space of all functions ϕ on \mathbb{R}^n which are of the class \mathbf{C}^{∞} and such that for any integer $j \ge 0$, $|\mathbf{x}|^j |D^{\alpha}\phi| < \infty$, for $|\alpha| = j$. This is referred to usually as the Schwartz class of functions.

Definition 2 A tempered distribution in \mathbb{R}^n is a continuous linear functional on the class of $\phi \in \mathcal{S}(\mathbb{R}^n).$

Remark 1 Note that every tempered-distribution is a distribution, but the converse is not true.

The Fourier transform of a continuous absolutely integrable function f on \mathbb{R}^n is defined by

$$\hat{f}(\mathbf{k}) = \mathcal{F}[f](\mathbf{k}) = (2\pi)^{-n/2} \int_{\mathbb{R}^n} \exp\left[-i\mathbf{k}\cdot\mathbf{x}\right] f(\mathbf{x})d\mathbf{x}$$

In particular, this defines Fourier-Transform for every $f \in \mathcal{S}(\mathbb{R}^n)$.

Theorem 3 If $f \in \mathcal{S}(\mathbb{R}^n)$, then $\hat{f} \in \mathcal{S}(\mathbb{R}^n)$. Moreover, the mapping is continuous from $\mathcal{S}(\mathbb{R}^n)$ to itself.

PROOF. We leave the proof to the reader. \Box

Theorem 4 Let $g \in \mathcal{S}(\mathbb{R}^n)$. Then there is a unique $f \in \mathcal{S}(\mathbb{R}^n)$ such that $g = \mathcal{F}[f]$. Futhermore, the inverse Fourier transform of g is given by

$$f(\mathbf{x}) = (2\pi)^{-n/2} \int_{\mathbb{R}^n} e^{i\mathbf{k}\cdot\mathbf{x}} g(\mathbf{k}) d\mathbf{k}$$
(20)

PROOF. Let $Q_M = [-M, M]^n$, and let f be given by the above formula. Then, we find

$$\begin{split} \tilde{f}(\mathbf{k}) &= (2\pi)^{-n/2} \int_{\mathbb{R}^n} e^{-i\mathbf{k}\cdot\mathbf{x}} f(\mathbf{x}) d\mathbf{x} = (2\pi)^{-n/2} \int_{\mathbb{R}^n} e^{-i\mathbf{k}\cdot\mathbf{x}} \int_{\mathbb{R}^n} e^{i\boldsymbol{\eta}\cdot\mathbf{x}} g(\boldsymbol{\eta}) d\boldsymbol{\eta} d\mathbf{x} \\ &= \lim_{M \to \infty} \int_{\mathbb{R}^n} \int_{Q_M} e^{i(\boldsymbol{\eta}-\mathbf{k})\cdot\mathbf{x}} g(\boldsymbol{\eta}) d\mathbf{x} d\boldsymbol{\eta} = \pi^{-n} \lim_{M \to \infty} \int_{\mathbb{R}^n} \prod_{i=1}^n \frac{\sin M(\eta_i - k_i)}{\eta_i - k_i} g(\boldsymbol{\eta}) d\boldsymbol{\eta} d\mathbf{x} \end{split}$$

However, it is easily seen that as $M \to \infty$, $\frac{\sin M(\eta_i - k_i)}{\eta_i - k_i} \to \pi \delta(\eta_i - k_i)$ in the sense of distribution. Therefore, it follows that $\hat{f}(\mathbf{k}) = g(\mathbf{k})$

$$f(\mathbf{k}) = g(\mathbf{k})$$

An analogous calculation shows that if $g = \hat{h}$ for some $h \in \mathcal{S}(\mathbb{R}^n)$, then h = f as given by equation (20). \Box

Theorem 5 Let $f, g \in \mathcal{S}(\mathbb{R}^n)$, then $(\hat{f}, \hat{g}) = (f, g)$.

