

Week 13 Notes, Math 8610, Tanveer

1. CHARACTERIZATION OF SPACES H AND V .

Recall spaces $\mathcal{V}$, H and V :

$$(1.1) \quad \mathcal{V} = \{v \in \mathcal{D}(\Omega), \nabla \cdot v = 0\}$$

and H is the closure of V in $L^2(\Omega)$, while V is the closure in $H_0^1(\Omega)$.

1.1. Characterization of gradient of a distribution. Let $\Omega \subset \mathbb{R}^n$ be open and let p be a distribution on Ω , *i.e.* using standard notation $p \in \mathcal{D}'(\Omega)$. We note that for any $v \in \mathcal{V}$,

$$(1.2) \quad \langle \nabla p, v \rangle = \langle \partial_{x_j} p, v_j \rangle = -\langle p, \partial_{x_j} v_j \rangle = 0$$

The converse of this result is also true as in the following proposition, though the proof is harder and will be skipped:

Proposition 1.1. *Let Ω be an open set of $\mathbb{R}^n$ and $f = (f_1, f_2, \dots, f_n)$, with $f_i \in \mathcal{D}'(\Omega)$. A necessary and sufficient condition that $f = \nabla p$ for some $p \in \mathcal{D}'(\Omega)$ is that*

$$(1.3) \quad \langle f, v \rangle = 0, \text{ for any } v \in \mathcal{V}$$

Definition 1.2. *We define the following subspace of $L^2(\Omega)$:*

$$(1.4) \quad L^2(\Omega)/\mathbb{R} = \left\{ p \in \mathcal{L}^2(\Omega), \int_{\Omega} p(x) dx = 0 \right\}$$

We will also use the following results without proof (See Deny & Lions *Ann. Inst. Fourier* **5**, 1954, pp 305-370.)

Proposition 1.3. *Let Ω be a bounded Lipschitz open set in $\mathbb{R}^n$.*

i. *If a distribution p has all its first-order derivatives $\partial_{x_i} p \in L^2(\Omega)$, then $p \in L^2(\Omega)$, which may be chosen to be in the subspace (1.4) with*

$$(1.5) \quad \|p\|_{L^2(\Omega)/\mathbb{R}} \leq c(\Omega) \|\nabla p\|_{L^2(\Omega)}$$

ii. *If a distribution p has all its first derivatives $\partial_{x_i} p \in H^{-1}(\Omega)$, then $p \in L^2(\Omega)$ and*

$$(1.6) \quad \|p\|_{L^2(\Omega)/\mathbb{R}} \leq c(\Omega) \|\nabla p\|_{H^{-1}(\Omega)}$$

In both cases, if Ω is any open set in $\mathbb{R}^n$, $p \in L_{loc}^2(\Omega)$.

Remark 1.4. Combining results in the previous two propositions we note that if $f \in H^{-1}(\Omega)$ (or $L_{loc}^2(\Omega)$) and $\langle f, v \rangle = 0$ for any $v \in \mathcal{V}$, then $f = \nabla p$ with $p \in L_{loc}^2(\Omega)$. Moreover, if Ω is open Lipschitz bounded, then $p \in L^2(\Omega)$ (or $H^1(\Omega)$)

2. CHARACTERIZATION OF THE SPACE H

We can now give the following characterization of H and $H^\perp$.

Theorem 2.1. *Let Ω be Lipschitz open bounded set in $\mathbb{R}^n$. Then*

$$(2.7) \quad H^\perp = \{u \in L^2(\Omega), u = \nabla p, p \in H^1(\Omega)\}$$

$$(2.8) \quad H = \{u \in L^2(\Omega), \nabla \cdot u = 0, \gamma_\nu u = 0\}$$

Proof. Assume u is in the space on the right side of (2.7). Then for any $v \in \mathcal{V}$,

$$(2.9) \quad (v, u) = (v, \nabla p) = -(\nabla \cdot v, p) = 0$$

Since $\mathcal{V}$ is dense in H , $u \in H^\perp$. Conversely, assume $u \in H^\perp$. Then for any $v \in \mathcal{V}$,

$$(2.10) \quad (u, v) = 0$$

implying from Proposition 1.1 that $u = \nabla p$ for $p \in \mathcal{D}'(\Omega)$. By proposition 1.3, $p \in H^1(\Omega)$ and therefore u belongs to the space on the right hand side of (2.7).

