

## Week 6 Notes, Math 8610, Tanveer

### 1. GLOBAL EXISTENCE THEOREM FOR REGULARIZED NAVIER-STOKES

Instead of the usual Navier-Stokes equation, we consider the *regularized* Navier-Stokes equation for  $u^\epsilon(x, t)$ :

$$(1.1) \quad u_t^\epsilon + \mathcal{I}_\epsilon ([\mathcal{I}_\epsilon u^\epsilon \cdot \nabla] \mathcal{I}_\epsilon u^\epsilon) = -\nabla p^\epsilon + \nu \mathcal{I}_\epsilon \Delta u^\epsilon, \quad \nabla \cdot u^\epsilon = 0, \quad u^\epsilon(x, 0) = u_0(x)$$

Using Hodge Projection operator, we project (1.1) into the space

$$(1.2) \quad V_s \equiv \{v : v \in H_s(\mathbb{R}^N), \quad \nabla \cdot v = 0\}$$

It is easily proved that the subspace  $V_s$  of  $H_s$  is itself a Banach space. Since  $\mathcal{P}$  commutes with operators  $\mathcal{I}_\epsilon$  and  $D$ , it follows from (1.1) that

$$(1.3) \quad u_t^\epsilon + \mathcal{P} \{ \mathcal{I}_\epsilon ([\mathcal{I}_\epsilon u^\epsilon \cdot \nabla] \mathcal{I}_\epsilon u^\epsilon) \} = \nu \mathcal{I}_\epsilon \Delta u^\epsilon$$

This regularized Navier-Stokes equation reduces to an ODE in the Banach space  $V^s$  and can be written symbolically in the form

$$(1.4) \quad \frac{d}{dt} u^\epsilon = F_\epsilon(u^\epsilon), \quad u^\epsilon|_{t=0} = u_0$$

where

$$(1.5) \quad F_\epsilon(u^\epsilon) = \nu \mathcal{I}_\epsilon^2 \Delta u^\epsilon - \mathcal{P} \{ \mathcal{I}_\epsilon ([\mathcal{I}_\epsilon u^\epsilon \cdot \nabla] \mathcal{I}_\epsilon u^\epsilon) \} \equiv F_\epsilon^1(u^\epsilon) - F_\epsilon^2(u^\epsilon)$$

**Lemma 1.1.** *Picard Theorem in Banach Space*

Let  $\mathbf{O} \subset \mathbf{B}$  be an open set in a Banach space and  $F : \mathbf{O} \rightarrow \mathbf{B}$  be a mapping that satisfies the following properties:

- i.  $F$  maps  $\mathbf{O}$  to  $\mathbf{B}$ ,
- ii.  $F$  is locally Lipschitz continuous, i.e. for any  $X \in \mathbf{O}$ , there exists  $L > 0$  and an open neighborhood  $U \subset \mathbf{O}$  containing  $X$  so that

$$\|F(X_1) - F(X_2)\| \leq L \|X_1 - X_2\|, \quad \text{for all } X_1, X_2 \in U$$

Then, for any  $X_0 \in \mathbf{O}$ , there exists time  $T$  such that the ODE

$$\frac{dX}{dt} = F(X), \quad X|_{t=0} = X_0$$

has a locally unique solution  $X \in \mathbf{C}^1[(-T, T) : \mathbf{O}]$ .

**Remark 1.2.** In the preceding Lemma,  $\|\cdot\|$  denotes the norm in the Banach space  $\mathbf{B}$ .

**Remark 1.3.** The proof of Lemma 1.1 is just like the classical Picard Theorem for ODEs in  $\mathbb{R}^N$ ; only that  $\mathbb{R}^N$  is replaced by Banach space  $\mathbf{B}$ .

Recall that the classical Picard Theorem is based on contraction mapping theorem applied to the integral equation:

$$(1.6) \quad X(t) = X_0 + \int_0^t F(X(\tau))d\tau$$

Smallness of  $T$  together with Lipschitz property guarantees a unique  $\mathbf{C}^0[(-T, T), \mathbf{O}]$  solution. The differential equation immediately implies that this solution is also in  $\mathbf{C}^1[(-T, T), \mathbf{O}]$ .

**Remark 1.4.** The Lemma above only guarantees local existence in  $t$ , the existence time  $T$  depending on the Lipschitz constant in a ball containing initial condition. This is deduced easily by applying a contraction mapping argument on (1.6). To get global existence, the following Lemma is useful.

**Remark 1.5.** We will now show that each of  $F_1^\epsilon$  and  $F_2^\epsilon$  satisfies the conditions for applying Lemma 1.2 in the Banach space  $V^s$  for any fixed  $\epsilon > 0$ . By appropriately choosing an open set  $\mathbf{O} \subset V^m$ , we will use Lemma 1.3 to establish global existence as well.

**Lemma 1.6.** local existence for regularized problem

For  $\mathbf{O} \equiv \{u \in V^m, \|u\|_m < M\}$ , the function  $F_\epsilon$  defined in (1.5) satisfies the requirement that for any  $u_1, u_2 \in \mathbf{O}$ ,

$$\|F_\epsilon(u_1) - F_\epsilon(u_2)\|_m \leq c_M(\epsilon, m, N)\|u_1 - u_2\|_m$$

where constant  $c_M$  only depends on  $M$ ,  $m$ ,  $\epsilon$  and  $N$ . Thus,  $F^\epsilon$  is locally Lipschitz in  $\mathbf{O}$ .