PROOF. We have

$$(f,g) = \int_{\mathbb{R}^n} f(\mathbf{x})\overline{g(\mathbf{x})}d\mathbf{x} = (2\pi)^{-n/2} \int_{\mathbb{R}^n} \overline{g(\mathbf{x})} \int_{\mathbb{R}^n} \hat{f}(\mathbf{k})e^{i\mathbf{k}\cdot\mathbf{x}}d\mathbf{k}d\mathbf{x}$$
$$= (2\pi)^{-n/2} \int_{\mathbb{R}^n} \hat{f}(\mathbf{k}) \int_{\mathbb{R}^n} \overline{g(\mathbf{x})}e^{-i\mathbf{k}\cdot\mathbf{x}}d\mathbf{x}d\mathbf{k} = \int_{\mathbb{R}^n} \overline{g(\mathbf{k})}\hat{f}(\mathbf{k})d\mathbf{k} = (\hat{f},\hat{g})$$

We now seek to give meaning to Fourier-Transform of tempered distribution.

Definition 6 Let $f \in \mathcal{S}'(\mathbb{R}^n)$. Then the Fourier transform of f is defined by the functional

 $(\mathcal{F}[f], \phi) = (f, \mathcal{F}^{-1}[\phi]) \text{ for } \phi \in \mathcal{S}(\mathbb{R}^n)$

Remark 2 It is not difficult to see that \mathcal{F} is a continuous mapping from $\mathcal{S}'(\mathbb{R}^n)$ onto itself. The formulas for Fourier transform and its inverse still hold for tempered distribution.

Example We want Fourier-transform of δ distribution. From definition

$$(\mathcal{F}[\delta],\phi) = (\delta, \mathcal{F}^{-1}[\phi]) = \mathcal{F}^{-1}[\phi](\mathbf{0}) = (2\pi)^{-n/2} \int_{\mathbb{R}^n} \phi(\mathbf{x}) d\mathbf{x}$$

Therefore $\mathcal{F}[\delta] = (2\pi)^{-n/2}$, a constant.

Example The above relation is symmetric. since the Fourier-transform of 1 equal to $(2\pi)^{n/2}\delta$ since

$$(\mathcal{F}[1],\phi) = (1,\mathcal{F}^{-1}[\phi]) = \int_{\mathbb{R}^n} \mathcal{F}^{-1}[\phi](\mathbf{x}) d\mathbf{x} = (2\pi)^{n/2} \mathcal{F} \mathcal{F}^{-1}[\phi](\mathbf{0}) = (2\pi)^{n/2} \phi(\mathbf{0})$$

Therefore, $\mathcal{F}[1] = (2\pi)^{n/2} \delta$

Example: Let $\delta(|\mathbf{x}| - a)$ represent a uniform mass distribution on a sphere of radius *a*, *i.e.*

$$(\delta(|\mathbf{x}| - a), \phi) = \int_{|\mathbf{x}| = a} \phi(\mathbf{x}) dS$$

Then,

$$\mathcal{F}[\delta(|\mathbf{x}|-a)](\mathbf{k}) = (2\pi)^{-n/2} \int_{|\mathbf{x}|=a} e^{-i\mathbf{k}\cdot\mathbf{x}} dS$$

For n = 3, using spherical polar coordinates, we get

$$\mathcal{F}[\delta(|\mathbf{x}|-a)](\mathbf{k}) = (2\pi)^{-n/2} \int_0^{\pi} \int_0^{2\pi} e^{-ia\rho\cos\theta} \sin\theta d\phi d\theta = \sqrt{\frac{2}{\pi}} a \frac{\sin a|\mathbf{k}|}{|\mathbf{k}|}$$

4 Examples of Fourier-Transform of Distributions

Example: Using the same argument, as for $\mathcal{F}[1]$, except with **k** replaced by $\mathbf{k} - \boldsymbol{\eta}$, we find:

$$\mathcal{F}\left[\exp[i\boldsymbol{\eta}\cdot\mathbf{x}]\right](\mathbf{k}) = (2\pi)^{m/2}\delta(\mathbf{k}-\boldsymbol{\eta})$$