Assume now that $u \in H$. Then $u = \lim_{m \rightarrow \infty} u_m$ in $E(\Omega)$, where $u_m \in \mathcal{V}$. Further $\gamma_\nu u = \lim_{m \rightarrow \infty} \gamma_\nu u_m = 0$ since $\gamma_\nu u_m = u_m \cdot n = 0$ for any $u_m \in \mathcal{V}$, recalling $\mathcal{V} \subset \mathcal{D}(\Omega)$. Hence $u \in H_*$, the space on the right side of (2.8), implying $H \subset H_*$. Assume H_{**} is the orthogonal complement of H in H_* . Then from (2.7), it follows that for $u \in H_{**}$, there exists $p \in H^1(\Omega)$ with $u = \nabla p$ and moreover from (2.8), it follows that

$$(2.11) \quad \Delta p = \nabla \cdot u = 0, \quad u \cdot n = \frac{\partial p}{\partial n} = 0$$

implying p is a constant (from Remark 1.7, in extra Week 12 notes), and therefore $u = 0$. This implies $H_* = H$ ■

Theorem 2.2. *Let Ω be an open bounded set of class C^2 . Then,*

$$(2.12) \quad L^2(\Omega) = H \oplus H_1 \oplus H_2$$

$$(2.13) \quad H_1 = \{u \in L^2(\Omega), u = \nabla p, p \in H^1(\Omega), \Delta p = 0\}$$

$$(2.14) \quad H_2 = \{u \in L^2(\Omega), u = \nabla p, p \in H_0^1(\Omega)\}$$

Proof. Clearly from the characterization of $H^\perp$ in 2.1, $H_1, H_2 \subset H^\perp$. Now, take $u \in H_1$ and $v \in H_2$, with $v = \nabla p$. Then from generalized Stokes formula

$$(2.15) \quad (u, v) = (u, \nabla p) = \langle \gamma_\nu u, \gamma_0 p \rangle - (\nabla \cdot u, p) = 0$$

Therefore, $H_1 \perp H_2$. Now, we seek to show that any $u \in L^2$ can be written as a sum of u_0 , u_1 and u_2 in H , H_1 and H_2 respectively. Define $u_2 = \nabla p$, where $p \in H_0^1$ to be the unique solution of

$$(2.16) \quad \Delta p = \nabla \cdot u \in H^{-1}(\Omega)$$

We then define $u_1 = \nabla q$, where $q \in H^1(\Omega)$ is the solution (unique upto additive constant, see Remark 1.7 week 12 extra notes) to the Neumann problem

$$(2.17) \quad \Delta q = 0, \quad \frac{\partial q}{\partial n} = \gamma_\nu(u - \nabla p),$$

which exists since $\nabla \cdot (u - \nabla p) = 0$ and therefore $u - \nabla p \in E(\Omega)$ and so $\gamma_\nu(u - \nabla p) \in H^{-1/2}(\Gamma)$ is well-defined (Note Theorem 1.2 of Week 12 extra notes). Now, consider $u_0 = u - u_1 - u_2$. We note that $\nabla \cdot u_0 = \nabla \cdot u - \nabla \cdot u_1 - \nabla \cdot u_2 = 0$ and $\gamma_\nu u_0 = \gamma_\nu(u - \nabla p) - \frac{\partial q}{\partial n} = 0$. Therefore $u_0 \in H$. ■

Remark 2.1. We may define $\mathcal{P}$ to be the orthogonal projection (Hodge projection) of $L^2(\Omega)$ onto H ; clearly $\mathcal{P}$ is continuous into $L^2(\Omega)$. In fact $\mathcal{P} : H^1(\Omega) \rightarrow H^1(\Omega)$ and is continuous in the norm of H^1 . In the proof of the previous theorem, let us assume $u \in H^1(\Omega)$; then $p \in H_0^1(\Omega) \cap H^2(\Omega)$; and $u - \nabla p \in H^1(\Omega)$ and $\gamma_\nu(u - \nabla p) \in H^{1/2}(\Omega)$. Finally, we infer from (2.17) that $q \in H^2(\Omega)$ and

$$(2.18) \quad \mathcal{P}u = u - \nabla(p + q) \in H^1(\Omega)$$

It is also clear that the mappings $u \rightarrow p$ and $u - \nabla p \rightarrow q$ are continuous in the appropriate spaces and we conclude that $\mathcal{P} : H_0^1(\Omega) \rightarrow H^1(\Omega)$ is continuous with

$$(2.19) \quad \|\mathcal{P}u\|_{H^1(\Omega)} \leq c(\Omega)\|u\|_{H^1(\Omega)}$$