*Proof.* Consider first  $F_\epsilon^1(u_1) - F_\epsilon^1(u_2)$ :

$$(1.7) \quad \|F_\epsilon^1(u_1) - F_\epsilon^1(u_2)\|_m = \nu \|\mathcal{I}_\epsilon^2 \Delta(u_1 - u_2)\|_m \leq \nu \|\mathcal{I}_\epsilon^2(u_1 - u_2)\|_{m+2} \leq \frac{C\nu}{\epsilon^2} \|u_1 - u_2\|_m,$$

where we used Lemma 2.4 of week 5 notes (parts iv and v). Now,

$$(1.8) \quad \begin{aligned} \|F_\epsilon^2(u_1) - F_\epsilon^2(u_2)\|_m &\leq \|\mathcal{P}\{\mathcal{I}_\epsilon([\mathcal{I}_\epsilon u_1^\epsilon \cdot \nabla]\mathcal{I}_\epsilon\{u_1^\epsilon - u_2^\epsilon\})\}\|_m + \|\mathcal{P}\{\mathcal{I}_\epsilon([\mathcal{I}_\epsilon\{u_1^\epsilon - u_2^\epsilon\} \cdot \nabla]\mathcal{I}_\epsilon u_2^\epsilon)\}\|_m \\ &\leq \|\mathcal{I}_\epsilon u_1^\epsilon\|_\infty \|\mathcal{I}_\epsilon\{Du_1^\epsilon - Du_2^\epsilon\}\|_m + \|\mathcal{I}_\epsilon\{u_1^\epsilon - u_2^\epsilon\}\|_\infty \|\mathcal{I}_\epsilon Du_2^\epsilon\|_m \\ &\leq c(\epsilon^{-N/2-1}\|u_1^\epsilon\|_0\|u_1^\epsilon - u_2^\epsilon\|_m + \epsilon^{-N/2-m-1}\|u_1^\epsilon - u_2^\epsilon\|_0\|u_2^\epsilon\|_0) \\ &\leq \frac{c}{\epsilon^{N/2+1+m}}(\|u_1^\epsilon\|_0 + \|u_2^\epsilon\|_0)\|u_1^\epsilon - u_2^\epsilon\|_m \end{aligned}$$

■

**Remark 1.7.** Note that (1.7) and (1.8) implies that the Lipschitz constant  $C$  only depends on  $N$ ,  $m$  and  $L_2$  norm of initial  $\|u^\epsilon\|_0$ , but otherwise independent of  $\|u^\epsilon\|_m$ . In the ensuing, we will show  $\|u^\epsilon(\cdot, t)\|_0 \leq \|u_0\|_0$ , and hence Lipschitz constant is independent of solution. Also, note that using  $u_2^\epsilon = 0$  and  $u_1^\epsilon = u^\epsilon$ :

$$(1.9) \quad \|F^\epsilon(u^\epsilon)\|_m \leq C(\|u^\epsilon\|_0, \epsilon, N, m) \|u^\epsilon\|_m$$

**Proposition 1.8.** Consider any initial condition  $u_0 \in V^m$ ,  $m \in \mathbb{Z}^+ \cup \{0\}$ . Then for any  $\epsilon > 0$ , there exists a unique solution  $u^\epsilon \in \mathbf{C}^1([0, T_\epsilon]; V^m)$  to (1.4), where  $T_\epsilon = T(\|u_0\|_m, \epsilon)$ . On any time interval  $[0, T]$  for which the solution belongs to  $\mathbf{C}^1([0, T]; V^0)$ ,

$$\sup_{0 \leq t \leq T} \|u^\epsilon\|_0 \leq \|u_0\|_0$$

*Proof.* Choose  $\mathbf{O} \subset V^m$  a ball of radius  $M$  that contains  $u = u_0$ . From Lemma 1.6, it follows that  $F_\epsilon$  is locally Lipschitz in  $M$ , and therefore from Picard Theorem Lemma 1.1, there exists sufficiently small  $T_\epsilon > 0$ , depending on  $\|u_0\|_m$  and  $\epsilon$ , so that there exists a unique solution  $u^\epsilon \in \mathbf{C}^1([0, T_\epsilon], \mathbf{O})$  to (1.4). This is the only solution in  $\mathbf{C}^1([0, T_\epsilon], V^m)$  since for sufficiently small  $T_\epsilon$  continuity implies that  $\|u^\epsilon - u_0\|_m$  is small.

To show the second part of the Theorem, we note that on taking the  $L_2$  inner product of (1.4) with  $u^\epsilon$ , we obtain on using properties of mollifiers and projections (see Lemma 1.13 of week 5 notes)

$$\begin{aligned} \frac{d}{dt} \frac{1}{2} \|u^\epsilon\|_0^2 &= \nu (u^\epsilon, \mathcal{I}_\epsilon^2 \Delta u^\epsilon)_0 - (u^\epsilon, \mathcal{P} \mathcal{I}_\epsilon [(\{\mathcal{I}_\epsilon u^\epsilon\} \cdot \nabla)(\mathcal{I}_\epsilon u^\epsilon)])_0 \\ &= -\nu (\mathcal{I}_\epsilon \nabla u^\epsilon, \mathcal{I}_\epsilon \nabla u^\epsilon) - (\mathcal{I}_\epsilon u^\epsilon, (\{\mathcal{I}_\epsilon u^\epsilon\} \cdot \nabla)(\mathcal{I}_\epsilon \nabla u^\epsilon))_0 \end{aligned}$$

Now since  $v^\epsilon \equiv \mathcal{I}_\epsilon u^\epsilon$  is divergence free, it follows that

$$(v^\epsilon, (v^\epsilon \cdot \nabla) v^\epsilon)_0 = 0$$

just as in the usual Navier-Stokes equation. So,

$$\frac{d}{dt} \frac{1}{2} \|u^\epsilon\|_0^2 + \nu \|\mathcal{I}_\epsilon \nabla u^\epsilon\|_0^2 = 0$$

Therefore,

$$\|u^\epsilon\|_0^2 \leq \|u_0\|_0^2$$

and the second Lemma statement follows.  $\blacksquare$

**Theorem 1.1.** *Global Existence for regularized N-S equation*

For any  $T > 0$  and initial condition  $u_0 \in V_m$ , the regularized Navier Stokes equation (1.4) has a solution  $u^\epsilon \in \mathbf{C}^1([0, T], V_m)$ .