If f is a 2π -periodic distribution represented by a Fourier-series:

$$f(x) = \sum_{n=1}^{\infty} c_n e^{inx},$$

we find that

$$\mathcal{F}[f](k) = \sqrt{2\pi} \sum_{n=-\infty}^{\infty} c_n \delta(k-n)$$

Definition 7 A distribution f is said to have a compact support, if there exists a compact \mathcal{K} so that for all test function ϕ with support in $\mathbb{R}^n \setminus \mathcal{K}$, $(f, \phi) = 0$. An example of this is $\delta(\mathbf{x})$, whose support is only $\{\mathbf{0}\}$.

Example Let f be a distribution with compact support. Then for any $\phi \in \mathbf{C}^{\infty}(\mathbb{R}^n)$, we set $(f, \phi) = (f, \phi_0)$, where $\phi_0 \in \mathcal{D}(\mathbb{R}^n)$ and ϕ_0 agrees with ϕ is a neighborhood of the support of f. If ϕ_1 also has similar property as ϕ_0 , it is clear from definition of f that $(f, \phi_0 - \phi_1) = 0$ since from construction, the support of $\phi_0 - \phi_1$ is outside the support of f. Thus, (f, ϕ) can be defined unambigously (not depending on which ϕ_0 is used).

We claim that $\mathcal{F}[f]$ is the function

$$\mathcal{F}[f](\mathbf{k}) = (2\pi)^{-m/2} \left(\overline{f(\mathbf{x})}, e^{-i\mathbf{k}\cdot\mathbf{x}}\right)$$

Here (\bar{f}, ϕ) is defined as the complex conjugate of $(f, \bar{\phi})$. This follows since for any $\phi \in \mathcal{S}(\mathbb{R}^n)$, we have

$$(2\pi)^{-n/2} \int_{\mathbb{R}^n} \left(f(\mathbf{x}), e^{i\mathbf{k}\cdot\mathbf{x}} \right) \phi(\mathbf{k}) d\mathbf{k} = (f, \mathcal{F}^{-1}[\phi]) = (2\pi)^{-n/2} \left(f, \int_{\mathbb{R}^n} e^{i\mathbf{k}\cdot\mathbf{x}} \phi(\mathbf{k}) d\mathbf{k} \right)$$

Example: Let $\delta(|\mathbf{x}| - a)$ represent a uniform mass distribution on a sphere of radius *a*, *i.e.*

$$(\delta(|\mathbf{x}|-a),\phi) = \int_{|\mathbf{x}|=a} \phi(\mathbf{x}) dS$$

Then,

$$\mathcal{F}[\delta(|\mathbf{x}|-a)](\mathbf{k}) = (2\pi)^{-n/2} \int_{|\mathbf{x}|=a} e^{-i\mathbf{k}\cdot\mathbf{x}} dS$$

For n = 3, using spherical polar coordinates, we get

$$\mathcal{F}[\delta(|\mathbf{x}|-a)](\mathbf{k}) = (2\pi)^{-n/2} \int_0^\pi \int_0^{2\pi} e^{-ia\rho\cos\theta} \sin\theta d\phi d\theta = \sqrt{\frac{2}{\pi}} a \frac{\sin a|\mathbf{k}|}{|\mathbf{k}|}$$

5 The Source Solution (fundamental solution) for the wave equation:

Consider solution to

$$S_{tt} = \Delta S$$
, for $\mathbf{x} \in \mathbb{R}^n, t \in \mathbb{R}$, with $S(\mathbf{x}, 0) = 0$, $S_t(\mathbf{x}, 0) = \delta(\mathbf{x})$ (21)

Fourier-transforming, we obtain

$$\hat{S}_{tt} = -\mathbf{k}^2 \hat{S}$$
 with $\hat{S}(\mathbf{k}, 0) = 0$ $\hat{S}_t(\mathbf{k}, 0) = (2\pi)^{-n/2}$ (22)