If Ω is C^{r+1} for integer $r \geq 1$, a similar argument shows that for $u \in H^r(\Omega)$, $\mathcal{P}u \in H^r(\Omega)$ and $\mathcal{P}$ is linear and continuous with

$$(2.20) \quad \|\mathcal{P}u\|_{H^r(\Omega)} \leq c(r, \Omega)\|u\|_{H^r(\Omega)}$$

3. CHARACTERIZATION OF SPACE V

Theorem 3.1. *Let Ω be an open bounded Lipschitz set. Then*

$$(3.21) \quad V = \{u \in H_0^1(\Omega) \mid \nabla \cdot u = 0\}$$

Proof. Define V_* to be the set on the right side of (3.21). It is clear that $V \subset V_*$ since V is the closure of $\mathcal{V}$ in H_0^1 . To prove $V = V_*$, it is enough to show that a continuous linear functional L in V_* , which

vanishes on V , is identically 0. We know there exists $l \in V'_*$ so that for any $v \in V_*$,

$$(3.22) \quad L(v) = \langle l, v \rangle$$

Since V_* is a closed subspace of $H_0^1(\Omega)$ it may be extended as a linear continuous functional on $H_0^1(\Omega)$ and so $l \in H^{-1}(\Omega)$ and we have $\langle l, v \rangle = 0$ for any $v \in \mathcal{V}$. Propositions 1.1 and 1.3 imply that $l = \nabla p$ and $p \in L^2(\Omega)$, and thus for any $v \in H_0^1(\Omega)$,

$$(3.23) \quad L(v) = \langle l, v \rangle = \langle \partial_{x_i} p, v_i \rangle = - (p, \partial_{x_i} v_i)$$

Therefore $L(v) = 0$ for $v \in V_*$. $\blacksquare$

4. EXISTENCE AND UNIQUENESS FOR THE STEADY STOKES EQUATIONS

let Ω be an open bounded set in $\mathbb{R}^n$ with boundary Γ and let $f \in L^2(\Omega)$. We seek to find solution to

$$(4.24) \quad -\nu \Delta u + \nabla p = f \text{ in } \Omega$$

$$(4.25) \quad \nabla \cdot u = 0 \text{ in } \Omega$$

$$(4.26) \quad u = 0 \text{ on } \Gamma$$

If f , u and p were smooth functions, it would follow from multiplying (4.24) and using integration by parts that for any $v \in \mathcal{V}$,

$$(4.27) \quad \nu (u, v)_1 = (f, v) ,$$

where $(u, v)_1 = (Du, Dv)$. Since each side of (4.27) depends linearly and continuously on $v \in H_0^1(\Omega)$, the equality (4.27) holds for any $v \in V$, the closure of $\mathcal{V}$ in $H_0^1(\Omega)$. If Ω is of class C^2 , then any smooth solution $u \in H_0^1(\Omega)$. From (4.25), $u \in V$ in addition to satisfying (4.27). We will now show that (4.27) provides for a weak formulation of Stokes equation (4.24)-(4.26).

Lemma 4.1. *Let Ω be an open bounded set of class C^2 . The following conditions are equivalent*

- i.** $u \in V$ and satisfies (4.27) for every $v \in V$.
- ii.** $u \in H_0^1(\Omega)$ satisfies (4.24)-(4.26) in the following weak sense: there exists $p \in L^2(\Omega)$ so that (4.24)-(4.25) are satisfied in the sense of distribution and $\gamma_0 u = 0$

Proof. If **(ii.)** is satisfied, then (4.27) follows for any $v \in \mathcal{V}$ since we can make (4.24) act on v in the sense of a distribution. Since $\mathcal{V}$ is dense in V in H_0^1 , statement **(i)** follows.