*Proof.* First, we note from (1.4), (1.9) that

$$\frac{d}{dt} \frac{1}{2} \|u^\epsilon\|_m^2 = (u^\epsilon, \partial_t u^\epsilon)_m = (u^\epsilon, F^\epsilon(u^\epsilon))_m \leq C(\|u_0\|_0, \epsilon) \|u^\epsilon\|_m^2$$

Therefore,

$$\|u^\epsilon(\cdot, t)\|_m \leq \|u_0\|_m e^{Ct}$$

For any  $T > 0$ , choose

$$\mathbf{O} \equiv \{u^\epsilon : u^\epsilon \in V^m, \|u^\epsilon\|_m < 2\|u_0\|_m e^{CT}\}$$

We know local  $\mathbf{C}^1([0, T_\epsilon], \mathbf{O})$  solution exists from previous proposition (1.8), where  $T_\epsilon$  only depends on  $\epsilon$ ,  $m$  and  $\|u_0\|_0$ , but otherwise independent of  $\|u_0\|_m$ . This is because the Lipschitz constant as pointed out in Remark 1.7 is only dependent on  $\|u_0\|_0$ ,  $\epsilon$  and  $m$ . Since  $\|u(\cdot, T_\epsilon)\|_0 \leq \|u_0\|_0$ , we may restart the clock at  $T_\epsilon$  and continue in steps of  $T_\epsilon$  until we get to  $t = T$ . ■

**Remark 1.9.** *Though the solution to the regularized Navier-Stokes equation (1.4) exists for all time, going to the limit  $\epsilon \rightarrow 0$  is not possible with the energy bounds obtained so far because they depend badly on  $\epsilon$ . So, now we seek energy bounds independent of  $\epsilon$ ; this will be possible only locally in time, as shall be seen shortly. Nonetheless, this allows us one to take  $\epsilon \rightarrow 0$  and obtain actual solution of Navier-Stokes equation locally in time.*

**Lemma 1.10.**  *$\epsilon$  independent Energy bounds for regularized problem:*

*Let  $u_0 \in V^m$ . Then the unique solution  $u^\epsilon \in \mathbf{C}^1([0, \infty); V^m)$  to the regularized Navier-Stokes equation guaranteed by Theorem 1.1 satisfies the following inequality*

$$\frac{d}{dt} \frac{1}{2} \|u^\epsilon\|_m^2 + \nu \|\mathcal{I}_\epsilon \nabla u^\epsilon\|_m^2 \leq c_m \|\nabla \mathcal{I}_\epsilon u^\epsilon\|_\infty \|u^\epsilon\|_m^2$$

Further, for  $m > N/2 + 1$ , we obtain for sufficiently small  $T$ ,

$$\sup_{t \in [0, T]} \|u^\epsilon\|_m \leq \frac{\|u_0\|_m}{1 - c_m T \|u_0\|_m} = \|u_0\|_m + \frac{\|u_0\|_m^2 c_m T}{1 - c_m T \|u_0\|_m}$$

*Proof.* We note that for any  $\alpha$ , with  $|\alpha| \leq m$ ,

$$(1.10) \quad (D^\alpha u^\epsilon, \partial_t D^\alpha u^\epsilon)_0 = (D^\alpha u^\epsilon, D^\alpha \mathcal{I}_\epsilon^2 \Delta u^\epsilon)_0 - (D^\alpha u^\epsilon, D^\alpha \mathcal{P} \{ \mathcal{I}_\epsilon ([\mathcal{I}_\epsilon u^\epsilon \cdot \nabla] \mathcal{I}_\epsilon u^\epsilon) \})_0$$

However, it is clear from properties of  $\mathcal{I}_\epsilon$  that

$$(D^\alpha u^\epsilon, D^\alpha \mathcal{I}_\epsilon^2 \Delta u^\epsilon)_0 = - (D^\alpha \nabla \mathcal{I}_\epsilon u^\epsilon, D^\alpha \nabla \mathcal{I}_\epsilon^2 u^\epsilon)_0$$

Further, on defining  $v^\epsilon = \mathcal{I}_\epsilon u^\epsilon$ , we get

$$(1.11) \quad \begin{aligned} (D^\alpha u^\epsilon, D^\alpha \mathcal{P} \{ \mathcal{I}_\epsilon ([\mathcal{I}_\epsilon u^\epsilon \cdot \nabla] \mathcal{I}_\epsilon u^\epsilon) \})_0 &= (D^\alpha \mathcal{I}_\epsilon u^\epsilon, D^\alpha [(\mathcal{I}_\epsilon u^\epsilon \cdot \nabla) \mathcal{I}_\epsilon u^\epsilon])_0 \\ &= (D^\alpha v^\epsilon, D^\alpha [(v^\epsilon \cdot \nabla) v^\epsilon] - (v^\epsilon \cdot \nabla) D^\alpha v^\epsilon)_0, \end{aligned}$$

since for any divergence free vector field  $v^\epsilon$ ,  $(w, v^\epsilon \cdot \nabla w) = 0$ . However, taking  $w^\epsilon = D^\alpha v^\epsilon$ , we obtain from using Lemma 1.12, week 5 lecture notes:

$$| (D^\alpha v^\epsilon, D^\alpha [(v^\epsilon \cdot \nabla) v^\epsilon] - (v^\epsilon \cdot \nabla) D^\alpha v^\epsilon)_0 | \leq \|Dv^\epsilon\|_\infty \|D^\alpha v^\epsilon\|_0^2$$

for  $m > N/2 + 1$ . Therefore, it follows from (1.10)-(1.11) summing over  $\alpha$ , with  $|\alpha| \leq m$ , we obtain

$$\frac{d}{dt} \frac{1}{2} \|u^\epsilon\|_m^2 + \nu \|\mathcal{I}_\epsilon \nabla u^\epsilon\|_m^2 \leq c_m \|\nabla \mathcal{I}_\epsilon u^\epsilon\|_\infty \|u^\epsilon\|_m^2$$