Therefore,

$$\mathcal{S}(\mathbf{k},t) = (2\pi)^{-n/2} \frac{\sin|\mathbf{k}|t}{|\mathbf{k}|}$$
(23)

For n = 3, from one of the previous examples, it follows that

$$S(\mathbf{x},t) = \frac{\delta(|\mathbf{x}| - t)}{4\pi t} \tag{24}$$

This method of finding Green's function is generally valid for any constant coefficient system in free-space. For example, if we have have a PDE of the form

$$\mathcal{P}(\partial_{\mathbf{x}})G = \delta(\mathbf{x})$$

where \mathcal{P} is a polynomial, then application of Fourier-Transform leads to an algebraic relation:

$$\hat{G}(\mathbf{k}) = \frac{1}{(2\pi)^{n/2} \mathcal{P}(i\mathbf{k})}$$

We can then recover G by Fourier-transform. Note that since the above is true for any dimension, it can accomodate PDEs involving both t and \mathbf{x} , but just considering a higher dimensional variable $\overline{\mathbf{x}} = (\mathbf{x}, t)$.

6 Laplace Transform:

If $f \in \mathcal{S}'(\mathbb{R})$ have support contained in $\{x \ge 0\}$. Then obviously $e^{-\mu x} f(x)$ is also in $\mathcal{S}'(\mathbb{R})$ for every $\mu > 0$. Formally, we have

$$\mathcal{F}\left[e^{-\mu x}f\right](\mathbf{k}) = \frac{1}{\sqrt{2\pi}} \int_0^\infty f(x)e^{-ikx}e^{-\mu x}dx = \mathcal{F}[f](k-i\mu)$$

Hence, it is sensible to define $\mathcal{F}[f](k-i\mu) = \mathcal{F}[fe^{-\mu x}]$. This defines $\mathcal{F}[f]$ in the lower half of the complex k-plane-as a generalized function of $\Re k$, depending of $\Im k$ as a paraemeter. Actually, however, this function is analytic k in the lower-half plane ($\Im k < 0$). The Laplace-transform is defined as

$$\mathcal{L}[f](s) = \sqrt{2\pi}\mathcal{F}[f](-is);$$

for $f \in S'$ with support in $\{x \ge 0\}$, it is defined in the right half-plane complex plane ($\Re s \ge 0$). Formally, we have

$$\mathcal{L}[f](s) = \int_0^\infty e^{-sx} f(x) dx$$

If $f \notin \mathcal{S}'(R)$, but $e^{-\mu x} f \in \mathcal{S}'(\mathbb{R})$ for some $\mu > 0$, then we can define $\mathcal{L}[f]$ in the right-half plane $\Re \ s \ge \mu$. We note that by inverting the Fourier-transform we obtain

$$e^{-\mu x}f(x) = \frac{1}{\sqrt{2\pi}}\mathcal{F}^{-1}[f](\mu + ik),$$

or equivalently,

$$f(x) = \frac{1}{2\pi i} \int_{\mu - i\infty}^{\mu + i\infty} e^{sx} \mathcal{L}[f](s) ds$$

In using the above formula, we must ensure that the resulting expression vanishes for x < 0, since this was our basic assumption. Typically, one shows this by closing the contour of integration by a half-circle to the right; e^{sx} decays rapidly in the right half plane. For this argument to work, it is necessary to choose μ to the right of the singularities of f. **Example:** Consider

$$u_t = u_{xx}$$
 for $x \in (0,1)$, $t > 0$ with $u(x,0) = 0$, $u(0,t) = 1 = u(1,t)$ for $t > 0$

Laplace transform in time leads to

$$s\mathcal{L}[u](x,s) = \mathcal{L}[u]_{xx}(x,s) \; ; \; \mathcal{L}[u](0,s) = \frac{1}{s} = \mathcal{L}[u](1,s)$$

The equation for the solution is

$$\mathcal{L}[u](x,s) = \frac{\cosh\left(\sqrt{s}\left(x - \frac{1}{2}\right)\right)}{s\cosh\left(\sqrt{s}/2\right)}$$

Using the inverse transform, we obtain

$$u(x,t) = \frac{1}{2\pi i} \int_{\mu-i\infty}^{\mu+i\infty} e^{st} \frac{\cosh\left(\sqrt{s}(x-\frac{1}{2})\right)}{s\cosh\left(\sqrt{s}/2\right)} ds$$

The integral cannot be evaluated in closed form, however, through contour deformation, and change of variables $\sqrt{s} - s_1$, it is possible to use calculus of residues (complex variable technique) and obtain a series form of solution.