Assume now $u \in V$ satisfies (4.27) for any $v \in \mathcal{V}$. Then, it follows that

$$(4.28) \quad \langle -\nu \Delta u - f, v \rangle = 0 \text{ for any } v \in \mathcal{V}$$

From Proposition 1.1 and 1.3, there exists $p \in L^2(\Omega)$ such that

$$(4.29) \quad -\nu \Delta u - f = -\nabla p$$

in the sense of distribution. Further since $u \in V \subset H_0^1$, $\nabla \cdot u = 0$ in the sense of distribution and $\gamma_0 u = 0$; thus statement (ii) follows. ■

Theorem 4.1. (*Projection Theorem*) For any open set $\Omega \subset \mathbb{R}^n$, which is bounded in some direction and every $f \in L^2(\Omega)$, the problem (4.27) has unique solution $u \in V$ (the result is equally valid for any $f \in H^{-1}(\Omega)$). More over, there exists a function $p \in L_{loc}^2(\Omega)$ such that (4.24)-(4.25) are satisfied in the sense of distribution.

If Ω is a bounded open set of class C^2 , then $p \in L^2(\Omega)$ and (4.24)-(4.25) are satisfied by u and p .

This theorem is a consequence of Lemma 4.1 and the following (Lax-Milgram) Theorem:

Theorem 4.2. If W is a separable real Hilbert Space with norm $\|\cdot\|_W$ and let $a(u, v)$ be a linear continuous form on $W \times W$, so that there exists $\alpha > 0$ such that

$$(4.30) \quad a(u, u) \geq \alpha \|u\|_W^2, \text{ for any } u \in W$$

Then for each $l \in W'$, the dual space of W , there exists unique $u \in W$ such that

$$(4.31) \quad a(u, v) = \langle l, v \rangle, \text{ for any } v \in W$$

To apply the above Theorem to prove Theorem 4.1, we take $W = V$ and $a(u, v) = (u, v)_1$ and define l so that $\langle l, v \rangle = (f, v)$. The space V is separable as a closed subspace of a separable space $H_0^1(\Omega)$ (in particular $V = \mathcal{P}H_0^1$).

Proof of Theorem 4.2 Uniqueness part of the theorem follows from the observation that if u_1 and u_2 are two solutions then

$$(4.32) \quad a(u_1 - u_2, v) = a(u_1, v) - a(u_2, v) = 0$$

Using $v = u_1 - u_2$, we obtain $0 \geq \alpha \|u_1 - u_2\|_W^2$, implying $u_1 = u_2$. Now consider existence question. Since W is separable, there exists $\{w_i\}_{i=1}^\infty$ which forms a basis for W . Define $W_m = \text{Span}\{w_1, w_2, \dots, w_m\} \subset W$. For each fixed integer $m \geq 1$, we define approximate solution u_m :

$$(4.33) \quad u_m = \sum_{i=1}^m \xi_{i,m} w_i$$

and require it to satisfy

$$(4.34) \quad a(u_m, v) = \langle l, v \rangle \quad , \text{ for any } v \in W_m$$

By replacing v by w_j , $j = 1, \dots, m$, we get a linear system of m equations for unknowns $\{\xi_{i,m}\}_{i=1}^m$:

$$(4.35) \quad a(u_m, w_j) = \langle l, w_j \rangle \quad , \text{ for } j = 1, 2, \dots, m$$

We now claim there exists a unique solution to (4.35) for if there were two such solutions their difference v_m would satisfy

$$(4.36) \quad a(v_m, w_j) = 0$$

It follows that $a(v_m, v_m) = 0$, which implies $v_m = 0$. Therefore, we have a unique solution to (4.34). Now, by substituting $v = u_m$ in (4.34), it follows that

$$(4.37) \quad \alpha \|u_m\|_W^2 \leq \|l\|_{W'} \|u_m\|_W \quad , \text{ implying } \|u_m\|_W \leq \frac{1}{\alpha} \|l\|_{W'}$$