Now, for  $m > N/2 + 1$ ,

$$\|\nabla v^\epsilon\|_\infty \leq c \|v^\epsilon\|_m \leq c \|u^\epsilon\|_m$$

Therefore,

$$\frac{d\|u^\epsilon\|_m}{dt} \leq c_m \|u^\epsilon\|_m^2$$

Integration gives rise to the desired energy bounds.  $\blacksquare$

## 2. LOCAL EXISTENCE FOR NAVIER-STOKES EQUATION

We now use the  $\epsilon$ -independent energy bounds for solutions to mollified Navier-Stokes equation to prove local existence of solution for the actual Navier-Stokes equation. First, we show that it forms a Cauchy sequence in an appropriate space:

**Lemma 2.1.** *For  $m > N/2 + 2$ , consider the family  $\{u^\epsilon\}_\epsilon$  of solution to the regularized N-S equation with same initial condition  $u^\epsilon(., 0) = u_0 \in V^m(\mathbb{R}^N)$  over time interval  $[0, T]$ , where  $T < \frac{1}{c_m \|u_0\|_m}$ . Note that we have  $\epsilon$ -independent energy bounds on this time interval. This forms a Cauchy sequence in  $\mathbf{C} \{[0, T], \mathbf{L}^2(\mathbb{R}^3)\}$ . Further, there exists a constant  $C$  only depending on  $\|u_0\|_m$  and time  $T$  so that for all  $\epsilon \geq \epsilon' > 0$ ,*

$$\sup_{t \in [0, T]} \|u^\epsilon - u^{\epsilon'}\|_0 \leq C\epsilon$$

*Proof.* Using  $\frac{d}{dt}u^\epsilon = F_\epsilon(u^\epsilon)$  for  $\epsilon = \epsilon$  and  $\epsilon = \epsilon'$ , subtracting the equation and taking the inner-product in  $L^2$ , we obtain

$$(2.12) \quad \frac{d}{dt} \frac{1}{2} \|u^{\epsilon'} - u^\epsilon\|_0^2 = \nu \left( \mathcal{I}_{\epsilon'}^2 \Delta u^{\epsilon'} - \mathcal{I}_\epsilon^2 \Delta u^\epsilon, u^{\epsilon'} - u^\epsilon \right) - \left( \mathcal{P} \mathcal{I}_{\epsilon'} \left[ \mathcal{I}_{\epsilon'} u^{\epsilon'} \cdot \nabla \mathcal{I}_{\epsilon'} u^{\epsilon'} - \mathcal{I}_\epsilon u^\epsilon \cdot \nabla \mathcal{I}_\epsilon u^\epsilon \right], u^{\epsilon'} - u^\epsilon \right) \equiv T_1 + T_2$$

We first estimate  $T_1$ :

$$(2.13) \quad T_1 = \nu \left( \{ \mathcal{I}_{\epsilon'}^2 - \mathcal{I}_\epsilon^2 \} \Delta u^{\epsilon'}, u^{\epsilon'} - u^\epsilon \right) + \nu \left( \mathcal{I}_\epsilon^2 \Delta [u^{\epsilon'} - u^\epsilon], u^{\epsilon'} - u^\epsilon \right)$$

Using part (iv) of Lemma 1.13 of week 5 notes, and taking  $w = \Delta u^{\epsilon'}$ , we obtain

$$\| \mathcal{I}_{\epsilon'}^2 w - \mathcal{I}_\epsilon^2 w \| \leq \| \mathcal{I}_{\epsilon'}^2 w - \mathcal{I}_{\epsilon'} w \| + \| \mathcal{I}_{\epsilon'} w - w \| + \| \mathcal{I}_\epsilon^2 w - \mathcal{I}_\epsilon w \| + \| \mathcal{I}_\epsilon w - w \|_0 \leq C \epsilon \| w \|_1$$

Therefore, using above and integration by parts on the latter term in  $T_1$ , we obtain

$$(2.14) \quad |T_1| \leq C \nu \epsilon \| u^\epsilon \|_3 \| u^{\epsilon'} - u^\epsilon \|_0 - \nu \| \mathcal{I}_\epsilon \nabla (u^{\epsilon'} - u^\epsilon) \|_0^2$$

Now, with respect to  $T_2$ , it is convenient to decompose

$$\begin{aligned} T_2 &= \left( \mathcal{P} (\mathcal{I}_{\epsilon'} - \mathcal{I}_\epsilon) \left[ \mathcal{I}_{\epsilon'} u^{\epsilon'} \cdot \nabla \mathcal{I}_{\epsilon'} u^{\epsilon'} \right], u^{\epsilon'} - u^\epsilon \right) + \left( \mathcal{P} \mathcal{I}_\epsilon \left[ (\mathcal{I}_{\epsilon'} - \mathcal{I}_\epsilon) u^{\epsilon'} \cdot \nabla \mathcal{I}_{\epsilon'} u^{\epsilon'} \right], u^{\epsilon'} - u^\epsilon \right) + \\ &+ \left( \mathcal{P} \mathcal{I}_\epsilon \left[ \mathcal{I}_\epsilon (u^{\epsilon'} - u^\epsilon) \cdot \nabla \mathcal{I}_{\epsilon'} u^{\epsilon'} \right], u^{\epsilon'} - u^\epsilon \right) + \left( \mathcal{P} \mathcal{I}_\epsilon \left[ \mathcal{I}_\epsilon u^\epsilon \cdot \nabla (\mathcal{I}_{\epsilon'} - \mathcal{I}_\epsilon) u^{\epsilon'} \right], u^{\epsilon'} - u^\epsilon \right) \\ &+ \left( \mathcal{P} \mathcal{I}_\epsilon \left[ \mathcal{I}_\epsilon u^\epsilon \cdot \nabla \mathcal{I}_\epsilon (u^{\epsilon'} - u^\epsilon) \right], u^{\epsilon'} - u^\epsilon \right) \equiv T_{2,1} + T_{2,2} + T_{2,3} + T_{2,4} + T_{2,5} \end{aligned}$$