7 Wave equation

7.1 Solution in higher dimension through Spherical Means

Assume u is a classical solution to the initial value problem for n-dimensional wave equation for $n \ge 2$:

$$u_{tt} - \Delta u = 0$$
 for $\mathbf{x} \in \mathbb{R}^n$ for $t > 0$ with $u(\mathbf{x}, 0) = \phi(\mathbf{x})$, $u_t(\mathbf{x}, 0) = \psi(\mathbf{x})$ (25)

where $\phi \in \mathbf{C}^2$ and $\psi \in \mathbf{C}^1$. For t > 0, r > 0, we define $U(\mathbf{x}; r, t)$ to be the spherical average over the surface of an *n*-dimensional ball $B(\mathbf{x}, r)$ of radius *r*, centered at \mathbf{x} , and denoted by

$$U(\mathbf{x}; r, t) = \frac{1}{A_r} \int_{\partial B(\mathbf{x}; r)} u(\mathbf{y}, t) d\mathbf{y} \equiv \oint_{\partial B(\mathbf{x}; r)} u(\mathbf{y}, t) d\mathbf{y}$$
(26)

where A_r is the surface area of an *n* dimensional ball of radius *r*. Note $A_r = n\alpha(n)r^{n-1}$, where volume of the *n*-dimensional sphere is $\alpha(n)r^n$. It is to be noted that

$$\lim_{r \to 0^+} U(\mathbf{x}; r, t) = u(\mathbf{x}, t)$$

from continuity of **u**. We can similarly define

$$G(\mathbf{x};r) = \oint_{\partial B(\mathbf{x};r)} \phi(\mathbf{y},t) d\mathbf{y}$$
(27)

$$H(\mathbf{x};r) = \int_{\partial B(\mathbf{x};r)} \psi(\mathbf{y},t) d\mathbf{y}$$
(28)

For fixed \mathbf{x} , we regard U as a function of r and t. We claim

Lemma 8 For fixed \mathbf{x} , $U(\mathbf{x}; r, t)$ is a solution of the initial value problem:

$$U_{tt} - U_{rr} - \frac{n-1}{r}U_r = 0 \text{ for } r > 0, \ t > 0 \text{ and } U(\mathbf{x}; r, 0) = G(\mathbf{x}, r), \ U_t(\mathbf{x}; r, 0) = H(\mathbf{x}, r)$$
(29)

PROOF. For convenience, we depart from our usual convention and denote 'surface area' element on the *n*-dimensional ball as dS. Symbol $dS_{\mathbf{y}}$ will denote surface area element in the variable \mathbf{y} . We note that

$$U(\mathbf{x}; r, t) = \oint_{\partial B(\mathbf{x}, r)} u(\mathbf{y}, t)) dS_{\mathbf{y}} = \oint_{\partial B(\mathbf{0}, 1)} u(\mathbf{x} + r\mathbf{z}, t)) dS_{\mathbf{z}}$$
(30)

Therefore,

$$U_{r}(\mathbf{x}; r, t) = \oint_{\partial B(\mathbf{0}, 1)} \mathbf{z} \cdot \nabla u(\mathbf{x} + r\mathbf{z}, t) dS_{\mathbf{z}} = \oint_{\partial B(\mathbf{x}, r)} \frac{\partial u}{\partial n} dS_{\mathbf{y}} = \frac{1}{A_{r}} \int_{\partial B(\mathbf{x}, r)} \frac{\partial u}{\partial n} dS_{\mathbf{y}}$$
$$= \frac{1}{A_{r}} \int_{B(\mathbf{x}, r)} \Delta u(\mathbf{y}, t) d\mathbf{y} == \frac{1}{n\alpha(n)r^{n-1}} \int_{B(\mathbf{x}, r)} \Delta u(\mathbf{y}, t) d\mathbf{y}, \quad (31)$$