Therefore, there exists subsequence $u_{m'} \rightarrow u \in W$ weakly. Take $v \in W_j$ to be a fixed element for some j . Then when $m' \geq j$, $v \in W_{m'}$ and according to (4.34)

$$(4.38) \quad a(u'_{m'}, v) = \langle l, v \rangle$$

On using the following Lemma 4.2 and taking the limit $m' \rightarrow \infty$, we obtain

$$(4.39) \quad a(u, v) = \langle l, v \rangle$$

Since this is true for $v \in W_j$ for any j we have

$$(4.40) \quad a(u, v) = \langle l, v \rangle \text{ for any } v \in W$$

Lemma 4.2. *Let $a(u, v)$ be a bilinear continuous form on a Hilbert space W . Let ϕ_m (or ψ_m) be a sequence of elements of W which converges to ϕ (or ψ) in the weak (or strong) topology of W . Then*

$$(4.41) \quad \lim_{m \rightarrow \infty} a(\psi_m, \phi_m) = a(\psi, \phi)$$

$$(4.42) \quad \lim_{m \rightarrow \infty} a(\phi_m, \psi_m) = a(\phi, \psi)$$

Proof. We write

$$(4.43) \quad a(\psi_m, \phi_m) - a(\psi, \phi) = a(\psi_m - \psi, \phi_m) + a(\psi, \phi_m - \phi)$$

Since a is continuous and the sequence ϕ_m is bounded

$$(4.44) \quad \left| a(\psi_m - \psi, \phi_m) \right| \leq c \|\psi_m - \psi\|_W \|\phi_m\|_W \leq c' \|\psi_m - \psi\|_W$$

and this term converges to 0 as $m \rightarrow \infty$.

We notice next that $v \rightarrow a(\psi, v)$ is continuous on W and there exists an element $A(\psi) \in W'$ with $a(\psi, v) = \langle A(\psi), v \rangle$ for every $v \in W$. Therefore, we can write

$$(4.45) \quad \lim_{m \rightarrow \infty} a(\psi, \phi_m - \phi) = \lim_{m \rightarrow \infty} \langle A(\psi), \phi_m - \phi \rangle = 0$$

To prove the second statement (4.42), we simply use $a^*(u, v) = a(v, u)$.

■

5. EIGENFUNCTIONS OF THE STOKES PROBLEM

Let Ω be an open bounded set in $\mathbb{R}^n$. Define $\Lambda : f \rightarrow \frac{1}{\nu}u$ to be the map defined in Theorem 4.1, which is clearly a linear and continuous map from $L^2(\Omega)$ onto $V \subset H_0^1(\Omega)$. Since Ω is bounded, the injection $H_0^1(\Omega)$ in $L^2(\Omega)$ is compact, implying the compactness of the operator Λ . Further, the Λ is self-adjoint and positive operator since

$$(5.46) \quad (\Lambda f_1, f_2) = \nu (u_1, u_2)_1 = (f_1, \Lambda f_2)$$

It follows that there exists orthonormal sequence of eigenfunctions $\{w_j\}_{j=1}^\infty \in V$ and corresponding set $\{\lambda_j\}_{j=1}^\infty$ of eigenvalues with $\lambda_j > 0$ and $\lambda_j \rightarrow \infty$ such that $\Lambda w_j = \frac{1}{\lambda_j} w_j$ and for any $j \geq 1$,

$$(5.47) \quad (w_j, v)_1 = \lambda_j (w_j, v) \text{ for any } v \in V$$

$$(5.48) \quad (w_j, w_k) = \delta_{j,k}$$

$$(5.49) \quad (w_j, w_k)_1 = \lambda_j \delta_{j,k}$$

Using Theorem 4.1, it follows that for any $j \geq 1$, there exists $p_j \in L^2(\Omega)$ so that

$$(5.50) \quad -\nu \Delta w_j + \nabla p_j = \lambda_j w_j \text{ in } \Omega$$

$$(5.51) \quad \nabla \cdot w_j = 0 \text{ in } \Omega$$

$$(5.52) \quad \gamma_0 w_j = 0$$

These are the eigenfunctions of the Stokes problem. If Ω is of class C^m for integer $m \geq 2$, a iterated application of Proposition 1.3 shows that

$$(5.53) \quad w_j \in H^m(\Omega), p_j \in H^{m-1}(\Omega), \text{ for any } j \geq 1$$

If Ω is of class C^∞ , then $w_j, p_j \in C^\infty(\overline{\Omega})$. and the asymptotic behavior $\lambda_j \sim c j^{n/2}$ can be derived from a variational approach.