Now, we note that for some  $C$ , independent of  $\epsilon$ ,

$$|T_{2,1}| \leq C \epsilon \| u^{\epsilon'} \|_1 \| u^{\epsilon'} - u^\epsilon \|_0 \| \mathcal{I}_\epsilon' \nabla u^{\epsilon'} \|_\infty \leq C \epsilon \| u^{\epsilon'} \|_m^2 \| u^\epsilon - u^{\epsilon'} \|_0$$

$$|T_{2,2}| \leq C \epsilon \| u^{\epsilon'} \|_1 \| u^{\epsilon'} - u^\epsilon \|_0 \| \mathcal{I}_{\epsilon'} \nabla u^{\epsilon'} \|_\infty \leq C \epsilon \| u^{\epsilon'} \|_m^2 \| u^\epsilon - u^{\epsilon'} \|_0$$

$$|T_{2,3}| \leq C \| u^{\epsilon'} - u^\epsilon \|_0^2 \| \mathcal{I}_{\epsilon'} \nabla u^{\epsilon'} \|_\infty \leq C \| u^{\epsilon'} \|_m \| u^\epsilon - u^{\epsilon'} \|_0^2$$

$$|T_{2,4}| \leq C \epsilon \| u^{\epsilon'} \|_1 \| u^{\epsilon'} - u^\epsilon \|_0 \| \mathcal{I}_{\epsilon'} \nabla u^{\epsilon'} \|_\infty \leq C \epsilon \| u^{\epsilon'} \|_m^2 \| u^\epsilon - u^{\epsilon'} \|_0$$

For  $T_{2,5}$ , it is useful to substitute  $v = \mathcal{I}_\epsilon u^\epsilon$ ,  $w = \mathcal{I}_\epsilon (u^{\epsilon'} - u^\epsilon)$ . Note that  $w$  and  $v$  is divergence free. Then we note that

$$T_{2,5} = (v \cdot \nabla w, w) = \int_{x \in \mathbb{R}^N} w_i v_j \partial_{x_j} w_i = 0$$

Therefore, from (2.12) and previous  $\epsilon$  independent bound on  $\| u^\epsilon \|_m$  over an interval  $[0, T]$ , (in last week's notes), it follows that

$$\frac{d}{dt} \| u^{\epsilon'} - u^\epsilon \|_0 \leq C_m(T) \left( \epsilon + \| u^{\epsilon'} - u^\epsilon \|_0 \right)$$

Using Gronwall's inequality, it follows that there exists some constant  $C$  depending on  $T$  so that for any  $t \in [0, T]$ ,

$$\|u^{\epsilon'}(., t) - u^\epsilon(., t)\|_0 \leq \epsilon C$$

■

**Proposition 2.2.** *If initial condition  $u_0 \in V^m$  for  $m > N/2 + 2$ , then for  $T < \frac{1}{c_m \|u_0\|_m}$ , there exists a solution to Navier-Stokes equation  $u \in \mathbf{C}([0, T], V^{m'}(\mathbb{R}^N))$ , while  $\partial_t u \in \mathbf{C}([0, T], V^{m'-2}(\mathbb{R}^N))$  for any  $N/2 + 2 < m' < m$ . More over, this solution is classical in the sense that  $u \in \mathbf{C}^0([0, T], \mathbf{C}^2(\mathbb{R}^N))$ ,  $\partial_t u \in \mathbf{C}^0([0, T], \mathbf{C}(\mathbb{R}^N))$ .*

*Proof.* Assume without loss of generality that  $\epsilon' \leq \epsilon$ . We note that for  $t \in [0, T]$ ,  $\|v^\epsilon\|_m \leq C$ , independent of  $\epsilon$ . From interpolation inequality for Sobolev norms and Lemma (2.12), for any  $t \in [0, T]$ ,

$$\|u^\epsilon(., t) - u^{\epsilon'}(., t)\|_{m'} \leq c \|u^\epsilon(., t) - u^{\epsilon'}(., t)\|_0^{1-m'/m} \|u^\epsilon(., t) - u^{\epsilon'}(., t)\|_m^{m'/m} \leq C_m(T) \epsilon^{1-m'/m}$$

Thus,  $u^\epsilon$  forms a Cauchy sequence in  $\mathbf{C}^0([0, T], V^{m'}(\mathbb{R}^N))$  and hence converges to a function  $u$  in the same space. Since  $m' > N/2 + 2$ , it follows that  $u \in \mathbf{C}^0([0, T], \mathbf{C}^2(\mathbb{R}^N))$ . Further, by taking the limit of  $\epsilon \rightarrow 0$  it follows that

$$\lim_{\epsilon \rightarrow 0^+} \nu (\mathcal{I}_\epsilon^2 \Delta u^\epsilon - \mathcal{P} \mathcal{I}_\epsilon [\mathcal{I}_\epsilon u^\epsilon \cdot \nabla \mathcal{I}_\epsilon u^\epsilon]) = \nu \Delta u - \mathcal{P}[u \cdot \nabla u]$$

Therefore,

$$\lim_{\epsilon \rightarrow 0} u_t^\epsilon = \nu \Delta u - \mathcal{P}[u \cdot \nabla u]$$

and the limiting function satisfies Navier-Stokes equation. Since  $\lim_{\epsilon \rightarrow 0} u^\epsilon = u$  in  $\mathbf{C}^0([0, T], V^{m'}(\mathbb{R}^N))$ , it follows that at least in the sense of distribution, we have  $\lim_{\epsilon \rightarrow 0^+} u_t^\epsilon = u_t$ . Therefore, the limiting function  $u$  satisfies the Navier-Stokes equation and satisfies initial condition  $u_0$ . From the equation itself, it follows that we have  $u_t \in \mathbf{C}^0([0, T], V^{m'-2}(\mathbb{R}^N))$ .