Thus, using (25), it follows that

$$U_r(\mathbf{x}; r, t) = \frac{1}{n\alpha(n)r^{n-1}} \int_{B(\mathbf{x}, r)} u_{tt} d\mathbf{y}$$
(32)

and therefore,

$$\frac{\partial}{\partial r} \left\{ r^{n-1} U_r(\mathbf{x}; r, t) \right\} = \frac{1}{n\alpha(n)} \int_{\partial B(\mathbf{x}; r)} u_{tt}(\mathbf{y}, t) dS_{\mathbf{y}} = r^{n-1} U_{tt}$$
(33)

This gives the PDE for U given in the Lemma. Further, it is clear from definition of G and H that U satisfies the given initial conditions. \Box

Theorem 9 (Kirchoff Formula for n = 3)

The solution to the initial value problem for the three-dimensional dimensional wave equation in free-space:

$$u_{tt} - \Delta u = 0$$
 for $\mathbf{x} \in \mathbb{R}^3$ for $t > 0$ with $u(\mathbf{x}, 0) = \phi(\mathbf{x})$, $u_t(\mathbf{x}, 0) = \psi(\mathbf{x})$ (34)

is given by

$$u(\mathbf{x},t) = \int_{\partial B(\mathbf{x},t)} \left\{ t\psi(\mathbf{y} + \phi(\mathbf{y}) + (\mathbf{y} - \mathbf{x}) \cdot \nabla \phi(\mathbf{y}) \right\} dS_{\mathbf{y}}$$
(35)

Proof.

If note that if we introduce transformation

$$\tilde{U}(\mathbf{x}; r, t) = rU(\mathbf{x}; r, t), \quad \tilde{G} = rG, \quad \tilde{H} = rH$$

Then, simple calculation shows

$$\tilde{U}_{tt} - \tilde{U}_{rr} = 0$$
 for $r > 0$, $t > 0$, with $\tilde{U}(r,0) = \tilde{G}(r)$, $\tilde{U}_t(r,0) = \tilde{H}(r)$, $\tilde{U}(0,t) = 0$

This is the Wave equation on a half-line with a homogeneous *Dirichlet* condition. As discussed in Week 4 lectures (see equation (32) on page 4, with c = 1) for $0 \le r \le t$, we obtain

$$\tilde{U}(\mathbf{x};r,t) = \frac{1}{2} \left[\tilde{G}(r+t) - \tilde{G}(t-r) \right] + \frac{1}{2} \int_{t-r}^{r+t} \tilde{H}(y) dy$$

Since $u(\mathbf{x},t) = \lim_{r \to 0^+} \frac{\tilde{U}(\mathbf{x};r,t)}{r}$,

$$\begin{split} u(\mathbf{x},t) &= \lim_{r \to 0^+} \left\{ \frac{1}{2r} \left[\tilde{G}(r+t) - \tilde{G}(t-r) \right] + \frac{1}{2r} \int_{t-r}^{r+t} \tilde{H}(y) dy \right\} \\ &= \tilde{G}'(t) + \tilde{H}(t) = \partial_t \left(t f_{\partial B(\mathbf{x},t)} \phi dS \right) + t f_{\partial B(\mathbf{x},t)} \psi dS = \partial_t \left(t f_{\partial B(\mathbf{0},1)} \phi(\mathbf{x}+t\mathbf{z}) dS_{\mathbf{z}} \right) + t f_{\partial B(\mathbf{0},1)} \psi dS_{\mathbf{z}} \\ &= \int_{\partial B(\mathbf{0},1)} \left\{ t \psi(\mathbf{x}+t\mathbf{z}) + \phi(\mathbf{x}+t\mathbf{z}) + t\mathbf{z} \cdot \nabla \phi(\mathbf{x}+t\mathbf{z}) \right\} dS_{\mathbf{z}} = f_{\partial B(\mathbf{x},t)} \left\{ t \psi(\mathbf{y}) + \phi(\mathbf{y}) + \nabla \phi(\mathbf{y}) \cdot (\mathbf{y}-\mathbf{x}) \right\} dS_{\mathbf{y}} \\ &\Box \end{split}$$