■

**Remark 2.3.** *The above proposition is not completely satisfactory since it suggests that if  $u_0 \in V^m$ , then it only assures  $u(., t) \in V^{m'}$ , for  $m' < m$ . In reality  $u(., t) \in V^m$  as well. However, to show this we need to work a bit harder.*

**Definition 2.4.** *A sequence  $\{v_n\}_n$  in a Hilbert Space  $\mathcal{H}$  is said to converge weakly to  $v$  if for any  $w \in \mathcal{H}$ ,  $\lim_{n \rightarrow \infty} (w, v_n) = (w, v)$ .*

A property of weakly convergent sequence that will be important for us is that they are also bounded. Also, the following Theorem proved in any standard text in analysis is useful:

**Theorem 2.1.** (*Banach-Alaogou Theorem*) Any bounded sequence in a Hilbert Space<sup>(1)</sup> has a subsequence that converges weakly.

**Remark 2.5.** In our context, the Hilbert Space  $\mathcal{H} = V^m$ .

**Definition 2.6.** A function  $v(., t) \in \mathcal{B}$ , a reflexive Banach Space, is said to be weakly continuous for  $t \in [0, T]$  if for any  $w \in \mathcal{B}^*$ , the dual Banach space, we have  $\langle w, v(., t) \rangle$  a continuous function of  $t \in [0, T]$ .

**Theorem 2.2.** *Local Existence of N-S solutions* Let  $u$  be the solution described by the previous proposition. Then

$$v \in \mathbf{C}([0, T], V^m) \cup \mathbf{C}^1([0, T], V^{m-2})$$

*Proof.* We know from prior energy estimates on the regularized Navier-Stokes equation that

$$\sup_{t \in [0, T]} \|u^\epsilon\|_m \leq M$$

and from the regularized N-S equation itself, it follows that

$$\sup_{t \in [0, T]} \|u^\epsilon\|_{m-2} \leq M_1$$

for some constants  $M$  and  $M_1$ . Since  $\{u^\epsilon\}_{\epsilon=1/n}$  is a bounded sequence in the Hilbert Space  $L^2([0, T], V^m)$ . Theorem 2.1 implies that there exists a subsequence which converges to  $u \in L^2([0, T], V^m)$ , as  $n \rightarrow \infty$  ( $\epsilon \rightarrow 0$ ). This must be the same  $u$  as in Proposition 2.2 since  $V^{m'} \subset V^m$  and  $\lim_{\epsilon \rightarrow 0} u^\epsilon = u$  in  $\mathbf{C}([0, T], V^{m'})$ . Further, for each  $t \in [0, T]$ , since  $u^\epsilon$  is a bounded sequence in the Hilbert Space  $V^m$ , there is a subsequence that converges to  $u(., t) \in V^m$ . Thus, it follows that

$$u \in \mathbf{L}^\infty([0, T], V^m)$$

Further, we claim

$$u \in \mathbf{C}_W([0, T], V^m)$$

First, we note that for  $0 < m' < m$ , the space  $V^{-m'}$  is dense in  $V^{-m}$ . Hence we take arbitrary  $\phi \in V^{-m'}$  and note that  $\langle \phi, u(., t) \rangle$  is continuous in  $t$  for  $t \in [0, T]$ , because  $u \in \mathbf{C}([0, T], V^{m'})$ . Therefore, the claim follows.

In view of weak continuity, we note that

$$\lim_{\delta \rightarrow 0} (u(., t+\delta) - u(., t), u(., t+\delta) - u(., t))_m = \lim_{\delta \rightarrow 0} (\|u(., t+\delta)\|_m^2 - \|u(., t)\|_m^2)$$

Thus to show  $u \in \mathbf{C}([0, T], V^m)$ , it is enough to show  $\|u(., t)\|_m$  is continuous.

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<sup>(1)</sup>More generally a reflexive Banach Space, in which case the definition of weak convergence involves the dual space



We first prove the right continuity at  $t = 0$ . We choose  $\phi_0 \in V^{-m}$  so that for any  $v \in V_m$ ,  $\langle \phi_0, v \rangle = (u_0, v)_m$ . In particular, this implies  $\|u_0\|^2 = \langle \phi_0, u_0 \rangle$ . Then from weak continuity,

$$\lim_{t \rightarrow 0^+} \langle \phi_0, u(\cdot, t) \rangle = \|u_0\|_m^2$$

Therefore, since  $\|u_0\|_m \|u\|_m \geq \langle \phi_0, u \rangle$

$$\liminf_{t \rightarrow 0^+} \|u(\cdot, t)\|_m \geq \|u_0\|_m$$

Now, from energy bounds,

$$\sup_{t \in [0, T]} \|u(\cdot, t)\|_m - \|u_0\|_m \leq \frac{\|u_0\|_m^2 c_m T}{1 - c_m T \|u_0\|_m}$$

Therefore,

$$\limsup_{t \rightarrow 0^+} \|u(\cdot, t)\|_m \leq \|u_0\|_m$$

So, right continuity of  $\|u(\cdot, t)\|_m$  has been proved at  $t = 0$ . It is clear that for any  $t \in [0, T]$ , we can repeat the same argument to show the right continuity.

To show left continuity, we have to deal differently for  $\nu = 0$  (Euler Equation) and  $\nu > 0$ .

For  $\nu = 0$ , the equations are time reversible, meaning that if we replace  $t$  by  $-t$  and  $u$  by  $-u$ , we get back the same (Euler) equation. So, left continuity follows from the same argument as the one above for right continuity.

For  $\nu > 0$ , we recall the energy inequality for  $t \in [0, T]$ :

$$\|u^\epsilon(\cdot, t)\|_m^2 + \nu \int_0^t \|\mathcal{I}_\epsilon \nabla u^\epsilon(\cdot, \tau)\|_m^2 d\tau = \|u^\epsilon(\cdot, 0)\|_m^2,$$

implying that there exists  $C$  independent of  $\epsilon$  so that

$$\nu \int_0^T \|\mathcal{I}_\epsilon \nabla u^\epsilon(\cdot, t)\|_m^2 dt \leq C$$