Theorem 10 (Poisson Formula for n = 2)

The solution to the initial value problem for the two-dimensional dimensional wave equation in free-space:

$$u_{tt} - \Delta u = 0$$
 for $\mathbf{x} \in \mathbb{R}^2$ for $t > 0$ with $u(\mathbf{x}, 0) = \phi(\mathbf{x})$, $u_t(\mathbf{x}, 0) = \psi(\mathbf{x})$ (36)

is given by

$$u(\mathbf{x},t) = \frac{1}{2} \int_{B(\mathbf{x},t)} \frac{\left\{ t\psi(\mathbf{y}) + t^2\psi(\mathbf{y} + t(\mathbf{y} - \mathbf{x}) \cdot \nabla\phi(\mathbf{y}) \right\}}{(t^2 - |\mathbf{y} - \mathbf{x}|^2)^{1/2}} d\mathbf{y}$$
(37)

PROOF. We imbed the 2-D problem as part of 3-D problem. With $\mathbf{\bar{x}} = (x_1, x_2, x_3)$, $\mathbf{x} = (x_1, x_2)$, $\bar{u}(\mathbf{\bar{x}}, t) = u(\mathbf{x}, t)$. Then \bar{u} satisfies the 3-D wave equation with initial condition

$$\bar{\phi}(\bar{\mathbf{x}}) = \phi(\mathbf{x}) \text{ and } \bar{\psi}(\bar{\mathbf{x}}) = \psi(\mathbf{x})$$

Then, we have from the 3-D calculation,

$$\bar{u}(\bar{\mathbf{x}},t) = \partial_t \left(t \oint_{\partial \bar{B}(\bar{\mathbf{x}},t)} \bar{\phi} d\bar{S} \right) + t \oint_{\partial \bar{B}(\bar{\mathbf{x}},t)} \bar{\psi} d\bar{S}$$

where $\overline{B}(\overline{\mathbf{x}},t)$ denotes the ball in \mathbb{R}^3 with center $\overline{\mathbf{x}}$ of radius t > 0, and $d\overline{S}$ denotes the two dimensional surface measure. Now we observe that

$$\int_{\partial \bar{B}(\bar{\mathbf{x}},t)} \bar{g} d\bar{S} = \frac{1}{4\pi t^2} \int_{\partial \bar{B}(\bar{\mathbf{x}},t)} \bar{g} d\bar{S} = \frac{2}{4\pi t^2} \int_{B(\mathbf{x},t)} g(\mathbf{y}) (1 + (\nabla \gamma)^2)^{1/2} d\mathbf{y}$$

where $\gamma(\mathbf{y}) = \sqrt{t^2 - |\mathbf{y} - \mathbf{x}|^2}$ for $\mathbf{y} \in B(\mathbf{x}, t)$. The factor 2 enters since $\partial \bar{B}(\bar{\mathbf{x}}, t)$ consists of two hemispheres. Computation shows that $[1 + (\nabla \gamma)^2]^{1/2} = t[t^2 - |\mathbf{y} - \mathbf{x}|^2]^{-1/2}$. Therefore,

$$\oint_{\partial \bar{B}(\bar{\mathbf{x}},t)} \bar{g} d\bar{S} = \frac{t}{2} \oint_{B(\mathbf{x},t)} \frac{g(\mathbf{y})}{\sqrt{t^2 - |\mathbf{y} - \mathbf{x}|^2}} d\mathbf{y} = \oint_{B(\mathbf{0},1)} \frac{g(\mathbf{x} + t\mathbf{z})}{\sqrt{1 - |\mathbf{z}|^2}} d\mathbf{z}$$

The rest of the theorem is straight-forward computation. $\hfill\square$

7.2 Source solution for Wave Equation

We consider source solution $S(\mathbf{x}, t)$ that satisfies:

$$S_{tt} = c^2 \Delta S$$
 for $\mathbf{x} \in \mathbb{R}^n$, $t \in \mathbb{R}$ with $S(\mathbf{x}, 0) = 0$; $S_t(\mathbf{x}, 0) = \delta(\mathbf{x})$ (38)

This is referred to as the *Riemann* problem. To find formula for S, let $\psi(\mathbf{x})$ be any test function and we define

$$u(\mathbf{x},t) = \int_{\mathbb{R}^n} S(\mathbf{x} - \mathbf{y}, t) \psi(\mathbf{y}) d\mathbf{y}$$
(39)

Then, assuming integration with respect to \mathbf{x} and t commutes with the integration with respect to \mathbf{y} , it follows that u satisfies wave equation as well, and satisfies initial conditions

$$u(\mathbf{x},0) = 0$$
, and $u_t(\mathbf{x},0) = \psi(\mathbf{x})$ (40)

From D'Alembert formula, the solution to this for n = 1 is given by

$$u(x,t) = \int_{-\infty}^{\infty} S(x-y,t)\psi(y)dy = \frac{1}{2c} \int_{x-ct}^{x+ct} \psi(y)dy$$

Therefore, $S(x - y, t) = \frac{1}{2c}$ for $y - x \in (-ct, ct)$ and 0 otherwise. Therefore,

$$S(x,t) = \frac{1}{2c}$$
 for $|x| < ct$ and 0 for $|x| > ct$ for $t > 0$ (41)

Similar formula can be found for t < 0. Notice that if we replace t by -t in the initial value problem, it only reverses the sign of ψ . Using Heaviside function H^1 , we obtain

$$S(x,t) = \frac{1}{2c}H(c^{2}t^{2} - x^{2})sgn(t)$$
(42)

For 1-D, the *Riemann* function is actually a function in the usual sense. This is not the case in higher dimension, where it is a distribution.

Note from *Kirchoff*-formula that solution for t > 0 for n = 3 is given by

$$\frac{1}{4\pi c^2 t} \int_{\partial B(\mathbf{x},t)} \psi(\mathbf{y}) dS_{\mathbf{y}} = u(\mathbf{x},t) = \int_{\mathbb{R}^3} S(\mathbf{x}-\mathbf{y},t) \psi(\mathbf{y}) d\mathbf{y} = \int_0^\infty dr \int_{\partial B(\mathbf{x},r)} S(\mathbf{y}-\mathbf{x},t) \psi(\mathbf{y}) dS_{\mathbf{y}}$$
(43)

Therefore for t > 0, $S(\mathbf{x}, t) = \frac{1}{4\pi c^2 t} \delta(|\mathbf{x}| - ct)$. We can similarly analyze the solution for t < 0, noticing that that replacing t by -t in the problem posed for S has the effect of switching its sign. Therefore, for t < 0, we must have $S(\mathbf{x}, t) = -\frac{1}{4\pi c^2(-t)} \delta(|\mathbf{x}| + ct)$. A uniform expression is given by

$$S(\mathbf{x},t) = \frac{1}{2\pi c} \delta(|\mathbf{x}|^2 - c^2 t^2) sgn(t)$$

In 2-D similar calculation using Poisson formula shows

$$S(\mathbf{x}, t) = \frac{1}{2\pi c} \left(c^2 t^2 - |\mathbf{x}|^2 \right)^{-1/2} \text{ for } |\mathbf{x}| < ct \text{ and } = 0 \text{ otherwise}$$

¹Recall H(x) = 1 for x > 0 and H(x) = 0 for x < 0)