Since  $\|\mathcal{I}_\epsilon v\|_{m+1} \rightarrow \|v\|_{m+1}$  as  $\epsilon \rightarrow 0^+$ , it follows that  $\{u^\epsilon\}_{\epsilon=1/n}$  is a bounded sequence in the Hilbert space  $L^2([0, T], V^{m+1})$ . It follows that there is a subsequence that converges to  $u$  as  $\epsilon \rightarrow 0$ . This implies that for almost any  $t \in [0, T]$ ,  $u(\cdot, t) \in V^{m+1}$ . Suppose we want to show left continuity at  $t = T_1 \in [0, T]$ . We choose  $T_1 > T_0 > 0$  so that solution  $u(\cdot, T_0) \in V^{m+1}$ . Then, starting at  $T = T_0$ , we continue. We can apply Proposition 2.2, with initial condition  $u(\cdot, T_0)$ . This ensures solution in  $\mathbf{C}([T_0, T'], V^{\tilde{m}})$  for  $\tilde{m} < m + 1$  for some  $T' > T_0$ . However, from uniqueness of classical solution, it follows that this is the same solution  $u \in \mathbf{C}([0, T], V^{m'})$  for  $m' < m$  guaranteed by Proposition 2.2. Therefore,  $u \in \mathbf{C}([T_0, T'], V^{\tilde{m}})$  can be continued past  $T'$  if

$\|u(., T')\|_{m+1} < \infty$  Indeed,  $T'$  can be extended to be as large as we like so long as  $\|u(., t)\|_{m+1}$  remains finite for  $t \in [T_0, T']$ .

However, in the process of derivation of  $\epsilon$  independent energy bounds (see Lemma 1.10 first statement), we notice that as long as  $\|\mathcal{I}_\epsilon \nabla u^\epsilon\|_\infty < C$ , where  $C$  is independent of  $\epsilon$ , then so is  $\|u^\epsilon(., t)\|_{m+1}$ . However,  $\|\mathcal{I}_\epsilon \nabla u^\epsilon(., t)\|_\infty \leq c\|u^\epsilon(., t)\|_m < C$ , independent of  $\epsilon$  for  $t \in [0, T]$ . Therefore,  $\|u(., t)\|_{m+1} < \infty$  for  $t \in [T_0, T']$  for any  $T' \leq T$ . Therefore  $u \in \mathbf{C}([T_0, T], V^{\tilde{m}})$  for any  $\tilde{m} < m + 1$  and in particular for  $\tilde{m} = m$ . Hence the left continuity of  $\|u(., t)\|_m$  at  $T = T_1$  follows. ■

### 3. SUFFICIENT CONDITION FOR GLOBAL EXISTENCE FOR N-S SOLUTION

First, we show that local unique NS solution in  $C([0, T], V_m)$  for  $m > \frac{N}{2} + 2$  that was proved in the last section may be extended beyond  $T$  (Recall  $T < \frac{1}{c_m \|u_0\|_m}$ ) as long as  $\|u(., t)\|_m$  remains finite.

**Lemma 3.1.** *Assume  $[0, \tilde{T})$  is the largest interval for which NS solution  $u \in C([0, \tilde{T}), V_m)$  for  $m > \frac{N}{2} + 2$  exists. If  $\tilde{T} < \infty$ , then  $\|u(., t)\|_m$  blows up as  $t \rightarrow \tilde{T}^-$ .*

*Proof.* Assume otherwise; therefore,  $\sup_{t \in [0, \tilde{T})} \|u(., t)\|_m \leq M < \infty$ . We know that if we restart the clock at any  $t_0 \in [0, \tilde{T})$ , solution will exist over a time interval  $[t_0, t_0 + T]$  for any  $T < \frac{1}{c_m M}$ . In particular, if we choose  $t_0 = \tilde{T} - \frac{1}{2c_m M}$ , the interval  $[0, t_0 + T]$  of existence of NS solution will exceed  $[0, \tilde{T})$  contradicting the definition of  $\tilde{T}$ . Hence  $\|u(., t)\|_m$  cannot remain finite as  $t \rightarrow \tilde{T}^-$ . ■

**Corollary 3.2.** *If for finite  $\tilde{T}$ ,  $[0, \tilde{T})$  is the maximal time for existence of NS solution in  $V_m$  for  $m > \frac{N}{2} + 2$ , then  $\int_0^t \|\nabla u(., \tau)\|_\infty d\tau$  must blow up as  $t \rightarrow \tilde{T}^-$ .*

*Proof.* This simply follows from energy inequality, which follows from the first statement of Lemma 1.10 as  $\epsilon \rightarrow 0$ :

$$\frac{d}{dt} \frac{1}{2} \|u(., t)\|_m^2 \leq C_m \|\nabla u(., t)\|_\infty \|u(., t)\|_m^2$$

and use of Gronwall and previous Lemmas. ■

We will now prove a sufficient condition for global existence of classical solutions to Navier-Stokes equation is the existence of  $L^1$  in time bounds of the  $L^\infty$  space norm of the vorticity.

For that purpose we need some properties of the Biot Savart Kernel  $K_N(x)$  that occurs in the relation between velocity and vorticity. Recall that in 2-D,

$$(3.15) \quad K_2(x) = \frac{1}{2\pi|x|^2} (-x_2, x_1),$$

where as in 3-D,  $K_3$  is an operator defined by

$$(3.16) \quad K_3(x)h = \frac{1}{4\pi} \frac{x \times h}{|x|^3}$$

It is to be noted from (3.18) and (3.16) that

$$(3.17) \quad K_N(\lambda x) = \lambda^{1-N} K_N(x), \text{ for } \lambda > 0, 0 \neq x \in \mathbb{R}^N$$

and hence  $K_N$  is homogeneous of degree  $(1 - N)$ .

**Definition 3.3.** *The principal value integral  $PV \int_{\mathbb{R}^N}$  will be defined such that*

$$PV \int_{\mathbb{R}^N} f(x)dx = \lim_{\epsilon \rightarrow 0^+} \int_{|x| > \epsilon} f(x)dx$$

**Lemma 3.4.** *Let  $K(x)$  be a function smooth outside  $x = 0$  and homogeneous of degree  $1 - N$ . Then  $\partial_{x_j} K$  in the sense of distribution is a linear functional defined by*

$$(\partial_{x_j} K, \phi)_0 = -(K, \partial_{x_j} \phi)_0 = PV \int_{\mathbb{R}^N} \partial_{x_j} K \phi dx - c_j(\delta, \phi)_0, \text{ for all } \phi \in \mathbf{C}_c^\infty,$$

where  $\delta$  is the Dirac distribution and  $c_j = \int_{|x|=1} x_j K(x) dx$

*Proof.* We note that since  $K \in L_{loc}^1(\mathbb{R}^N)$ , from use of dominated convergence theorem, it follows that

$$(K, \partial_{x_j} \phi)_0 = \lim_{\epsilon \rightarrow 0^+} \int_{|x| \geq \epsilon} K \partial_{x_j} \phi dx = \lim_{\epsilon \rightarrow 0^+} \left\{ - \int_{|x| \geq \epsilon} \partial_{x_j} K \phi dx + \int_{|x|=\epsilon} K \phi \frac{x_j}{|x|} dx \right\}$$

The first term on the right hand side gives  $PV \int$ . In the second term changing variable  $x \rightarrow \epsilon x$  and use of homogeneous property of  $K$  gives rise to

$$\lim_{\epsilon \rightarrow 0^+} \int_{|x|=\epsilon} K \phi \frac{x_j}{|x|} dx = \lim_{\epsilon \rightarrow 0^+} \int_{|x|=1} \epsilon^{1-N} K(x) \phi(\epsilon x) \frac{x_j}{|x|} \epsilon^{N-1} dx = \phi(0) c_j$$

Hence the Lemma follows.  $\blacksquare$

**Lemma 3.5. Potential Theory Results**

*Let  $u$  be a smooth,  $L^2 \cap L^\infty$  divergence free velocity field and  $\omega = \nabla \times u$ . Then*

$$\|\nabla u\|_\infty \leq c \left( 1 + \ln^+ \|u\|_3 + \ln^+ \|\omega\|_0 \right) (1 + \|\omega\|_\infty),$$

where  $\ln^+ v = \ln v$  if  $v > 1$  and 0 otherwise.

**Remark 3.6.** *The proof relies on the expression*

$$(3.18) \quad \nabla u(x) = PV \int_{\mathbb{R}^N} \nabla_x K_N(x-y) \omega(y) dy + c\omega(x)$$

*Details given in Proposition 3.8 and Lemma 4.6 in Bertozzi & Majda book. This is a result from potential theory and has nothing to do with the evolution of  $u(x, t)$  in Navier-Stokes equation.*

**Theorem 3.1.** *Beale-Kato-Majda sufficient condition for global regularity*

*Let initial  $u_0 \in V^m$ ,  $m > N/2 + 2$  so that there exists a classical solution  $u$  to Navier-Stokes or Euler equation, locally in time. Then, if for any  $T > 0$ , if there exists constant  $C$  so that*

$$\int_0^T \|\omega(\cdot, t)\|_\infty dt \leq C,$$

*then, the solution to Navier-Stokes equation exists globally in time, i.e.  $u \in \mathcal{C}^0([0, \infty), V^m) \cap \mathcal{C}^1([0, \infty), V^{m-2})$ . Also, if the maximal time for existence  $T < \infty$ , then*

$$\lim_{t \rightarrow T^-} \int_0^T \|\omega(\cdot, t)\|_\infty dt = \infty$$

*Proof.* We have shown that

$$\int_0^T \|\nabla u(\cdot, t)\|_\infty dt \leq C,$$

is enough to guarantee a classical solution in  $[0, T]$  since

$$\|u(\cdot, T)\|_m \leq \|u_0\|_m \exp \left[ \int_0^T c_m \|\nabla u(\cdot, t)\|_\infty dt \right]$$

So, we only need to show that  $\int_0^T \|\nabla u(\cdot, t)\|_\infty dt$  is controlled by similar integral over  $\omega$ .

Since vorticity  $\omega$  satisfies

$$\omega_t + u \cdot \nabla \omega = \omega \cdot \nabla u + \nu \Delta \omega$$

by taking the inner product with  $\omega$  it follows that

$$\frac{d}{dt} \frac{1}{2} \|\omega(\cdot, t)\|_0^2 \leq \|\nabla u(\cdot, t)\|_\infty \|\omega(\cdot, t)\|_0^2,$$

implying

$$\|\omega(\cdot, t)\|_0 \leq \|\omega_0\|_0 \exp \left[ \int_0^T \|\nabla u(\cdot, t)\|_\infty dt \right]$$

Using above estimate on  $\|u(.,t)\|_m$  for  $m = 3$  and above estimate for  $\|\omega(.,t)\|_0$ , it follows from the potential theory estimates of 3.5 that

$$\|\nabla u(.,t)\|_\infty \leq C \left[ 1 + \int_0^t \|\nabla u(.,\tau)\|_\infty d\tau \right] (1 + \|\omega(.,t)\|_\infty)$$

Therefore, using Gronwall's Lemma

$$\|\nabla u(.,t)\|_\infty \leq \|\nabla u_0\|_\infty \exp \left[ C \int_0^t (1 + \|\omega(.,\tau)\|_\infty) d\tau \right]$$

■

**Corollary 3.7.** *For  $N = 2$ , NS solution  $u(.,t) \in V_m$  exists globally in time.*

*Proof.* Assume otherwise, i.e. there exists maximal time interval  $[0, T)$ , for  $T < \infty$ . Recall in 2-D scalar  $\omega$  satisfies

$$\omega_t + u \cdot \nabla \omega = \nu \Delta \omega,$$

using maximum principle,  $\|\omega(.,t)\|_\infty \leq \|\omega_0\|_\infty$ , implying that  $\int_0^T \|\omega(.,t)\|_\infty dt$  is finite and hence from BKM, solution exists in  $[0, T]$ . Since  $\|u(.,T)\|_m$  is finite, the solution may be extended beyond  $T$ , contradicting definition of  $T$ . ■

**Remark 3.8.** *Note that the above Corollary holds for forced NS equation as well using similar arguments.*